

# Wyatt McAllister

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## EDUCATION

### UNIVERSITY OF ILLINOIS

#### PH.D. IN ELECTRICAL ENGINEERING

May 2020 | Urbana-Champaign, IL

Conc. in Control and Data Science

Cur. Cum. GPA: 4.0 / 4.0

### UNIVERSITY OF ILLINOIS

#### MS IN ELECTRICAL ENGINEERING

May 2018 | Urbana-Champaign, IL

Conc. in Control and Data Science

Cum. GPA: 4.0 / 4.0

#### BS IN ELECTRICAL ENGINEERING

May 2016 | Urbana-Champaign, IL

Conc. in Control Systems

College of Engineering

Cum. GPA: 3.92 / 4.0

## LINKS

<https://wyattsmcall1.github.io>

## COURSEWORK

### GRADUATE

Autonomous Decision Making, MDPs and Reinforcement Learning, Stochastic Control, Statistical Learning Theory, Random Processes, Nonlinear Control, State Space Control (*Research Asst.*)

### UNDERGRADUATE

Control Systems, Intro to Robotics, Digital Systems Laboratory, Fields and Waves, Microelectronic Circuits, Semiconductor Devices, Intro to Power Electronics, Probability with Engineering Applications, Analog and Digital Signal Processing, Intro to Computing Systems

## SKILLS

### SOFTWARE

C++ • C • Java • MatLab • Python  
Mathematica •  $\LaTeX$  • Photoshop

### HARDWARE

ROS • System Verilog • OpenCV •  
EagleCAD PCB Design • Control Design

### LANGUAGE

Spanish: Full Professional Proficiency

## PROFESSIONAL EXPERIENCE

### MICROSOFT SURFACE HUB | SUMMER HARDWARE INTERN

May–August 2015 | Portland, OR

- Used capabilities studies to improve accuracy of vision system used in the manufacturing process
- Designed a custom testing fixture for the incoming quality control of power supplies

### VIEW RAY INCORPORATED | SUMMER HARDWARE INTERN

May–August 2014 | Oakwood Village, OH

- Worked on a system for MRI targeted radiation therapy to prevent the irradiation of healthy tissues
- Created a fiber optic cable testing box to efficiently measure data flow in the system

## RESEARCH

### DISTRIBUTED AUTONOMOUS SYSTEMS LAB | RESEARCHER

May 2017–Present | Champaign-Urbana, IL

- Designed a multi-agent planning algorithm for robotic weed killing, with an associated simulation framework including a realistic weed growth model

### ADVANCED CONTROLS RESEARCH LAB | RESEARCHER

August 2016–May 2017 | Champaign-Urbana, IL

- Created a ROS software interface for the Automation Supporting Prolonged Independent Residence for the Elderly (ASPIRE) program

### BRETL GROUP | UNDERGRADUATE RESEARCHER

August–December 2015 | Champaign-Urbana, IL

- Designed a testing fixture for experiments for extending the one-dimensional model for a deformable rod to a model of two dimensional objects with planar deformation

## PUBLICATIONS

- [1] W. McAllister, D. Osipych, G. Chowdhary, and A. Davis. Multi-agent planning for coordinated robotic weed killing. In *Intelligent Robots and Systems (IROS)*, 2018 IEEE/RSJ International Conference on. IEEE, 2018.

### UNIVERSITY OF ILLINOIS | GRADUATE TEACHING ASSISTANT

August 2016 - May 2018 | Champaign-Urbana, IL

- Fields and Waves I (ECE329) with Dr. Lynford Goddard
- Principles of Experimental Research (ECE446) with Dr. Lynford Goddard
- Introduction to Digital Signal Processing (ECE310) with Dr. Yoram Bresler and Dr. Stephen Levinson

## AWARDS

2018	Shun Lien Chuang Memorial Award in ECE	Top 1/503
2016	Highest Honors	GPA >3.8/4.0
2016	John Bardeen Award in ECE	Top 1/2500
2014-2018	Dean's List	Top 20th Percentile

## SOCIETIES

2016	Tau Beta Pi Engineering Honor Society	Top 12th Percentile
2015	Eta Kappa Nu IEEE Honor Society	Top 25th Percentile