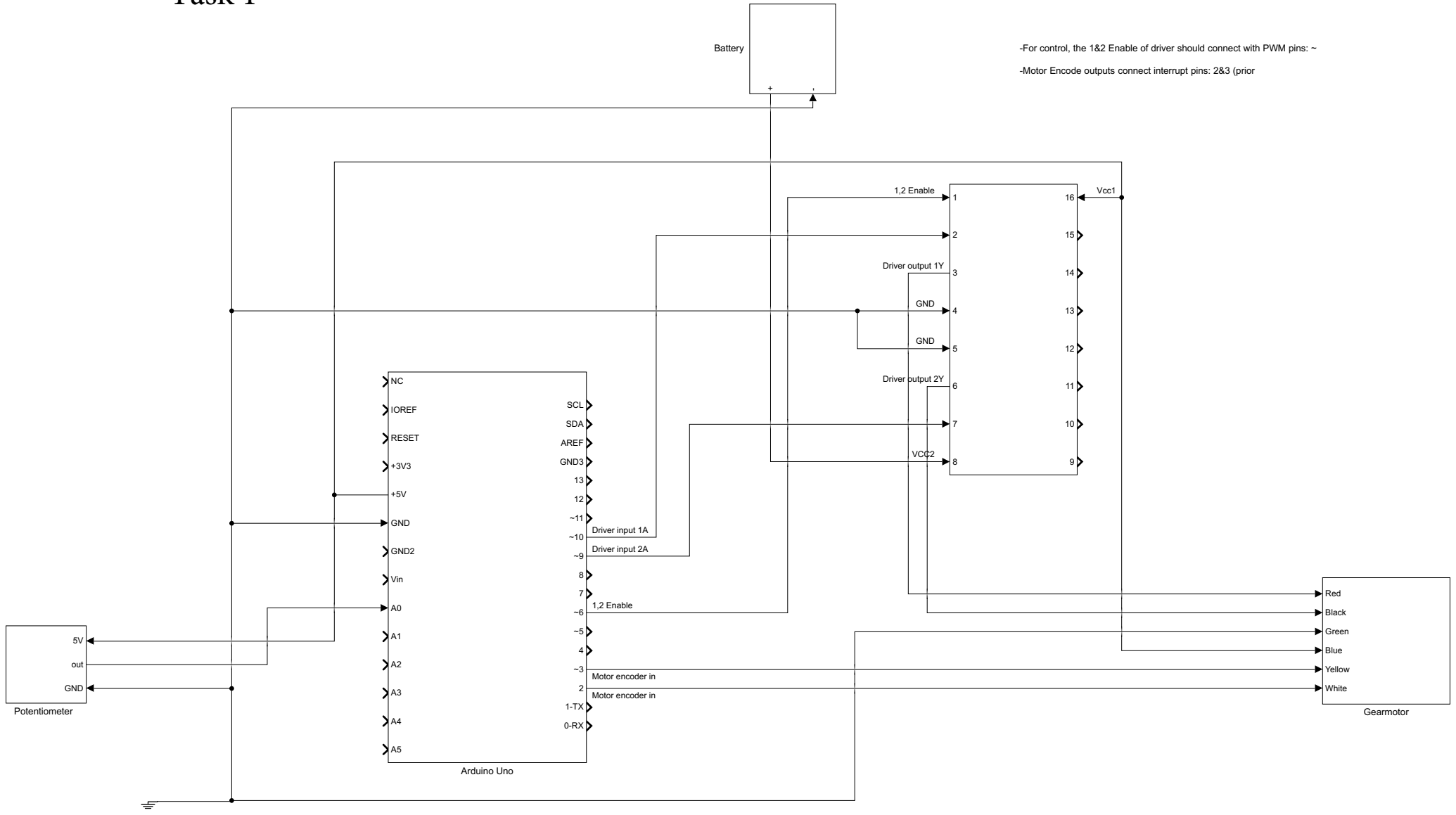


Circuit Diagram

Task 1



-For control, the 1&2 Enable of driver should connect with PWM pins: ~
-Motor Encode outputs connect interrupt pins: 2&3 (prior