Communication-Efficient Learning of Deep Networks from Decentralized Data



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1) Introduction

- Enormous amounts of data on our mobile devices suitable for learning models, but private in nature
- Federated learning allows users to collectively reap the benefits of shared models trained from such data without the need to centrally store it.
- Every client (k): trains on local data with SGD for E epochs with batch size B to obtain a gradient estimate (g_k) and sends updated weights (w^k) to the server, with learning rate η . $w^k \leftarrow w^k - \eta g_k$
- Server: combines the weights of the clients (k) to obtain a new model (w_{t+1}) and re-distributes the new model back to the clients for further training. $w_{t+1} \leftarrow \frac{1}{K} \sum_{k=1}^{K} w_{t+1}^k$

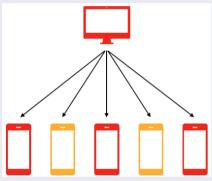


Figure: Sketch of a federated environment

2.2) Unbalanced data distribution w/o weights

• unbalanced data distribution w/o weight contribution of clients; i.e. the partition P_k of the training data is independent but unevenly distributed, which affects the gradient estimates g_k

$$w^k \leftarrow w^k - \eta \frac{1}{n_k} \nabla \sum_{i \in \underline{P_k}} L_i(w)$$

$$w_{t+1} \leftarrow \frac{1}{K} \sum_{k=1}^{K} w_{t+1}^{k}$$

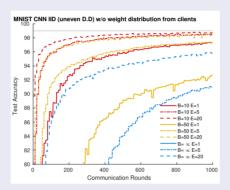
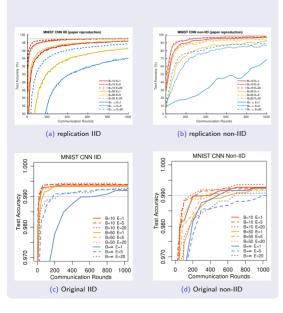


Figure: Uneven data distribution w/o weight contribution of clients

2.1) Replication

• reproduction of the original results from the paper



2.3) Unbalanced data distribution w/ weights

• unbalanced data distribution w/ weight contribution of clients; i.e. averaging model is based on fraction of local training data

$$w^k \leftarrow w^k - \eta \frac{1}{n_k} \nabla \sum_{i \in \underline{P_k}} L_i(w)$$

$$w_{t+1} \leftarrow \frac{1}{K} \sum_{k=1}^{K} \frac{\frac{n_k}{n}}{n} w_{t+1}^k$$

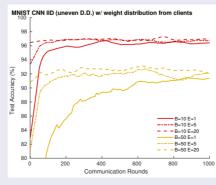


Figure: Uneven data distribution w/ weight contribution of clients

2.4) Original algorithm with Gaussian noise appended

• Gaussian noise added to weight updates before communication with clients

$$w^k \leftarrow w^k - \eta \frac{1}{n_k} \nabla \sum_{i \in P_i} L_i(w)$$

$$w_{t+1} \leftarrow \frac{1}{K} \sum_{k=1}^{K} \left(w_{t+1}^k + N(0, \sigma^2) \right)$$

Best performing model trains on batch size of 10 for 20 local epochs.

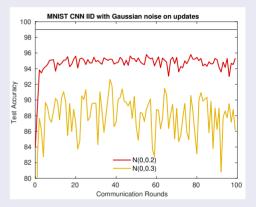


Figure: Learning curves of model with Gaussian noise on updates

3) Conclusion & Discussions

- replication has slightly worse results than original paper
- unbalanced data distribution led to worse performance
- unbalanced data distribution corrected with weights does not solve the problem
- adding Gaussian noise led to worse algorithm accuracy, yet the model converged

Table: Amount of rounds needed to reach 99% accuracy

Е	В	IID	NON-IID	ud_IID	ud_w_IID
1	10	-	-	-	-
5	10	586	-	-	-
20	10	646	616	-	-
1	50	-	-	-	-
5	50	-	-	-	-
20	50	-	-	-	-
1	∞	-	-	-	-
5	∞	-	-	-	-
20	∞	-	-	-	-

References



H. Brendan McMahan and Eider Moore and Daniel Ramage and Seth Hampson and Blaise Agüera y Arcas. 1602.05629, 2016. https://arxiv.org/abs/1602.05629



https://github.com/shaoxiongji/federated-learning