```
@ crt0.s
                                                                        (a
                                                                        @
(a
@ Initialization file for EE52 ARM VoIP phone project. It sets up the IRQ
                                                                        @
@ vector table, initializes the stacks for both the IRQ and System modes,
@ sets up the Master Clock, all of the chip selects for external memories,
@ and will eventually call all of the intialization functions for each
                                                                        @
@ hardware block. Finally it invokes the main user interface code.
                                                                        @
                                                                        @
                                                                        @
@
 Revision History:
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@
@
   2008/02/02 Joseph Schmitz Modified code from Arthur Chang to make it
                                                                        @
@
                                                                        @
                              available to the students.
@
   2011/01/27 Joseph Schmitz Split into crt0.s and boot.s.
                                                                        @
                                                                        @
@
   2011/01/31 Joseph Schmitz Removed unused comments.
@
   2012/01/24 Glen George
                              Updated comments, modified included files,
                                                                        @
@
                              and cleaned up the code a little.
                                                                        @
@
   2012/01/29 Glen George
                              Added comments explaining initialization.
                                                                        @
(a
                                                                        (a
"at91rm9200.inc"
.include
.include
           "system.inc"
           "macro.inc"
.include
.include
           "interfac.inc"
.text
.arm
@ In this file you must do at least the following:
   - As you write other functions/code for the various hardware blocks, you
@
     will call the initialization functions for them from here as well.
@ low level_init
@ Description: Initializes the ARM processor modes, calls the
              initialization functions for the different parts
@
              of the code, and then calls the main loop.
@ Operational Description: Initializes arm processor modes,
@
                         then goes through and calls a sequence
@
                         of initialization functions for various
@
                         files. Finally, the main loop is called
@
                         (or for the audio demo, audio demo is called)
@ Arguments: None
@
 Return values: never returns
@
 Local variables: None
@
 Shared variables: None
@ Global Variables: None
@
 Inputs: None
@ Outputs: None
@ Error Handling: None
```

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@ Algorithms: None
@ Data Structures: None
@ Limitations: None
@ Registers Changed (besides ARM convention r0-r3): None
@ Known Bugs: None
 Special notes: None
@ Revision History:
@ Name
                                       Date
                  Comment.
@ Will Werst
                   Initial version
                                       Some lonely night around 6/10/17
.global low level init
low level init:
   @Uncomment instruction below to prevent ROM code from executing after
   @bootloader runs. This effectively creates a dummy ROM code that does nothing.
   @B low level init
@ Stack and IRQ Initialization
          r0, =TOP STACK
                                           @load address for top of the stack
   LDR
   @ put the CPU in interrupt mode and set the stack pointer for this mode
           cpsr c, #ARM MODE IRQ | I BIT | F BIT
   MOV
           sp, r0
   @ adjust the starting stack address for the interrupt stack just setup
           r0, r0, #IRQ STACK SIZE
   @ put the CPU in supervisor mode and set the stack pointer for this mode
           cpsr c, #ARM_MODE_SVC | I_BIT | F_BIT
   MSR
   MOV
           sp, r0
   @ adjust the starting stack address for the supervisor mode stack just setup
           r0, r0, #SVC_STACK_SIZE
   @ finally, put the CPU in user mode and set the stack pointer for this mode
   MSR
           cpsr c, #ARM MODE USR | F BIT
   MOV
           sp, r0
@ user initialization goes here
BL init system
                                           @ Initialize the system
   BL keypad init
                                           @ Initialize the keypad
                                           @ Initialize the audio
   BL audio init
                                           @ Initialize the display
   BL display init
loop:
   @BL
            audioDemo
                                    @ Uncomment this line to run the audioDemo
   _{\mathrm{BL}}
           main
                                    @ run the main function (no arguments)
   В
           low level init
                                    @ if main returns (shouldn't)
                                    @ reinitialize everything and start
                                    @ over
.end
```