

A²-FLOW: ALIGNMENT-AWARE PRE-TRAINING FOR SPEECH SYNTHESIS WITH FLOW MATCHING

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ABSTRACT

Recent advances in speech synthesis have enabled highly natural and speaker-adaptive speech generation by leveraging large-scale transcribed datasets. However, requiring tens of thousands of hours of annotated speech is impractical in low-resource settings. Existing pre-trained speech models often utilize masked speech inpainting for pre-training and show strong performance on various speech generation tasks using limited task-specific data. Nonetheless, these models still require external alignment mechanisms or extensive additional training to learn alignment for alignment-aware tasks, such as text-to-speech (TTS). In this paper, we propose A²-Flow, an alignment-aware pre-training method for flow matching models in speech synthesis. A²-Flow integrates alignment learning directly into the pre-training process using discrete speech units, enabling the model to efficiently adapt to alignment-aware tasks without the need for separate alignment mechanisms. By embedding alignment learning into pre-training, A²-Flow facilitates alignment-free voice conversion (VC) and allows for faster convergence during TTS fine-tuning, even with limited transcribed data, making it highly suitable for low-resource scenarios. Experimental results show that A²-Flow superior zero-shot VC performance compared to existing models and matches state-of-the-art TTS performance using only a small amount of transcribed data. Moreover, we demonstrate that A²-Flow can be more efficiently applied to alignment-aware speech synthesis tasks than existing pre-training methods, providing a practical and scalable solution for high-quality speech synthesis across diverse settings.

1 INTRODUCTION

Large-scale speech synthesis models have shown exceptional performance in generating highly natural and expressive speech across a wide range of emotions and voice styles, achieving impressive zero-shot text-to-speech (TTS) capabilities even with minimal reference audio (Wang et al., 2023; Kim et al., 2024; Le et al., 2023; Kharitonov et al., 2023; Eskimez et al., 2024). Many non-autoregressive zero-shot TTS models (Shen et al., 2024; Kim et al., 2023b; Le et al., 2023) follow the approach of early non-autoregressive models (Ren et al., 2019; Kim et al., 2020) by using a phoneme duration predictor to align phonemes with speech. This approach simplifies the training of generative decoders by allowing them to focus solely on speech generation rather than alignment modeling. However, the naturalness of the generated speech becomes highly dependent on the performance of the duration predictor, and this approach limits the generative decoder’s ability to capture richer information beyond alignment.

Recent non-autoregressive TTS approaches have aimed to eliminate the need for external alignment models by learning alignment jointly with speech generation (Lee et al., 2024; Lovelace et al., 2024; Gao et al., 2023; Eskimez et al., 2024). Among these, E2TTS (Eskimez et al., 2024) uses a flow matching decoder to jointly model text-speech alignment and speech generation, resulting in highly natural prosody and improved generalization to new speakers. However, similar to other zero-shot TTS models, E2TTS relies on a large amount of transcribed data, which is often unavailable in low-resource settings. SpeechFlow (Liu et al., 2024) mitigates the need for large transcribed datasets by using untranscribed speech data during pre-training and generalizes well across tasks such as TTS with minimal fine-tuning. However, it does not learn alignment during pre-training, making it less effective for alignment-aware TTS models like E2TTS, as shown in our experiments.

In this work, we introduce A²-Flow, an alignment-aware pre-training method that integrates discrete HuBERT (Hsu et al., 2021) units into E2TTS’s training framework to learn alignment between unit sequences and speech frames. By using de-duplicated units that retain only phonetic content, A²-Flow effectively learns alignment without relying on external duration models. This allows for direct application to zero-shot voice conversion, where phonetic content can be transferred to the target speaker’s voice without additional fine-tuning. For TTS tasks, we fine-tune A²-Flow with transcribed data to jointly learn text-speech alignment, eliminating the need for separate alignment modules. To further enhance pronunciation accuracy, we introduce a simple timestep shifting strategy, improving text alignment early in the sampling process and enhancing overall pronunciation accuracy.

Our experimental results demonstrate that our pre-training model successfully captures the alignment between unit sequences and speech frames. By leveraging this pre-training approach, A²-Flow efficiently learns text-speech alignment with 500 hours of data and a few fine-tuning iterations, achieving high pronunciation accuracy. Even with a limited amount of transcribed data, A²-Flow outperforms many existing zero-shot TTS models and achieves comparable results to E2TTS. Moreover, we show that A²-Flow can effectively learn text-speech alignment also for other languages, demonstrating its capability as a multilingual pre-training method. This highlights the flexibility and scalability of A²-Flow, making it a robust foundation for multilingual TTS systems in low-resource settings. Additionally, without any fine-tuning, the pre-trained model itself outperforms existing zero-shot voice conversion models by a large margin, further validating the effectiveness of our pre-training approach.

2 METHOD

In this section, we explain the masked speech modeling approach using flow matching as described in Section 2.1. We discuss how this framework is utilized by 3 different models (Voicebox, Speech-Flow, and E2TTS), and outline the motivation for our proposed method. In Section 2.2, we present the pre-training method of A²-Flow and describe its application to voice conversion and TTS.

2.1 BACKGROUND: FLOW MATCHING-BASED MASKED SPEECH MODELING

The proposed framework leverages flow matching to model the distribution of mel-spectrograms for various speech synthesis tasks. The core idea is to transform a sample x_0 from a simple prior distribution $p_0(x)$ into a data distribution $q(x)$ through a time-dependent vector field v_t .

2.1.1 PROBLEM FORMULATION: FLOW MATCHING

Given a mel-spectrogram $x \in \mathbb{R}^{D \times T}$, we define a flow $\phi_t(x)$ parameterized by v_t , which describes how x_0 evolves into x over time $t \in [0, 1]$ as follows:

$$\frac{d\phi_t(x)}{dt} = v_t(\phi_t(x); \theta, c), \quad \phi_0(x) = x_0, \quad (1)$$

where v_t is the vector field estimated by the model, θ represents the model parameters, and c is an optional conditioning input that varies based on the task. The model is optimized by minimizing the optimal transport conditional flow matching (OT-CFM) loss:

$$L_{\text{CFM}}(\theta) = \mathbb{E}_{t \sim U[0,1], q(x_1), p_0(x_0)} \|u_t(\phi_{t,x_1}(x_0)|x_1) - v_t(\phi_{t,x_1}(x_0); \theta, c)\|^2, \quad (2)$$

where $\phi_{t,x_1}(x)$ is the optimal transport conditional flow path, and $u_t(x|x_1)$ is the conditional vector field for each data sample $x_1 \sim q(x)$. The optimal transport conditional flow path can be defined as:

$$\phi_{t,x_1}(x) \sim \mathcal{N}(tx_1, (1 - (1 - \sigma_{\min})t)^2 I), \quad (3)$$

where σ_{\min} is a small constant. The target conditional vector field $u_t(x|x_1)$ can then be written as:

$$u_t(x|x_1) = \frac{x_1 - (1 - \sigma_{\min})x}{1 - (1 - \sigma_{\min})t}. \quad (4)$$

By incorporating the conditional probability path and target vector field into the OT-CFM loss in Eq. 2, we can reformulate the objective as:

$$L_{\text{CFM}}(\theta) = \mathbb{E}_{t,x_1,x_0} \|v_t(\phi_{t,x_1}(x_0); \theta, c) - u_t(\phi_{t,x_1}(x_0)|x_1)\|^2, \quad (5)$$

108 which encourages the estimated vector field v_t to match the ground truth vector field u_t .
 109
 110 The OT-CFM objective allows the model to estimate the marginal vector field $u_t(x)$, which inter-
 111 polates between the prior distribution $p_0(x)$ and the data distribution $q(x)$. As a result, the model
 112 learns to generate data samples by solving the ordinary differential equation in Eq. 1 using the
 113 learned vector field.
 114

115 2.1.2 MASKED SPEECH MODELING FRAMEWORK

116 To apply flow matching to masked speech modeling, we first randomly mask regions of the mel-
 117 spectrogram x , using a binary mask $m \in \{0, 1\}^{D \times T}$, and define the masked input as $x_{\text{mask}} =$
 118 $(1 - m) \odot x$. Our masking strategy follows Voicebox (Le et al., 2023), where between 70% to 100%
 119 of the mel-spectrogram is randomly masked, with a 10% probability of fully masking the entire
 120 input.
 121

122 During training, the masked mel-spectrogram x_{mask} is concatenated with a noisy mel-spectrogram
 123 $\phi_{t,x_1}(x_0)$ along the channel dimension for each timestep t . The model is then trained to inpaint the
 124 masked regions using the surrounding context based on the following modified CFM loss:
 125

$$L_{\text{masked-CFM}}(\theta) = \mathbb{E}_{t \sim U[0,1], q(x_1), p_0(x_0)} \|m \odot (u_t(\phi_{t,x_1}(x_0)|x_1) - v_t(\phi_{t,x_1}(x_0); \theta, c))\|^2, \quad (6)$$

126 where c represents all conditioning inputs, including x_{mask} .
 127

128 During inference, given a reference speech x^{ref} , we concatenate x^{ref} with a masked region along
 129 the temporal axis to form $x_{\text{mask}}^{\text{ref}}$, which serves as the conditioning input. The model then fills in
 130 the masked region of the mel-spectrogram using the estimated vector field, taking into account the
 131 speaker information from the reference speech. This enables the model to perform zero-shot speaker
 132 adaptation based on the reference speech.
 133

134 2.1.3 CONDITIONING INPUT FOR DIFFERENT MODELS

135 The conditioning input c plays a crucial role in guiding the generative model during training and
 136 inference. Below, we outline the different conditioning inputs used in Voicebox (Le et al., 2023),
 137 SpeechFlow (Liu et al., 2024), and E2TTS (Eskimez et al., 2024).
 138

139 **Voicebox** Voicebox is a zero-shot TTS model that uses the masked mel-spectrogram x_{mask} along
 140 with a sequence of aligned phoneme transcripts as the conditioning input c . During training, ground
 141 truth alignments are used, while during inference, estimated phoneme durations from a separate
 142 phoneme duration predictor are used to perform alignment and enable zero-shot TTS.
 143

144 **SpeechFlow** SpeechFlow is a pre-training method that uses only the masked mel-spectrogram
 145 x_{mask} as the conditioning input c during pre-training and does not employ any additional condi-
 146 tioning. During fine-tuning, task-specific conditioning inputs can be added, such as using aligned
 147 phoneme transcripts for zero-shot TTS, similar to Voicebox.
 148

149 **E2TTS** E2TTS is a zero-shot TTS model that uses x_{mask} and an unaligned text input y as condi-
 150 tioning inputs c . To match the length of y to the speech input, filler tokens are padded at the end
 151 of y . E2TTS learns the alignment between the unaligned text input and speech without requiring a
 152 separate duration modeling module, distinguishing itself from Voicebox’s approach.
 153

154 By using unaligned text input as a conditioning input, E2TTS jointly models text-speech alignment
 155 without explicitly learning phoneme alignment, allowing it to generate more natural speech with a
 156 simpler architecture compared to Voicebox. However, E2TTS still requires a large amount of paired
 157 text-speech data for effective training. Although E2TTS uses 200,000 hours of untranscribed data
 158 for pre-training (Wang et al., 2024), it still requires tens of thousands of hours of paired text-speech
 159 data and additional training iterations to learn alignment.
 160

161 Similarly, while SpeechFlow is pre-trained using only masked speech modeling without any con-
 162 ditioning, it can serve as a good initialization point for tasks that do not require explicit alignment
 163 learning, such as Voicebox. However, it remains unclear whether SpeechFlow can effectively per-
 164 form joint alignment and masked speech modeling with limited data under the E2TTS framework.
 165

In Fig. 2, we experimentally demonstrate that SpeechFlow struggles to learn alignment when trained with limited transcribed data under the E2TTS training framework.

These limitations of existing methods highlight the need for a pre-training approach that not only leverages untranscribed data effectively but also facilitates alignment-aware learning. In the next section, we introduce A²-Flow, an alignment-aware pre-training method that specifically addresses these challenges.

2.2 A²-FLOW

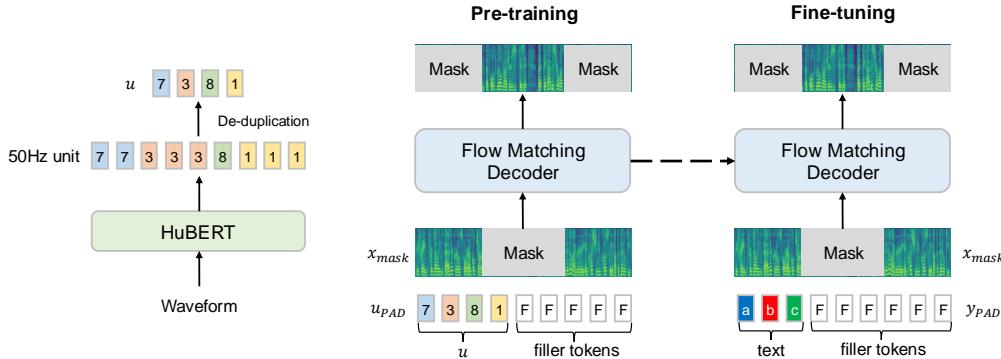


Figure 1: An overview of A²-Flow. During pre-training, A²-Flow utilizes discrete speech unit sequences extracted from HuBERT, allowing the model to learn unit-speech alignment. In the fine-tuning stage, the unit sequences are replaced with text sequences from transcribed data.

We introduce A²-Flow, an alignment-aware pre-training method that utilizes discrete HuBERT units (Hsu et al., 2021). This approach integrates masked speech modeling and alignment learning, thereby making untranscribed speech data useful for downstream tasks like TTS. By jointly learning masked speech and alignment, A²-Flow facilitates the alignment process during fine-tuning and enables more efficient text-speech alignment learning, even with a small amount of transcribed data. This results in TTS systems that can synthesize highly natural and intelligible speech without the need for external alignment mechanisms.

To achieve alignment learning during the pre-training stage, we incorporate discrete HuBERT units—self-supervised speech representations obtained from untranscribed data—into the training process. These units primarily capture phonetic content, enabling the model to learn alignment between the units and the corresponding speech frames. For joint learning of alignment and masked speech modeling, we directly adopt the E2TTS training approach, where text inputs are replaced with discrete unit representations during pre-training, as depicted in Fig. 1.

Alignment-Aware Pre-Training Our strategy for alignment-aware pre-training involves removing alignment information from discrete speech units, allowing the model to relearn unit alignment directly during pre-training. To begin, we extract continuous speech representations from 16kHz speech waveforms using the HuBERT model and generate a 50Hz discrete unit sequence $u_{50\text{Hz}}$ using HuBERT’s k-means quantizer. This 50Hz unit sequence represents speech as a sequence of indices ranging from 0 to $K - 1$, where K is the number of clusters in the k-means quantizer. As shown in Fig. 1, these 50Hz unit sequences often contain repeated indices for continuous speech segments. Since $u_{50\text{Hz}}$ is already aligned with the speech, we remove these repetitions to eliminate duration information, resulting in a de-duplicated unit sequence $u = [u_1, \dots, u_L]$.

In A²-Flow, we adopt a similar strategy to E2TTS by padding the de-duplicated unit sequence u with filler tokens F to match the length of the corresponding mel-spectrogram x , creating a padded sequence $u_{PAD} = [u_1, \dots, u_L, F, \dots, F]$. This padded sequence is concatenated with x_{mask} and used as part of the conditioning input c to predict the masked regions by optimizing the training objective defined in Eq. 6. During pre-training, A²-Flow uses the de-duplicated units as additional context to guide the inpainting of the masked regions. This approach helps the model learn to extract speaker-specific and acoustic characteristics from the surrounding regions while aligning the de-duplicated units with the corresponding speech.

216 For multilingual pre-training, we include language IDs as an additional input to the decoder to
 217 distinguish between languages within the shared discrete unit space. This allows A²-Flow to better
 218 capture language-specific characteristics and more effectively model each language independently.
 219

220 **Voice Conversion** Unlike pre-training methods (Liu et al., 2024; Wang et al., 2024), A²-Flow
 221 can be directly used for voice conversion tasks without requiring any additional fine-tuning. By
 222 leveraging discrete HuBERT units that capture detailed phonetic content, A²-Flow can effectively
 223 convert the source speaker’s speech into the target speaker’s voice, achieving high-quality outputs
 224 with minimal adjustment.

225 For voice conversion, we extract de-duplicated unit sequences u^{src} and u^{ref} from the source and
 226 target speech, respectively, and concatenate the mel-spectrogram of the target reference speech x^{ref}
 227 with a mask of the source length. Next, we concatenate the extracted de-duplicated sequences $u =$
 228 $[u^{\text{ref}}; u^{\text{src}}]$ and pad them with filler tokens to match the combined length of x^{ref} and the masked
 229 source region. Feeding this sequence into the pre-trained flow matching model, the model generates
 230 speech for the masked region by combining the content of u^{src} (source speech) with the speaker
 231 characteristics of x^{ref} (target reference speech). This results in voice-converted speech that aligns
 232 the source content with the target speaker’s voice.

233 Through alignment-aware pre-training, A²-Flow can generate speech samples from the de-
 234 duplicated unit sequence, where duration information has been removed, rather than relying on
 235 the original 50Hz unit representation. This flexibility allows A²-Flow to perform voice conversion
 236 with varied alignments, providing more diverse and natural outputs compared to conventional voice
 237 conversion methods that depend solely on the original unit sequence.

238 **Fine-tuning For Text-to-Speech** To perform TTS using the pre-trained A²-Flow, we initialize
 239 text embeddings for TTS and fine-tune the pre-trained model using transcribed data with the same
 240 objective as in E2TTS. As shown in Fig. 1, we condition the flow matching decoder on the padded
 241 text sequence y_{PAD} , where the text sequence y is padded with the filler tokens to match the length
 242 of the speech. We also train a transformer-based total length predictor to estimate the overall speech
 243 duration based on the reference mel-spectrogram and input text. The predictor takes the text se-
 244 quence y and a short random chunk of the mel-spectrogram x_{cut} as inputs and is trained to estimate
 245 the log-scale of the speech length d divided by a scaling factor s using an L2 regression loss.

246 For zero-shot TTS, given a target reference audio x^{ref} and the transcript y to generate, we first use the
 247 total length predictor to estimate the total length of speech corresponding to y . We then concatenate
 248 x^{ref} with a mask of the predicted length to obtain $x_{\text{mask}}^{\text{ref}} = [x^{\text{ref}}; \text{Mask}]$. After concatenating the
 249 target reference transcript y^{ref} with the transcript y , we pad it to match the length of $x_{\text{mask}}^{\text{ref}}$. The flow
 250 matching decoder then generates samples for the masked regions by solving Eq. 1.
 251

252 **Sampling** During the sampling process, we apply classifier-free guidance (CFG) (Ho & Salimans,
 253 2021) by adjusting the vector field estimated through flow matching according to the CFG scale
 254 γ . Additionally, we modify the sampling process to employ a timestep shifting technique inspired
 255 by Esser et al. (2024) to sample more values of t closer to 0. This approach ensures that the noisy
 256 mel-spectrogram x_t for smaller values of t remains better aligned with the text, resulting in higher
 257 pronunciation accuracy.

258 If the ODE is traditionally solved using uniformly spaced timesteps $t_n = \frac{n}{N}, n = 0, \dots, N - 1$, we
 259 modify it by non-linearly shifting t_n as defined in Eq. 7, where \hat{t}_n is computed as follows:
 260

$$\hat{t}_n = t_n / (1 + (\alpha - 1) * (1 - t_n)), \quad (7)$$

261 for a given $\alpha \geq 1$. When $\alpha = 1$ this corresponds to uniform sampling, while larger values of α
 262 result in more frequent sampling of t near 0. In our experiments, we set $\alpha = 3$ as the default value.
 263 The process of sampling using timestep shifting is explained in more detail in Section A.2.2
 264

265 3 EXPERIMENTS

266 In this section, we describe the experimental setup, including model architecture, data, training de-
 267 tails, and the baselines used for evaluation. We also provide a detailed explanation of the evaluation
 268 metrics and methods for both voice conversion and text-to-speech (TTS) tasks.

270 **Model Architecture** We employ a modified Diffusion Transformer (DiT) (Peebles & Xie, 2023)
 271 architecture by removing the 2D patchify layers. Our model configuration is identical to the DiT-L
 272 variant, using a decoder with a hidden size of 1024, 16 attention heads, and a total of 24 trans-
 273 former layers, resulting in 450M parameters. The model integrates Adaptive LayerNorm (AdaLN)
 274 to incorporate embeddings of both the flow matching timestep t and the language ID used during
 275 multi-lingual pre-training, allowing for effective conditioning on these factors.

276 During the pre-training phase, we extract discrete unit sequences using the HuBERT-Large
 277 model (Hsu et al., 2021), trained on 220K hours of multilingual data. The unit sequences are obtained
 278 using a k-means quantizer trained on the Espresso dataset (Nguyen et al., 2023) with $K = 2000$
 279 clusters. We utilize pre-trained checkpoints made available through the textlesslib library¹.
 280

281 **Data** For pre-training, we use a total of 40K hours of speech data, which includes 37K hours
 282 of English data from LibriTTS (Zen et al., 2019), LibriVox (Kearns, 2014) and Multilingual Lib-
 283 riSpeech (MLS) (Pratap et al., 2020) datasets, combined with 3K hours of multi-lingual data from
 284 the CML dataset, covering seven different languages. To fine-tune the pre-trained model for TTS,
 285 we use the transcribed data from the LibriTTS dataset for English, and transcribed data from three
 286 other languages (German, French, and Spanish) in the CML dataset to build separate TTS models
 287 for each language. The CML transcribed data includes 1500 hours of German, 440 hours of Spanish,
 288 and 280 hours of French speech. All speech data is resampled to 22kHz. We convert each 22kHz
 289 waveform into an 80-bin log-scale mel-spectrogram using a window length of 1024, hop length of
 290 256, and frequency range of $f_{\min} = 0$ to $f_{\max} = 11025$. These mel-spectrograms serve as the data x
 291 used for flow matching in our experiments.
 292

293 **Training and Fine-tuning** During pre-training, we use AdamW optimizer with a learning rate of
 294 $1e^{-4}$. We train the model for a total of 700K iterations on 32 A100 GPUs, with a batch size of 4
 295 per GPU. For fine-tuning on the TTS task, we initialize the model with the pre-trained weights, and
 296 the optimizer is re-initialized. We fine-tune the pre-trained model separately on the transcribed data
 297 from LibriTTS and CML-German, CML-French, and CML-Spanish datasets. For all fine-tuning
 298 processes, we lower the learning rate to a peak value of $2e^{-5}$, which is reached over 5000 iterations
 299 using a warm-up schedule. We fine-tune the pre-trained model for 150K iterations on 8 A100 GPUs,
 300 with a batch size of 4 per GPU. After reaching the peak learning rate, it is linearly decayed to zero
 301 over the remaining iterations.
 302

303 **Inference** During inference, we solve the ordinary differential equation using the Euler method,
 304 with 32 sampling steps and a default classifier-free guidance scale of $\gamma = 2$. For voice conversion, we
 305 set the default timestep shifting parameter to $\alpha = 1$ to perform uniform timestep sampling, while for
 306 TTS, we use $\alpha = 3$ to improve pronunciation accuracy. Once the mel-spectrograms are generated
 307 by the flow matching decoder, we convert them into 22kHz waveforms using a BigVGAN-based
 308 vocoder (Lee et al.)
 309

310 **Baselines for Voice Conversion** We compare the performance of A²-Flow against three voice
 311 conversion baselines: Any-to-Any VC (Kovela et al., 2023), UnitSpeech (Kim et al., 2023a), and
 312 SelfVC (Neekhara et al., 2024) on the LibriSpeech test-clean dataset. The Any-to-Any VC model is
 313 trained on speakers from the test-clean dataset, making it a suitable many-to-many voice conversion
 314 baseline that has already learned from reference speakers. UnitSpeech performs speaker adaptation
 315 by fine-tuning for 500 iterations on a given reference audio, which makes it a fine-tuning-based
 316 voice conversion baseline. Lastly, SelfVC, a recently proposed zero-shot voice conversion model,
 317 has been shown to outperform several voice conversion models in zero-shot settings, making it a
 318 strong benchmark for comparison.
 319

320 **Baselines for Text-to-Speech** We use several models as baselines for zero-shot TTS, including
 321 Voicebox, CLAM-TTS, DiTTO-TTS, E2TTS, and SpeechFlow fine-tuned specifically for the TTS
 322 task. The results of each model are reported using the evaluation metrics provided in their respec-
 323 tive papers for direct comparison in zero-shot TTS scenarios. Additionally, we re-implement E2TTS
 324 and SpeechFlow, training both using the same amount of data and identical model architecture as
 325 A²-Flow with 32 GPUs over 700K iterations. Note that, unlike the pre-training of SpeechFlow and
 326

¹<https://github.com/facebookresearch/textlesslib>

324 A²-Flow, E2TTS is trained with transcripts for the entire 40K hours of data. To evaluate the per-
 325 formance of E2TTS under limited data conditions, we train E2TTS on 500 hours of LibriTTS data
 326 using 8 GPUs. We refer to this model as E2TTS-LT. For the re-implemented versions of E2TTS,
 327 E2TTS-LT, and SpeechFlow, we apply our timestep shifting scale to $\alpha = 3$, ensuring that com-
 328 parisons exclude improvements due to differences in the sampling method. This setup allows us
 329 to systematically compare the alignment learning and performance of A²-Flow, SpeechFlow, and
 330 E2TTS under various training configurations.

331

332 **Evaluation and Metrics** We evaluate zero-shot TTS performance using two evaluation tasks fol-
 333 lowing the approach described in (Wang et al., 2023; Le et al., 2023). The first task is the continuation
 334 task, where for all test samples between 4 to 10 seconds long, we provide the first 3 seconds of audio
 335 along with the entire transcript and generate speech beyond the initial 3 seconds. The second task
 336 is the cross-reference synthesis task, where for each test sample between 4 to 10 seconds long, we
 337 use the transcript of the sample and a randomly selected 3-second segment from another sample of
 338 the same speaker as the reference audio for zero-shot TTS. For each task, the generated samples
 339 are evaluated by measuring speaker similarity to the 3-second reference audio using a speaker simi-
 340 larity metric, and pronunciation accuracy is measured using the word error rate (WER) between
 341 the ground truth transcript and the transcript obtained from an ASR model applied to the generated
 342 audio.

343

343 To evaluate voice conversion performance, we use all samples between 4 to 10 seconds long in the
 344 test set. Each sample is used as the source audio, and a 3-second segment is randomly extracted
 345 from a different speaker’s sample to serve as the reference audio. The model then generates speech
 346 that matches the content of the source audio while adopting the voice characteristics of the reference
 347 speaker. We evaluate the pronunciation accuracy and speaker similarity of the generated speech
 348 compared to the reference audio. Performance is reported as the average WER and SECS values
 349 across 1130 pairs from the LibriSpeech test-clean set.

350

350 For the speaker similarity metric, we follow (Wang et al., 2023) and use a WavLM-based speaker
 351 verification model (Chen et al., 2022) to map both samples to speaker embeddings and measure
 352 the cosine similarity between them. We measure speaker similarity between the reference ground
 353 truth audio and the generated audio, as defined as SECS-O in the Voicebox (Le et al., 2023). For
 354 pronunciation accuracy, we also follow (Wang et al., 2023) and use the same HuBERT-L-based ASR
 355 model (Hsu et al., 2021) to measure the WER of English-generated speech, and for other languages,
 356 we use the Whisper-large v2 (Radford et al., 2022) model to measure WER.

357

357 For subjective evaluation, we generate zero-shot TTS samples using A²-Flow and compare them
 358 against samples downloaded from the demo pages of SpeechFlow and E2TTS. We conduct A/B
 359 tests with 100 human evaluators, asking them to choose the sample that more closely matches the
 360 reference audio in terms of prosody, emotion, and timbre. Each evaluator performs 9 A/B tests when
 361 comparing with SpeechFlow and 19 A/B tests when comparing with E2TTS.

362

363 4 RESULTS

364

365 4.1 ALIGNMENT-AWARE PRE-TRAINING DYNAMICS

366

367 In this section, we analyze the training dynamics of A²-Flow during pre-training and its impact on
 368 text-speech alignment during TTS fine-tuning. We compare A²-Flow with E2TTS and SpeechFlow,
 369 highlighting differences in alignment performance across training iterations.

370

370 For pre-training evaluation, we measure the model’s ability to reconstruct masked regions using
 371 the unit sequence of the full utterance. We mask speech segments except for the first 3 seconds
 372 of each sample in the LibriTTS test-clean set and measure the pronunciation accuracy (WER) and
 373 speaker similarity (SECS-O) of generated samples. Fig. 3 in Appendix demonstrates that A²-Flow
 374 achieves a WER of 3% after 100K iterations, effectively learning text-speech alignment during pre-
 375 training. As training progresses, the model maintains its alignment ability and further enhances
 376 speaker similarity.

377

377 To show the effectiveness of our alignment-aware pre-training approach in the context of TTS tasks
 378 that require joint modeling of text and speech alignment, we compare A²-Flow with SpeechFlow

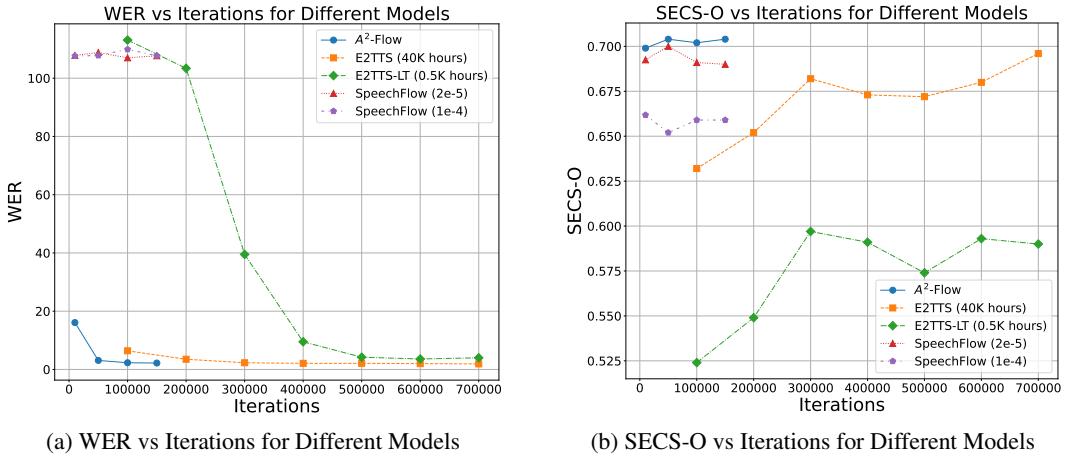


Figure 2: Comparison of WER and SECS-O across training iterations for various models

pre-training followed by fine-tuning on the LibriTTS dataset, E2TTS-LT trained on LibriTTS, and E2TTS trained on 40K hours of transcribed data. Fig. 2 illustrates the pronunciation accuracy (WER) and speaker similarity (SECS-O) during zero-shot TTS for each model across different training iterations.

While E2TTS efficiently learns text-speech alignment with a large amount of transcribed data, it struggles under low-resource conditions, requiring over 400K iterations to achieve acceptable performance with limited data. In contrast, A²-Flow, with its pre-trained alignment capabilities, achieves comparable results with significantly fewer fine-tuning iterations.

On the other hand, when SpeechFlow is pre-trained using only masked speech modeling and then fine-tuned on the LibriTTS dataset, it struggles to learn text-speech alignment. Although SpeechFlow achieves high speaker similarity when fine-tuned with learning rate of $2e^{-5}$, it fails to learn text-speech alignment, resulting in WER values exceeding 100%. Increasing the learning rate to $1e^{-4}$ leads to a drop in speaker similarity without effectively improving alignment.

The performance curve of E2TTS-LT further highlights the challenges of learning text-speech alignment from scratch using only a small amount of data, as it requires many iterations to converge. This demonstrates that SpeechFlow, when trained solely with masked speech modeling, is not an effective initialization for TTS models requiring joint text-speech alignment. In contrast, A²-Flow’s alignment-aware pre-training with discrete speech units makes it highly efficient for learning text-speech alignment during TTS fine-tuning, even with limited data.

4.2 MODEL COMPARISONS

Table 1: Objective metric results on the TTS Cross Reference Synthesis task using the LibriSpeech test-clean dataset. † indicates results directly reported by each model, while * represents results obtained from re-implemented experiments. “SpeechFlow-E2*” refers to the SpeechFlow model fine-tuned using the E2TTS approach. “PT” indicates whether pre-training was used.

MODEL	PT	UNLABELED DATA (H)	LABELED DATA (H)	WER↓	SECS-O↑
CLAM-TTS†	✗	0	55,000	5.11	0.495
DITTO-TTS†	✗	0	55,000	2.56	0.627
VOICEBOX†	✗	0	60,000	1.9	0.662
SPEECHFLOW†	✓	60,000	960	2.1	0.700
E2TTS†	✗	0	50,000	2.0	0.675
E2TTS †	✓	200,000	50,000	1.9	0.708
E2TTS*	✗	0	40,000	1.9	0.696
E2TTS-LT*	✗	0	500	4.0	0.590
SPEECHFLOW-E2*	✓	40,000	500	107.7	0.690
A ² -FLOW	✓	40,000	500	2.2	0.704

Zero-shot Text-to-Speech We compare the performance of A²-Flow, fine-tuned solely on the LibriTTS dataset, with other zero-shot TTS models. Table 1 shows that A²-Flow achieves comparable pronunciation accuracy (WER) and higher speaker similarity (SECS-O) than most baselines, including Voicebox. A²-Flow also performs on par with E2TTS while using as little as 1% of the transcribed data required by most zero-shot TTS models.

Compared to E2TTS (Eskimez et al., 2024), which required 200K hours of unlabeled data and 800K fine-tuning iterations with 50K hours of labeled data to achieve a WER of 1.9 and SECS-O of 0.708, A²-Flow achieves similar performance with significantly fewer fine-tuning iterations, far less labeled data, and reduced computational resources. In contrast, SpeechFlow, when fine-tuned using the E2TTS framework (referred to as SpeechFlow-E2), achieves a high SECS-O score but fails to achieve reasonable WER values, highlighting the difficulty of adapting SpeechFlow to tasks requiring text-speech alignment.

These results demonstrate that A²-Flow provides an efficient alternative to existing pre-training methods, effectively modeling alignment while minimizing reliance on transcribed data and computational resources. By leveraging alignment-aware pre-training, A²-Flow delivers robust zero-shot TTS performance, requiring only a fraction of the resources used by the previous approaches like E2TTS.

Table 2: A/B test results comparing A²-Flow against SpeechFlow and E2TTS, respectively. “Win” indicates cases where A²-Flow was preferred.

MODEL	WIN-TIE-LOSE
A ² -FLOW VS SPEECHFLOW	41.6% – 24.4% – 34.0%
A ² -FLOW VS E2TTS	34.8% – 30.2% – 35.0%

To further validate our model, we conducted a subjective A/B test to compare the samples generated by A²-Flow against those from E2TTS and SpeechFlow. Evaluators were asked to select the sample that better matched the reference audio in terms of prosody, emotion, and timbre. The results of the A/B test, presented in Table 2, show that A²-Flow is almost comparable to E2TTS, with a slight preference towards E2TTS, and outperforms SpeechFlow (Liu et al., 2024). The results show that A²-Flow performs comparably to E2TTS and outperforms SpeechFlow in subjective evaluations, highlighting its ability to efficiently model text-speech alignment without relying on an external alignment mechanism. We have uploaded the samples used in the subjective evaluation to the demo page link in Section A.1, and we encourage readers to listen to the samples on the demo page.

Table 3: TTS Continuation results for non-English languages. Non-English models are trained on respective CML datasets and evaluated on their corresponding test sets.

MODEL	LANGUAGE	FINE-TUNING DATASET	LABELED DATA (H)	WER↓	SECS-O↑
GT	GERMAN	—	—	7.5	0.628
A ² -FLOW	GERMAN	CML-GERMAN	1400	7.6	0.609
GT	SPANISH	—	—	5.1	0.674
A ² -FLOW	SPANISH	CML-SPANISH	440	6.2	0.634
GT	FRENCH	—	—	6.0	0.619
A ² -FLOW	FRENCH	CML-FRENCH	280	7.7	0.564

To show that A²-Flow can achieve high zero-shot TTS performance across languages, we fine-tune the model on three languages from the CML-Dataset—German, Spanish, and French—using 150K iterations for each. We evaluate the models on the test sets of each language and perform the TTS continuation task for samples between 4 and 10 seconds, as done on LibriSpeech. As shown in Table 3, A²-Flow effectively learns text-speech alignment for each language, demonstrating pronunciation accuracy (WER) and speaker similarity (SECS-O) that are not significantly worse compared to the ground truth, despite differences in language. These results indicate that A²-Flow can leverage untranscribed data to build strong zero-shot TTS models for multiple languages, even when large-scale transcribed data is unavailable.

Zero-shot Voice Conversion We compare our model with three voice conversion baselines—Any-to-Any VC (Kovela et al., 2023), UnitSpeech (Kim et al., 2023a), and SelfVC (Neekhara et al., 2024)—using the LibriSpeech test-clean dataset. Among these, Any-to-Any VC is a VC baseline directly trained on the test-clean dataset, while UnitSpeech is a fine-tuning-based VC baseline that

486 Table 4: Objective metric results for the Voice Conversion Cross Reference Synthesis task.
487

MODEL	ZERO-SHOT	WER \downarrow	SECS-O \uparrow
ANY-TO-ANY VC	✗	3.0	0.648
UNITSPEECH	✗	2.9	0.674
SELFVC	✓	3.2	0.375
A ² -FLOW	✓	3.6	0.67

492 adapts to the reference speech with 500 iterations of fine-tuning. SelfVC serves as a zero-shot VC
 493 baseline. The results of cross-reference synthesis for each model are presented in Table 4. Although
 494 A²-Flow shows a slightly higher WER compared to other baselines, it achieves significantly higher
 495 speaker similarity than the zero-shot baseline SelfVC. Additionally, it demonstrates performance
 496 comparable to or exceeding that of baselines directly trained or fine-tuned on the test set’s reference
 497 audio, highlighting the effectiveness of large-scale unit-based alignment-aware pre-training for voice
 498 conversion.

500 4.3 ABLATION STUDY
501

502 We perform an ablation study on the pre-trained A²-Flow model for TTS tasks, exploring the impact
 503 of different sampling steps, classifier-free guidance scales (γ), and timestep shifting scales (α) on
 504 cross-reference synthesis performance. Table 5 shows that setting classifier-free guidance scale $\gamma =$
 505 1 results in significantly worse WER and SECS-O, confirming $\gamma = 2$ as the optimal value. A key
 506 finding of this work is that, for a flow matching model trained to jointly model alignment in TTS,
 507 using timestep shifting with $\alpha = 3$, which samples more frequently from the noisier t regions, results
 508 in improved pronunciation accuracy and better speaker similarity compared to uniform timestep
 509 sampling ($\alpha = 1$) at the same number of sampling iterations. Therefore, we use $\alpha = 3$ as the default
 510 value. For Euler sampling steps, performance does not improve beyond 32 steps, while reducing
 511 steps to 16 leads to a drop in performance. Thus, we use 32 steps as the default setting.

512 Table 5: Ablation study results of A²-Flow on zero-shot TTS with variations in Euler sampling steps,
513 classifier-free guidance scale γ , and timestep shifting scale α .
514

MODEL	NFE	CFG SCALE	α	WER \downarrow	SECS-O \uparrow
A ² -FLOW	32	2	1	2.7	0.695
			2	2.3	0.703
			3	2.2	0.704
	32	3	1	3.3	0.679
			3	2.2	0.704
			2.3	0.706	
	16	3	1	2.7	0.698
			2.2	0.704	
			2.3	0.701	

523 5 CONCLUSION
524

526 In this work, we proposed A²-Flow, an alignment-aware pre-training approach tailored for speech
 527 synthesis tasks that involve generating natural phonetic content, such as voice conversion and text-to-
 528 speech (TTS). By incorporating de-duplicated unit sequences instead of text into the E2TTS frame-
 529 work, our method enables the model to learn the alignment between input units and speech during
 530 the pre-training phase. This alignment-aware pre-training can be directly applied to zero-shot voice
 531 conversion tasks or used to build a TTS model that jointly models text-speech alignment with min-
 532 imal fine-tuning. As a result, A²-Flow achieves comparable performance to state-of-the-art models
 533 like E2TTS using only 1% of the transcribed data. Moreover, our method consistently outperforms
 534 existing zero-shot TTS and zero-shot VC models by a significant margin. We further demonstrated
 535 that A²-Flow can model text-speech alignment for multiple languages, making it adaptable to mul-
 536 tilingual TTS scenarios. Our findings highlight that A²-Flow is better suited for alignment-aware
 537 tasks compared to pre-training methods like SpeechFlow, which do not incorporate any condition-
 538 ing. Since our approach can learn effectively with only speech data and language IDs, A²-Flow
 539 offers a viable solution for scenarios where large-scale transcribed datasets are not available, and
 provides significant advantages for alignment-aware speech synthesis tasks.

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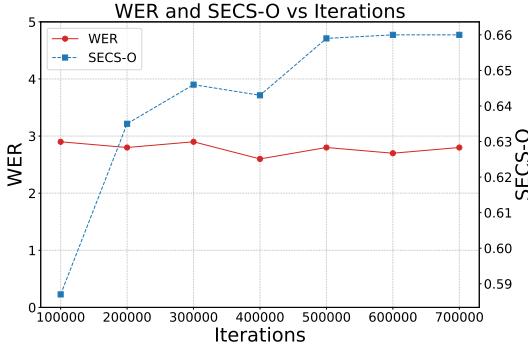
702 **A APPENDIX**

703

704 **A.1 DEMO PAGE**

705

706 The demo page link is <https://anonymous.4open.science/r/demo-page-B24F/index.md>. The demo
 707 page provides the comparison samples used for subjective evaluation as well as the samples generated
 708 by the models used for voice conversion.



721 Figure 3: Reconstruction performance of A^2 -Flow during pre-training across different training iterations.
 722

723

724 **A.2 MODEL DETAILS**

725

726 **A.2.1 TOTAL LENGTH PREDICTOR**

727

728 A^2 -Flow utilizes a total length predictor to estimate the duration of the speech corresponding to the
 729 input text sequence. The total length predictor is composed of a convolution-based pre-network for
 730 projecting the reference audio and a transformer network for predicting the total length from the
 731 reference audio and the text input. Specifically, the total length predictor takes the reference audio
 732 x_{ref} and the text input sequence y as inputs. The reference audio x_{ref} is first processed through the
 733 convolutional pre-network, which consists of three convolutional layers, each with a kernel size of 5,
 734 to project x_{ref} into an intermediate representation h_{ref} . Then, a special token [SPC] is prepended to
 735 the text input sequence y to provide a placeholder for predicting the total length. The representations
 736 h_{ref} , the special token [SPC], and the text input sequence y are concatenated along the time axis
 737 and input into the transformer network.

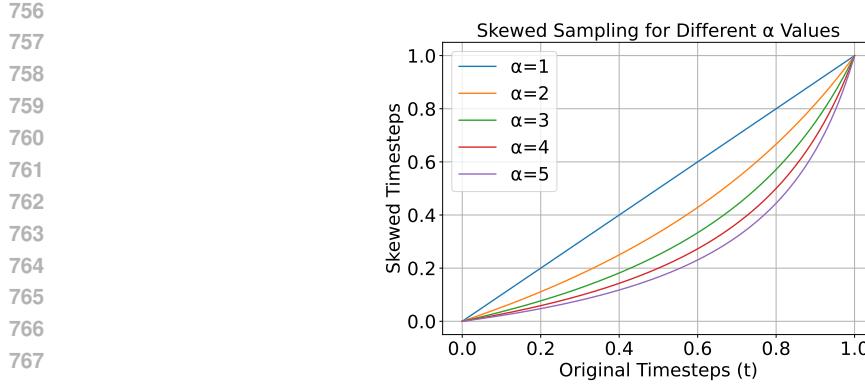
738 The transformer network employs Rotary Positional Embedding (RoPE) to capture positional information,
 739 with separate rotary embeddings applied to the reference audio and text input sequence. The
 740 network is configured with a hidden size of 512, 8 layers, and 8 heads in the multi-head attention
 741 mechanism, resulting in a total of 30 million parameters. The output from the transformer network is
 742 taken from the position of the special token [SPC], which is then projected into a scalar value. This
 743 scalar represents the logarithmic value of the speech length d , scaled by a scaling factor s , i.e., $\log \frac{d}{s}$.
 744 This design enables the total length predictor to effectively estimate the duration of the generated
 745 speech while leveraging both reference audio and text input.

746 **A.2.2 ADDITIONAL EXPLANATION ON Timestep SHIFTING**

747

748 A^2 -Flow utilizes the timestep shifting function in Eq. 7 for sampling during the inference process.
 749 Fig. 4 illustrates the timestep shifting function depending on the value of the timestep shifting scale
 750 α . When $\alpha = 1$, the function performs uniform sampling, similar to the standard Euler method. As
 751 the shifting scale α increases, more timesteps are sampled near the noise-dominated region ($t = 0$).
 752 This allows for finding more accurate alignment between the input and the speech during smaller
 753 timesteps.

754 The sampling process is shown in Alg. 1. During sampling, as described in Section 2, the uniformly
 755 sampled timesteps $t_i = \frac{i}{N}$ are mapped to \hat{t}_i using the timestep shifting function. The ODE is
 756 then solved iteratively at these shifted timesteps to generate samples. At each timestep of the ODE

Figure 4: Visualization of the timestep shifting function according to the value of α .

solution, the algorithm performs repetitive computations for the vector field value, depending on whether classifier-free guidance is applied.

Algorithm 1 Skewed Sampling for Solving ODE

```

776 1: Initialize  $x_0 \sim N(O, I)^T$ 
777 2: Set the following parameters:
778 3:    $c$  = all conditioning inputs
779 4:    $N$  = number of sampling steps
780 5:    $\alpha$  = timestep shifting scale
781 6:    $\gamma$  = classifier-free guidance scale
782 7: Define  $f(t) = \frac{t}{1+(\alpha-1)(1-t)}$  // Timestep shifting function
783 8: for  $i = 0$  to  $N - 1$  do
784 9:    $t_i \leftarrow \frac{i}{N}$ ,  $t_{i+1} \leftarrow \frac{i+1}{N}$ 
785 10:   $\hat{t}_i \leftarrow f(t_i)$ ,  $\hat{t}_{i+1} \leftarrow f(t_{i+1})$ 
786 11:   $v_c \leftarrow v(x_{\hat{t}_i}, c, \hat{t}_i; \theta)$  // Conditional vector field
787 12:   $v_u \leftarrow v(x_{\hat{t}_i}, \phi, \hat{t}_i; \theta)$  // Unconditional vector field
788 13:   $v_{\hat{t}_i} \leftarrow v_c + \gamma \cdot (v_c - v_u)$ 
789 14:   $x_{\hat{t}_{i+1}} \leftarrow x_{\hat{t}_i} + v_{\hat{t}_i} \cdot (\hat{t}_{i+1} - \hat{t}_i)$ 
790 15: end for
791 16: return  $x_1$ 

```

792
 793
 794 A.3 ADDITIONAL RESULTS
 795

796 Table 6: Objective metric and UTMOS results on the TTS Cross Reference Synthesis task using
 797 the LibriSpeech test-clean dataset. * represents results obtained from re-implemented experiments.
 798 “SpeechFlow-E2*” refers to the SpeechFlow model fine-tuned using the E2TTS approach. “PT”
 799 indicates whether pre-training was used.

MODEL	PT	UNLABELED (H)	LABELED (H)	WER \downarrow	SECS-O \uparrow	UTMOS \uparrow
E2TTS*	✗	0	40,000	1.9	0.696	4.01
E2TTS-LT*	✗	0	500	4.0	0.590	4.01
SPEECHFLOW-E2*	✓	40,000	500	107.7	0.690	3.68
A ² -FLOW	✓	40,000	500	2.2	0.704	4.03

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 806 **Speech Naturalness** We present the naturalness evaluation results for samples generated by the
 807 reproduced baselines E2TTS, E2TTS-LT, SpeechFlow-E2, and A²-Flow on the LibriSpeech test-
 808 clean dataset in Table 1. To assess the naturalness of the samples, we use UTMOS (Saeki et al.,
 809 2022), a model trained to predict the Mean Opinion Score (MOS) for audio naturalness, and report
 the average predicted MOS as a proxy for naturalness. Table 6 shows the UTMOS scores for each

model, with the ground truth audio of all evaluation samples achieving an average UTMOS score of 4.10. In comparison, both the reproduced E2TTS and our A²-Flow demonstrate the ability to generate highly natural audio.

Performance Comparison of E2TTS and A²-Flow We compare the performance of E2TTS and A²-Flow across different training iterations. For E2TTS, we evaluate both the original model trained for the total number of iterations used in previous comparisons and an extended version trained for an additional 150K iterations, resulting in a total of 850K iterations. For A²-Flow, we present results fine-tuned solely on LibriTTS for 150K and 300K iterations. Additionally, we evaluate the performance of “A²-Flow-T,” which was fine-tuned on the entire 40K hours of labeled data, similar to E2TTS.

In Table 1, we compared the reproduced results of A²-Flow and E2TTS using only the proposed sampling method, timestep shifting, during inference. Here, we also provide performance results without timestep shifting, where the timestep shifting scale is set to $\alpha = 1$.

Table 7 summarizes the results of E2TTS and A²-Flow across different training setups, using $\alpha = 3$ as the timestep shifting scale during inference. All E2TTS models were trained using 32 GPUs, while A²-Flow utilized 32 GPUs for the full pre-training phase and fine-tuning on the same amount of transcribed data as E2TTS. Fine-tuning on LibriTTS alone was performed with 8 GPUs.

The experimental results show that E2TTS exhibits minimal improvement in objective metrics even after 150K additional iterations beyond the initial 700K. In contrast, A²-Flow achieves a higher SECS-O score with just 150K iterations of fine-tuning. When fine-tuned on LibriTTS for 300K iterations, A²-Flow slightly sacrifices SECS-O for improved WER, achieving results comparable to E2TTS. Furthermore, A²-Flow-T, fine-tuned on 40K hours of transcribed data like E2TTS, maintains a similar WER while pushing SECS-O to 0.711, demonstrating the effectiveness of alignment-aware pre-training even with the same amount of transcribed data.

For E2TTS without timestep shifting ($\alpha = 1$), the results show a slight degradation in WER compared to its counterpart using timestep shifting ($\alpha = 3$). Overall, these results highlight that the proposed timestep shifting method improves alignment accuracy for both A²-Flow and E2TTS, further validating its utility.

Table 7: Objective metric results of E2TTS and A²-Flow across different training iterations and timestep shifting scales on the LibriSpeech test-clean dataset. * represents results obtained from re-implemented experiments. Training details specify the number of iterations and GPU configurations used.

MODEL	TRAINING DETAILS	α	WER \downarrow	SECS-O \uparrow	UTMOS \uparrow
E2TTS*	700K (32GPU)	3	1.9	0.696	4.01
E2TTS*	850K (32GPU)	3	2.0	0.695	4.02
E2TTS*	700K (32GPU)	1	2.1	0.697	3.98
E2TTS*	850K (32GPU)	1	2.2	0.690	4.01
A ² -FLOW	700K (32GPU) / 150K (8GPU)	3	2.2	0.704	4.03
A ² -FLOW	700K (32GPU) / 300K (8GPU)	3	1.9	0.695	4.06
A ² -FLOW-T	700K (32GPU) / 150K (32GPU)	3	2.0	0.711	4.01
A ² -FLOW	700K (32GPU) / 150K (8GPU)	1	2.6	0.699	4.00
A ² -FLOW	700K (32GPU) / 300K (8GPU)	1	2.1	0.690	4.04
A ² -FLOW-T	700K (32GPU) / 150K (32GPU)	1	2.2	0.710	3.99

Pre-training with Different Units In our experiments, we utilized the HuBERT espresso model², pre-trained on 220K hours of data, for alignment-aware pre-training. To investigate the impact of different HuBERT unit representations on TTS performance, we provide results using an alternative HuBERT model. Specifically, we use the HuBERT-base model trained on 960 hours of LibriSpeech, employing units with a clustering size of $K = 200$. We pre-train the model on the same 40K hours of unlabeled data and fine-tune it on 500 hours of the LibriTTS dataset to compare results.

Table 8 presents the TTS downstream performance with different unit representations used during pre-training. Our results demonstrate that the proposed alignment-aware pre-training method

²<https://github.com/facebookresearch/textlesslib/tree/main/examples/expreso>

864 achieves comparable performance even when using HuBERT units trained with minimal data and
 865 only 200 clusters. This highlights the robustness of our pre-training approach with respect to the
 866 choice of unit representation.

868 Table 8: Objective metric results for A²-Flow on the TTS Cross Reference Synthesis task using
 869 the LibriSpeech test-clean dataset with different HuBERT unit representations during pre-training.
 870 HuBERT-Expresso (K=2000) refers to the model pre-trained on 220K hours of data, while HuBERT-
 871 LS960 (K=200) refers to the model trained on 960 hours of LibriSpeech.

MODEL	HUBERT UNITS	WER↓	SECS-O↑	UTMOS↑
A ² -FLOW	HUBERT-EXPRESSO (K=2000)	2.2	0.704	4.03
A ² -FLOW	HUBERT-LS960 (K=200)	2.2	0.703	4.02

876 A.4 LIMITATION

878 A limitation of A²-Flow is that it relies on self-supervised speech units for pre-training, making it
 879 less generalizable to non-speech audio domains compared to methods like SpeechFlow, which do
 880 not use any specific conditioning. Another limitation arises from the E2TTS framework itself, which
 881 necessitates a separate total length predictor to estimate the overall speech duration, preventing
 882 joint modeling of the total duration of generated speech. Investigating pre-training methods that
 883 can jointly model all aspects of speech generation including total length of the audio could be a
 884 promising direction for future research.

885 A.5 HUMAN EVALUATION METHOD

887 To compare the performance of A²-Flow with other models, we used the Defined AI ³ platform to
 888 conduct human evaluations. Each evaluation judgment was compensated at a rate of \$0.15, and the
 889 evaluations were performed by 100 human evaluators, all located in the United States. Evaluators
 890 were selected based on the platform’s internal agreement score filtering criteria to ensure reliability.

891 Each evaluator assessed all provided samples, with payments calculated based on the number of
 892 judgments completed. Specifically, evaluators were compensated for 19 judgments for comparisons
 893 with E2TTS and 9 judgments for comparisons with SpeechFlow. During the evaluation, each evalua-
 894 tor was presented with a 3-second reference audio clip alongside two audio samples generated by
 895 the models in a randomized order. The following instruction was provided:

896 “Between the two samples, which one sounds closer to the reference in terms of prosody, emotion,
 897 and timbre? If the two samples sound equally similar to the reference, choose ‘Neither.’”

899 This setup encouraged evaluators to consider the overall quality of the generated audio in relation
 900 to the reference audio, encompassing aspects such as prosody, emotion, and timbre, to determine
 901 which sample was better.

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³<https://defined.ai/crowd-as-a-service>