# **Vector Algebra and Calculus**

- 1. Revision of vector algebra, scalar product, vector product
- 2. Triple products, multiple products, applications to geometry
- 3. Differentiation of vector functions, applications to mechanics
- 4. Scalar and vector fields. Line, surface and volume integrals, curvilinear co-ordinates
- 5. Vector operators grad, div and curl
- 6. Vector Identities, curvilinear co-ordinate systems
- 7. Gauss' and Stokes' Theorems and extensions
- 8. Engineering Applications

# 6. Vector Operators: Grad, Div and Curl

- We introduce three field operators which reveal interesting collective field properties, viz.
  - the **gradient** of a scalar field,
  - the **divergence** of a vector field, and
  - the **curl** of a vector field.
- There are two points to get over about each:
  - The mechanics of taking the grad, div or curl, for which you will need to brush up your calculus of several variables.
  - The underlying physical meaning that is, why they are worth bothering about.

- Recall the discussion of temperature distribution, where we wondered how a scalar would vary as we moved off in an arbitrary direction ...
- If  $U(\mathbf{r})$  is a scalar field, its **gradient** is defined in Cartesians coords by

$$gradU = \frac{\partial U}{\partial x}\hat{\mathbf{i}} + \frac{\partial U}{\partial y}\hat{\mathbf{j}} + \frac{\partial U}{\partial z}\hat{\mathbf{k}} .$$

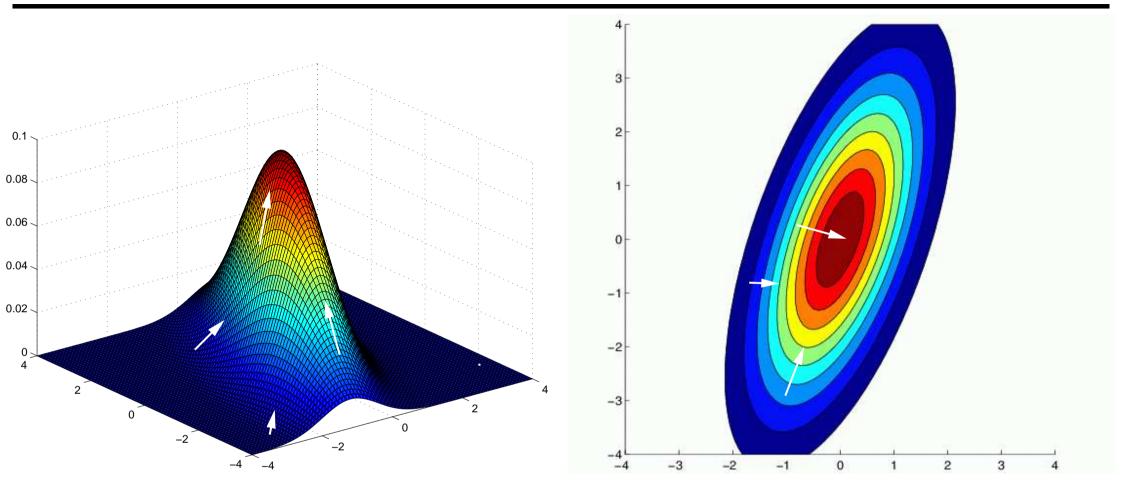
ullet It is usual to define the **vector operator**  $\nabla$ 

$$\mathbf{\nabla} = \left[ \hat{\mathbf{i}} \; \frac{\partial}{\partial x} \; + \; \hat{\mathbf{j}} \; \frac{\partial}{\partial y} \; + \; \hat{\mathbf{k}} \; \frac{\partial}{\partial z} \right]$$

which is called "del" or "nabla". We can write grad $U \equiv \nabla U$ 

NB: grad U or  $\nabla U$  is a **vector** field!

• Without thinking too hard, notice that grad U tends to point in the direction of greatest change of the scalar field U



### Examples of gradient evaluation

**1.** 
$$U = x^2$$

$$\nabla U = \left[\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z}\right] x^2$$
Only  $\partial/\partial x$  exists so

$$\nabla U = 2x\hat{\mathbf{i}}$$
.

**2.** 
$$U = r^2 = x^2 + y^2 + z^2$$
, so

$$\nabla U = \left[\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z}\right] (x^2 + y^2 + z^2)$$

$$= 2x\hat{\mathbf{i}} + 2y\hat{\mathbf{j}} + 2z\hat{\mathbf{k}}$$

$$= 2 \mathbf{r}$$

**3.**  $U = \mathbf{c} \cdot \mathbf{r}$ , where **c** is constant.

$$\nabla U = \left[\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z}\right] (c_1 x + c_2 y + c_3 z)$$
$$= c_1 \hat{\mathbf{i}} + c_2 \hat{\mathbf{j}} + c_3 \hat{\mathbf{k}} = \mathbf{c} .$$

# Another Example ...

**4.** U = f(r), where  $r = \sqrt{(x^2 + y^2 + z^2)}$ 

U is a function of r alone so df/dr exists. As U = f(x, y, z) also,

$$\frac{\partial f}{\partial x} = \frac{df}{dr} \frac{\partial r}{\partial x} \qquad \frac{\partial f}{\partial y} = \frac{df}{dr} \frac{\partial r}{\partial y} \qquad \frac{\partial f}{\partial z} = \frac{df}{dr} \frac{\partial r}{\partial z} .$$

$$\Rightarrow \nabla U = \frac{\partial f}{\partial x} \hat{\mathbf{i}} + \frac{\partial f}{\partial y} \hat{\mathbf{j}} + \frac{\partial f}{\partial z} \hat{\mathbf{k}} \qquad = \frac{df}{dr} \left( \frac{\partial r}{\partial x} \hat{\mathbf{i}} + \frac{\partial r}{\partial y} \hat{\mathbf{j}} + \frac{\partial r}{\partial z} \hat{\mathbf{k}} \right)$$

But  $r = \sqrt{x^2 + y^2 + z^2}$ , so  $\partial r/\partial x = x/r$  and similarly for y, z.

$$\Rightarrow \nabla U = \frac{df}{dr} \left( \frac{x \hat{\mathbf{i}} + y \hat{\mathbf{j}} + z \hat{\mathbf{k}}}{r} \right) = \frac{df}{dr} \left( \frac{\mathbf{r}}{r} \right) .$$

Note that f(r) is spherically symmetrical and the resultant vector field is radial out of a sphere.

• We know that the total differential and grad are defined as

$$dU = \frac{\partial U}{\partial x}dx + \frac{\partial U}{\partial y}dy + \frac{\partial U}{\partial z}dz \& \nabla U = \frac{\partial U}{\partial x}\hat{\mathbf{i}} + \frac{\partial U}{\partial y}\hat{\mathbf{j}} + \frac{\partial U}{\partial z}\hat{\mathbf{k}}$$

ullet So, we can rewrite the change in U as

$$dU = \nabla U \cdot (dx\hat{\mathbf{i}} + dy\hat{\mathbf{j}} + dz\hat{\mathbf{k}}) = \nabla U \cdot d\mathbf{r}$$

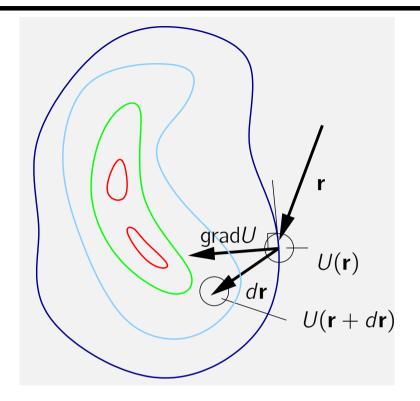
• Conclude that

 $\nabla U \cdot d\mathbf{r}$  is the small change in U when we move by  $d\mathbf{r}$ 

Significance /ctd

- We also know (Lecture 3) that  $d\mathbf{r}$  has magnitude ds.
- So divide by *ds*

$$\Rightarrow \frac{dU}{ds} = \nabla U \cdot \left[ \frac{d\mathbf{r}}{ds} \right]$$



- But  $d\mathbf{r}/ds$  is a unit vector in the direction of  $d\mathbf{r}$ .
- Conclude that

gradU has the property that the rate of change of U wrt distance in any direction  $\hat{\mathbf{d}}$  is the projection of gradU onto that direction  $\hat{\mathbf{d}}$ 

Directional derivatives 6.8

• That is

$$\frac{dU}{ds}$$
 (in direction of  $\hat{\mathbf{d}}$ ) =  $\nabla U \cdot \hat{\mathbf{d}}$ 

- The quantity dU/ds is called a **directional derivative**.
- In general, a directional derivative
  - had a different value for each direction,
  - has no meaning until you specify the direction.
- We could also say that

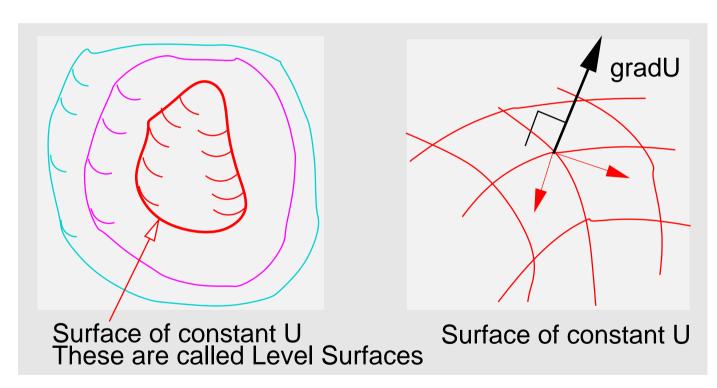
### At any point P, grad*U*

- $^{st}$  points in the direction of greatest rate of change of U wrt distance at P, and
- \* has magnitude equal to the rate of change of U wrt distance in that direction.

- Think of a surface of constant U the locus (x, y, z) for U(x, y, z) = const
- If we move a tiny amount **within** the surface, that is in any tangential direction, there is no change in U, so dU/ds = 0. So for any  $d\mathbf{r}/ds$  in the surface

$$\nabla U \cdot \frac{d\mathbf{r}}{ds} = 0.$$

Conclusion is that: gradU is NORMAL to a surface of constant U



• Let **a** be a vector field:

$$\mathbf{a}(x,y,z) = a_1\hat{\mathbf{i}} + a_2\hat{\mathbf{j}} + a_3\hat{\mathbf{k}}$$

• The divergence of **a** at any point is defined in Cartesian co-ordinates by

$$\operatorname{div} \mathbf{a} = \frac{\partial a_1}{\partial x} + \frac{\partial a_2}{\partial y} + \frac{\partial a_3}{\partial z}$$

- The divergence of a vector field is a scalar field.
- ullet We can write div as a scalar product with the  $oldsymbol{
  abla}$  vector differential operator:

$$\operatorname{div} \mathbf{a} \equiv \left[ \hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z} \right] \cdot \mathbf{a} \equiv \nabla \cdot \mathbf{a}$$

a	div <b>a</b>
ΧÎ	1
$\mathbf{r}(=x\hat{\mathbf{i}}+y\hat{\mathbf{j}}+z\hat{\mathbf{k}})$	3
$r/r^{3}$	0
r <b>c</b>	$(\mathbf{r} \cdot \mathbf{c})/r$ where $\mathbf{c}$ is constant

**Eg 3:** div  $(\mathbf{r}/r^3) = 0$ 

The *x* component of  $\mathbf{r}/r^3$  is  $x.(x^2 + y^2 + z^2)^{-3/2}$ 

We need to find  $\partial/\partial x$  of it ...

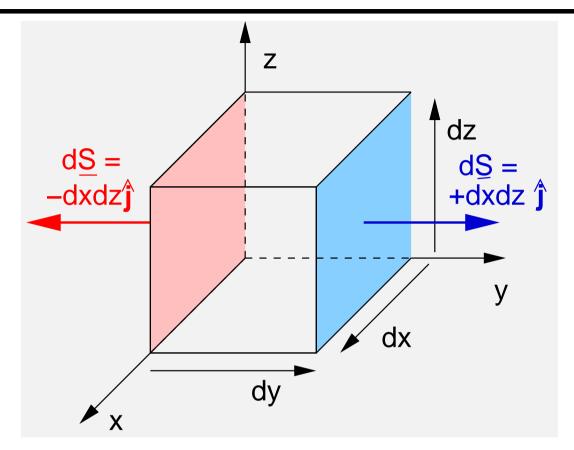
$$\frac{\partial}{\partial x}x.(x^2+y^2+z^2)^{\frac{-3}{2}} = 1.(x^2+y^2+z^2)^{\frac{-3}{2}} + x\frac{-3}{2}(x^2+y^2+z^2)^{\frac{-5}{2}}.2x$$
$$= r^{-3}(1-3x^2r^{-2})$$

Adding this to similar terms for y and z gives

$$r^{-3} (3 - 3(x^2 + y^2 + z^2)r^{-2}) = r^{-3} (3 - 3) = 0$$

The significance of div

- Consider vector field f(r) (eg water flow).
   This vector has magnitude equal to the mass of water crossing a unit area perpendicular to the direction of f per unit time.
- Take volume element dV and compute balance of the flow of  $\mathbf{f}$  in and out of dV.

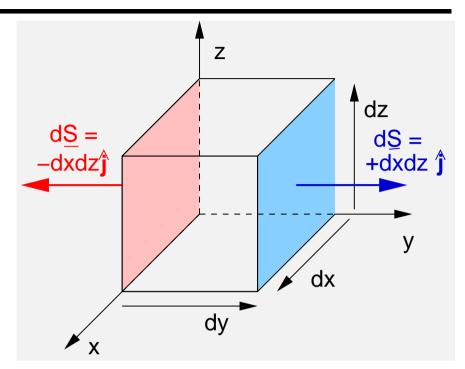


Look at the shaded face on the left
 The contribution to OUTWARD flux from surface is

$$\mathbf{f}(y) \cdot d\mathbf{S} = [f_x(y)\hat{\mathbf{i}} + f_y(y)\hat{\mathbf{j}} + f_z(y)\hat{\mathbf{k}}] \cdot (-dx \ dz \ \hat{\mathbf{j}}) = -f_y(y)dxdz.$$

- A similar contribution, but of opposite sign, will arise from the opposite face ...
- BUT! we must remember that we have moved along y by an amount dy.
- So that this OUTWARD amount is

$$\mathbf{f}(y+dy) \cdot d\mathbf{S} = f_y(y+dy)dxdz$$
$$= \left(f_y + \frac{\partial f_y}{\partial y}dy\right)dxdz$$



• Hence the total outward amount from these two faces is

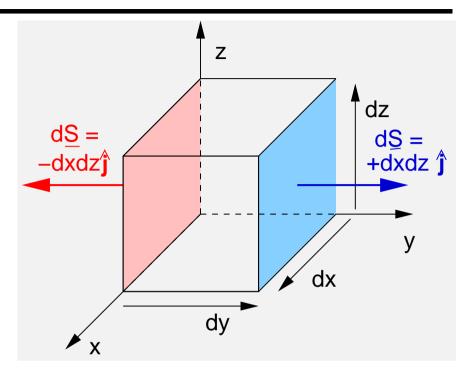
$$-f_{y}dxdz + \left(f_{y} + \frac{\partial f_{y}}{\partial y}dy\right)dxdz = \frac{\partial f_{y}}{\partial y}dydxdz = \frac{\partial f_{y}}{\partial y}dV$$

• Repeat: Total efflux from these faces is

$$\frac{\partial f_y}{\partial y} dy dx dz = \frac{\partial f_y}{\partial y} dV$$

• Summing the other faces gives a total outward flux

$$\left(\frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z}\right) dV = (\nabla \cdot \mathbf{f}) dV$$



#### • Conclusion:

The divergence of a vector field represents the flux generation per unit volume at each point of the field.

- \* **Di**vergence because it is an efflux not an influx.
- \* We also saw that the total efflux from the infinitesimal volume was equal to the flux integrated over the surface of the volume.

• grad U of any scalar field U is a vector field. We can take the div of any vector field.  $\Rightarrow$ we can certainly compute div(grad U)

$$\nabla \cdot (\nabla U) = \left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z}\right) \cdot \left(\left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z}\right) U\right)$$

$$= \left(\left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z}\right) \cdot \left(\hat{\mathbf{i}} \frac{\partial}{\partial x} + \hat{\mathbf{j}} \frac{\partial}{\partial y} + \hat{\mathbf{k}} \frac{\partial}{\partial z}\right)\right) U$$

$$= \left(\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} + \frac{\partial^2 U}{\partial z^2}\right)$$

• The operator  $\nabla^2$  (del-squared) is called the **Laplacian** 

$$\nabla^2 U = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right) U$$

and often appears in engineering in Laplace's equation and Poisson's equation

$$\nabla^2 U = 0$$
 and  $\nabla^2 U = \rho$ 

# $\clubsuit$ Examples of $\nabla^2 U$ evaluation

U	$\nabla^2 U$
$r^2(=x^2+y^2+z^2)$	6
$xy^2z^3$	$2xz^3 + 6xy^2z$
1/r	0

Let's prove the last example

$$1/r = (x^2 + y^2 + z^2)^{-\frac{1}{2}}$$
 and so

$$\frac{\partial^2}{\partial x^2} (x^2 + y^2 + z^2)^{-\frac{1}{2}} = \frac{\partial}{\partial x} - x \cdot (x^2 + y^2 + z^2)^{-3/2}$$

$$= -(x^2 + y^2 + z^2)^{-3/2} + 3x \cdot x \cdot (x^2 + y^2 + z^2)^{-5/2}$$

$$= \frac{1}{r^3} \left( -1 + 3\frac{x^2}{r^2} \right)$$

Adding up similar terms for y and z

$$\nabla^2 \frac{1}{r} = \frac{1}{r^3} \left( -3 + 3 \frac{(x^2 + y^2 + x^2)}{r^2} \right) = 0$$

The curl of a vector field 6.17

- ullet So far we have seen the operator abla ...
  - (i) Applied to a scalar field  $\nabla U$ ; and (ii) Dotted with a vector field  $\nabla \cdot \mathbf{a}$ .
- You are now overwhelmed by irrestible urge to ...

(iii) cross it with a vector field: 
$$\nabla \times \mathbf{a}$$

• This gives the curl of a vector field

$$\nabla \times \mathbf{a} \equiv \operatorname{curl}(\mathbf{a})$$

• We can follow the pseudo-determinant recipe for vector products, so that

$$\nabla \times \mathbf{a} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_x & a_y & a_z \end{vmatrix} = \left( \frac{\partial a_z}{\partial y} - \frac{\partial a_y}{\partial z} \right) \hat{\mathbf{i}} + \left( \frac{\partial a_x}{\partial z} - \frac{\partial a_z}{\partial y} \right) \hat{\mathbf{j}} + \left( \frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y} \right) \hat{\mathbf{k}}$$

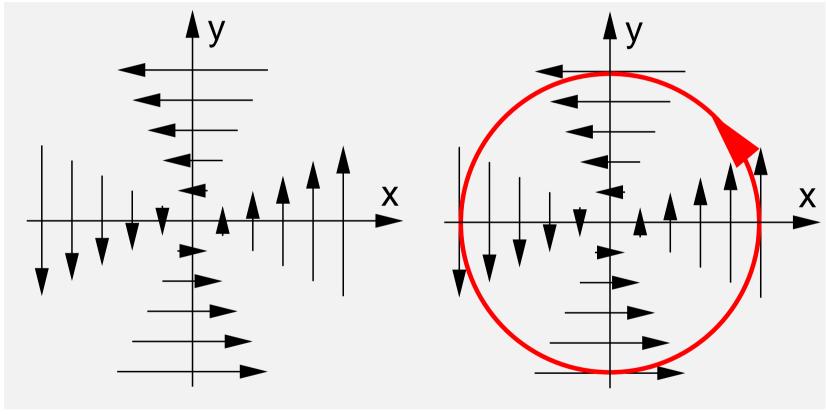
# Examples of curl evaluation

a	$\nabla \times a$
$-y\hat{\mathbf{i}} + x\hat{\mathbf{j}}$	2 <b>ƙ</b>
$x^2y^2\hat{\mathbf{k}}$	$2x^2y\hat{\mathbf{i}} - 2xy^2\hat{\mathbf{j}}$

2nd example:

$$\nabla \times (x^2 y^2 \hat{\mathbf{k}}) = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ 0 & 0 & x^2 y^2 \end{vmatrix}$$
$$= \hat{\mathbf{i}} x^2 2y - \hat{\mathbf{j}} 2x y^2$$
$$= 2x^2 y \hat{\mathbf{i}} - 2x y^2 \hat{\mathbf{j}}$$

- First example gives a clue ... the field  $\mathbf{a} = -y\hat{\mathbf{i}} + x\hat{\mathbf{j}}$  is sketched below.
- This field has a curl of  $2\hat{\mathbf{k}}$ , which is in the r-h screw direction out of the page.
- You can also see that a field like this must give a finite value to the line integral around the complete loop  $\oint_C \mathbf{a} \cdot d\mathbf{r}$ .

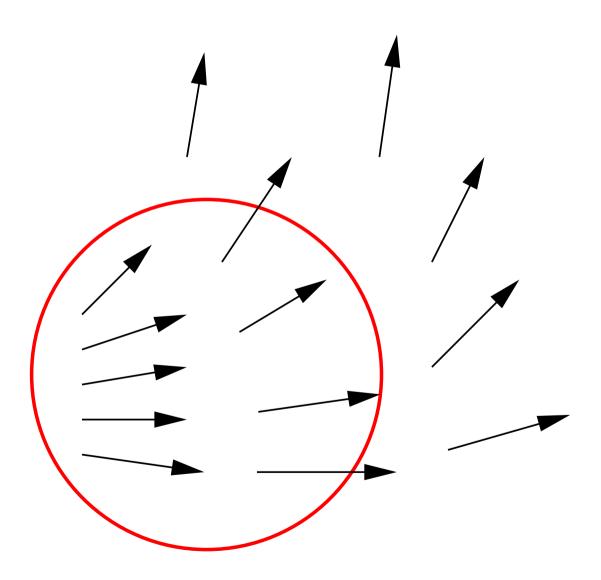


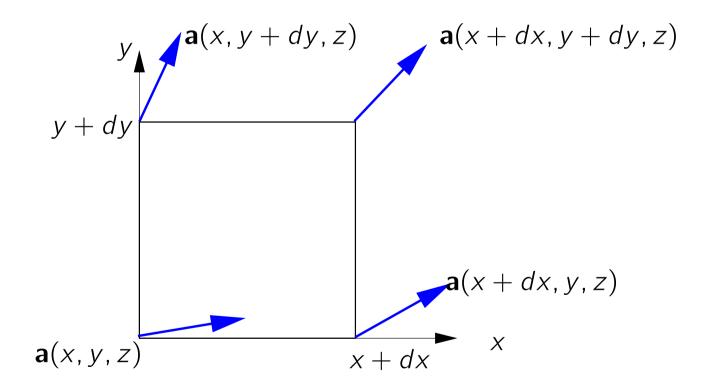
- In fact curl is closely related to the line integral around a loop.
- The **circulation** of a vector field **a** round any closed curve *C* is defined to be

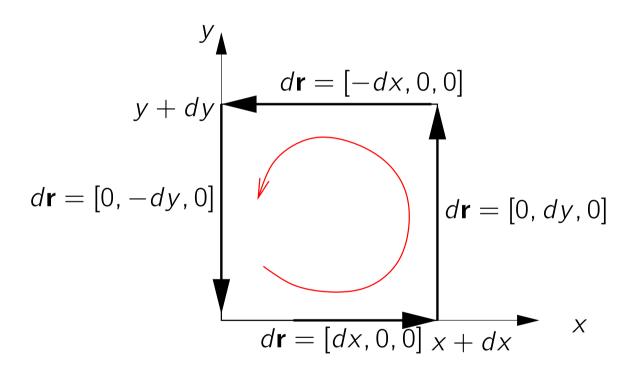
$$\oint_C \mathbf{a} \cdot d\mathbf{r}$$

The **curl** of the vector field **a** represents the

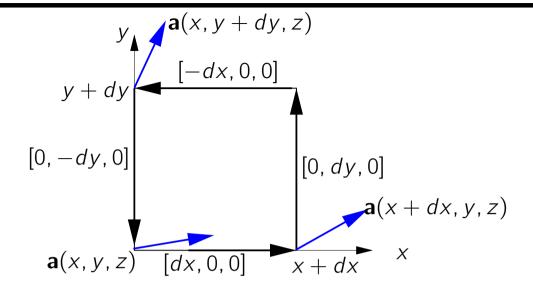
- $\ast$  the  $\emph{vorticity}$ , or
- \* the circulation per unit area in the direction of the area's normal







ullet Consider the circulation round the perimeter of a rectangle dx by dy ...



$$\oint_{C} \mathbf{a} \cdot d\mathbf{r} = \mathbf{a}(x, y, z). [dx \ 0 \ 0] + \mathbf{a}(x + dx, y, z). [0 \ dy \ 0] + \mathbf{a}(x, y + dy, z). [-dx \ 0 \ 0] + \mathbf{a}(x, y, z). [0 \ -dy \ 0]$$

$$\oint_{C} \mathbf{a} \cdot d\mathbf{r} = \mathbf{a}(x, y, z) \cdot [dx \ 0 \ 0] + \mathbf{a}(x + dx, y, z) \cdot [0 \ dy \ 0] 
+ \mathbf{a}(x, y + dy, z) \cdot [-dx \ 0 \ 0] + \mathbf{a}(x, y, z) \cdot [0 \ -dy \ 0] 
= a_{x}(x, y, z) dx + a_{y}(x + dx, y, z) 
- a_{x}(x, y + dy, z) dx - a_{y}(x, y, z) dy 
= a_{x} dx + a_{y} dy + \frac{\partial a_{y}}{\partial x} dx dy 
- a_{x} dx - \frac{\partial a_{x}}{\partial y} dy dx - a_{y} dy 
= \left[\frac{\partial a_{y}}{\partial x} - \frac{\partial a_{x}}{\partial y}\right] dx dy 
= (\nabla \times \mathbf{a}) \cdot dx dy \hat{\mathbf{k}} 
= (\nabla \times \mathbf{a}) \cdot d\mathbf{S}$$

 $\bullet$  Rceapping: consider circulation round the perimeter of a rectangle dx by dy

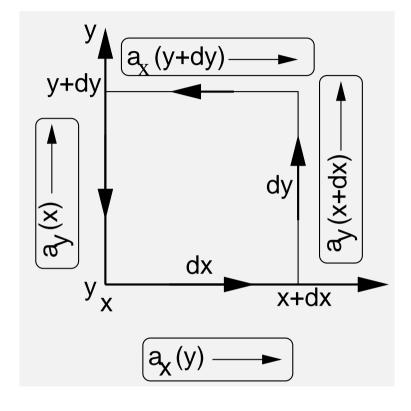
• The fields in the x-direction at bottom and top are

$$a_x(y)$$
 and  $a_x(y+dy) = a_x(y) + \frac{\partial a_x}{\partial y} dy$ 

• The fields in the y-direction at left and right are

$$a_y(x)$$
 and  $a_y(x + dx) = a_y(x) + \frac{\partial a_y}{\partial x} dx$ 

• Summing around from the bottom in anticlockwise order



$$dC = +[a_x(y) \ dx] + [a_y(x + dx) \ dy] - [a_x(y + dy) \ dx] - [a_y(x) \ dy]$$
$$= \left(\frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y}\right) \ dx \ dy = (\nabla \times \mathbf{a}) \cdot dx dy \hat{\mathbf{k}} = (\nabla \times \mathbf{a}) \cdot d\mathbf{S}$$

• A vector field with zero divergence is said to be

### solenoidal.

• A vector field with zero curl is said to be

#### irrotational.

• A scalar field with zero gradient is said to be

#### constant.

Summary 6.28

#### • Today we've introduced ...

- The gradient of a scalar field
- The divergence of a vector field
- The Laplacian
- The curl of a vector field
- We've described the grunt of working these out in Cartesian coordinates ... If your partial differentiation is flaky, sort it.
- We've given some insight into what "physical" aspects of fields they relate too.

  Worth spending time thinking about these. Vector calculus is the natural language of engineering in 3 vector spaces...