# Size Wu

S-Lab for Advanced Intelligence Nanyang Technological University 50 Nanyang Avenue, Singapore 639798 Cellphone: +65 8048 1678 Email: size001@e.ntu.edu.sg GitHub: https://github.com/wusize

#### EDUCATION

# Nanyang Technological University (NTU)

Ph.D. student in School of Computer Science and Engineering

University of Science and Technology of China (USTC)

Bachelor of Electronic and Information Engineering (AI)

GPA: 3.8/4.3 (Ranking Top 10%)

Singapore, Singapore Jan 2022—Present Hefei, China Aug 2017—Jun 2021

# RESEARCH INTERESTS

Open-vocabulary Visual Recognition; Object Detection; Vision-language Models; Multi-view Human Pose Estimation

## Papers & Patents

- [1] **Size Wu**, Wenwei Zhang, Sheng Jin, Wentao Liu, and Chen Change Loy. Aligning bag of regions for open-vocabulary object detection. In *CVPR*, 2023.
- [2] **Size Wu**, Sheng Jin, Wentao Liu, Lei Bai, Chen Qian, Dong Liu, and Wanli Ouyang. Graph-based 3d multi-person pose estimation using multi-view images. In *ICCV*, 2021.
- [3] Jiahang Wang, **Size Wu**, Sheng Jin, Wentao Liu, and Chen Qian. Object detection method, device, electronic equipment and storage medium, 2022. Chinese Invention Patent, CN115131705A.
- [4] Size Wu, Sheng Jin, Wentao Liu, and Chen Qian. 3d keypoint detection method, device, electronic equipment and storage medium, 2021. Chinese Invention Patent, CN113610967A.
- [5] Size Wu, Sheng Jin, Wentao Liu, and Chen Qian. 3d human pose adjustment method, device, electronic equipment and storage medium, 2021. Chinese Invention Patent, CN113610966A.

## RESEARCH EXPERIENCE

#### Ph.D. Student

NTU, Jan 2022—Present

- Augmentation for Open-Vocabulary Object Detection: Propose an augmentation on image-text pairs for open-vocabulary object detection (OVD), which improves several main-stream OVD methods on multiple benchmarks. Submitted to ICCV 2023.
- Aligning Bag of Regions for Open-vocabulary Object detection: Propose to distill knowledge from pretrained vision-language models (VLMs) on a bag of regions for open-vocabulary object detection (OVD). The method effectively exploits the VLMs' ability to represent co-existing and contextually related concepts. It achieves state-of-the-art performance on multiple OVD benchmarks. CVPR 2023. Code.

## Research Intern

SenseTime, Beijing, Oct 2020—Dec 2021

- Multi-view 3D Human Pose Estimation: Propose three task-specific graph neural networks (GNNs) for multi-view Human Pose Estimation. The GNNs efficiently match human centers, locate human locations and refine human pose estimations. The proposed method achieves state-of-the-art performance on CMU Panoptic and Shelf datasets with significantly lower computation complexity. ICCV 2021. Code.
- Multi-view Multi-person Tracking: Give solution to the Multi-camera Multiple People Tracking (MMP-Tracking) Challenge by aggregating geometric and appearance features. The method is applied in industrial projects. Achieve the 3rd place in the top-down view track without expensive training in a challenge in the ICCV 2021 Multicamera Multiple People Tracking Workshop.

# **National Innovation Training Program**

**USTC**, April 2019—Dec 2020

• Image Colorization: Use deep learning approach to automatically colorize gray-scale images. The techniques exploited in this project mainly include feature extraction/aggregation, self- attention mechanism, adversarial training, etc. Code.

## OPEN-SOURCE PROJECT

MMPose

Oct 2020—Present

I am one of the developers of MMPose, an open-source project in GitHub for 2d and 3d human pose estimation. And I am the core developer of the multi-view 3d pose estimation in MMPose.

# CORE QUALIFICATIONS

**Programming**: Python, C/C++, MATLAB

English: TOEFL 106/120, GRE 337/340+4.0/5.0

# AWARDS AND HONORS

- $\bullet$  Scholarship For Outstanding students, USTC. 2018—2020.
- National Encouragement Scholarship, USTC. 2018, 2019.
- $\bullet$  Talent Program in Information Science and Technology. USTC. 2017—2021.
- Security AI Challenger: Ninth Place Award (out of 36489 teams), Alibaba Cloud Tianchi. 2021
- AI Innovation and Application Competition: Second Place Award, CAICT. 2021
- Multi-camera Multiple People Tracking Challenge: Third place in Top-down View Track, ICCV2021.