

Workshop: Building end-toend ML workflows with Arm

Gian Marco Iodice, Tech Lead ACL, Arm

Wei Xiao, Principal Evangelist AI Ecosystem, Arm

Hands-on session pre-requisites

Install VNC (Virtual Network Computing) viewer

In order to control the Raspberry desktop interface through your laptop, it is necessary to install VNC viewer (https://www.realvnc.com). This will allow to control the Raspberry Pi UI using the screen, keyboard and mouse of your laptop.

Note: VNC server is already included with Raspbian OS and it requires to be launched before establishing the connection from your laptop.

VNC viewer is supported on various platforms including Windows, Linux, MacOS, Chrome OS, Android and many more. For this workshop, we recommend installing VNC viewer on Chrome browser through the Chrome Web Store.

https://www.realvnc.com/en/connect/download/viewer/

Chrome browser

- 1. Install VNC[®] Viewer for Google Chrome[™] from Chrome web store
- 2. Open Chrome browser
- 3. In the navigation bar, type:

- chrome://extensions/
- 4. In the search extensions field, look for VNC viewer and run it

Default login for Raspbian OS

• User: pi

• Password: raspberry

Using the serial terminal

Windows

- 1. Download and install the PuTTY terminal
 - https://www.putty.org
- 2. Execute (as administrator) putty.exe
- 3. Under Connection type, select:
 - Serial
- 4. In the Serial line field, enter the COM# for your USB serial port. You can find the COM# number from the Device Manager under the section "Ports (COM & LPT)"
- 5. In the **Speed field**, type:
 - 115200
- 6. Click Open.
- 7. If you cannot see the login screen, press Enter multiple times

MacOS

- 1. Launch the Terminal app from Spotlight (cmd + space).
- 2. In the **Terminal**, enter the command:
 - \$ Is /dev/cu.usbserial-*
- 3. From the list of devices, copy the name of the device that contains **cu.usbserial**.
- 4. In the **Terminal**, enter the command:
 - \$ screen /dev/cu.usbserial-*<name> 115200

This command will start the serial communication with the Raspberry Pi

5. If you cannot see the login screen, press Enter multiple times

Linux

- 1. Open the terminal (ctrl +alt + t)
- 2. In the Terminal, enter the command:
 - \$ sudo apt-get install screen

Note: Skip if already installed

- 3. In the **Terminal**, enter the command:
 - \$ ls /dev/ttyUSB*
- 4. From the list of the devices, copy the name of the device that contains ttyUSB (I.e. ttyUSB0)
- 5. In the **Terminal**, enter the command:
 - \$ sudo screen /dev/ttyUSB<number> 115200
- 6. If you cannot see the login screen, press Enter multiple times

Backup

Install Raspbian OS on Raspberry Pi 4

https://www.raspberrypi.org/documentation/installation/installing-images/

Note: Arm Cortex-A72 is an aarch64 architecture but Raspbian OS is based on an armv7 (aarch32) filesystem. This means that the Arm Compute Library will not be able to call the optimized routines for aarch64

VNC for Raspberry Pi

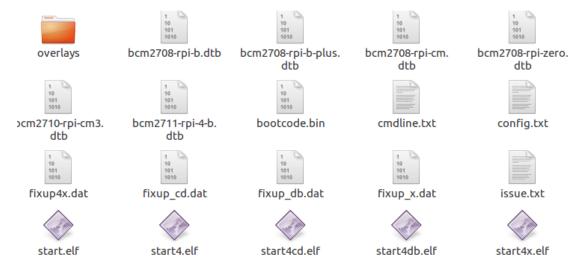
https://www.raspberrypi.org/documentation/remote-access/vnc/

Enabling Remote Access (SSH) on Raspbian OS

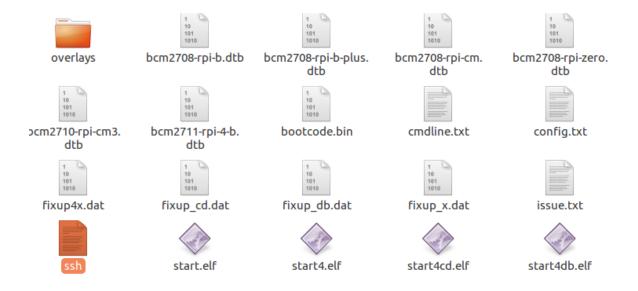
By default, Raspbian OS has the remote access disabled.

In order to allow SSH connections with wired ethernet cable, you need to:

- 1. Insert the sdcard with Raspbian OS in your laptop
- 2. Open the boot directory of the card



3. Write an empty txt file (without extension) named "ssh"



Enabling Serial Communication

By default, Raspbian OS has the serial communication disabled.

In order to allow serial login, you need to:

- 1. Open the **Terminal** on your Raspberry Pi and type:
 - \$ sudo raspi-config
- 2. Go down to Interfacing options

```
Raspberry Pi Software Configuration Tool (raspi-config)

1 Change User Password Change password for the current user
2 Network Options Configure network settings
3 Boot Options Configure options for start-up
4 Localisation Options Set up language and regional settings to match your location
5 Interfacing Options Configure connections to peripherals
6 Overclock Configure overclocking for your Pi
7 Advanced Options Configure advanced settings
8 Update Update this tool to the latest version
9 About raspi-config Information about this configuration tool
```

3. Click on Serial and select Yes

```
P1 Camera Enable/Disable connection to the Raspberry Pi Camera
P2 SSH Enable/Disable remote command line access to your Pi using SSH
P3 VNC Enable/Disable graphical remote access to your Pi using RealVNC
P4 SPI Enable/Disable automatic loading of SPI kernel module
P5 I2C Enable/Disable automatic loading of I2C kernel module
P6 Serial Enable/Disable shell and kernel messages on the serial connection
P7 1-Wire Enable/Disable one-wire interface
P8 Remote GPIO Enable/Disable remote access to GPIO pins
```

4. Reboot your Raspberry Pi

Launch VNC viewer from Chrome Browser

- 1. Open Chrome browser
- 2. In the navigation bar, type:
 - chrome://extensions/
- 3. Look for VNC® Viewer for Google Chrome™ and execute the App

SSH on Linux or MacOS

https://www.raspberrypi.org/documentation/remote-access/ssh/unix.md

Cross-compile ArmNN/ArmNN SDK

https://developer.arm.com/solutions/machine-learning-on-arm/developer-material/how-to-guides/cross-compiling-arm-nn-for-the-raspberry-pi-and-tensorflow

Cross-compile Compute Library (Development branch)
Linux host

Before you begin, we recommend reading the Arm Compute Library documentation available at https://arm-software.github.io/ComputeLibrary/v19.08/

For the performance analysis hands-on session, the Arm Compute Library development branch must be cloned from the Linaro repository in order to access the experimental benchmark framework.

The benchmark framework allows to profile the performance of all the examples included with the library.

Note: The experimental benchmark framework is not available in the official release of Compute Library on GitHub.

1. Open https://mlplatform.org/contributing/ and click on the Arm Compute Library repository (https://review.mlplatform.org/#/admin/projects/ml/ComputeLibrary)

Development Repositories

Project	Repository
Arm NN	https://review.mlplatform.org/#/admin/projects/ml/armnn
Arm Compute Library	https://review.mlplatform.org/#/admin/projects/ml/ComputeLibrary
Arm Android NN Driver	https://review.mlplatform.org/#/admin/projects/ml/android-nn-driver

2. Clone the project with Git

Note: For Cross-compiling the Arm Compute Library, the cross-compiler version on your host machine must match the compiler version on your Raspberry Pi.

If you want to know what compiler version is used on Raspbian OS, you can follow the instructions below:

- 1. Open the **Terminal** on your Raspberry Pi and type:
 - \$g++-v

The GCC version should be returned by this command.

```
pi@raspberrypi:~$ g++ -v
Using built-in specs.
COLLECT_GCC=g++
COLLECT_LTO_WRAPPER=/usr/lib/gcc/arm-linux-gnueabihf/8/lto-wrapper
Target: arm-linux-gnueabihf
Configured with: ../src/configure -v --with-pkgversion='Raspbian 8.3.0-6+rpi:
with-gcc-major-version-only --program-suffix=-8 --program-prefix=arm-linux-gnueabine-libquadmath --enable-nls --enable-bootstrap --enable-clocale=gnu --enable-libquadmath --disable-libquadmath-support --enable-plugin --with-system-zlinus-gnueabine-libquadmath --disable-werror --enable-checking=release --build=arm-linus-gnueabine-libquadmath-support --enable-plugin --with-system-zlinus-gnueabine-libquadmath --disable-werror --enable-checking=release --build=arm-linus-gnueabine-libquadmath-support --enable-plugin --with-system-zlinus-gnueabine-libquadmath-support --enable-plugin --with-system-zlinus-gnueabine-libquadmath-system-zlinus-gnueabine-libquadmath-system-z
```

The GNU toolchain required for this workshop is the **arm-linux-gnueabihf** (32 bit) **8.3.0** available at the following link:

https://www.linaro.org/downloads/)

Linaro Toolchain

The flatest Arm release of the pre-built GNU cross-toolchain for Cortex-A GCC 8.3-2019.03 is now available on the Arm Developer website.

Linaro provides monthly GCC source archive snapshots of the current Linaro GCC release branch, as well as quarterly releases of pre-built Linaro GNU cross-toolchain binary archives.

The following tables provide direct access to the most common Linux and bare-metal ABI variants of the Linaro binary cross-toolchain quarterly releases. Both x86_64 Linux and Mingw32 (MS Windows compatible) host binaries are provided:

Latest Linux Targeted Binary Toolchain Releases

arm-linux-gnueabihf	32-bit Armv7 Cortex-A, hard-float, little-endian	Release-Notes	Binaries	Source
armv8l-linux-gnueabihf	32-bit Armv8 Cortex-A, hard-float, little-endian	Release-Notes	Binaries	Source
aarch64-linux-gnu	64-bit Armv8 Cortex-A, little-endian	Release-Notes	Binaries	Source

Once the toolchain has been installed as described in the Arm Compute Library documentation, you can compile the library using the following instruction:

\$ scons -j6 arch=armv7a examples=1 asserts=1 opencl=0 gles_compute=0 neon=1 timers=1 debug=0 Werror=0 validation_tests=0 benchmark_tests=0

All the executables will be in the folder build

How to use Streamline

https://developer.arm.com/docs/100769/0605/introduction-to-streamline-performance-analyzer