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EE 329-01 F'24  
Group P  
2024-Sept-28

## EE 329 A2

This code is designed to validate the use of a keypad, using the same LED array used in A2. The code functions through polling to determine if a key is pressed, and if so, goes into a subroutine to determine which key is pressed by scrolling through each column, then each row. This program was helpful for organizing file structure in C, making various source and header files, as well as writing multiple #define statements to make code more legible.

### Link to YouTube Presentation:

<https://youtu.be/oWzriSy2BYs>

### Obtained Data:

Figure A2(a): 3x4 Keypad and 4xLED Wiring

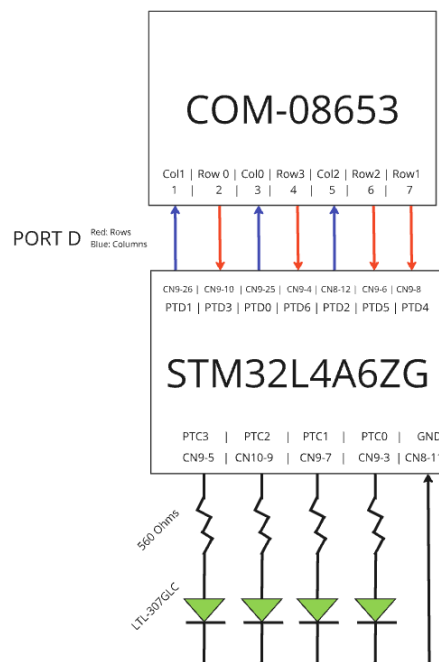


Table A2(a): Pull-Up/Pull-Down resistances found in pg.176 of STM32 Datasheet

| Resistance       | Min           | Nominal       | Max           |
|------------------|---------------|---------------|---------------|
| <b>Pull Up</b>   | 25 k $\Omega$ | 40 k $\Omega$ | 55 k $\Omega$ |
| <b>Pull Down</b> | 25 k $\Omega$ | 40 k $\Omega$ | 55 k $\Omega$ |

## Pseudocode Flow Chart:

### Main:

```

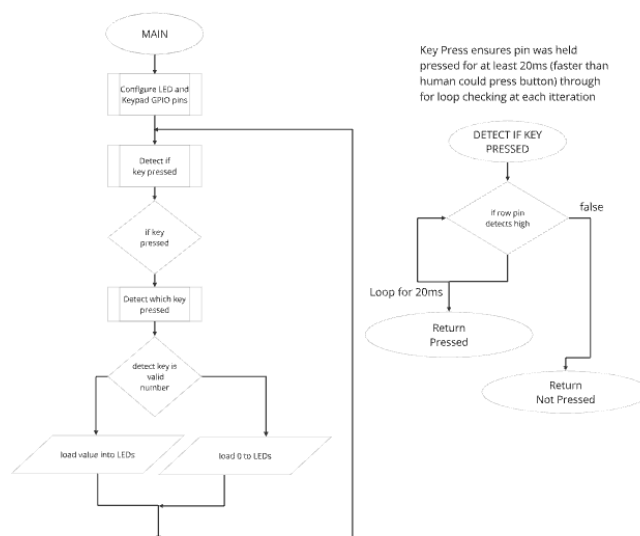
initializeLEDGPIO()
initializeKeypadGPIO()
loop
    ifKeyPressed
        detectWhichKeyPressed
            ifNotValid → display zero
            ifValid → display key pressed
    
```

### ifKeyPressed:

```

columns = high
poll rows
    if row high
        read high for 10ms (debounce)
            if high for 10ms → return pressed
            else → return not pressed
    
```

### MAIN AND DEBOUNCE OPERATIONS



## **Formatted Source Code main.h:**

```
-----  
main.h  
-----  
  
/**  
*****  
* @file           : main.h  
* project         : EE329 Lab A2  
* author          : Wyatt Tack (wwt) - wtack@calpoly.edu  
* date           : 9/27/2024  
* firmware        : ST-Link V1  
* @attention      : Copyright (c) 2024 STMicroelectronics. All rights  
reserved.  
*****  
*  
*   main header for defines for C and stm32 headers/hal  
*  
*****  
*/  
  
#ifndef __MAIN_H  
#define __MAIN_H  
  
#ifdef __cplusplus  
extern "C" {  
#endif  
  
/* Includes -----*/  
#include "stm32l4xx_hal.h"  
  
/* Exported functions prototypes -----*/  
void SystemClock_Config(void);  
void Error_Handler(void);  
  
#ifdef __cplusplus  
}  
#endif  
  
#endif
```

## Formatted Source Code main.c:

```
/**
 * *****
 * @file      : main.c
 * project    : EE329 Lab A2
 * author     : Wyatt Tack (wvt) - wtack@calpoly.edu
 * date       : 9/27/2024
 * firmware   : ST-Link V1
 * @attention : Copyright (c) 2024 STMicroelectronics. All rights reserved.
 * *****
 *
 * Takes in input from 3x4 (0-9 *#) keypad, then writes the hex value of the
 * number to the LED array. LEDs display 0 if glitch, LEDs display 0xF for 0,
 * 0xA for *, and 0xC for #
 *
 * Keypad defined at GPIOC Col PTC0-2, Row PTC3-6
 * LEDs defined at GPIOC PTC0-3
 * *****
 */

#include "main.h"
#include "keypad.h"
void Led_Config(void);

int main(void)
{
    // Initialize system clock, keypad registers, led registers, and held value
    HAL_Init();
    SystemClock_Config();
    Keypad_Config();
    Led_Config();
    //uint8_t currentKeyValue = 0;
    //GPIOC->BSRR = GPIO_PIN_0;
    while (1)
    {
        if (Keypad_IsAnyKeyPressed())
        {
            if (Keypad_WhichKeyPressed() > 0 && Keypad_WhichKeyPressed() < 16) {
                //currentKeyValue = Keypad_WhichKeyPressed();
                //GPIOC->ODR = (currentKeyValue);
                GPIOC->ODR = Keypad_WhichKeyPressed();
            }
            else
                GPIOC->ODR = (0x0);
        }
    }
}

//***** ledConfig *****/
void Led_Config(void)
{
    // configure GPIO pins PC0-3 for:
    // output mode, push-pull, no pull up or pull down, high speed
    RCC->AHB2ENR |= (RCC_AHB2ENR_GPIOCEN);
    GPIOC->MODER  &= ~(GPIO_MODER_MODE0 | GPIO_MODER_MODE1
                                                                | GPIO_MODER_MODE2 | GPIO_MODER_MODE3);
    GPIOC->MODER |= (GPIO_MODER_MODE0 | GPIO_MODER_MODE1_0
                                                                | GPIO_MODER_MODE2_0 | GPIO_MODER_MODE3_0);
    GPIOC->OTYPER &= ~(GPIO_OTYPER_OT0 | GPIO_OTYPER_OT1
                                                                | GPIO_OTYPER_OT2 | GPIO_OTYPER_OT3);
    GPIOC->PUPDR  &= ~(GPIO_PUPDR_PUPD0 | GPIO_PUPDR_PUPD1
                                                                | GPIO_PUPDR_PUPD2 | GPIO_PUPDR_PUPD3);
    GPIOC->OSPEEDR |= ((3 << GPIO_OSPEEDR_OSPEED0_Pos) |
                      (3 << GPIO_OSPEEDR_OSPEED1_Pos) |
                      (3 << GPIO_OSPEEDR_OSPEED2_Pos) |
                      (3 << GPIO_OSPEEDR_OSPEED3_Pos));
    GPIOC->BRR = (GPIO_PIN_0 | GPIO_PIN_1
                                                                | GPIO_PIN_2 | GPIO_PIN_3);
}

// System
void SystemClock_Config(void)
{
    RCC_OscInitTypeDef RCC_OscInitStruct = {0};
    RCC_ClkInitTypeDef RCC_ClkInitStruct = {0};

    /** Configure the main internal regulator output voltage
    */
    if (HAL_PWREx_ControlVoltageScaling(PWR_REGULATOR_VOLTAGE_SCALE1) != HAL_OK)
    {
        Error_Handler();
    }

    /** Initializes the RCC Oscillators according to the specified parameters
    * in the RCC_OscInitTypeDef structure.
    */
    RCC_OscInitStruct.OscillatorType = RCC_OSCILLATORTYPE_MSI;
    RCC_OscInitStruct.MSISState = RCC_MSI_ON;
    RCC_OscInitStruct.MSICalibrationValue = 0;
    RCC_OscInitStruct.MSIClockRange = RCC_MSIRANGE_6;
    RCC_OscInitStruct.PLL.PLLState = RCC_PLL_NONE;
    if (HAL_RCC_OscConfig(&RCC_OscInitStruct) != HAL_OK)
    {
        Error_Handler();
    }

    /** Initializes the CPU, AHB and APB buses clocks
    */
    RCC_ClkInitStruct.ClockType = RCC_CLOCKTYPE_HCLK|RCC_CLOCKTYPE_SYSCLK
                                  |RCC_CLOCKTYPE_PCLK1|RCC_CLOCKTYPE_PCLK2;
    RCC_ClkInitStruct.SYSCLKSource = RCC_SYSCLKSOURCE_MSI;
    RCC_ClkInitStruct.AHBCLKDivider = RCC_SYSCLK_DIV1;
    RCC_ClkInitStruct.APB1CLKDivider = RCC_HCLK_DIV1;
    RCC_ClkInitStruct.APB2CLKDivider = RCC_HCLK_DIV1;

    if (HAL_RCC_ClockConfig(&RCC_ClkInitStruct, FLASH_LATENCY_0) != HAL_OK)
    {
        Error_Handler();
    }
}

void Error_Handler(void)
{
    __disable_irq();
    while (1)
    {
    }
}

#ifdef USE_FULL_ASSERT
void assert_failed(uint8_t *file, uint32_t line)
{
}
#endif
```

## Formatted Source Code keypad.h:

```
-----
keypad.h
-----

/**
 * *****
 * @file           : keypad.h
 * project          : EE329 Lab A2
 * author           : Wyatt Tack (wyt) - wtack@calpoly.edu
 * date            : 9/27/2024
 * firmware         : ST-Link V1
 * @attention       : Copyright (c) 2024 STMicroelectronics. All rights
reserved.
 * *****
 *
 *   main header for defines for keypad.h
 *
 * *****
 */

#ifndef INC_KEYPAD_H_
#define INC_KEYPAD_H_
#include "stm32l4xx_hal.h"

//----- KEYPAD Defines -----
#define COL_PORT GPIOD
#define COL_PINS (GPIO_PIN_0 | GPIO_PIN_1 | GPIO_PIN_2)
#define ROW_PORT GPIOD
#define ROW_PINS (GPIO_PIN_3 | GPIO_PIN_4 | GPIO_PIN_5 | GPIO_PIN_6)
#define SETTLE 1900 //defined as time for 20ms loop instruction (*5.5us)

#define BIT0_COL GPIO_PIN_0 //defined as first bit for columns
#define BIT0_ROW GPIO_PIN_3 //defined as first bit for rows
#define NUM_COLS 3
#define NUM_ROWS 4
#define NO_KEYPRESS 0x0
#define KEY_ZERO 11
#define CODE_ZERO 0xF

//----- function prototypes -----
void Keypad_Config(void);
int Keypad_IsAnyKeyPressed(void);
int Keypad_WhichKeyPressed(void);

#endif /* INC_KEYPAD_H_ */
```

## Formatted Source Code keypad.c:

```
/**
 * @file : keypad.c
 * project : EE329 Lab A2
 * author : Wyatt Tack (wtt) - wtack@calpoly.edu
 * date : 9/27/2024
 * firmware : ST-Link V1
 * @attention : Copyright (c) 2024 STMicroelectronics. All rights reserved.
 */
/*
 * Keypad pulling function source file provided on behalf of the EE329 lab
 * manual. Adapted from EE329 lab manual.
 */
#include "keypad.h"

// ----- modified from excerpt from keypad.c -----
void Keypad_Config(void) { // must be manually changed if separate GPIO port is used

    // set for port D as current config
    // Port clock initialize
    RCC->AHB2ENR |= (RCC_AHB2ENR_GPIODEN);
    // Column pin initialize - Push Pull, no PU/PD, high speed
    COL_PORT->MODER &= ~(GPIO_MODER_MODE0 | GPIO_MODER_MODE1 | GPIO_MODER_MODE2);
    COL_PORT->MODER |= (GPIO_MODER_MODE0_0 | GPIO_MODER_MODE1_0 | GPIO_MODER_MODE2_0);
    COL_PORT->OTYPER &= ~(GPIO_OTYPER_OT0 | GPIO_OTYPER_OT1 | GPIO_OTYPER_OT2 | GPIO_OTYPER_OT3);
    COL_PORT->PUPDR &= ~(GPIO_PUPDR_PUPD0 | GPIO_PUPDR_PUPD1 | GPIO_PUPDR_PUPD2 | GPIO_PUPDR_PUPD3);
    COL_PORT->OSPEEDR |= ((GPIO_OSPEEDR_OSPEED0 | GPIO_OSPEEDR_OSPEED1 | GPIO_OSPEEDR_OSPEED2));
    // Row pin initialize - Input, pull down
    ROW_PORT->MODER &= ~(GPIO_MODER_MODE3 | GPIO_MODER_MODE4 | GPIO_MODER_MODE5 | GPIO_MODER_MODE6);
    ROW_PORT->PUPDR &= ~(GPIO_PUPDR_PUPD3 | GPIO_PUPDR_PUPD4 | GPIO_PUPDR_PUPD5 | GPIO_PUPDR_PUPD6);
    ROW_PORT->PUPDR |= (GPIO_PUPDR_PUPD3_1 | GPIO_PUPDR_PUPD4_1 | GPIO_PUPDR_PUPD5_1 | GPIO_PUPDR_PUPD6_1);
}

// -----
int Keypad_IsAnyKeyPressed(void) {
    // drive all COLUMNS HI; see if any ROWS are HI
    // return true if a key is pressed, false if not
    COL_PORT->BSRR = COL_PINS; // set all columns HI
    for (uint16_t idx=0; idx<SETTLE; idx++) { // let it settle
        ;
    }
    if ((ROW_PORT->IDR & ROW_PINS) != 0) { // got a keypress!
        for (uint16_t idx=0; idx<SETTLE; idx++) {
            if ((ROW_PORT->IDR & ROW_PINS) == 0) return(0); // if key held for 20ms then return 1 (debounce)
        }
        return(1);
    }
    else
        return(0); // nope.
}

// -----
int Keypad_WhichKeyPressed(void) {
    // detect and encode a pressed key at {row,col}
    // assumes a previous call to Keypad_IsAnyKeyPressed() returned TRUE
    // verifies the Keypad_IsAnyKeyPressed() result (no debounce here),
    // determines which key is pressed and returns the encoded key ID
    int8_t iRow=0, iCol=0, iKey=0; // keypad row & col index, key ID result
    int8_t bGotKey = 0; // bool for keypress, 0 = no press

    COL_PORT->BSRR = COL_PINS; // set all columns HI
    for (iRow = 0; iRow < NUM_ROWS; iRow++) { // check all ROWS
        if (ROW_PORT->IDR & (BIT0_ROW << iRow)) { // keypress in iRow!!
            COL_PORT->BSRR = (COL_PINS); // set all cols LO
            for (iCol = 0; iCol < NUM_COLS; iCol++) { // 1 col at a time
                COL_PORT->BSRR = (BIT0_COL << iCol); // set this col HI
                if (ROW_PORT->IDR & (BIT0_ROW << iRow)) { // keypress in iCol!!
                    bGotKey = 1;
                    break; // exit for iCol loop
                }
            }
            if (bGotKey)
                break;
        }
    }
    // encode {iRow,iCol} into LED word : row 1-3 : numeric, '1'-'9'
    // row 4 : '*'=10, '0'=15, '#'=12
    // no press: send NO_KEYPRESS
    if (bGotKey) {
        iKey = (iRow * NUM_COLS) + iCol + 1; // handle numeric keys ...
        if (iKey == KEY_ZERO) // works for '*', '#' too
            iKey = CODE_ZERO;
        return(iKey); // return encoded keypress
    }
    return( NO_KEYPRESS ); // unable to verify keypress
}
```