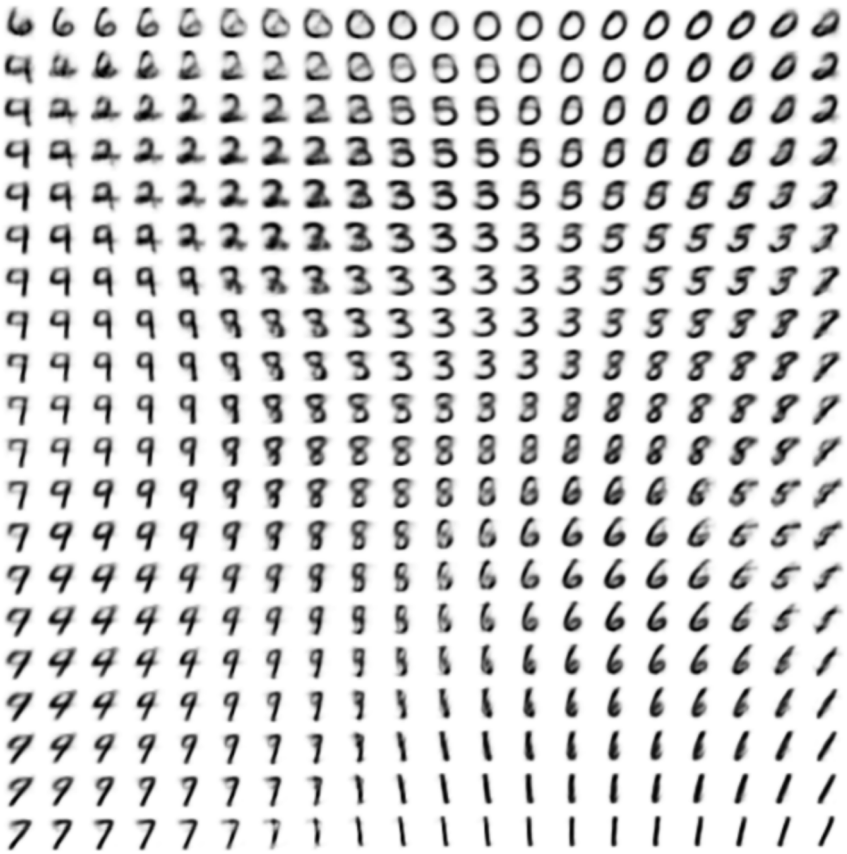
Variational autoencoders (VAEs)

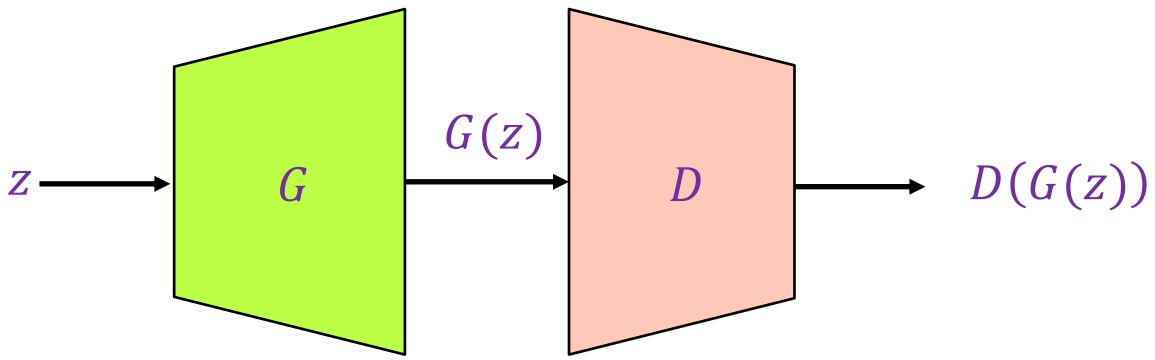


Outline

- Basic VAE formulation
- Highlights of recent work

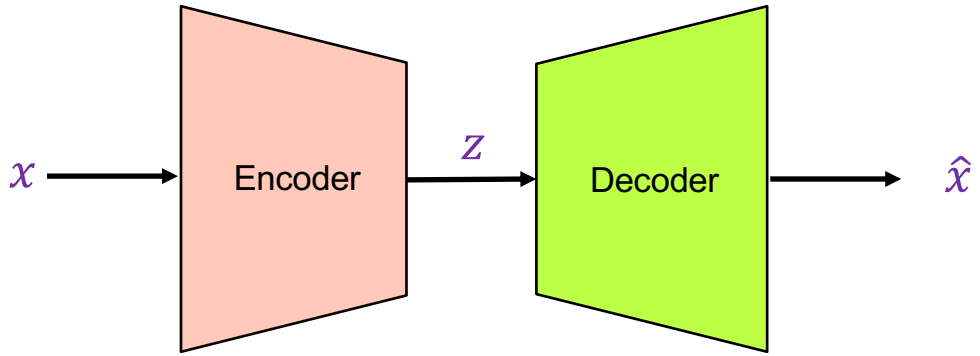
Recall: GANs

- Training:
  - Discriminator: low scores for fake data, high scores for real data
  - Generator: increase discriminator score on fake data
- Test time: discard discriminator and use generator to sample from learned distribution



Variational autoencoders: Overview

- Probabilistic formulation based on *variational Bayes* framework
- At training time, jointly learn *encoder* and *decoder* by maximizing (a bound on) the data likelihood
- At test time, discard encoder and use decoder to sample from the learned distribution



D. Kingma and M. Welling, Auto-Encoding Variational Bayes, ICLR 2014

Variational autoencoders: Overview

- Probabilistic generative model of the data distribution:

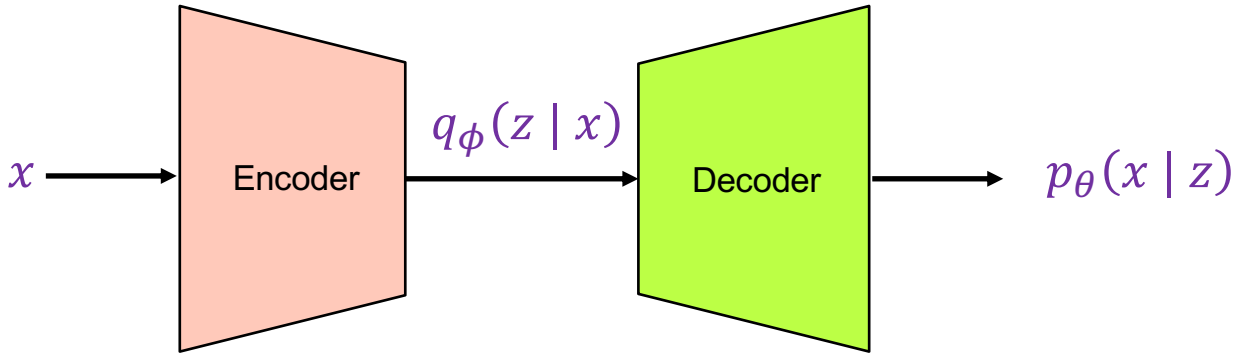
Sample z from *prior* $p(z)$
(usually Gaussian)

Sample x from
conditional $p(x|z)$

Try to approximate the conditional with neural network

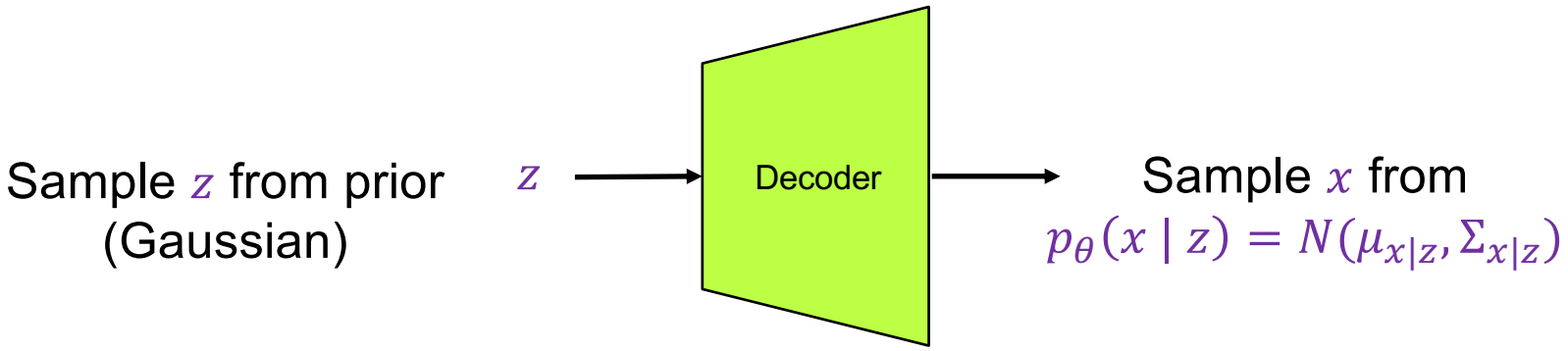
Variational autoencoders: Overview

- At training time, jointly learn *encoder* and *decoder*
- **Encoder:** given inputs x, output $q_\phi(z \mid x)$
  - Specifically, output mean and (diagonal) covariance, or $\mu_{z|x}$ and $\Sigma_{z|x}$, so that $q_\phi(z \mid x) = N(\mu_{z|x}, \Sigma_{z|x})$
- **Decoder:** given z, output $p_\theta(x \mid z)$
  - Specifically, output $\mu_{x|z}$ and $\Sigma_{x|z}$ so that $p_\theta(x \mid z) = N(\mu_{x|z}, \Sigma_{x|z})$
- **Training objective:** (a bound on) data likelihood under the model



Variational autoencoders: Overview

- At test time, discard encoder and use decoder to sample from $p_\theta(x \mid z) = N(\mu_{x|z}, \Sigma_{x|z})$



Variational autoencoders: Training

- Objective: maximize the *variational lower bound* on the data likelihood:

$$\log p_\theta(x) \geq \mathbb{E}_{z\sim q_\phi(z|x)}[\log p_\theta(x|z)] - D_{KL}\left(q_\phi(z|x), p(z)\right)$$

Adapted from J. Johnson

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1. Run training point x through encoder to get a distribution over latent codes z
2. Encoder output should match the prior $p(z)$
   - Closed form solution when q_ϕ is diagonal Gaussian and p is unit Gaussian (Assume z has dimension J):

$$-D_{KL}\left(q_\phi(z|x), p(z)\right) = \sum_{j=1}^{J}\left(1 + \log\left(\left(\Sigma_{z|x}\right)_j^2\right) - \left(\mu_{z|x}\right)_j^2 - \left(\Sigma_{z|x}\right)_j^2\right)$$

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2. Encoder output should match the prior $p(z)$
3. Sample code z from encoder output
4. Run sampled z through decoder to get a distribution over data samples
5. Original input should be likely under the distribution output in (4)

Adapted from J. Johnson

Variational autoencoders: Training

- Objective: maximize the *variational lower bound* on the data likelihood:

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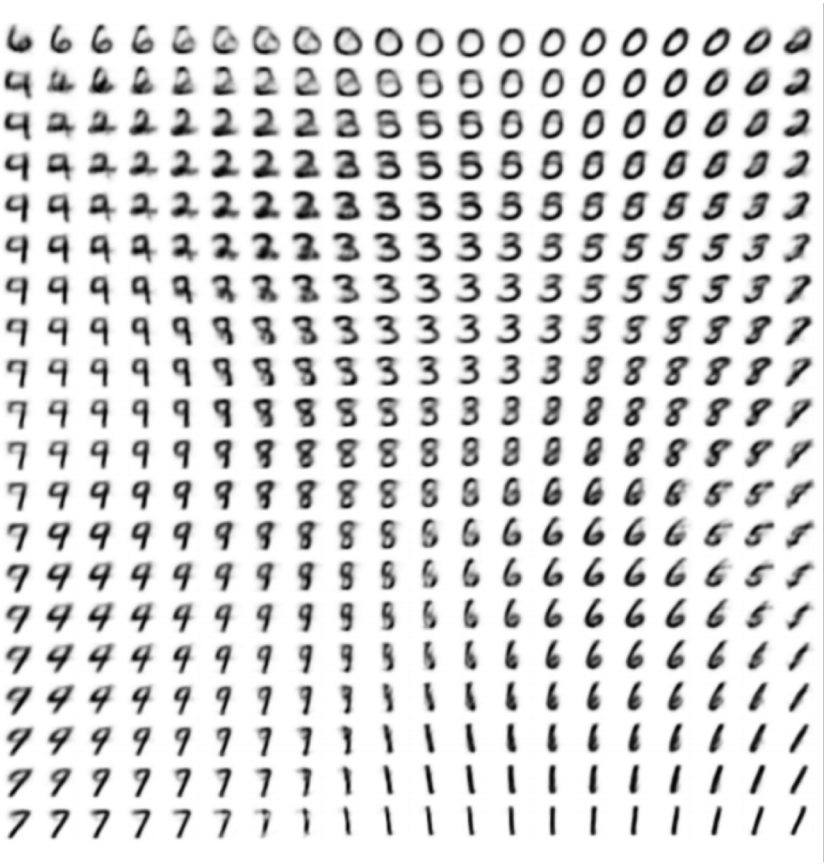
- Objective for the entire dataset:

$$\mathbb{E}_{x\sim D}\left[\mathbb{E}_{z\sim q_\phi(z|x)}[\log p_\theta(x|z)] - D_{KL}\left(q_\phi(z|x), p(z)\right)\right]$$

For further details, see: C. Doersch, Tutorial on Variational Autoencoders, 2016

Original results

- Learned 2D manifolds:



D. Kingma and M. Welling, Auto-Encoding Variational Bayes, ICLR 2014

Variational autoencoders: Generating data

Image source

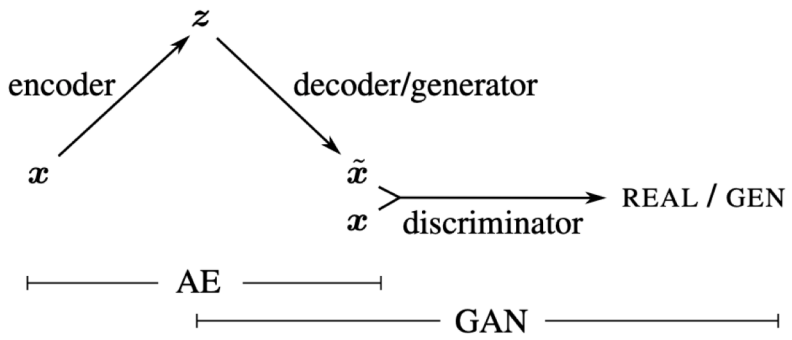
Basic VAE framework: Summary

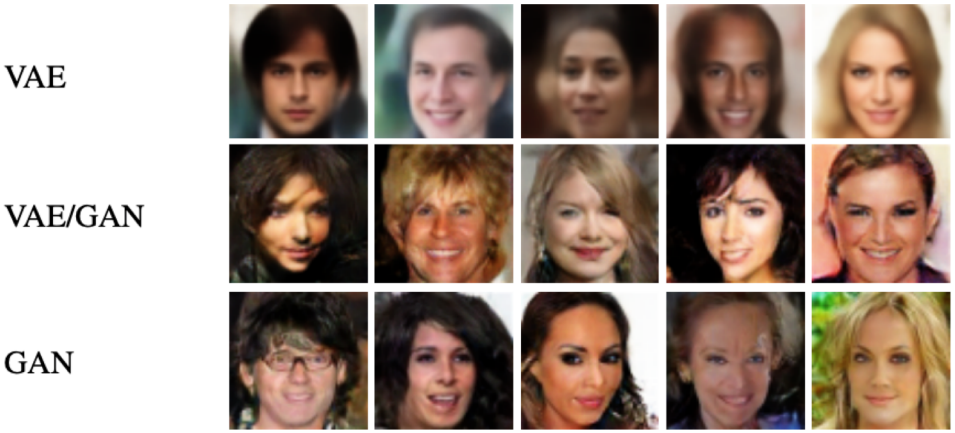
- Pros:
  - Principled mathematical formalism for generative models
  - Allows inference of code given image, can be useful for controlling the latent space
- Cons:
  - Samples blurrier and lower quality compared to GANs
- Active areas of research:
  - More powerful and flexible approximations for relevant probability distributions
  - Combining VAEs and GANs
  - Incorporating structure in latent variables, e.g., hierarchical or categorical distributions

Adapted from J. Johnson

Combining VAEs and GANs

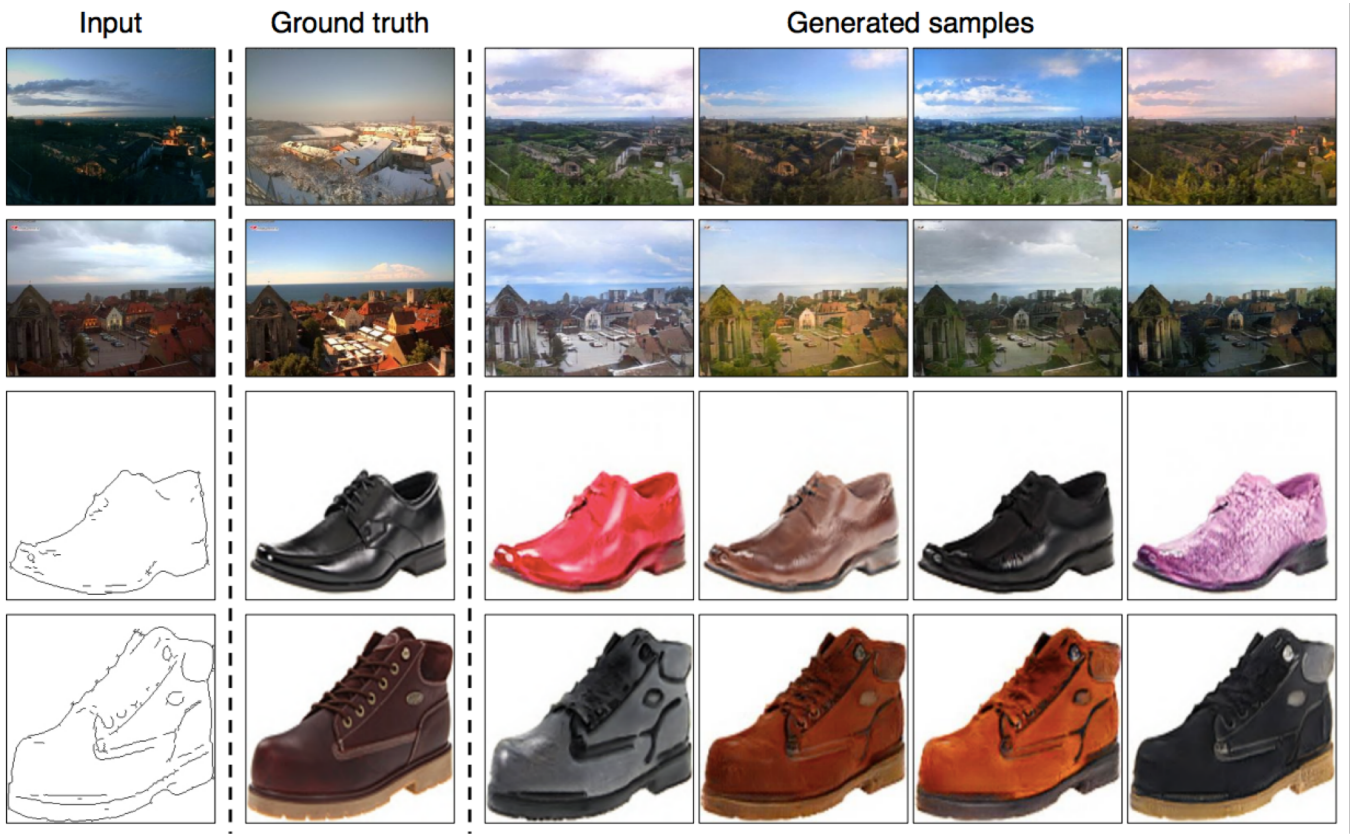
- Define decoder probability model $p_\theta(x|z)$ not in terms of reconstruction errors in pixel space, but in terms of errors in discriminator feature space





A. Larsen, S. Sonderby, H. Larochelle, O. Winther, Autoencoding beyond pixels using a learned similarity metric, ICML 2016

Combining VAEs and GANs: BicycleGANs



J.Y. Zhu, R. Zhang, D. Pathak, T. Darrell, A. A. Efros, O. Wang, E. Shechtman, Toward Multimodal Image-to-Image Translation, NIPS 2017

Combining VAEs and GANs: BicycleGANs

- Key ideas:
  - Image-to-image translation is a *one-to-many* problem. Need to model conditional distribution of output given input parametrized by z
  - To prevent mode collapse (or many-to-one mapping from z to output), need to encourage the mapping between output and latent code to be invertible
  - Propose BicycleGAN framework to simultaneously learn mappings in both directions

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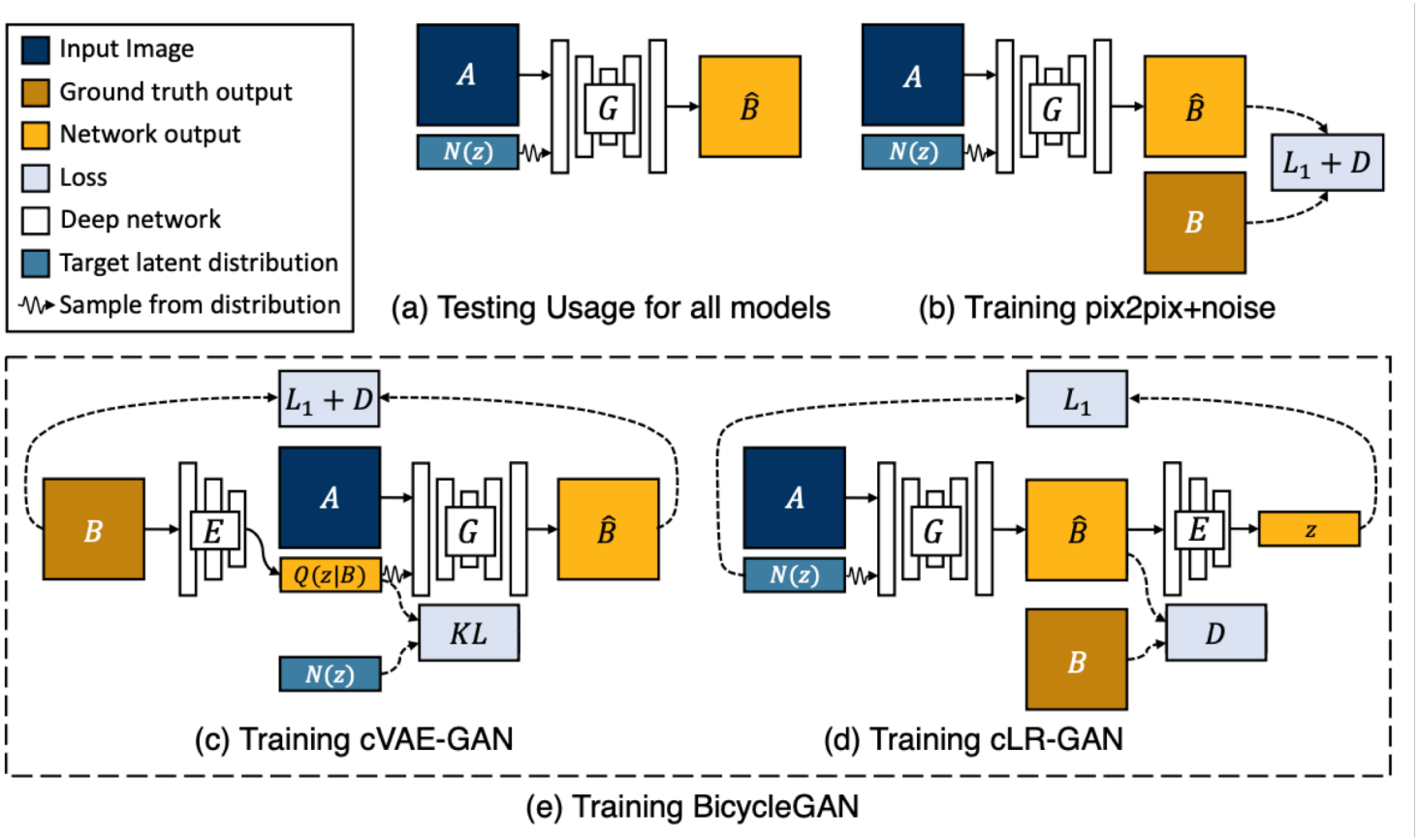
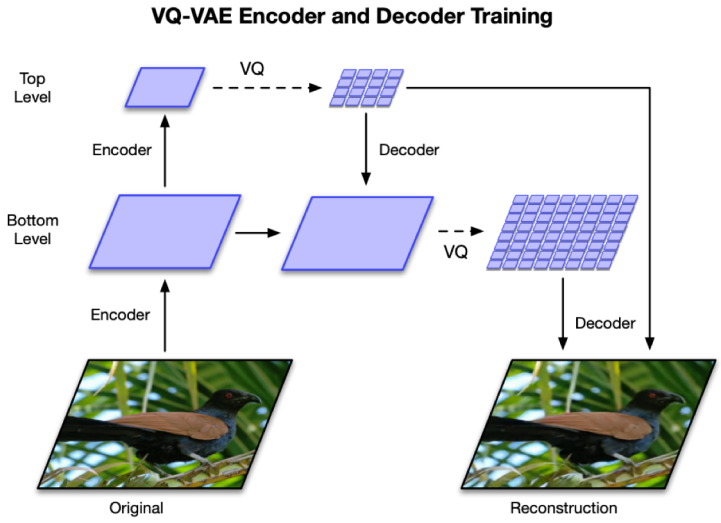


J.Y. Zhu, R. Zhang, D. Pathak, T. Darrell, A. A. Efros, O. Wang, E. Shechtman, Toward Multimodal Image-to-Image Translation, NIPS 2017

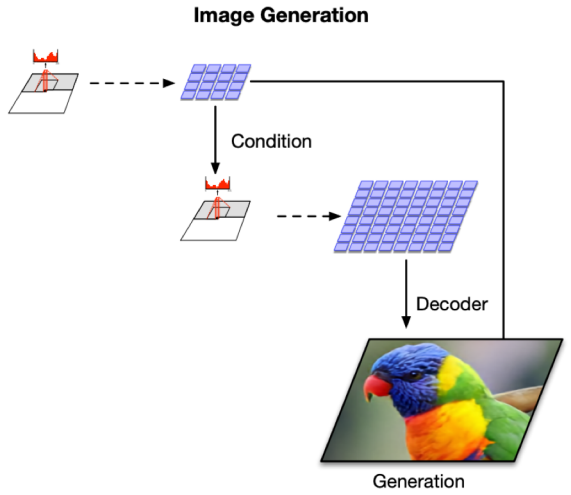
Generating better samples: VQ-VAE-2

- Combining VAE and autoregressive models:

Train a VAE-like model to generate multiscale grids of latent codes



Use a multiscale autoregressive model (PixelCNN) to sample in latent code space



A. Razavi, A. van den Oord, O. Vinyals, Generating Diverse High-Fidelity Images with VQ-VAE-2, NeurIPS 2019

Generating better samples: VQ-VAE-2

- 256 x 256 class-conditional samples, trained on ImageNet:

Generating better samples: VQ-VAE-2

- 256 x 256 class-conditional samples, trained on ImageNet:

Generating better samples: VQ-VAE-2

- 1024 x 1024 generated faces, trained on FFHQ:

Generating better samples: Hierarchical VAE

Figure 1: 256×256-pixel samples generated by NVAE, trained on CelebA HQ [28].

A. Vahdat, J. Kautz, NVAE: A Deep Hierarchical Variational Autoencoder, arXiv 2020