

Bài tập

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Source code

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def depthFirstSearch(problem):
    from game import Directions
    from util import Stack

    trace = {}
    trace[problem.getStartState()] = (-1, -1)
    marked = {}
    s = Stack()
    s.push(problem.getStartState())

    while not s.isEmpty():
        state = s.pop()

        if problem.isGoalState(state):
            path = []
            while (state != problem.getStartState()):
                direct = trace[state][1]
                if direct == 'West':
                    path.append(Directions.WEST)
                elif direct == 'South':
                    path.append(Directions.SOUTH)
                elif direct == 'North':
                    path.append(Directions.NORTH)
                elif direct == 'East':
                    path.append(Directions.EAST)
                state = trace[state][0]

            path.reverse()
            print(path)
            return path

        if state in marked:
            continue
        marked[state] = 1

        for next_state, direct, _ in problem.getSuccessors(state):
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        if next_state in marked:
            continue
        trace[next_state] = [state, direct]
        s.push(next_state)

    return []

def breadthFirstSearch(problem):
    from game import Directions
    from util import Queue

    trace = {}
    trace[problem.getStartState()] = (-1, -1)
    q = Queue()
    q.push(problem.getStartState())

    while not q.isEmpty():
        state = q.pop()

        if problem.isGoalState(state):
            path = []
            while (state != problem.getStartState()):
                direct = trace[state][1]
                if direct == 'West':
                    path.append(Directions.WEST)
                elif direct == 'South':
                    path.append(Directions.SOUTH)
                elif direct == 'North':
                    path.append(Directions.NORTH)
                elif direct == 'East':
                    path.append(Directions.EAST)
                state = trace[state][0]

            path.reverse()
            print(path)
            return path

        for next_state, direct, _ in problem.getSuccessors(state):

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    if next_state in trace:
        continue
    trace[next_state] = [state, direct]
    q.push(next_state)

return []
```