
3D image tools

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Topics

- Generation of 3D synthetic images
- Converting to polygon surface representation
- Filtering polygon representations
- Viewing 3D polygon models



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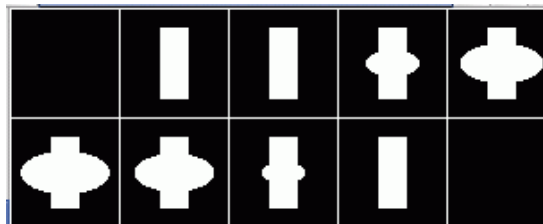
A simple 3D Synthetic test object

```
#!/bin/sh
vgenim s=60 z=50 e=25,12,12 of=im1
vgenim s=60 z=50 r=8,20,20 of=im2
vop -or im1 im2 -o im3
vdim -c im3 -o im4
rm -f im5
vclip im4 f=1 -o im5
# make a visualization of the image
for i in 6 11 16 21 26 31 36 41 46
do
    echo "i is $i"
    vclip im4 f=$i | vxfile of=im5
done
vtile im5 -ib -xb n=5,2 -o im6
```

Im5 is the test object image

For human review:

Im6 is every 5th image of im5 in a tiled single-image presentation



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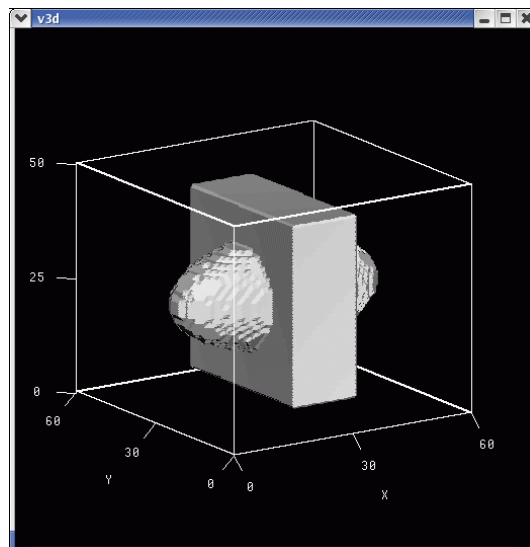
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3D Object visualization of the test image

```
vpol -t im3 -o pol1
v3d pol1
```

To visualize the surface of a 3D Binary region use vpol to convert to a (triangular) polygon representation and then use v3d to display

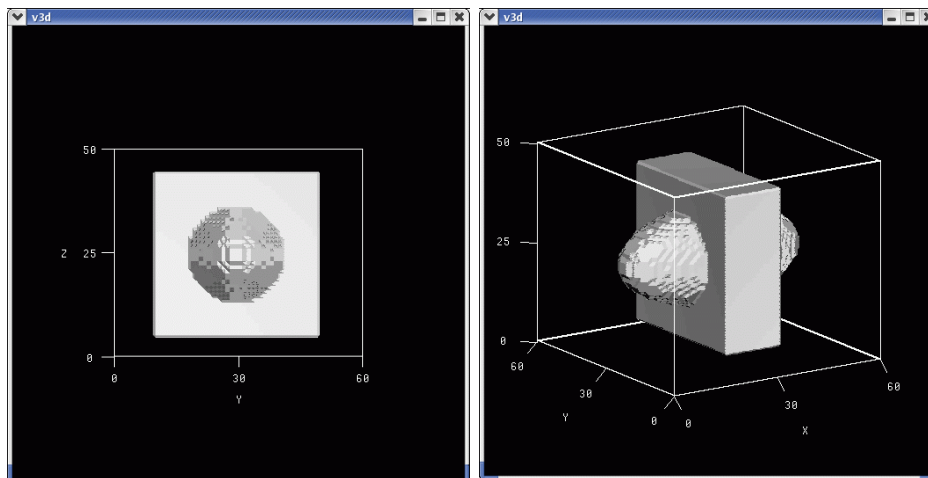
Use the interactive controls of v3d to select grey light shaded visualization



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Different viewing directions



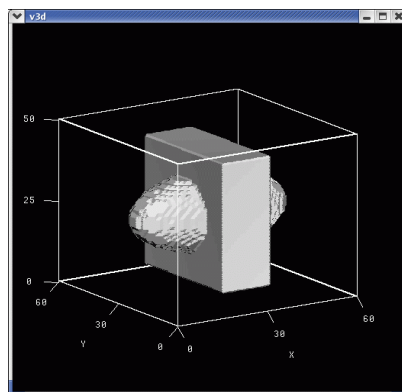
The interactive controls from v3d provide for viewing from different directions



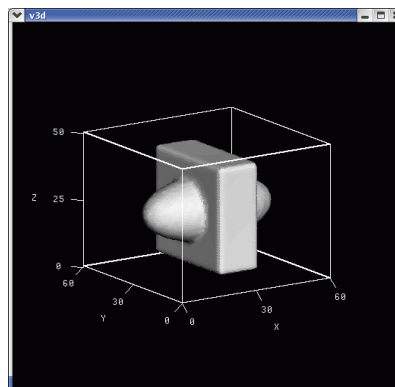
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Polygon smoothing



`v3pfilt -a pol1 -o pol2`
`v3pfilt -a pol2 | v3pfilt -a of=pol3`



pol3 is shown above, v3pfilt
smooths the polygon surface for
improved viewing

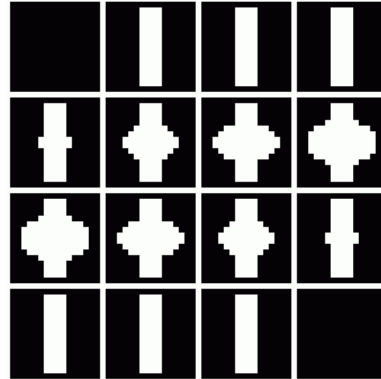


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A smaller 3D test image

```
#!/bin/sh
vgenim s=16 z=16 e=6,4,4 of=im1
vgenim s=16 z=16 r=2,7,7 of=im2
vop -or im1 im2 -o im3
vdim -c im3 -o im4
# make visualization image
vtile im4 -ib -xb n=4,4 -o im6
#
v3pol -t im3 -o pol1
v3pfilt -a pol1 -o pol2
v3pfilt -a pol2 | v3pfilt -a of=pol3
```



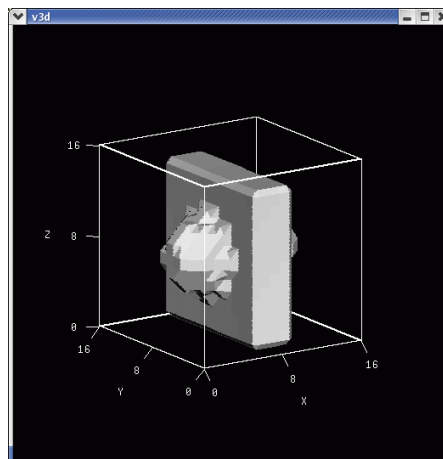
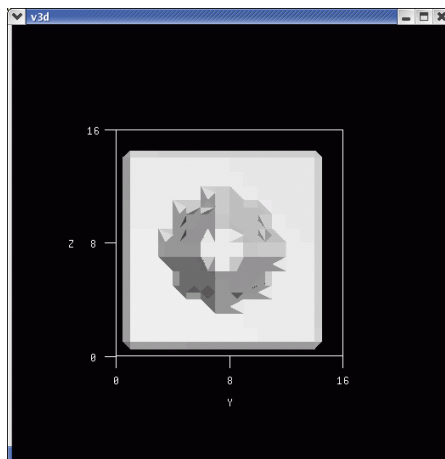
The modified script recreates all the previous images with a smaller size. By making the image smaller we can visualize all the 2D images and better see the effects of polygon smoothing



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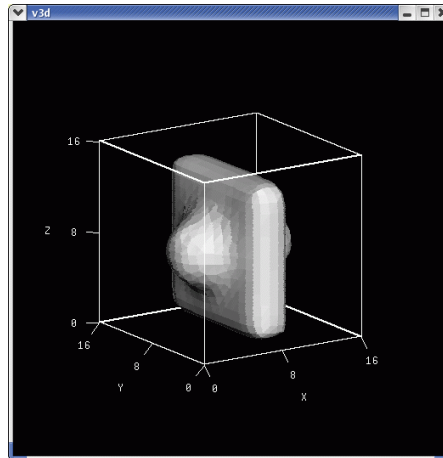
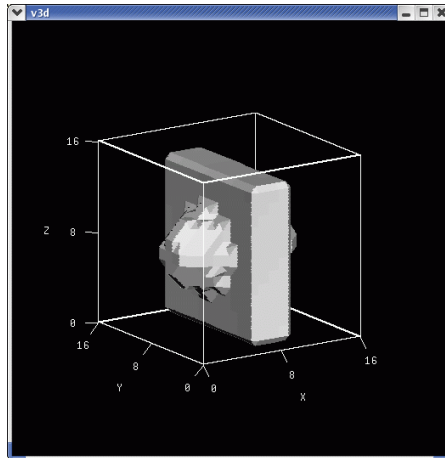
Small image without smoothing



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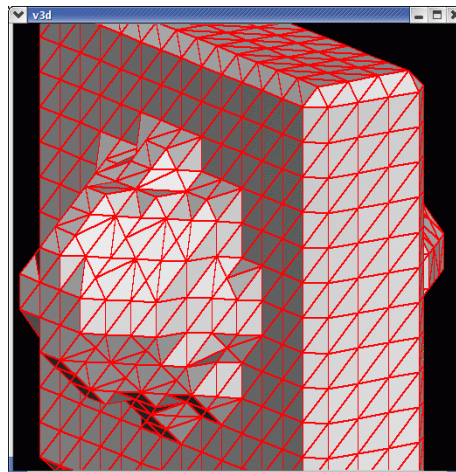
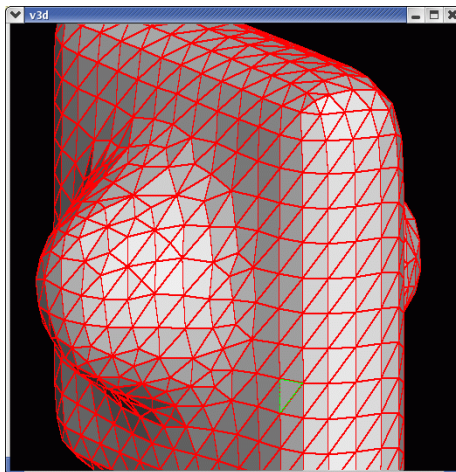
Small image with polygon smoothing



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Details of the triangular surface



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The Third Image Dimension

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3D Computer Vision Methods

- Thresholding
- Split and Merge Region Growing
- Image filtering (isotropic)
- Gradient Measurement (isotropic)
- The Method of Moments
- Feature Classification (all methods)



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3D Algorithms with Issues

- Image Filtering (anisotropic)
 - how to define an anisotropic kernel?
- Edge Detection (anisotropic)
 - Non-maximum suppression
 - Thresholding with hysteresis
 - complex neighborhood decisions



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3D Lines and 3D Surfaces

- B-Splines are well defined for 3D lines and 3D surfaces
- Splines that pass through knot points can be defined for 3D lines and 3D surfaces
- How to decompose a volume to a surface representation?
 - computer graphics: surface polygon models and volume models



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Polygon Representation

- Marching cubes: convert a thresholded 3D image to a set of 3D surface Polygons
 - Concept similar to boundary tracing
- 3D Polyline Algorithm?



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2D Boundary Representation and 3D Surface Representation

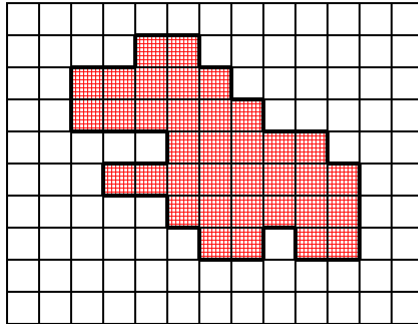
- Crack Edge (2D and 3D)
- Chain Code (2D)
- Marching cubes (2D version)
- 3D Marching cubes



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Crack Edge Model



The crack edge model may be extended to 3D where each “crack” is a square polygon having the size of one voxel face

e.g. Brice and Fennema, Boundary melting

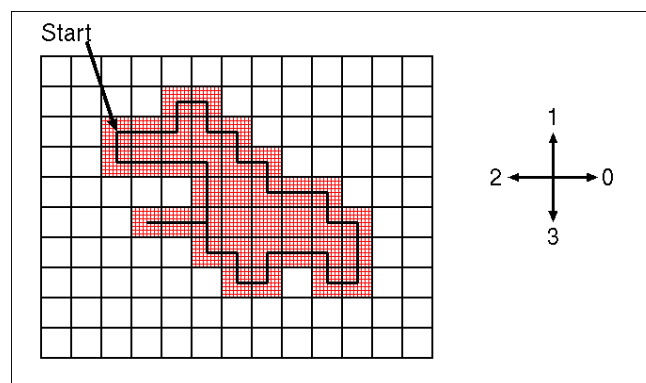


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Chain Code

Trace the boundary of a region using a boundary following algorithm and record the trajectory from pixel to pixel with an efficient direction code.



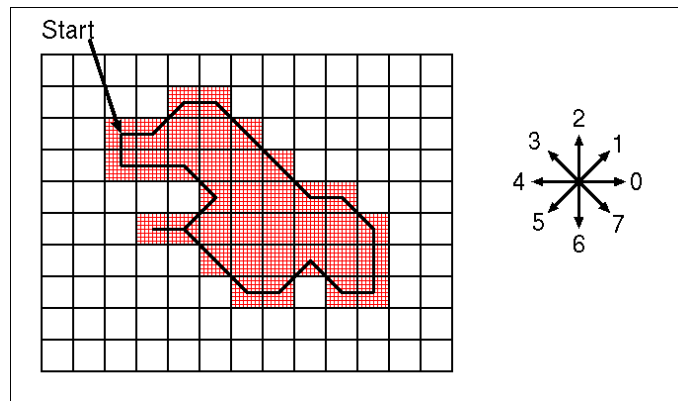
0,0,1,0,3,0,3,0,3,0,0,3,0,3,3,2,1,2,2,3,2,1,2,1,2,2,0,0,1,1,2,2,2,1



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Eight-Direction Chain Code



0,1,0,7,7,7,0,7,6,6,4,3,5,4,3,3,4,0,1,3,4,4,2

- For the example image: 4-Dir. $34 \times 2 = 68$ bits 8-Dir. $23 \times 3 = 69$ bits
- A 3D volume could be represented by set of CCs one for each “slice”



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Marching Cubes

How to convert from a binary volume image to a smooth polygon surface?

- Consider partitioning the space between 1 voxels and 0 voxels
- Local $2 \times 2 \times 2$ partitioning algorithm produces a global solution



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2D Version (Marching Squares?)

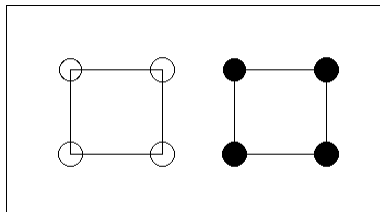
- Partition the space between each 2x2 group of adjacent pixels
- There are sixteen possible arrangements of 2x2 binary pixels



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All pixels have the same value



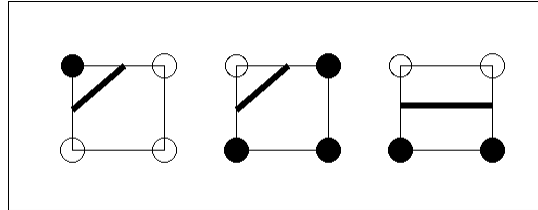
- 2 arrangements
 - all one \Rightarrow no partition
 - all zero \Rightarrow no partition



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Simple partition arrangements



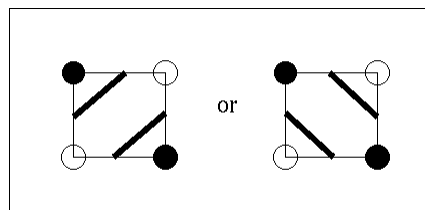
- There are 4 different orientations for each of the above arrangements
- 12 arrangements in total



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One final challenging arrangement



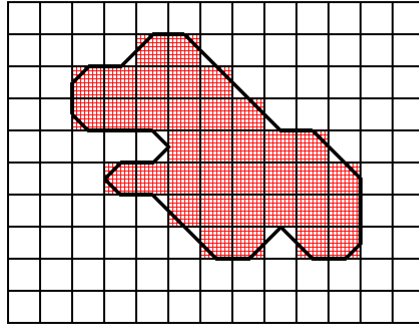
- There are two orientations of the above arrangement and one of two possible partitions must be selected
- This selection determines the connectivity convention (4 or 8)



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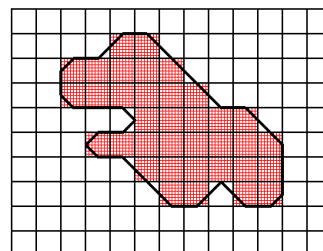
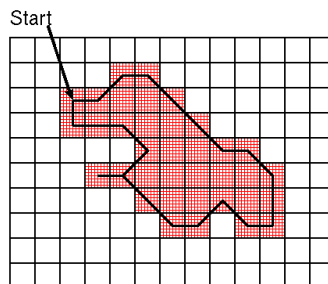
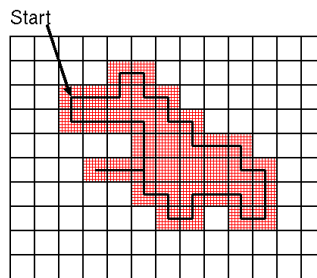
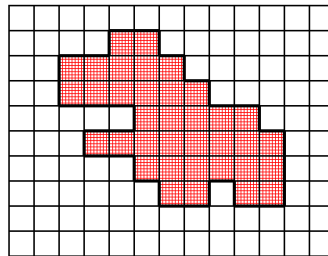
Marching Squares Boundary



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2D Boundary Codes



Marching Cubes (3D)

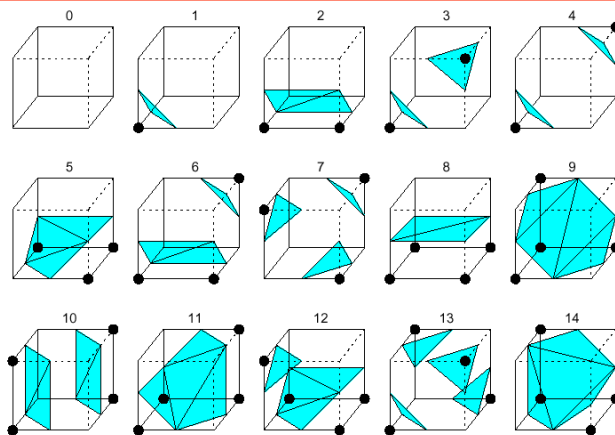
- There are 256 $2 \times 2 \times 2$ arrangements
- Partitioning is achieved by polygons
- Frequently, for convenience, polygons are restricted to triangles



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Marching Cubes



- 14 different cube arrangements and their triangular polygon partitioning
- Several arrangements require 4 triangles for the partition



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Summary: Boundary and Surface Representation

- A 2D boundary can be efficiently represented by a chain code (4-dir or 8-dir)
- The surfaces of the crack edges (square planes) could be used for volume surface representation
- Marching cubes provides a better solution for volume surface representation

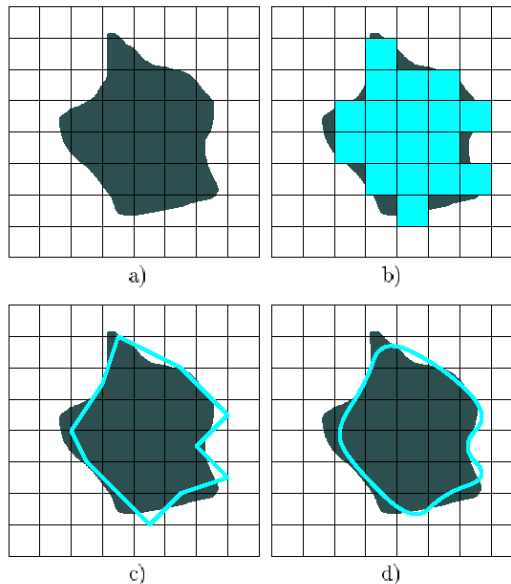


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Boundary Location? (2D)

- (a) region
- (b) Pixel Representation
- (c) Marching Cubes
- (d) Smoothed Marching Cubes



Pixel resolution limits the accuracy and quality of a boundary representation

3D Region Visualization

How to create a 3D model ?

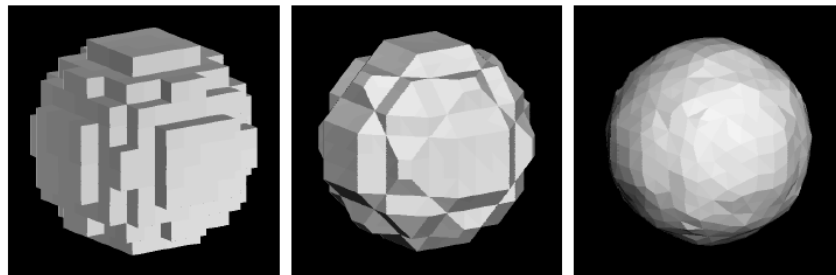
- Threshold 3D image
 - obtain 3D binary image
- Marching Cubes algorithm
 - obtain 3D polygon representation from 3D image
- Smoothing
 - remove voxel quantization artifacts



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3D Surface Representations of a Sphere



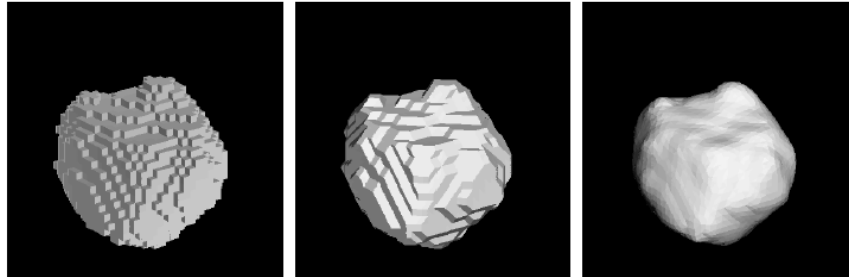
(a) Crack Edge (b) marching cubes (c) Smoothed MC



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3D Surface Representations of a pulmonary nodule



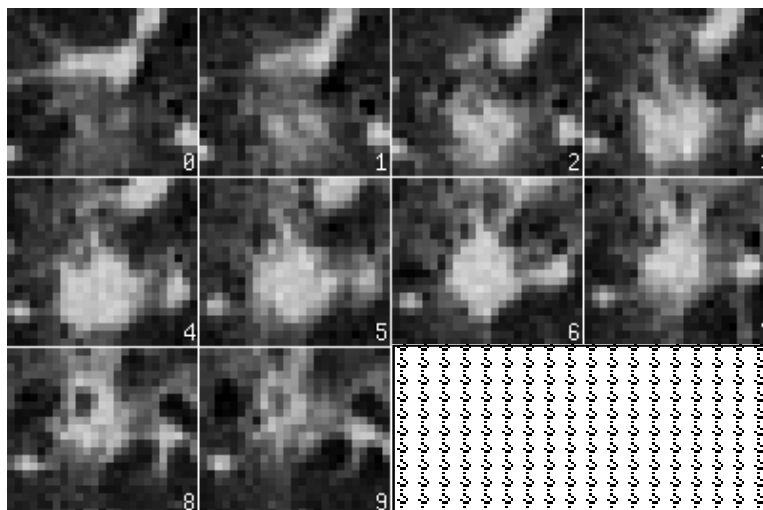
(a) Crack Edge (b) marching cubes (c) Smoothed MC



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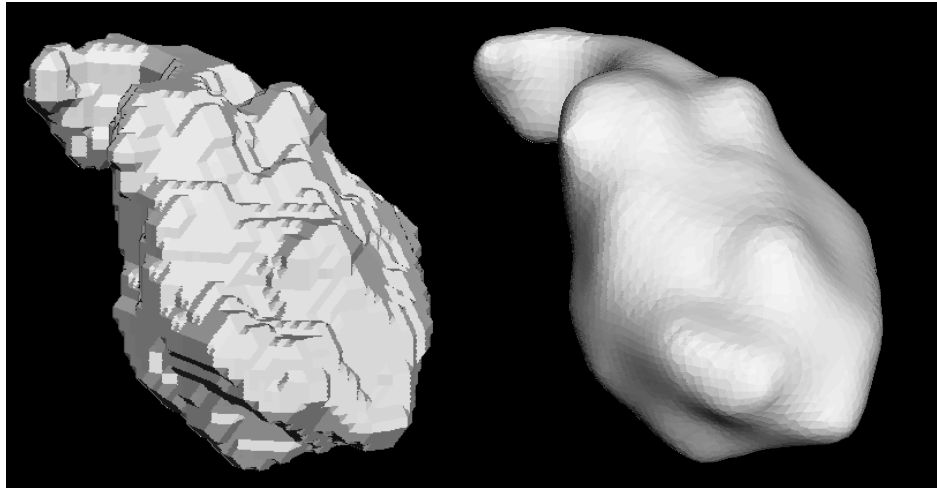
A Pulmonary Nodule: The CT Slices



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Shaded Light Marching Cubes and Smoothing



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Smoothing Methods

- 2D Boundary smoothing by local filtering
 - Replace each boundary point by a weighted sum of its neighbors
- 3D Polygon smoothing
 - Replace each vertex by a weighted sum of the neighboring vertices
- Repeat process several times for a Gaussian like filter function
- Issues: what weights to use and how many repetitions; i.e., how much smoothing



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2D Boundary Smoothing

- Given a boundary vector

$$p[i] = (x[i], y[i])$$

- Replace each element with a weighted fraction of its two adjacent neighbors

$$p'[i] = \alpha \left(\frac{p[i-1] + p[i+1]}{2} \right) + (1 - \alpha)p[i]$$



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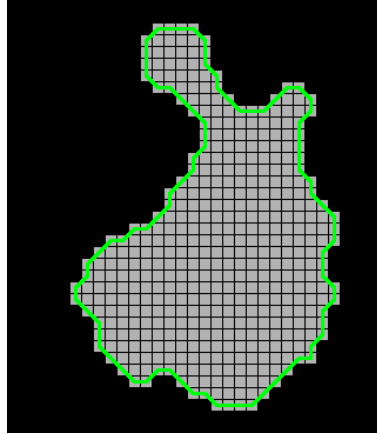
2D CT Image and Segmentation of a Pulmonary Nodule



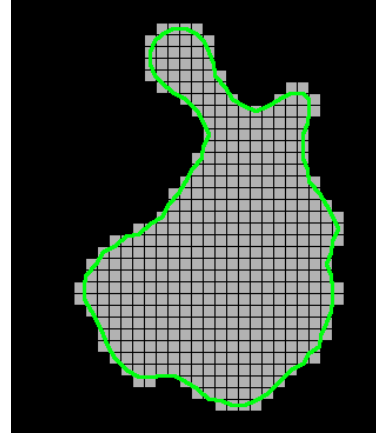
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Chain code and weight filter



8-direction Chain code



0.9 weight filter



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Repeated Operation

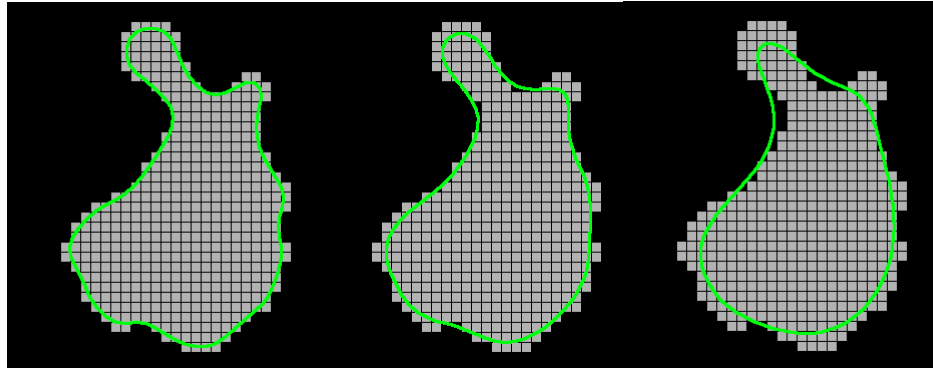
- Simple weighted smoothing will only change boundary location by up to 1 pixel.
- Repeat the weighted smoothing operation n times; the smoothing function approximates Gaussian weighting of the near neighbors



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Boundary smoothing $\alpha = 0.5$



$n = 3$

$n = 10$

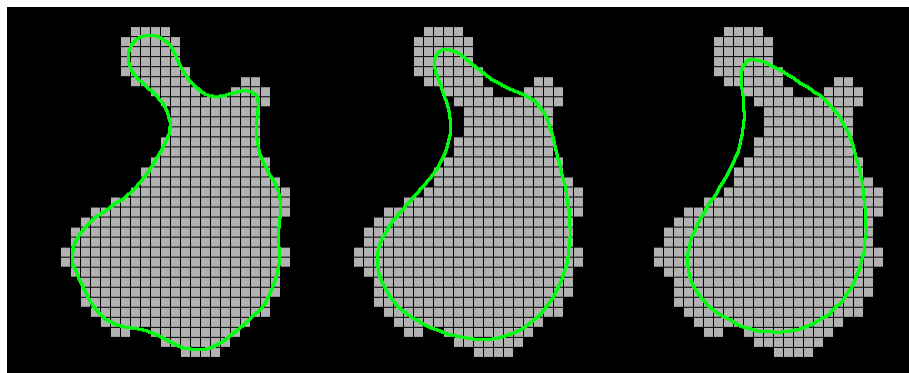
$n = 30$



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Boundary smoothing $n = 30$



$\alpha = 0.1$

$\alpha = 0.5$

$\alpha = 0.99$



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3D Surface Properties

Why bother with a 3D polygon representation (beyond a pretty picture) ?

- Computation of object properties:
 - volume, surface area, center of mass
- Characterization of surface
 - surface curvature
- Object manipulation and comparison
 - scale, rotation, and translation



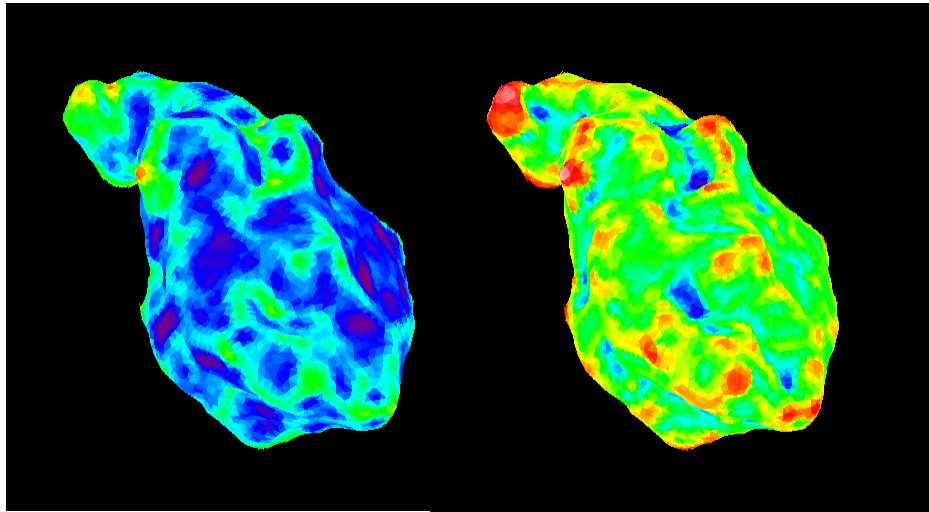
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Magnitude

Curvature

Magnitude + Direction



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Polygon Shading

- Light model
 - Lambertian surface, single light source
- Range shading (radar)
 - distance to the viewer
- Dimension shading
 - shade across one of the three dimensions
- Wire frame
 - outlines of the polygons
- Custom shading
 - shade using some object property



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Summary: Surface Visualization Methods

- Smoothing
 - reduce voxel quantization and marching cube artifacts
- Rendering Methods
 - range, light, axis --- for depth cues
 - polygon boundaries --- for depth cues
 - outside surface --- for context
 - inside section --- for density distribution
 - gradient --- for surface characterization
 - animation --- additional views and depth cues



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