

### Exact Solution:

Given,

$$u_t = u_{xx} + u_{yy} + u$$

Making the substitution  $u = we^t$  gives,

$$w_t = w_{xx} + w_{yy}$$

In spherical coordinates we have

$$w_t = \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^3 w}{\partial r^3} + \frac{1}{r^2} \frac{\partial^3 w}{\partial \theta^3}$$

The exact solution is beyond the scope of this assignment. However, we still need to develop a spatial boundary condition ( $w(t = 0)$ ) which satisfies the above equation. Given an initial velocity  $w_t = v_0$  and proposing a radially symmetric solution  $w(x, y) = R(r)$  gives,

$$v_0 = \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^3 w}{\partial r^3} = \frac{1}{r} \frac{\partial w}{\partial r} \left( r \frac{\partial w}{\partial r} \right)$$

$$rv_0 = \frac{\partial w}{\partial r} \left( r \frac{\partial w}{\partial r} \right)$$

$$\frac{1}{2} r^2 v_0 + c_1 = r \frac{\partial w}{\partial r}$$

$$\frac{1}{r} r^2 v_0 + c_1 \ln(r) + c_2 = w$$

The natural log blows up at the origin which is included in this problem, so we require  $c_1 = 0$ . And we require that  $w(R) = 0$  so this give the value of  $c_2$  such that we are left with,

$$w(r) = \frac{1}{r} (r^2 - R^2) \quad \rightarrow \quad \text{Initial condition} \quad [1]$$

### Computational Solution (Douglas-Rachford ADI):

Calling the differential operators  $\nabla_{xx} = A$  and  $\nabla_{yy} = B$  then using the backward Euler method gives,

$$\frac{U^{n+1} - U^n}{k} = (A + B)U^{n+1} + U^{n+1} \quad [2]$$

Or in terms of spherical coordinates

$$w_t = \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^3 w}{\partial r^3} + \frac{1}{r^2} \frac{\partial^3 w}{\partial \theta^3}$$

$$\begin{aligned}\frac{U^{n+1} - U^n}{k} &= \left( \frac{1}{r_i} \frac{U_{i+1,j} - U_{i,j}}{h_R} + \frac{U_{i-1,j} - 2U_{i,j} + U_{i+1,j}}{h_R} \right) + \frac{1}{r_i^2} \left( \frac{U_{i,j-1} - 2U_{i,j} + U_{i,j+1}}{h_R} \right) + U_{i,j} \\ &= \left( \frac{U_{i-1,j} - \left(2 + \frac{h_R}{r_i}\right)U_{i,j} + \left(1 + \frac{h_R}{r_i}\right)U_{i+1,j}}{h_R} \right) + \left( \frac{U_{i,j-1} - 2U_{i,j} + U_{i,j+1}}{r_i^2 h_R} \right) + U_{i,j}\end{aligned}$$

Factoring out  $1/r_i^2$  so as to avoid singularities,

$$\begin{aligned}\frac{U^{n+1} - U^n}{k} &= \frac{1}{r_i^2} \left\{ \left( \frac{U_{i-1,j}r_i^2 - (2r_i^2 + r_i h_R)U_{i,j} + (r_i^2 - r_i h_R)U_{i+1,j}}{h_R} \right) + \left( \frac{U_{i,j-1} - 2U_{i,j} + U_{i,j+1}}{h_R} \right) \right\} + U_{i,j} \\ &= \frac{1}{r_i^2} \{ \mathbf{R}U^{n+1} + \mathbf{T}U^{n+1} \} + U^{n+1} \\ &= \frac{1}{r_i^2} \{ (\mathbf{R} + \mathbf{T})U^{n+1} \} + U^{n+1} \quad [2]\end{aligned}$$

Where  $\mathbf{T}$  stands for ‘theta’. The proposed Douglas Rachford ADI scheme is just like last time, only now the definition of the matrices have changed,

$$\left( 1 - \frac{k}{r_i^2} \mathbf{R} \right) U^{n*} = \left( 1 + \frac{k}{r_i^2} \mathbf{T} \right) U^n$$

$$\left( 1 - \frac{k}{r_i^2} \mathbf{T} \right) U^{n+1} = U^{n*} - \frac{k}{r_i^2} \mathbf{T} U^{n*}$$

$$(r_i^2 - k\mathbf{R})U^{n*} = (r_i^2 + k\mathbf{T})U^n$$

$$(r_i^2 - k\mathbf{T})U^{n+1} = r_i^2 U^{n*} - k\mathbf{T}U^{n*} \quad [2]$$

## Some Notes About the Code:

The methodology adapted for this problem was to solve the problem in polar coordinates. Two primary difficulties were encountered

- 1) The factors of  $1/r_i$ ,  $1/r_i^2$  in the definitions of  $\mathbf{R}$ ,  $\mathbf{T}$  cause the algorithm to blow up. This was temporarily addressed by adjusting the vector  $\vec{r}$  such that  $\vec{r}[0] = \frac{h_R}{3} \approx 0.1$
- 2) Drawing the grid in the figure below, ‘ghost points’ arise on the left column and bottom row. These points (depicted in red in the figure) represent negative  $r$ ,  $\theta$  values. To deal with them, in lines 126-131 of the code the following identifications are made;

$$i_g = j_A/M$$

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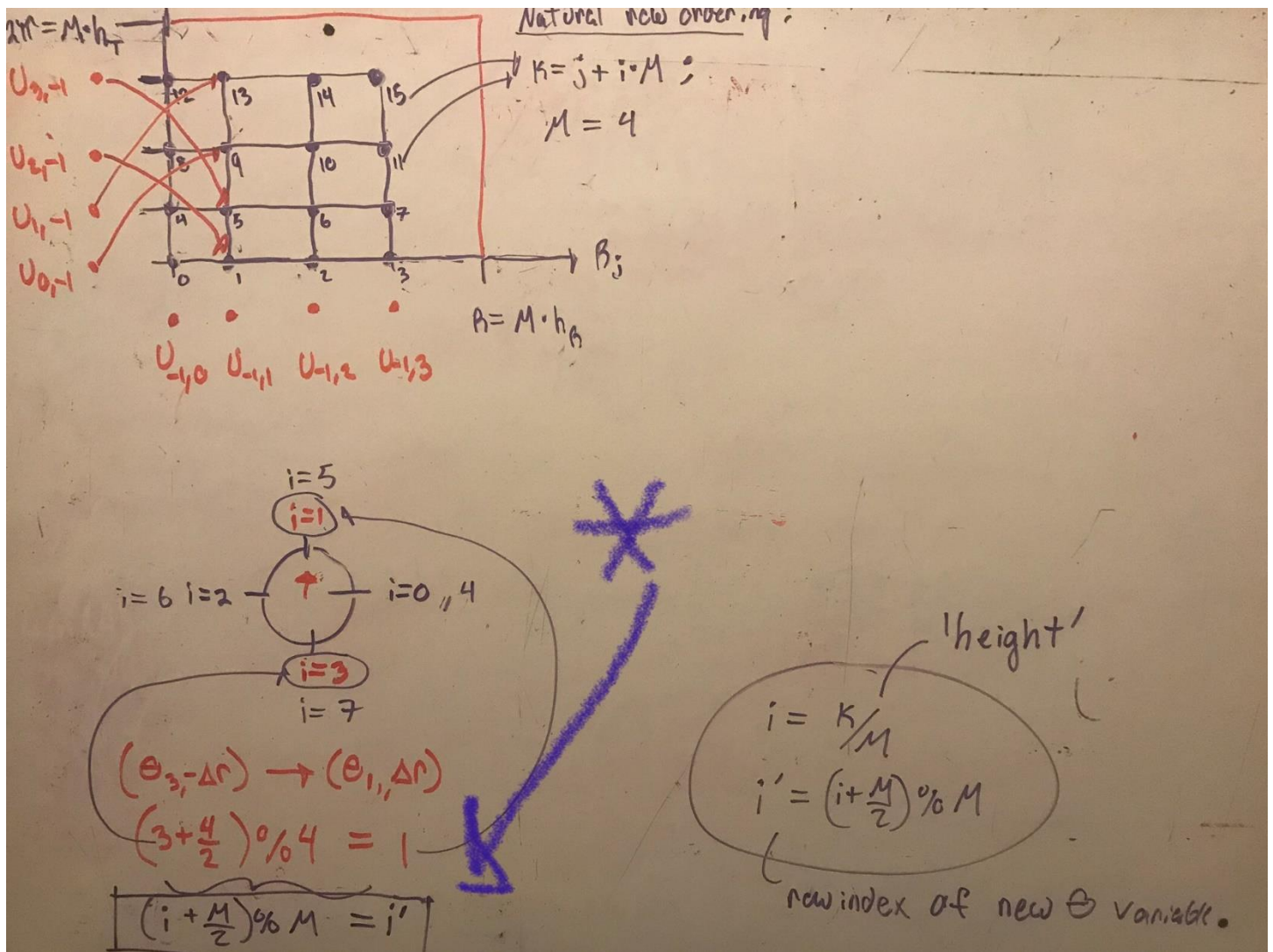
identify row index of ghost point (subscript ‘g’ denotes that it is a subscript on the grid and subscript A denotes it is an index of matrix A)

$$I_g = \left( i_g + \frac{M}{2} \right) \% M$$

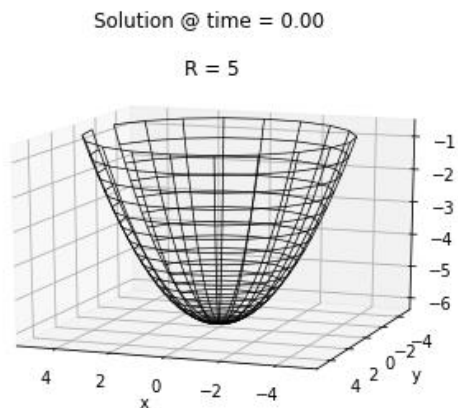
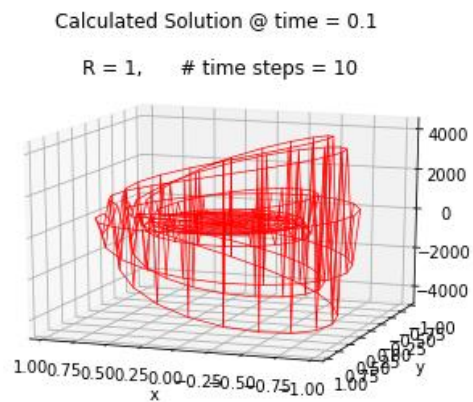
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identify corresponding point that is within the grid and shifted by  $\pi$ , i.e.  $\theta_{I_g} = \theta_{i_g} + \pi$

The figure below helps clarify what is happening;

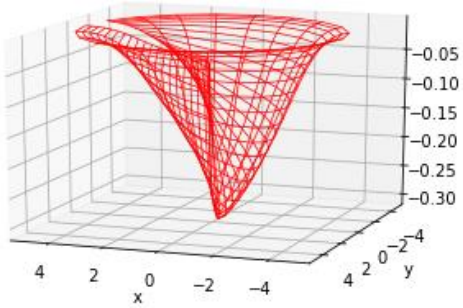


The results for a grid of  $M = 20$  ,  $N = 10$  time steps (with time step value  $k = 1/1000$ ) and for various values of  $R$  are as follows;



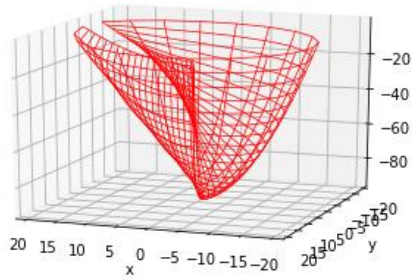
Calculated Solution @ time = 0.1

R = 5, # time steps = 10



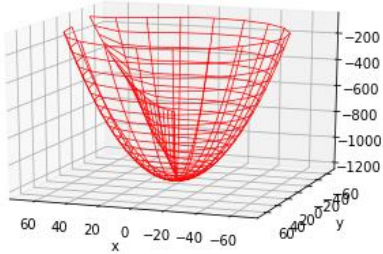
Calculated Solution @ time = 0.1

R = 20, # time steps = 10



Calculated Solution @ time = 0.1

R = 70, # time steps = 10



Calculated Solution @ time = 0.1

R = 100, # time steps = 10

