### APPENDIX

**Proof of Proposition 1**: Adding the constant term  $(\lambda_i^{k-1})^2/2\rho$  to the right-hand side of (2a).

$$\min_{\mathbf{x}_{i} \in \mathcal{X}_{i}} L_{i}^{k} = \frac{1}{2} \mathbf{x}_{i,\text{Re}}^{T} \mathbf{Q}_{i} \mathbf{x}_{i,\text{Re}} + d_{i} \mathbf{x}_{i,\text{Re}} + \lambda_{i}^{k-1} (x_{i,\text{Sh}} - y_{i,\text{Sh}}^{k-1}) 
+ \frac{\rho}{2} (x_{i,\text{Sh}} - y_{i,\text{Sh}}^{k-1})^{2} + \frac{(\lambda_{i}^{k-1})^{2}}{2\rho}$$

$$= \frac{1}{2} \mathbf{x}_{i,\text{Re}}^{T} \mathbf{Q}_{i} \mathbf{x}_{i,\text{Re}} + d_{i} \mathbf{x}_{i,\text{Re}} + \frac{\rho}{2} \left( x_{i,\text{Sh}} - y_{i,\text{Sh}}^{k-1} + \frac{\lambda_{i}^{k-1}}{2} \right)^{2}$$
(A1)

Set  $x'_{i,\text{Sh}}^{k} = x_{i,\text{Sh}}^{k} - y_{i,\text{Sh}}^{k-1} + \lambda_{i}^{k-1}/\rho$ ,  $x'_{i} = [x_{i,\text{Re}}^{T}, x'_{i,\text{Sh}}]^{T}$ ,  $x'_{i} \in \mathbb{R}^{R_{i}+1}$ ,  $\theta_{i,\text{Re}} = [-\overline{x}_{i,1} \cdots -\overline{x}_{i,R_{i}} \ \underline{x}_{i,1} \cdots \ \underline{x}_{i,R_{i}}]^{T}$ ,  $\theta_{i,\text{Sh}}^{k} = D_{i} - y_{i,\text{Sh}}^{k-1} + \lambda_{i}^{k-1}/\rho$ , then the (A1) can be expressed as:

$$\min_{\mathbf{x}'_i} L_i^k(\mathbf{x}'_i, \boldsymbol{\theta}_i) = \frac{1}{2} \mathbf{x}'_i^T \boldsymbol{Q}'_i \mathbf{x}'_i + \boldsymbol{d}'_i \mathbf{x}'_i,$$
(A2a)

s.t. 
$$A_i \mathbf{x}'_i + \boldsymbol{\theta}_{i,Re} \le \mathbf{0}$$
;  $\boldsymbol{\mu}_i$  (A2b)

$$\mathbf{1}^{1\times(R_i+1)}\mathbf{x}'_i - \theta_{i\,\mathrm{Sh}}^k = 0: \eta_i \tag{A2c}$$

$$\mathbf{Q}'_{i} = \begin{bmatrix} \mathbf{Q}_{i} & \mathbf{0}^{R_{i}} \\ \mathbf{0}^{1 \times R_{i}} & \rho \end{bmatrix}, \mathbf{d}'_{i} = \begin{bmatrix} \mathbf{d}_{i} & 0 \end{bmatrix}$$
(A2d)

where, (A2b) corresponds to the resource constraint (1b), and (A2c) corresponds to prosumer's power balance constraint (1c). The multipliers for (A2b) and (A2c) are denoted as  $\mu_i$  and  $\eta_i$ .

Defining the optimal solution of (A2) as  $\mathbf{x'}_{i}^{*} = [\mathbf{x}_{i,Re}^{*T}, \mathbf{x'}_{i,Sh}^{k^{*}}]^{T}$ , the KKT conditions can be written as:

$$\frac{\partial L_i(\boldsymbol{x'}_i^*,\boldsymbol{\theta}_i)}{\partial \boldsymbol{x'}_i^*} = \boldsymbol{Q'}_i \boldsymbol{x'}_i^* + \boldsymbol{d'}_i^{\mathrm{T}} + \boldsymbol{A}_i^{\mathrm{T}} \boldsymbol{\mu}_i + \boldsymbol{1}^{R+1} \eta_i = \boldsymbol{0}, \quad (A3a)$$

$$(\mathbf{A}_i)_{\mathbf{A}_s} \mathbf{x'}_i^* + (\boldsymbol{\theta}_{i \, \mathrm{Re}})_{\mathbf{A}_s} = \mathbf{0}, \tag{A3b}$$

$$(\boldsymbol{\mu}_i)_{\Delta} \geq \mathbf{0},$$
 (A3c)

$$(\boldsymbol{A}_{i})_{I,s} \boldsymbol{x}'_{i} + (\boldsymbol{\theta}_{i,Re})_{I,s} \leq \boldsymbol{0}, \tag{A3d}$$

$$(\boldsymbol{\mu}_i)_{I} = \mathbf{0}, \tag{A3e}$$

$$\mathbf{1}^{1 \times (R_i + 1)} \mathbf{x'}_i^* - \theta_{i, Sh}^k = 0 \tag{A3f}$$

where,  $(\cdot)_{A,s}$  and  $(\cdot)_{I,s}$  are matrix reorganization operators, which that combine the rows corresponding to active and inactive constraints within the *s* segments into new matrices.

Support  $p_A$  and  $p_I$  denote the number of active and inactive constraints. Combining (A3a), (A3b), and (A3f), we have

$$\mathbf{Q}_{i}^{\prime}\mathbf{x}_{i}^{\prime*} + \mathbf{d}_{i}^{\prime T} + \begin{bmatrix} (\mathbf{A}_{i})_{A,s}^{T} & \mathbf{1}^{R_{i}} \\ \mathbf{0}^{1 \times P_{A}} & 1 \end{bmatrix} \begin{bmatrix} (\boldsymbol{\mu}_{i})_{A} \\ \eta_{i} \end{bmatrix} = \mathbf{0},$$
 (A4a)

$$\begin{bmatrix} (\boldsymbol{A}_{i})_{A,s} & \boldsymbol{0}^{p_{A}} \\ \boldsymbol{1}^{1 \times R_{i}} & 1 \end{bmatrix} \boldsymbol{x}_{i}^{\prime *} + \begin{bmatrix} (\boldsymbol{\theta}_{i,Re})_{A,s} \\ -\boldsymbol{\theta}_{i,Sh}^{k} \end{bmatrix} = \boldsymbol{0},$$
 (A4b)

Simplifying  $(A3c)\sim(A3d)$  and  $(A4a)\sim(A4b)$ , then:

$$\boldsymbol{H}_{1,i,s}\boldsymbol{\Gamma}_{i,s} \geq \boldsymbol{0}, \boldsymbol{H}_{1,i,s} = \begin{bmatrix} (\boldsymbol{E}^{2R_i})_{A,s} & \boldsymbol{0}^{p_A} \\ \boldsymbol{0}^{1 \times 2R_i} & 0 \end{bmatrix}, \boldsymbol{\Gamma}_{i,s} = \begin{bmatrix} (\boldsymbol{\mu}_i)_{A,s} \\ \eta_i \end{bmatrix}$$
(A5a)

$$(A_i)_{I,s} x'_i^* + H_{2,i,s} \theta_i'^k \le 0, H_{2,i,s} = \begin{bmatrix} (E^{2R_i})_{I,s} & \mathbf{0}^{p_1} \\ \mathbf{0}^{1 \times 2R_i} & 0 \end{bmatrix}$$
 (A5b)

$$\mathbf{Q}_{i}^{\prime}\mathbf{x}_{i}^{\prime*} + \mathbf{d}_{i}^{\prime T} + \mathbf{G}_{i,s}^{T}\mathbf{\Gamma}_{i,s} = \mathbf{0}, \mathbf{G}_{i,s} = \begin{bmatrix} (\mathbf{A}_{i})_{A,s} & \mathbf{0}^{p_{A}} \\ \mathbf{1}^{1 \times R_{i}} & 1 \end{bmatrix}$$
(A5c)

$$G_{i}\boldsymbol{x}_{i}^{\prime^{*}} + \boldsymbol{H}_{3,i,s}\boldsymbol{\theta}_{i}^{\prime k} = \boldsymbol{0}, \boldsymbol{H}_{3,i,s} = \begin{bmatrix} (\boldsymbol{E}^{2R_{i}})_{A,s} & \boldsymbol{0}^{p_{A}} \\ \boldsymbol{0}^{1 \times 2R_{i}} & -1 \end{bmatrix}$$
(A5d)

The  $E^{2R_i}$  denotes an identity diagonal matrix of size  $2R_i \times 2R_i$ . (A5a), (A5b), (A5c) and (A5d) correspond to (A3c), (A3d), (A5a) and (A5b), respectively.

Considering the mutual exclusivity of the upper and lower resource constraints, rank( $G_{i,s}$ )=  $p_A$ +1 and  $G_{i,s}Q_i^{r-1}G_{i,s}^T$  is invertible. Hence, combining (A5c) and (A5d), we have

$$\boldsymbol{\Gamma}_{i,s} = \boldsymbol{M}_{1,i,s} \boldsymbol{\theta}_{i}^{\prime k} + \boldsymbol{M}_{2,i,s} \tag{A6a}$$

$$\mathbf{M}_{1,i,s} = (\mathbf{G}_{i,s} \mathbf{Q}_{i}^{'-1} \mathbf{G}_{i,s}^{\mathrm{T}})^{-1} \mathbf{H}_{3,i,s}$$
 (A6b)

$$\mathbf{M}_{2,i,s} = -(\mathbf{G}_{i,s} \mathbf{Q}_{i}^{'-1} \mathbf{G}_{i,s}^{\mathrm{T}})^{-1} \mathbf{G}_{i,s} \mathbf{Q}_{i}^{'-1} \mathbf{d}_{i}^{'\mathrm{T}}$$
(A6c)

By substituting (A6a) into (A5c), we obtain

$$\mathbf{x'}_{i}^{*} = \mathbf{W}_{1,i,s} \mathbf{\theta}_{i}^{\prime k} + \mathbf{W}_{2,i,s} \tag{A7a}$$

$$\boldsymbol{W}_{1,i,s} = -\boldsymbol{Q}_{i}^{r-1} \boldsymbol{G}_{i,s}^{\mathrm{T}} \boldsymbol{M}_{1,i,s} \tag{A7b}$$

$$W_{2is} = -Q_{i}^{-1} d_{i}^{T} - Q_{i}^{-1} G_{is}^{T} M_{2is}$$
(A7c)

Combining (A7a) with the definitions of  $x_i^*$ , we have

$$x_{i,\text{Sh}}^{k^*} = w_{1,i,s}' \theta_i'^k + w_{2,i,s}' + y_{i,\text{Sh}}^{k-1} - \frac{\lambda_i^{k-1}}{\rho}$$
(A8c)

where,  $w'_{1,i,s} = W_{1,i,s,R_i+1}$  and  $w'_{2,i,s} = W_{2,i,s,R_i+1}$  represent the vectors corresponding to the  $(R_i+1)$ -th row of  $W_{1,i,s}$  and  $W_{2,i,s}$ , respectively. To ensure the complementary slackness condition holds, (A8c) is further substituted into (A5a)~(A5b) (A5b), yielding the following domain:

$$\Theta'_{i,s} := \left\{ \boldsymbol{\theta}_{i}^{\prime k} \middle| \begin{aligned} \boldsymbol{H}_{1,i,s}(\boldsymbol{M}_{1,i,s}\boldsymbol{\theta}_{i}^{\prime k} + \boldsymbol{M}_{2,i,s}) &\geq \mathbf{0}, \\ (\boldsymbol{A}_{i})_{I,s}(\boldsymbol{W}_{1,i,s}\boldsymbol{\theta}_{i}^{\prime k} + \boldsymbol{W}_{2,i,s}) + \boldsymbol{H}_{2,i,s}\boldsymbol{\theta}_{i}^{\prime k} &\leq \mathbf{0} \end{aligned} \right\}$$
(A9)

According to (A8c)~(A9), we can derive **Proposition 1**. The prosumer's best response can be characterized by piecewise linear function. The domain of each segment depends on the cost coefficients and the active constraints.

## $\blacksquare$ End of proof of *Proposition 1*.

# **Proof of Proposition 3:**

Since prosumers are not coupled in (4), it is equivalent to show that the  $\hat{x}_i^k$  of each prosumer satisfies the (15).

- 1) For prosumers in  $\mathcal{Z}_{C}^{k}$ . According to the KKT conditions, (15) is satisfied with  $\widehat{\boldsymbol{x}}_{i}^{k} = \boldsymbol{x}_{i}^{k^{*}}$  and  $\widehat{\boldsymbol{\alpha}}_{i}^{k} = \boldsymbol{\alpha}_{i}^{k^{*}}$ .
  - 2) For prosumers in  $\mathcal{I}/\mathcal{I}_{C}^{k}$ . Combining (1c) and (13) and A1

$$\sum_{r \in \mathcal{R}} (\underline{x}_{i,r} - x_{i,r}^*) \le x_{i,\text{Sh}}^{k^*} - \tilde{x}_{i,\text{Sh}}^k \le \sum_{r \in \mathcal{R}} (\overline{x}_{i,r} - x_{i,r}^*)$$
(A10a)

$$-\xi \le x_{i,\text{Sh}}^{k*} - \tilde{x}_{i,\text{Sh}}^{k} \le \xi \tag{A10b}$$

According to (13) and (1c) existing  $\delta_i$  have

$$\max\{(\underline{x}_{i,r} - x_{i,r}^{k^*}), -\xi\} \le \delta_{i,r} \le \min\{(\overline{x}_{i,r} - x_{i,r}^{k^*}), \xi\},$$
 (A11a)

$$\sum_{r \in \mathcal{R}} \delta_{i,r} = x_{i,\mathrm{Sh}}^{k^*} - \tilde{x}_{i,\mathrm{Sh}}^k \tag{A11b}$$

Assume the  $\hat{x}_{i,r}^k = x_{i,r}^{k^*} + \delta_{i,r}$ , then we have

$$\tilde{x}_{i,\text{Sh}}^k + \sum_{r \in \mathcal{R}_i} \hat{x}_{i,r}^k = x_{i,\text{Sh}}^{k^*} + \sum_{r \in \mathcal{R}_i} x_{i,r}^{k^*} = D_i$$
 (A12a)

$$\underline{x}_{i,r} \le \hat{x}_{i,r}^k \le \overline{x}_{i,r}, -\xi \le \hat{x}_i^k - x_i^{k*} \le \xi$$
 (A12b)

Under  $\hat{x}_i^k$ , the multipliers of the inactive constraints in (4) are set to 0, and that of active constraints are consistent with  $\alpha_{i,r}^{k^*}$ . The complementary slackness conditions are satisfied.

## ■ End of proof of *Proposition 3*.

## **Proof of Proposition 5:**

According to (3c), (4) and the definition of  $d_P^k$ , we have

$$\boldsymbol{d}_{P}^{k} = \frac{\partial f(\boldsymbol{x}^{k})}{\partial \boldsymbol{x}} + \boldsymbol{A}_{C}^{T} \boldsymbol{\lambda}^{k} + \rho \boldsymbol{A}_{C}^{T} \boldsymbol{B}_{C} (-\boldsymbol{y}^{k-1} + \boldsymbol{y}^{k}) + \boldsymbol{A}_{C}^{T} \boldsymbol{\alpha}^{k} \quad (A13)$$

Combining (5c) and the KKT conditions of (5a)~(5b), then  $P_G - B_C^T \lambda^k + \mathbf{1}^{I+1} \gamma^k = \mathbf{0}$  (A14)

Support the auxiliary variable  $u^k$ , where

$$\boldsymbol{u}^{k} := \boldsymbol{d}_{P}^{k} - \boldsymbol{A}_{C}^{T} \boldsymbol{\lambda}^{k} - \rho \boldsymbol{A}_{C}^{T} \boldsymbol{B}_{C} (-\boldsymbol{y}^{k-1} + \boldsymbol{y}^{k}) - \boldsymbol{A}_{P}^{T} \boldsymbol{\alpha}^{k} = \frac{\partial f(\boldsymbol{x}^{k})}{\partial \boldsymbol{x}}$$
(A15)

Since f(x) is a convex function, we have

$$\langle \boldsymbol{u}^k + \boldsymbol{A}_{C}^{T} \boldsymbol{\lambda}^* + \boldsymbol{A}_{P}^{T} \boldsymbol{\alpha}^*, \boldsymbol{x}^k - \boldsymbol{x}^* \rangle \ge 0$$
 (A16a)

$$\langle \boldsymbol{B}_{C}^{\mathsf{T}} \boldsymbol{\lambda}^{k} - \boldsymbol{1}^{I+1} \boldsymbol{\gamma}^{k} - \boldsymbol{B}_{C}^{\mathsf{T}} \boldsymbol{\lambda}^{*} + \boldsymbol{1}^{I+1} \boldsymbol{\gamma}^{*}, \boldsymbol{y}^{k} - \boldsymbol{y}^{*} \rangle = 0$$
 (A16b)

Bring (5c) and (A15) to (A16), then we obtain

$$0 \leq \left\langle \boldsymbol{d}_{P}^{k}, \boldsymbol{x}^{k} - \boldsymbol{x}^{*} \right\rangle - \left\langle \boldsymbol{\lambda}^{k} - \boldsymbol{\lambda}^{*}, \boldsymbol{A}_{C}(\boldsymbol{x}^{k} - \boldsymbol{x}^{*}) \right\rangle$$

$$- \left\langle \rho \boldsymbol{B}_{C}(-\boldsymbol{y}^{k-1} + \boldsymbol{y}^{k}), \boldsymbol{A}_{C}(\boldsymbol{x}^{k} - \boldsymbol{x}^{*}) \right\rangle$$

$$- \left\langle (\boldsymbol{\lambda}^{k} - \boldsymbol{\lambda}^{*}), -\boldsymbol{B}_{C}(\boldsymbol{y}^{k} - \boldsymbol{y}^{*}) \right\rangle$$

$$+ \left\langle -(\boldsymbol{\alpha}^{k} - \boldsymbol{\alpha}^{*}), \boldsymbol{A}_{P}(\boldsymbol{x}^{k} - \boldsymbol{x}^{*}) \right\rangle$$

$$+ \left\langle -(\boldsymbol{\gamma}^{k} - \boldsymbol{\gamma}^{*}), \boldsymbol{1}^{I+1}(\boldsymbol{y}^{k} - \boldsymbol{y}^{*}) \right\rangle$$

$$+ \left\langle -(\boldsymbol{\gamma}^{k} - \boldsymbol{\gamma}^{*}), \boldsymbol{1}^{I+1}(\boldsymbol{y}^{k} - \boldsymbol{y}^{*}) \right\rangle$$
(A17)

According to **Proposition 3**, we have that

$$\left\langle -(\boldsymbol{\alpha}^k - \boldsymbol{\alpha}^*), A_{\mathrm{P}}(\boldsymbol{x}^k - \boldsymbol{x}^*) \right\rangle \le 0$$
 (A18a)

$$\left\langle -(\boldsymbol{\gamma}^k - \boldsymbol{\gamma}^*), \mathbf{1}^{I+1}(\boldsymbol{y}^k - \boldsymbol{y}^*) \right\rangle = 0$$
 (A18b)

Combining (A17) and (A18), we can get

$$\langle \boldsymbol{d}_{P}^{k}, \boldsymbol{x}^{k} - \boldsymbol{x}^{*} \rangle - \langle \rho \boldsymbol{B}_{C}(-\boldsymbol{y}_{Sh}^{k-1} + \boldsymbol{y}_{Sh}^{k}), \boldsymbol{A}_{C}(\boldsymbol{x}^{k} - \boldsymbol{x}^{*}) \rangle$$

$$- \langle \boldsymbol{\lambda}^{k} - \boldsymbol{\lambda}^{*}, -\boldsymbol{B}_{C}(\boldsymbol{y}^{k} - \boldsymbol{y}^{*}) + \boldsymbol{A}_{C}(\boldsymbol{x}^{k} - \boldsymbol{x}^{*}) \rangle \ge 0$$
(A19)

Bringing (5c) into the third term on (A19), we have

$$\left\langle \boldsymbol{d}_{P}^{k}, \boldsymbol{x}^{k} - \boldsymbol{x}^{*} \right\rangle - \left\langle \boldsymbol{\lambda}^{k} - \boldsymbol{\lambda}^{*}, \frac{1}{\rho} (\boldsymbol{\lambda}^{k} - \boldsymbol{\lambda}^{k-1}) \right\rangle$$

$$\geq \left\langle \rho \boldsymbol{B}_{C}(-\boldsymbol{y}^{k-1} + \boldsymbol{y}^{k}), \boldsymbol{A}_{C}(\boldsymbol{x}^{k} - \boldsymbol{x}^{*}) \right\rangle$$
(A20)

With multiplying both sides of (A20) by  $2\rho$ , (19) is obtained

#### ■ End of proof of *Proposition 5*.

### **Proof of Proposition 6:**

According to the definition of inner product, we have

$$\frac{2}{\rho} \left| \left\langle \boldsymbol{\omega}^{k-1} - \boldsymbol{x}^{k}, \boldsymbol{d}_{P}^{k} \right| \right| \leq \frac{2}{\rho} \left\langle \left| \boldsymbol{\omega}^{k-1} \right| + \left| \boldsymbol{x}^{k} \right|, \left| \boldsymbol{d}_{P}^{k} \right| \right\rangle$$
(A21)

According to (16) and the definition of  $d_P^k$ , there are

$$\left| \frac{\partial L'_{P}(\boldsymbol{x}^{k}, \boldsymbol{\alpha}^{k})}{\partial \boldsymbol{x}} - \frac{\partial L'_{P}(\boldsymbol{x}^{k*}, \boldsymbol{\alpha}^{k*})}{\partial \boldsymbol{x}} \right| = \left| d_{P}^{k} \right| \le \boldsymbol{\xi}'$$
(A22)

Combining (17b)~(17c) and (A22), we can get

$$\frac{2}{\rho} \left\langle \left| \boldsymbol{\omega}^{k-1} \right| + \left| \boldsymbol{x}^{k} \right|, \left| \boldsymbol{d}_{P}^{k} \right| \right\rangle \leq \frac{2}{\rho} \left\langle \left| \boldsymbol{\omega}^{k-1} \right| + \overline{\boldsymbol{x}}_{\max}^{k}, \boldsymbol{\xi}' \right\rangle \tag{A23a}$$

$$\left|\boldsymbol{\omega}^{k-1}\right| \le \overline{\boldsymbol{\omega}}^{k-1} \tag{A23b}$$

Then, we can obtain

$$\left\langle \left| \boldsymbol{\omega}^{k-1} \right| + \left| \boldsymbol{x}^{k} \right|, \left| \boldsymbol{d}_{P}^{k} \right| \right\rangle \leq \left\langle \overline{\boldsymbol{\omega}}^{k-1} + \overline{\boldsymbol{x}}_{\max}^{k}, \boldsymbol{\xi}' \right\rangle$$
 (A24)

According to (17a), (A22) and (A24), the (20) is satisfied.

■ End of proof of *Proposition 6*.

## **Proof of Proposition 7:**

According to (17c) and **Proposition 6**, we can get

$$\|\boldsymbol{\omega}^{k-1} - \boldsymbol{x}^*\|_2^2 - \|\boldsymbol{\omega}^k - \boldsymbol{x}^*\|_2^2$$

$$= -\|\boldsymbol{\omega}^k - \boldsymbol{\omega}^{k-1}\|_2^2 - 2\langle \boldsymbol{\omega}^{k-1} - \boldsymbol{x}^*, \boldsymbol{\omega}^k - \boldsymbol{\omega}^{k-1}\rangle$$

$$= -\rho^2 \|\boldsymbol{d}_{P}^k\|_2^2 + 2\rho\langle \boldsymbol{\omega}^{k-1} - \boldsymbol{x}^k, \boldsymbol{d}_{P}^k \rangle + 2\rho\langle \boldsymbol{x}^k - \boldsymbol{x}^*, \boldsymbol{d}_{P}^k \rangle \quad (A25)$$

$$\geq -\rho^2 \|\boldsymbol{d}_{P}^k\|_2^2 + 2\rho\langle \boldsymbol{x}^k - \boldsymbol{x}^*, \boldsymbol{d}_{P}^k \rangle - 2\rho \|\langle \boldsymbol{\omega}^k - \boldsymbol{x}^*, \boldsymbol{d}_{P}^k \rangle\|$$

$$\geq 2\rho\langle \boldsymbol{x}^k - \boldsymbol{x}^*, \boldsymbol{d}_{P}^k \rangle - \rho^2 \sigma \|\boldsymbol{A}_{C} \boldsymbol{x}^k - \boldsymbol{B}_{C} \boldsymbol{y}^{k-1}\|_2^2$$

Similarly, we have

$$\begin{aligned} & \left\| \boldsymbol{\lambda}^{k-1} - \boldsymbol{\lambda}^* \right\|_2^2 - \left\| \boldsymbol{\lambda}^k - \boldsymbol{\lambda}^* \right\|_2^2 \\ &= \left\| \boldsymbol{\lambda}^{k-1} - \boldsymbol{\lambda}^k \right\|_2^2 + 2 \left\langle \boldsymbol{\lambda}^{k-1} - \boldsymbol{\lambda}^k, \boldsymbol{\lambda}^k - \boldsymbol{\lambda}^* \right\rangle \end{aligned}$$
(A26)

Furthermore, according to **Proposition 5**,  $(A25)\sim(A26)$  and (5c), we have

$$\Phi^{k-1} - \Phi^k$$

$$\geq \rho^{2} \| \mathbf{A}_{C} \mathbf{x}^{k} - \mathbf{B}_{C} \mathbf{y}^{k} \|_{2}^{2} - \rho^{2} \sigma \| \mathbf{A}_{C} \mathbf{x}^{k} - \mathbf{B}_{C} \mathbf{y}^{k-1} \|_{2}^{2}$$

$$-\rho^{2} \| \mathbf{B}_{C} (-\mathbf{y}^{k} + \mathbf{y}^{*}) \|_{2}^{2} + \rho^{2} \| \mathbf{B}_{C} (-\mathbf{y}^{k-1} + \mathbf{y}^{*}) \|_{2}^{2}$$

$$-2\rho^{2} \langle \mathbf{B}_{C} (-\mathbf{y}^{k} + \mathbf{y}^{k-1}), \mathbf{A}_{C} (\mathbf{x}^{k} - \mathbf{x}^{*}) \rangle$$
(A27)

Due to  $A_C x^* - B_C y^* = 0$  and Cauchy-Schwarz Inequality, the fifth term on the right-hand side of (A27) can be written as  $2\rho^2 \langle B_C (-y^k + y^{k-1}), A_C (x^k - x^*) \rangle$ 

$$= \rho^{2} \left( \left\| \boldsymbol{B}_{C} (-\boldsymbol{y}_{=}^{k-1} + \boldsymbol{y}_{=}^{k}) \right\|_{2}^{2} + \left\| \boldsymbol{A}_{C} \boldsymbol{x}^{k} - \boldsymbol{B}_{C} \boldsymbol{y}^{k} \right\|_{2}^{2} - \left\| \boldsymbol{A}_{C} \boldsymbol{x}^{k} - \boldsymbol{B}_{C} \boldsymbol{y}^{k-1} \right\|_{2}^{2} \right)$$

$$- \rho^{2} \left( \left\| \boldsymbol{B}_{C} (-\boldsymbol{y}^{k-1} + \boldsymbol{y}^{k}) \right\|_{2}^{2} + \left\| \boldsymbol{B}_{C} (-\boldsymbol{y}^{k} + \boldsymbol{y}^{*}) \right\|_{2}^{2} - \left\| \boldsymbol{B}_{C} (-\boldsymbol{y}^{k-1} + \boldsymbol{y}^{*}) \right\|_{2}^{2} \right)$$

$$(A28)$$

Bring (A28) to (A27), we obtain

$$\Phi^{k-1} - \Phi^k \ge \rho^2 (1 - \sigma) \| \boldsymbol{A}_{C} \boldsymbol{x}^k - \boldsymbol{B}_{C} \boldsymbol{y}^{k-1} \|_{2}^{2}$$
(A29)

Obviously, is a non-increasing and positive sequence. Then,

$$\{y^k\}, \{\lambda^k\}, \text{ and } \{\omega^k\} \text{ are bounded sequences. And we can get}$$

$$\lim_{k \to \infty} \mathbf{A}_{\mathbf{C}} \mathbf{x}^k - \mathbf{B}_{\mathbf{C}} \mathbf{y}^{k-1} = \mathbf{0}$$
(A30)

Besides, based on *Proposition 3*,  $\{x^k\}$  is bounded sequence. Since  $\{x^k\}$ ,  $\{y^k\}$ ,  $\{\lambda^k\}$  is bounded,  $\{\alpha^k\}$  and  $\{\gamma^k\}$  are bounded, according to KKT conditions of (4) and (5).

■ End of proof of *Proposition 7*.

### **Proof of Proposition 8:**

With Bolzano-Weierstrass Theorem, there are K satisfying

$$\lim_{k \to \infty, k \in \mathcal{K}} \lambda^{k} = \overline{\lambda}, \lim_{k \to \infty, k \in \mathcal{K}} \alpha^{k} = \overline{\alpha}, \lim_{k \to \infty, k \in \mathcal{K}} \gamma^{k} = \overline{\gamma}$$
(A31)

According to **Proposition 6**, (A30) and the definition of  $\omega^k$ , we have

$$\left\langle \boldsymbol{\omega}^{k-1} - \boldsymbol{x}^{k}, \boldsymbol{d}_{P}^{k} \right\rangle = \left\| \boldsymbol{d}_{P}^{k} \right\|^{2} = 0 \tag{A32}$$

Since  $\{\omega^k\}$  and  $\{x^k\}$  are bounded, we obtain

$$\langle \boldsymbol{x}^{k}, \boldsymbol{d}_{P}^{k} \rangle = \langle \boldsymbol{\omega}^{k}, \boldsymbol{d}_{P}^{k} \rangle = \langle \boldsymbol{A}_{C} \boldsymbol{x}^{k} - \boldsymbol{B}_{C} \boldsymbol{y}^{k-1}, \boldsymbol{A} \boldsymbol{x}^{k} \rangle = 0$$
 (A33)

Support the Fenchel conjugate function of f is f\*. According to Legendre Transform Definition, there are

$$\mathbf{u}^{k} = \partial f(\mathbf{x}^{k}) \Leftrightarrow \mathbf{x}^{k} = \partial f^{*}(\mathbf{u}^{k})$$
(A34)

Due to convexity, we have

$$f^{*}(-\boldsymbol{A}_{C}^{T}\boldsymbol{\lambda}^{*} - \boldsymbol{A}_{P}^{T}\boldsymbol{\alpha}^{*})$$

$$\geq f^{*}(\boldsymbol{u}^{k}) + \left\langle \partial f^{*}(\boldsymbol{u}^{k}), -\boldsymbol{A}_{C}^{T}\boldsymbol{\lambda}^{*} - \boldsymbol{A}_{P}^{T}\boldsymbol{\alpha}^{*} - \boldsymbol{u}^{k} \right\rangle$$
(A35)

Bring (A15) into (A35), we can get

$$f^{*}(-A_{C}^{T}\boldsymbol{\lambda}^{*} - A_{P}^{T}\boldsymbol{\alpha}^{*})$$

$$\geq f^{*}(\boldsymbol{u}^{k}) + \langle \boldsymbol{x}^{k}, A_{C}^{T}(\boldsymbol{\lambda}^{k-1} - \boldsymbol{\lambda}^{*}) \rangle$$

$$+ \langle A_{C}\boldsymbol{x}^{k}, \rho(A_{C}\boldsymbol{x}^{k} - \boldsymbol{B}_{C}\boldsymbol{y}^{k-1}) \rangle$$

$$- \langle \boldsymbol{x}^{k}, \boldsymbol{d}_{P}^{k} \rangle + \langle \boldsymbol{x}^{k}, A_{P}^{T}(\boldsymbol{\alpha}^{k} - \boldsymbol{\alpha}^{*}) \rangle$$
(A36)

According to (A15) and (A30)~(A33), we have

$$\lim_{k \to \infty, k \in \mathcal{K}} \mathbf{u}^{k} = -\mathbf{A}_{c}^{T} \overline{\lambda} - \mathbf{A}_{p}^{T} \overline{\alpha}$$
(A37)

Besides,  $\gamma^k$  and  $\gamma^*$  satisfy the KKT conditions of problem (1) and (5a)~(5b). Hence, there are

$$\mathbf{1}^{1\times(I+1)} \mathbf{v}^{k} = \mathbf{1}^{1\times(I+1)} \mathbf{v}^{*} = \mathbf{0}$$
 (A38a)

$$P_{G} - B_{C}^{T} \lambda^{k} + 1^{I+1} \gamma^{k} = 0, P_{G} - B_{C}^{T} \lambda^{*} + 1^{I+1} \gamma^{*} = 0$$
 (A38b)

Based on (A31)~(A33) and (A38b), the (A36) can be written as following when  $k \to \infty, k \in \mathcal{K}$ .

$$f^{*}(-A_{C}^{T}\boldsymbol{\lambda}^{*} - A_{P}^{T}\boldsymbol{\alpha}^{*})$$

$$\geq f^{*}(-A_{C}^{T}\overline{\boldsymbol{\lambda}} - A_{P}^{T}\overline{\boldsymbol{\alpha}}) + \langle A_{C}\boldsymbol{x}^{k}, \overline{\boldsymbol{\lambda}}^{-}\boldsymbol{\lambda}^{*} \rangle$$

$$+ \langle A_{P}\boldsymbol{x}^{k}, \boldsymbol{\alpha}^{k} - \boldsymbol{\alpha}^{*} \rangle - \langle \boldsymbol{B}_{C}\boldsymbol{y}^{k-1}, \overline{\boldsymbol{\lambda}}^{-}\boldsymbol{\lambda}^{*} \rangle$$

$$+ \langle \boldsymbol{y}^{k-1}, \boldsymbol{1}^{l+1}(\boldsymbol{\gamma}^{k-1} - \boldsymbol{\gamma}^{*}) \rangle$$
(A39)

Bringing (A30), (A38b) and (15a) into (A39) yields

$$f^{*}(-\boldsymbol{A}_{C}^{T}\boldsymbol{\lambda}^{*} - \boldsymbol{A}_{P}^{T}\boldsymbol{\alpha}^{*})$$

$$\geq f^{*}(-\boldsymbol{A}_{C}^{T}\overline{\boldsymbol{\lambda}} - \boldsymbol{A}_{P}^{T}\overline{\boldsymbol{\alpha}}) - \langle \boldsymbol{b}_{P}, \overline{\boldsymbol{\alpha}} \rangle$$

$$-\langle \boldsymbol{A}_{P}\boldsymbol{x}^{k} + \boldsymbol{b}_{P}, \boldsymbol{\alpha}^{*} \rangle + \langle \boldsymbol{b}_{P}, \boldsymbol{\alpha}^{*} \rangle$$

$$\geq f^{*}(-\boldsymbol{A}_{C}^{T}\overline{\boldsymbol{\lambda}} - \boldsymbol{A}_{P}^{T}\overline{\boldsymbol{\alpha}}) - \langle \boldsymbol{b}_{P}, \overline{\boldsymbol{\alpha}} \rangle + \langle \boldsymbol{b}_{P}, \boldsymbol{\alpha}^{*} \rangle$$
(A40)

That is

$$f^{*}(-\boldsymbol{A}_{\mathrm{C}}^{\mathrm{T}}\boldsymbol{\lambda}^{*}-\boldsymbol{A}_{\mathrm{P}}^{\mathrm{T}}\boldsymbol{\alpha}^{*})-\left\langle\boldsymbol{b}_{\mathrm{P}},\boldsymbol{\alpha}^{*}\right\rangle \geq f^{*}(-\boldsymbol{A}_{\mathrm{C}}^{\mathrm{T}}\overline{\boldsymbol{\lambda}}-\boldsymbol{A}_{\mathrm{P}}^{\mathrm{T}}\overline{\boldsymbol{\alpha}})-\left\langle\boldsymbol{b}_{\mathrm{P}},\overline{\boldsymbol{\alpha}}\right\rangle$$
(A41)

Moreover, solving the primary problem (1) is equivalent to solving its dual problem:

$$\min_{\boldsymbol{\lambda}, \boldsymbol{\alpha}, \boldsymbol{\gamma}} f^* (-\boldsymbol{A}_{\mathrm{C}}^{\mathrm{T}} \boldsymbol{\lambda} - \boldsymbol{A}_{\mathrm{P}}^{\mathrm{T}} \boldsymbol{\alpha}) - \boldsymbol{P}_{\mathrm{G}} - \langle \boldsymbol{b}_{\mathrm{P}}, \boldsymbol{\alpha} \rangle - \langle \boldsymbol{0}, \boldsymbol{\lambda} \rangle - \langle \boldsymbol{0}, \boldsymbol{\gamma} \rangle \quad (A42)$$

Since (1) is a convex programming,  $\bar{\lambda}$ ,  $\bar{\alpha}$ ,  $\bar{\gamma}$  is the global optimal solution  $\lambda^*$ ,  $\alpha^*$ ,  $\gamma^*$ . Similarly, there are  $\mathcal{K}' \subseteq \mathcal{K}$  satisfying

$$\lim_{k \to \infty, k \in \mathcal{K}'} \mathbf{x}^k = \overline{\mathbf{x}}, \lim_{k \to \infty, k \in \mathcal{K}'} \mathbf{y}^k = \overline{\mathbf{y}}$$
(A43)

According to (A15) and (A31)~(A33), we have

$$\lim_{k \to \infty, k \in \mathcal{K}'} \boldsymbol{u}^{k} = \overline{\boldsymbol{u}} = -\boldsymbol{A}_{C}^{T} \overline{\boldsymbol{\lambda}} - \boldsymbol{A}_{P}^{T} \overline{\boldsymbol{\alpha}} = \frac{\partial f(\boldsymbol{x})}{\partial \boldsymbol{x}}$$
(A43)

According to  $\overline{\lambda} = \lambda^*$ ,  $\overline{\alpha} = \alpha^*$ ,  $\overline{\gamma} = \gamma^*$ , (15), (A30), (A38) and (A43), the KKT conditions of (1) are satisfied by  $\{\overline{\lambda}, \overline{\alpha}, \overline{\gamma}, \overline{x}, \overline{y}\}$ . Therefore, it is the optimal solution.

Based on (A32),  $\{\omega^k\}$  is a global convergence sequence that converges to  $\omega^{\infty}$ . Similarly, there is  $\mathcal{K}'' \subseteq \mathcal{K}'$  satisfying

$$\lim_{k \to \infty} \boldsymbol{\omega}^k = \boldsymbol{\omega}^{\infty} \tag{A44a}$$

$$\lim_{k \to \infty, k \in \mathcal{K}''} \left\| -y^k + y^* \right\|_2^2 = \liminf_{k \to \infty} \left\| -y^k + y^* \right\|_2^2$$
 (A44b)

Introduce an auxiliary variable which satisfies

$$\phi^{k} = \|\boldsymbol{\omega}^{k} - x^{*}\|_{2}^{2} + \rho^{2} \|-\mathbf{y}^{k} + \mathbf{y}^{*}\|_{2}^{2}$$
(A45)

According to (A44), we have

$$\lim_{k \to \infty, k \in \mathcal{K}''} \phi^k = \liminf_{k \to \infty} \phi^k = \left\| \boldsymbol{\omega}^{\infty} - \boldsymbol{x}^* \right\|^2 + \rho^2 \liminf_{k \to \infty} \left\| -\boldsymbol{y}^k + \boldsymbol{y}^* \right\|^2$$
(A46)

From (A21a),  $\Phi^k$  is global convergence. Then, we can get  $\limsup_{k \to \infty} \Phi^k = \lim_{k \to \infty} \Phi^k = \lim_{k \to \infty} \Phi^k$  (A47)

According to  $\mathcal{K}'' \subseteq \mathcal{K}'$ , (21b), (A31), and  $\overline{\lambda} = \lambda^*$ , we have

$$\lim_{k \to \infty, k \in \mathcal{K}^{"}} \Phi^{k} = \lim_{k \to \infty, k \in \mathcal{K}^{"}} \phi^{k} = \liminf_{k \to \infty} \phi^{k}$$
(A48)

Combining (21b) and (A45), we obtain

$$\limsup_{k \to \infty} \| \boldsymbol{\lambda}^{k} - \boldsymbol{\lambda}^{*} \|^{2} = \limsup_{k \to \infty} (\boldsymbol{\Phi}^{k} - \boldsymbol{\phi}^{k})$$

$$\geq \limsup_{k \to \infty} \boldsymbol{\Phi}^{k} - \liminf_{k \to \infty} \boldsymbol{\phi}^{k} = 0$$
(A49)

That is  $\lim_{k\to\infty} \lambda^k = \lambda^*$ . Since  $\Phi^k$ ,  $\lambda^k$ ,  $\omega^k$  is global convergence,  $y^k$  is also global convergence. So

$$\lim_{k \to \infty} \mathbf{y}^k = \mathbf{y}^* \tag{A50}$$

■ End of proof of *Proposition 8*.