On the Provenance of Linked Data Statistics

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Abstract

As the amount of linked data published on the web grows, attempts are being made to describe and measure it. However even basic statistics about a graph, such as its size, are difficult to express in a uniform and predictable way. In order to be able to sensibly interpret a statistic it is necessary to know how it was calculate. In this paper we survey the nature of the problem and outline a strategy for addressing it.

1 Background and Motivation

For the past several years datasets of Linked Open Data on the web have been catalogued and made into a diagram [6] to illustrate their proliferation and interconnectedness. More recently some statistics about these datasets have been calculated [3]. Amongst the published statistics are, for example the number of triples in various graphs or unions of graphs across a particular domain of interest. Some more sophisticated statistics are also given in absolute terms, e.g. the absolute number of links outgoing from a particular dataset.

In conjunction with this work, a vocabulary [1] has been developed for describing RDF datasets. This vocabulary contains predicates for describing common statistics, for example the number of triples or number of distinct subjects, as well as some more generic facilities for annotating a dataset description with other types of statistical information.

Inasmuch as these statistics help to understand some of the properties of these data at a coarse grained level and get a rough idea of their dimensions they are quite useful and indeed valuable contributions. However as always we must ask what they mean. As, for example, void:triples denotes the size of the dataset, intuitively we might think that this gives some idea of the amount of information contained in it. But, most datasets carry a greater or lesser amount of redundant information. It might be included to make querying easier or to make extracts more easily readable by a human. In some sense it could be argued that when counting triples that this redundant information

should be left out. It is also easily demonstrated that an unlimited amount of redundant triples can easily be added to any dataset without really changing the information content. Clearly the meaning of void:triples is somewhat of a moving target.

The problem is exacerbated when more sophisticated statistics are calculated. In the example of the outgoing links from one dataset to another, one might want to normalise their count by dividing by the size of the dataset – to arrive at a measure that might be called "out-link density". Perhaps such a measure would tell us something about the character of the dataset itself, independent of its size. But because this measure is built on the basic notion of the size of the dataset we need to do some work before arriving at a meaningful value for it.

Notation Conventions: Throughout the following, where RDF data is explicitly represented, the Notation 3 [2] syntax is used and declarations for common namespaces such as *rdf*, *rdfs*, *owl*, *foaf*, *dct* are ommitted. In addition RDF terms and statements are represented in a fixed-with font.

2 Redundancy in Graphs

A well known trivial example of adding redundancy to graphs uses blank nodes. Blank nodes are to be read as existential variables [7].

Example 1. Production Rules

If we start with a graph containing one statement,

bob a foaf:Person.

we can then add a statement with a blank node,

_:b1 a foaf:Person.

which simply says "there exists someone that is a foaf:Person". This information was already contained in the original graph and really adds nothing new. And we can add as many more blank nodes, _:b2, _:b3, ..., _:bn. What does this do to a count of the size of the graph?

Such a production rule that generated these redundant triples would called *unsafe* [4] but it is quite possible to add a finite amount redundant information with safe rules as well. The question of how much redundant information has been added remains.

Example 2. Graph Reduction

As more realistic example, elaborated with the opposite strategy of removing redundancy, consider the following graph, and description logic fragment:

```
egin{array}{lll} s_1 & {
m bob\ a\ foaf:Person.} \\ s_2 & {
m bob\ foaf:knows\ alice.} \\ s_3 & {
m alice\ a\ foaf:Person.} \\ s_4 & {
m alice\ foaf:knows\ bob.} \\ \hline s_5 & {
m foaf:knows\ rdfs:domain\ foaf:Person.} \\ s_6 & {
m foaf:knows\ rdfs:range\ foaf:Person.} \\ \hline \end{array}
```

If this is accompanied by the RDF semantic rules [7] (Section 4) concerning domains and ranges, namely,

$$\begin{array}{lll} r_1 & \{ \text{?s ?p ?o. ?p rdfs:domain ?A} \} \\ & => \{ \text{?s a ?A } \}. \\ r_2 & \{ \text{?s ?p ?o. ?p rdfs:range ?B} \} \\ & => \{ \text{?o a ?B } \}. \end{array}$$

we can immediately see that, under the given rules, statements s_1 and s_3 are redundant as they can be derived from the statements involving the predicate foaf:knows and knowledge about its domain and range.

We need to make some distinction here between the graph under consideration, $s_1, ..., s_4$ and the extra information we have drawn upon, s_5, s_6 . In general the latter will come from a source external to the former, being referenced as a vocabulary. It can also easily be seen that the description logic fragment could just as well be expressed as a rule itself,

```
r_3 {?a foaf:knows ?b} => {?a a foaf:Person. ?b a foaf:Person.}
```

We can further see that if we have r_3 , we don't need r_1 or r_2 . So far we have shown that for,

$$G = \{s_1, ..., s_4\} \cup \{s_5, s_6\}$$

$$\mathcal{R} = \{r_1, r_2\}$$

$$G' = \{s_2, s_4\}$$

$$\mathcal{R}' = \{r_3\}$$

the G and G' under \mathcal{R} and \mathcal{R}' respectively are in some sense equivalent, though it remains to state explicitly what is meant by that. By inspection we can see that G' is half the size of G, in terms of number of statements, so we might say that 50% of G was redundant. It is not immediately clear if \mathcal{R} and \mathcal{R}' are the same or different sizes.

3 Rules and Redundancy

The examples above rely on rules or what are often called entailment regimes. Some common ones are defined in a placeholder vocabulary by the W3C [8]. Rules may be applied in the usual way, as in the first example, to produce statements and this is known as calculating the closure of the graph.

Definition 1. The closure of a graph, G with respect to a set of rules, \mathcal{R} is the set of all statements produced by applying \mathcal{R} to G until exhaustion, in other words adding all statements that it is possible to infer given the data and the rules. We will denote this operation as $G^{\mathcal{R}+}$.

Calculating $G^{\mathcal{R}^+}$ is computationally expensive but tractable with safe rules. Note that the closure with respect to an empty ruleset is just the graph itself, or $G = G^{\emptyset^+}$.

Definition 2. The cardinality of a graph, G is simply the number of triples it contains and is denoted |G|.

This is enough to provide a stable notion of the size of the graph by adding in a predictable proportion of redundancy by specifying the entailment regime. Comparing the cardinality of two graphs side-by side can thus be done in a meaningful way.

4 The Minimisation Problem

What might be better than considering graphs which have had redundancy added, however predictable it might be, is to consider graphs with all possible redundancy eliminated. This question was first considered in [10] where Meier proposed applying rules negatively.

Algorithm 1. Meier's Algorithm¹

The problem was further considered by Polleres et al. in [11] and given the name MINI-RDF. The formulation builds on Meier's work and asks how difficult it is to find an irreducible graph given a set of rules and a set of constraints². Constraints are simply rules that specify that a certain amount of redundancy must be left in the graph when a reduction has been completed. It turns out that the problem is not tractable in general.

¹Meier didn't explicitly state the use of backwards chaining but simply said to check if a given triple was possible to infer from the remaining triples under the given rules. The formulation given here comes from an actual implementation by the author of the present paper [13].

²They also considered the problem of rule reduction in addition to graph reduction, the general case of the simplifications to the rules given in the second example above.

Whilst Meier's algorithm can be completed in polynomial time, it will only find an irreducible graph that entails the same closure of the original. It was proven in [11] that finding the *smallest* irreducible graph is in general also intractable.

Definition 3. A minimisation of a graph, G with respect to a set of rules, \mathcal{R} is the smallest possible graph that has the same closure with respect to \mathcal{R} as G and is written, $G^{\mathcal{R}-}$. $G^{\mathcal{R}-}$ is a solution to MINI-RDF $(G, \mathcal{R}, \emptyset)$.

Example 3.

It can be easily seen that G^{R-} is not, in general, unique. For example, consider the following graph, $G = \{s_1, s_2\}$ and rule, $\mathcal{R} = \{r_1\}$,

either of s_1 or s_2 could be deleted from G to obtain $G^{\mathcal{R}-}$.

Since finding $G^{\mathcal{R}}$ is in general intractable, a potentially fruitful avenue of future research is to consider the circumstances under which it can be solved in polynomial time. Obviously the trivial case, $G^{\emptyset-}$ is solvable. For some kinds of rules, such as those in the second example above, the minimisation will be unique. For a broader set of rules, such as those with loops as in the third example above, $|G^{\mathcal{R}-}|$ will be unique. This last, the set of cardinality-preserving rules for which calculating the minimisation of a graph is tractable, is the broadest set of interest for the present purposes – rules in this class are practical to apply to remove as much redundancy as possible from the graph.

5 Redundancy Revisited

We are now in a position to make some formal definitions of what we mean by redundancy in graphs.

Definition 4. The redundancy contained in a graph, G with respect to a set of rules, \mathcal{R} is given by $1 - |G^{\mathcal{R}-}|/|G|$.

The foregoing considerations give rise to four fundamental statistics about a graph, given a set of rules,

- The cardinality of the graph as published.
- The cardinality of the closure of the graph under a given set of rules.
- The cardinality of a minimal graph under a given set of rules.
- The redundancy of the graph under a given set of rules.

From these it is possible to build up more elaborate statistics in a predictable way. To take the "out-link density" example from the introduction, this might be expressed as,

$$D_{out}^+(G) = \frac{|G_{out}^{\mathcal{R}+}|}{|G^{\mathcal{R}+}|}$$

or alternatively,

$$D_{out}^{-}(G) = \frac{|G_{out}^{\mathcal{R}-}|}{|G^{\mathcal{R}-}|}$$

Where the numerator has been constructed by selecting triples whose objects are resources in a different graph from the minimised graph. If the rules are as strong as possible, such a statistic might tell us something charactistic of the graph, if it is closer to 0 the graph contains mostly internal information as might be the case with large datasets such as DBpedia or OpenCyc. A void:Linkset on the other hand might have a characteristic out-link density closer to 1 as most of its statements express the relationships between other datasets.

6 Vocabulary Considerations

The fact that the three of the fundamental statistics depend on the rules used means that in order to express them unambiguously we need also to mention the rules or entailment regimes. This is not a large burden but does mean that we need a vocabulary for it. Such a vocabulary would need to have predicates for including both Horn rules and description logics. As support for the Rule Interchange Format [5] becomes more common it will be necessary to include rules expressed in this language as well.

The placeholder vocabulary for entailment regimes [8] is a good starting point. The URIs defined there are useful as recognisable unique identifiers but as yet have no formal descriptions beyond pointers to the human readable documentation – there is no automated way to discover which rules each regime implies.

The [9] vocabulary could be adapted for this but it relies heavily on modelling SPARQL CONSTRUCT queries. While it has been shown [12] that there is a mapping from these types of queries to FOPL, most rulesets aren't written this way and it doesn't make so much sense to map rules from their native representation to this vocabulary simply in order to indicate their use.

We therefore propose a lightweight vocabulary [14] for Graph Normalisation, gn, as exemplified below³,

Example 4. Graph Normalisation Vocabulary

³Recent work on the voiD vocabulary tends to deprecate the void:statItem predicate and the use of the SCOVO vocabulary for expressing statistics. In our view this mechanism should be retained or replaced with something similar to support the expression of statistical provenance.

```
eg:dataset a void:Dataset ;
  void:statItem [
    scovo:dimension eg:redundancy ;
    rdf:value 0.3 ;
    gn:normalisation [
        a gn:MiniRDF ;
        gn:rules [
            a gn:RuleSet ;
            gn:n3 <.../rdfs-rules.n3> ;
        gn:dlogic owl:, foaf: ;
        gn:rif <.../rif-rules.rif>
    ]
    ]
]
```

Additionally, gn:constraints is defined for completeness to support specification of the *MINI-RDF* problem though in practice this would probably never be used.

In this way, to check or recreate this statistic one might procede from such a description as follows,

Example 5. Redundancy Calculation

- 1. Fetch the dataset in question, G.
- 2. Fetch Horn (N3, RIF) rules.
- 3. Fetch description logics, making sure to follow $\mathtt{owl:imports}$, collectively D.
- 4. Transform the description logics into their equivalent Horn rules.
- 5. Construct \mathcal{R} as the set all the rules fetched.
- 6. Run Meier's algorithm using $G \cup D$ as the graph for the backchaining step.
- 7. Compute $1 |G^{R-}|/|G|$.

This example of course assumes that the all rules used are tractable for $G^{\mathcal{R}-}$ and cardinality preserving.

It should be noted that the current practice with respect to void:triples is simply the above with an empty ruleset. In this way some amount of backwards compatibility with current practice is maintained.

7 Optimising with Graph Diffs

If finding a $G^{\mathcal{R}-}$ is tractable, it is still a computationally expensive operation. If provenance information is kept for datasets such that given the previous version

and the provenance metadata it is possible to reconstruct the current version there is a significant optimisation to be had, especially for large datasets that experience incremental change.

Starting with a minimisation of the previous version, $G_i^{\mathcal{R}^-}$, and a pair of graphs I and D representing triples to be inserted or deleted⁴ such that $G_{i+1} = G_i - D + I$, we can construct $G_{i+1}^{\mathcal{R}^-}$ by first calculating, $G_i^{\mathcal{R}^-} - D$ since if they aren't in G_{i+1} they won't be in its minimisation. This intermediate graph is a possibly non-minimal subgraph of G_{i+1} . Because the order of the triples in minimise() doesn't matter we can now run it only testing the triples in I.

8 Conclusion

We have reviewed the truism that in order to be able to sensibly interpret statistics one must know how they are calculated. Looking at how this applies to descriptions of RDF graphs we have seen that apparently simple statistics can be calculated in a number of ways. Thus the importance of provenance of the statistics has been highlighted. A proposal for how this provenance information might be expressed was put forward and some interesting areas for further theoretical research were noted.

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 $^{^4}$ Assuming blank nodes are handled via some sort of skolemisation mechanism.

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