SVM

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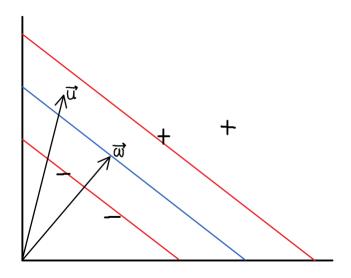
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1 Intuition

Assume there are 2 classes: - and + in a 2-dimensional space. We want to classify unknown samples into these 2 classes with SVM, by finding a hyperplane that best separates the 2 classes. In this case:

 \vec{u} is an unknown sample.

 \vec{w} is a vector perpendicular to the separation hyperplane.



Decision rule:

$$if \quad \vec{\omega} \cdot \vec{u} \geq c, \ then \quad \vec{u} \in + \\ (The \ projection \ of \ \vec{u} \ on \ \vec{w})$$

More generally (c = -b):

$$if \quad \vec{\omega} \cdot \vec{u} + b \ge 0, \quad then \Rightarrow \vec{u} \in +$$
 (1)

2 Question: What is \vec{w} and b?

Assume for known samples:

$$\vec{\omega} \cdot \vec{x}_+ + b \ge 1$$

$$\vec{\omega} \cdot \vec{x}_- + b \le -1$$

Now let's introduce a variable y_i for mathematical convenience:

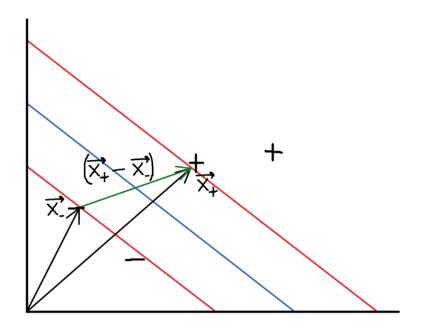
$$y_i = \left\{ \begin{array}{ll} +1 & for + samples \\ -1 & for - samples \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} y_i(\vec{\omega} \cdot \vec{x}_+ + b) \ge 1 \\ y_i(\vec{\omega} \cdot \vec{x}_- + b) \ge 1 \end{array} \right.$$

$$\Rightarrow y_i(\vec{\omega} \cdot \vec{x}_i + b) - 1 \ge 0$$

Assume for \vec{x}_i between (&on) the 2 solid lines:

$$\Rightarrow y_i(\vec{\omega} \cdot \vec{x}_i + b) - 1 = 0 \tag{2}$$



width (between the red lines) =
$$(\vec{x}_{+} - \vec{x}_{-}) \cdot \underbrace{\frac{\vec{\omega}}{||\vec{\omega}||}}_{\text{unit vector}}$$

 $\frac{\vec{\omega}}{||\vec{\omega}||}$: This makes a unit vector that gives the direction perpendicular to separation hyperplane(a straight line here in this case).

$$(2) \Rightarrow \begin{cases} \vec{x}_{+}\vec{\omega} = 1 - b \\ -\vec{x}_{-}\vec{\omega} = 1 + b \end{cases}$$
$$\Rightarrow \mathbf{width} = (1 - b + 1 + b) \frac{1}{||\vec{\omega}||} = \frac{2}{||\vec{\omega}||}$$
(3)

 \Rightarrow We want to max $\frac{1}{||\vec{\omega}||}$ (maximize the margin of the separation hyperplane between the 2 classes).

$$\Rightarrow \quad \min\{||\vec{\omega}||\} \ \Rightarrow \quad \min\{\frac{1}{2}||\vec{\omega}||^2\} \quad (for \ mathematical \ convenience)$$

(How find extremum with constraints? $\Rightarrow Lagrange$)

$$L = \frac{1}{2} ||\vec{\omega}||^2 - \sum_{i} \alpha_i [y_i(\vec{\omega} \cdot \vec{x}_i + b) - 1]$$

(How to take derivative of vectors? It has the same form of scalars.)

$$\frac{\partial L}{\partial \vec{\omega}} = \vec{\omega} - \sum_{i} \alpha_{i} y_{i} \vec{x}_{i} = 0$$

$$\Rightarrow \quad \vec{\omega} = \sum_{i} \underbrace{\alpha_{i}}_{\text{(scalar)}} \cdot \underbrace{y_{i}}_{\text{(+1,-1)}} \cdot \vec{x}_{i}$$
(4)

It is proved to be a convex space, so no local extremum.

2.1 *Important observation 1

 $\vec{\omega}$ is a linear sum of the sample vectors.

$$\frac{\partial L}{\partial b} = -\sum_{i} \alpha_{i} y_{i} = 0 \Rightarrow \sum_{i} \alpha_{i} y_{i} = 0$$

Plug (4) into L:

$$L = \frac{1}{2} \left(\sum_{i} \alpha_{i} y_{i} \vec{x}_{i} \right) \left(\sum_{j} \alpha_{j} y_{i} \vec{x}_{j} \right) - \sum_{i} \alpha_{i} y_{i} \vec{x}_{i} \left(\sum_{j} \alpha_{j} y_{i} \vec{x}_{j} \right) - \underbrace{\sum_{i} \alpha_{i} y_{i}}_{=0} \cdot b + \sum_{i} \alpha_{i}$$

$$L = \sum_{i} \alpha_{i} - \frac{1}{2} \sum_{i} \sum_{j} \alpha_{i} \alpha_{j} y_{i} y_{j} \underline{\vec{x}_{i}} \underline{\vec{x}_{j}}$$

$$(5)$$

2.2 *Important observation 2

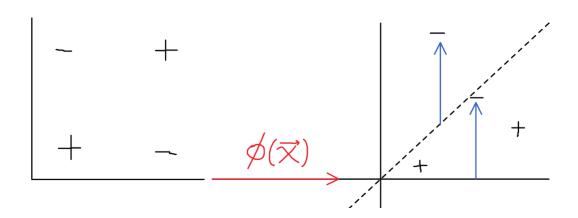
Maximization depends only on the dot products of sample vectors.

Decision rule:

$$if \quad \sum_{i} \alpha_{i} y_{i} \vec{x}_{i} \cdot \vec{u} + b \geq 0, \quad then +$$

3 Linearly inseparable instances

Apply transformation to sample vectors: $\phi(\vec{x})$ (In this case, convert the samples from 2d to 3d space)



Now the goal is:

$$max\{\phi(\vec{x}_i)\cdot\phi(\vec{x}_j)\}$$

And the decision rule contains:

$$\phi(\vec{x}_i) \cdot \phi(\vec{u}_j)$$

If we can find kernel function:

$$K(\vec{x}_i \cdot \vec{x_j}) = \phi(\vec{x}_i) \cdot \phi(\vec{x}_j)$$

Then we do not need the transformation ϕ . Because K provides the product of those 2 vectors in another space, I don't have to know the transformation ϕ .

4 Popular kernels

• linear kernel:

$$(\vec{u}\vec{v}+1)^n$$

• radio basis function(rbf):

$$e^{-\frac{||x_i-x_j||}{\sigma}}$$