

# Xiyang Wu

**Tel:** (+1) 470-313-8459 | **Email:** [wuxiyang@umd.edu](mailto:wuxiyang@umd.edu) | **Portfolio:** [wuxiyang1996.github.io](https://wuxiyang1996.github.io)  
**Address:** 8222 Greenbelt Station Pkwy, Greenbelt, MD, USA, 20770

## EDUCATION

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### University of Maryland

*Ph.D. in Electrical and Computer Engineering, GAMMA Laboratory*

Advisor: Dinesh Manocha      GPA: 3.80/4.00

College Park, MD

*Aug. 2021 – May. 2026 (Expected)*

### Georgia Institute of Technology

*M.S. in Electrical and Computer Engineering, CORE Robotics Laboratory*

Advisor: Matthew Gombolay      GPA: 4.00/4.00

Atlanta, GA

*Aug. 2019 – May. 2021*

### Tianjin University

*B.Eng. in Measuring and Controlling Technologies and Instruments (Honors Class)*

Advisor: Xiaodong Zhang      GPA: 3.85/4.00

Tianjin, China

*Sep. 2015 – Jul. 2019*

## PUBLICATION

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1. **Xiyang Wu**, Rohan Chandra, Tianrui Guan, Amrit Singh Bedi, Dinesh Manocha. Intent-Aware Planning in Heterogeneous Traffic via Distributed Multi-Agent Reinforcement Learning. *7th Annual Conference on Robot Learning (CoRL) (Oral)*, 2023
2. **Xiyang Wu**, Rohan Chandra, Tianrui Guan, Amrit Singh Bedi, Dinesh Manocha. iPLAN: Intent-Aware Planning in Heterogeneous Traffic via Distributed Multi-Agent Reinforcement Learning. *MRS Workshop at IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) (Best Paper Award)*, 2023
3. Haoyue Liu, **Xiyang Wu**, Ning Yan, Zexiao Li, Xiaodong Zhang. A novel image registration-based dynamic photometric stereo method for online defect detection in aluminum alloy castings. *Digital Signal Processing*, 2023

## PREPRINTS

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(\* indicates equal contributions)

1. Chak Lam Shek\*, **Xiyang Wu\***, Dinesh Manocha, Pratap Tokekar, Amrit Singh Bedi. LANCAR: Leveraging Language for Context-Aware Robot Locomotion in Unstructured Environments. *arXiv:2310.00481, Submitted to International Conference on Robotics and Automation (ICRA)*, 2024
2. Esmaeil Seraj, **Xiyang Wu**, Matthew Gombolay. FireCommander: An Interactive, Probabilistic Multi-agent Environment for Joint Perception-Action Tasks. *arXiv:2011.00165*, 2020

## RESEARCH EXPERIENCE

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### GAMMA Laboratory, University of Maryland

*Research Assistant      Advisor: Dinesh Manocha*

College Park, MD

*Sep. 2022 – Now*

- **Large Language Model in Robot Navigation** (In progress). Using Large Language Model and reinforcement learning in robot trajectory planning.
- **Intent-aware Autonomous Driving**. We designed a distributed multi-agent reinforcement learning (MARL) algorithm that jointly predicts trajectories and intents in dense and heterogeneous traffic scenarios. We used behavioral incentive for high-level decision-making strategy that sets planning sub-goals and instant incentive for low-level motion planning to execute sub-goals to model agents' incentives to their strategies.

### Cognitive Optimization and Relational (CORE) Robotics Laboratory

*Research Assistant      Advisor: Matthew Gombolay*

Atlanta, GA

*Jan. 2020 – Dec. 2020*

- **FireCommander: Multi-agent Wildfire Pruning System with Learning from Demonstration**  
We investigated and implemented the state-of-art of reinforcement learning approaches on the simulation environment we designed for multi-agent firefighting tasks.

## Laboratory of Micronano Manufacturing Technology

Research Assistant      Advisor: Xiaodong Zhang

Tianjin, China

Sep. 2018 – Jul. 2019

- **Online Scratch Inspection System with Photometric Stereo Method.** We designed the online defect detection system with the photometric stereo method and multiple image processing approaches.

## TEACHING EXPERIENCE

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### Graduate Teaching Assistant

*University of Maryland*

*ENEE 664: Optimal Control*

*Spring 2023*

*ENEE 245: Digital Circuits and Systems Laboratory*

*Spring 2023*

*ENEE 303: Analog and Digital Electronics*

*Fall 2022*

*ENEE 307: Electronic Circuits Design Laboratory*

*Spring 2022*

*ENEE 322: Signal and System Theory*

*Fall 2021*

## HONOR & AWARDS

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- Best Paper Award, IROS 2023 MRS Workshop
- Merit Student Award in Tianjin University, 2018
- Samsung Scholarship, 2017
- Secondary Scholarship in Hexagon Innovation Laboratory in Tianjin University, 2016
- National Secondary Award in the 10th iCAN International Contest of Innovation, 2016

## ACADEMIC SERVICE

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- **Reviewer:** IEEE Access, ICRA 2024, RA-L