

求下列矩阵的 QR 分解

$$\begin{bmatrix} 4 & 2 & 3 & 0 \\ -2 & 3 & -1 & 1 \\ 1 & 3 & -4 & 2 \\ 1 & 0 & 1 & -1 \\ 3 & 1 & 3 & -2 \end{bmatrix}$$

解: 记  $x_1 = \begin{bmatrix} 4 \\ -2 \\ 1 \\ 1 \\ 3 \end{bmatrix}$ ,  $x_2 = \begin{bmatrix} 2 \\ 3 \\ 3 \\ 0 \\ 1 \end{bmatrix}$ ,  $x_3 = \begin{bmatrix} 3 \\ -1 \\ -4 \\ 1 \\ 3 \end{bmatrix}$ ,  $x_4 = \begin{bmatrix} 0 \\ 1 \\ 2 \\ -1 \\ -2 \\ = \end{bmatrix}$ , 补充向量  $x_5 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ ,  $Q =$

$$\begin{bmatrix} q_1 & q_2 & q_3 & q_4 & q_5 \end{bmatrix}, R = \begin{bmatrix} r_{11} & r_{12} & r_{13} & r_{14} \\ 0 & r_{22} & r_{23} & r_{24} \\ 0 & 0 & r_{33} & r_{34} \\ 0 & 0 & 0 & r_{44} \\ 0 & 0 & 0 & 0 \end{bmatrix}。$$

将  $x_1, x_2, x_3, x_4, x_5$  正交化

$$\begin{cases} y_1 = x_1 \\ y_2 = x_2 - q_1 q_1^T x_2 \\ y_3 = x_3 - q_1 q_1^T x_3 - q_2 q_2^T x_3 \\ y_4 = x_4 - q_1 q_1^T x_4 - q_2 q_2^T x_4 - q_3 q_3^T x_4 \\ y_5 = x_5 - q_1 q_1^T x_5 - q_2 q_2^T x_5 - q_3 q_3^T x_5 - q_4 q_4^T x_5 \end{cases}$$

$$\text{因此 } y_1 = x_1 = \begin{bmatrix} 4 \\ -2 \\ 1 \\ 1 \\ 3 \end{bmatrix}, \text{ 故 } r_{11} = \|y_1\|_2 = \sqrt{4^2 + (-2)^2 + 1^2 + 1^2 + 3^2} = \sqrt{31},$$

$$q_1 = \frac{y_1}{\|y_1\|_2} = \frac{1}{\sqrt{31}} \begin{bmatrix} 4 \\ -2 \\ 1 \\ 1 \\ 3 \end{bmatrix}$$

$$y_2 = x_2 - q_1 q_1^T x_2 = x_2 - \frac{8}{\sqrt{31}} q_1 = \frac{1}{31} \begin{bmatrix} 30 \\ 109 \\ 85 \\ -8 \\ 7 \end{bmatrix}, \text{ 故 } r_{12} = \frac{8}{\sqrt{31}}, r_{22} = \|y_2\|_2 = \frac{\sqrt{20119}}{31},$$

$$q_2 = \frac{y_2}{\|y_2\|_2} = \frac{1}{\sqrt{20119}} \begin{bmatrix} 30 \\ 109 \\ 85 \\ -8 \\ 7 \end{bmatrix}$$

$$y_3 = x_3 - q_1 q_1^T x_3 - q_2 q_2^T x_3 = x_3 - \frac{20}{\sqrt{31}} q_1 + \frac{346}{\sqrt{20119}} q_2 = \frac{1}{20119} \begin{bmatrix} 18817 \\ 43555 \\ -64046 \\ 4371 \\ 23839 \end{bmatrix}, \text{ 故 } r_{13} = \frac{20}{\sqrt{31}}, r_{23} = -\frac{346}{\sqrt{20119}}, r_{33} = \|y_3\|_2 = \frac{\sqrt{6940411192}}{20119},$$

$$q_3 = \frac{y_3}{\|y_3\|_2} = \frac{1}{\sqrt{6940411192}} \begin{bmatrix} 18817 \\ 43555 \\ -64046 \\ 4371 \\ 23839 \end{bmatrix}$$

$$y_4 = x_4 - q_1 q_1^T x_4 - q_2 q_2^T x_4 - q_3 q_3^T x_4 = x_4 + \frac{7}{\sqrt{31}} q_1 - \frac{273}{\sqrt{20119}} q_2 + \frac{136586}{\sqrt{6940411192}} q_3 = \frac{1}{6940411192} \begin{bmatrix} 6013609338 \\ -510177602 \\ -1304757388 \\ -4022794050 \\ -6582413706 \end{bmatrix},$$

$$\text{故 } r_{14} = -\frac{7}{\sqrt{31}}, r_{24} = \frac{273}{\sqrt{20119}}, r_{34} = -\frac{136586}{\sqrt{6940411192}}, r_{44} = \|y_4\|_2 = \frac{\sqrt{97637212462855908128}}{6940411192},$$

$$q_4 = \frac{y_4}{\|y_4\|_2} = \frac{1}{\sqrt{97637212462855908128}} \begin{bmatrix} 6013609338 \\ -510177602 \\ -1304757388 \\ -4022794050 \\ -6582413706 \end{bmatrix}$$

$$y_5 = x_5 - q_1 q_1^T x_5 - q_2 q_2^T x_5 - q_3 q_3^T x_5 - q_4 q_4^T x_5 = x_5 - \frac{3}{\sqrt{31}} q_1 - \frac{30}{\sqrt{20119}} q_2 - \frac{18817}{\sqrt{6940411192}} q_3 - \frac{6013609338}{\sqrt{97637212462855908128}} = \frac{1}{97637212462855908128} \begin{bmatrix} 1731463246370915200 \\ 865731623185457600 \\ -173146324637091520 \\ 11600803750685131840 \\ -5540683118919241008 \end{bmatrix}, \text{ 故}$$

$$\|y_5\|_2 = \frac{\sqrt{169055252963920205791897348744815352064}}{97637212462855908128}$$

,

$$q_5 = \frac{y_5}{\|y_5\|_2} = \frac{1}{\sqrt{169055252963920205791897348744815352064}} \begin{bmatrix} 1731463246370915200 \\ 865731623185457600 \\ -173146324637091520 \\ 11600803750685131840 \\ -5540683118919241008 \end{bmatrix}.$$

综上可得

$$Q = \begin{bmatrix} \frac{4}{\sqrt{31}} & \frac{30}{\sqrt{20119}} & \frac{18817}{\sqrt{6940411192}} & \frac{6013609338}{\sqrt{97637212462855908128}} & \frac{1731463246370915200}{\sqrt{169055252963920205791897348744815352064}} \\ \frac{-2}{\sqrt{31}} & \frac{109}{\sqrt{20119}} & \frac{43555}{\sqrt{6940411192}} & \frac{-510177602}{\sqrt{97637212462855908128}} & \frac{865731623185457600}{\sqrt{169055252963920205791897348744815352064}} \\ \frac{1}{\sqrt{31}} & \frac{85}{\sqrt{20119}} & \frac{-64046}{\sqrt{6940411192}} & \frac{-1304757388}{\sqrt{97637212462855908128}} & \frac{-173146324637091520}{\sqrt{169055252963920205791897348744815352064}} \\ \frac{1}{\sqrt{31}} & \frac{-8}{\sqrt{20119}} & \frac{4371}{\sqrt{6940411192}} & \frac{-4022794050}{\sqrt{97637212462855908128}} & \frac{11600803750685131840}{\sqrt{169055252963920205791897348744815352064}} \\ \frac{3}{\sqrt{31}} & \frac{7}{\sqrt{20119}} & \frac{23839}{\sqrt{6940411192}} & \frac{-6582413706}{\sqrt{97637212462855908128}} & \frac{-5540683118919241008}{\sqrt{169055252963920205791897348744815352064}} \end{bmatrix}$$

,

$$R = \begin{bmatrix} \sqrt{31} & \frac{8}{\sqrt{31}} & \frac{20}{\sqrt{31}} & -\frac{7}{\sqrt{31}} \\ 0 & \frac{\sqrt{20119}}{31} & -\frac{346}{\sqrt{20119}} & \frac{273}{\sqrt{20119}} \\ 0 & 0 & \frac{\sqrt{6940411192}}{20119} & -\frac{136586}{\sqrt{6940411192}} \\ 0 & 0 & 0 & \frac{\sqrt{97637212462855908128}}{6940411192} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

验证：

$$QR = \begin{bmatrix} 4 & 2 & 3 & 0 \\ -2 & 3 & -1 & 1 \\ 1 & 3 & -4 & 2 \\ 1 & 0 & 1 & -1 \\ 3 & 1 & 3 & -2 \end{bmatrix} = A$$

将上述运算结果的 Q、R 矩阵和 Matlab 自带函数分解的 Q、R 矩阵作比较，手算的 Q、R 矩阵转化为小数形式如下：

```
Q =  
  
    0.718421208107100    0.211503743913783    0.225869600743011    0.608593802791436    0.133167713302033  
   -0.359210604053550    0.768463602886746    0.522811843564961   -0.051631376341360    0.066583856651016  
    0.179605302026775    0.599260607755719   -0.768775280288405   -0.132045035826559   -0.013316771330203  
    0.179605302026775   -0.056400998377009    0.052467238393352   -0.407117820784564    0.892223679123619  
    0.538815906080325    0.049350873579883    0.286151108684309   -0.666158369079114   -0.426136738752114  
  
R =  
  
    5.567764362830022    1.436842416214199    3.592106040535498   -1.257237114187424  
                   0    4.575530993334844   -2.439343179805633    1.924684069615427  
                   0                   0    4.140818644263973    1.639508172773820  
                   0                   0                   0    1.423713110948314  
                   0                   0                   0                   0
```

Matlab 自带函数分解的 Q、R 矩阵如下：

```
A =  
  
     4     2     3     0  
    -2     3    -1     1  
     1     3    -4     2  
     1     0     1    -1  
     3     1     3    -2  
  
>> [Q,R]=qr(A)  
  
Q =  
  
   -0.718421208107100   -0.211503743913783    0.225869600743012    0.608593802791436   -0.133167716494799  
    0.359210604053550   -0.768463602886746    0.522811843564961   -0.051631376341360   -0.066583858247399  
   -0.179605302026775   -0.599260607755719   -0.768775280288405   -0.132045035826559    0.013316771649480  
   -0.179605302026775    0.056400998377009    0.052467238393352   -0.407117820784564   -0.892223700515151  
   -0.538815906080325   -0.049350873579883    0.286151108684309   -0.666158369079114    0.426136692783356  
  
R =  
  
   -5.567764362830022   -1.436842416214200   -3.592106040535499    1.257237114187425  
                   0   -4.575530993334843    2.439343179805634   -1.924684069615428  
                   0                   0    4.140818644263972   -1.639508172773820  
                   0                   0                   0    1.423713110948314  
                   0                   0                   0                   0
```

可以看到，Matlab 自带函数分解的  $Q$  矩阵在数值上等于  $-q_1$ 、 $-q_2$ 、 $q_3$ 、 $q_4$ 、 $-q_5$ ，相应的， $R$  矩阵的第 1、2、5 行是手算  $R$  矩阵对应行的相反数，这也证明了上述计算结果的正确性。