

# Distributed Training

Machine Learning Operations
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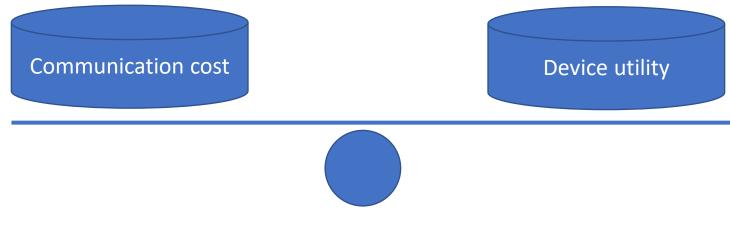
## What is distributed computations?



### Computing on multiple threads/devices/nodes in parallel

We focus on training as it is the most computationally expensive part but doing testing or inference can also be done in distributed manner

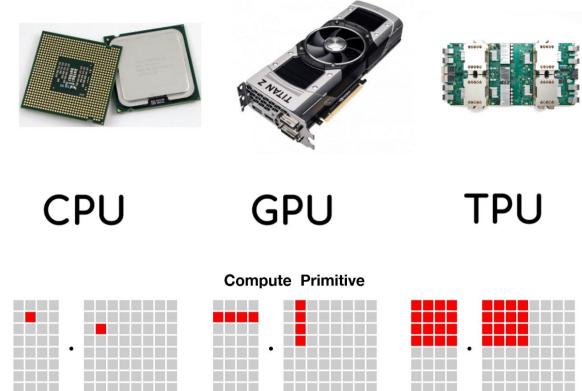
Distributed computing is not always beneficial:



### Devices



- Three types of devices
  - CPU
    - General compute unit
    - 2-128 threads
  - GPU
    - Rendering unit
    - 1000-10000 threads
  - TPU
    - Specialized unit
    - 8-2048 threads



vector

tensor

scalar

### Memory

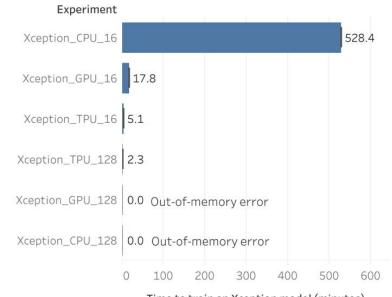


# Equally important to what device you are using, is the amount of memory that you have available

### With more memory

- Faster data transfer
- Higher data modality
- Larger models

	СРИ	GPU	TPU
Standard	32-64 GiB	12 GiB	64 GiB
Maximum	256 GiB	24 GiB	32 TiB



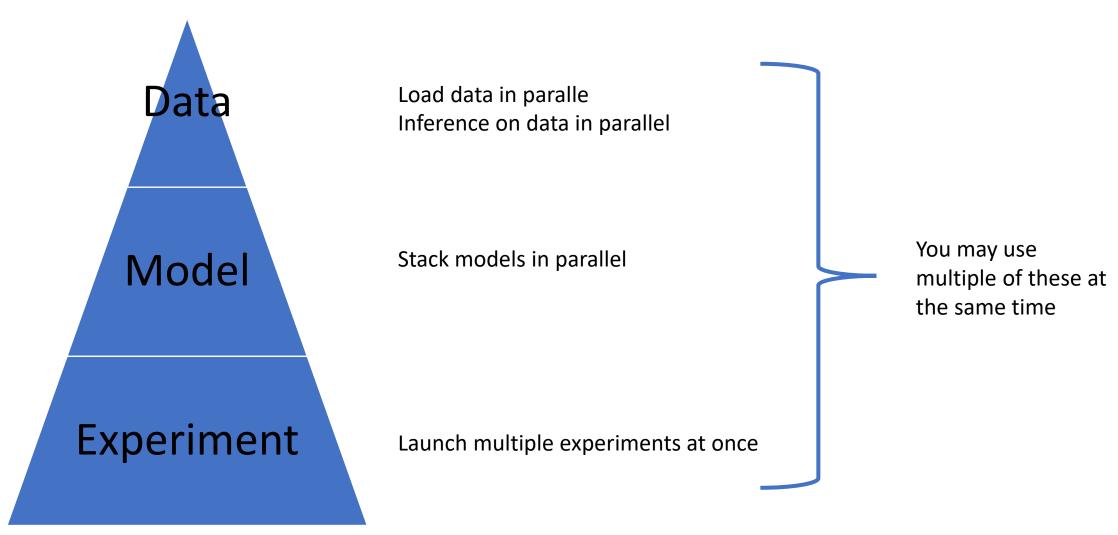
Time to train an Xception model (minutes)

Figure 3: CPUs vs GPUs vs TPUs for training an Xception model for 12 epochs. Y-Axis labels indicate the choice of model, hardware, and batch size for each experiment. Increasing the batch size to 128 for TPUs resulted in an additional ~2x speedup.

https://towardsdatascience.com/when-to-use-cpus-vs-gpus-vs-tpus-in-a-kaggle-competition-9af708a8c3eb

## Many layers of distributed computations



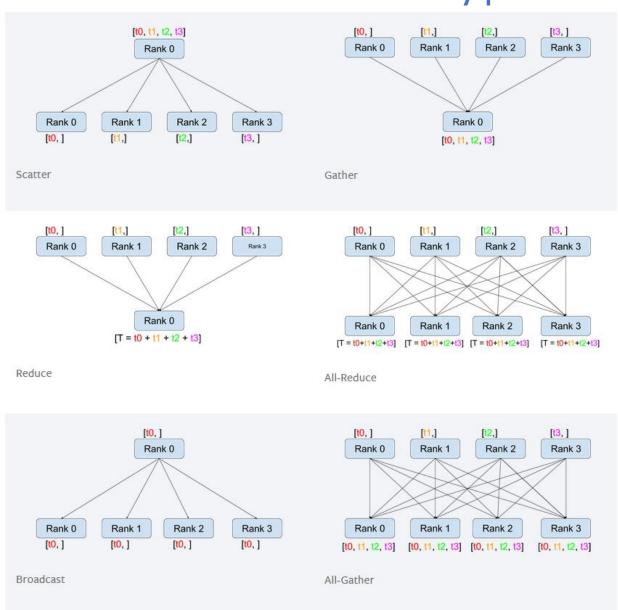


## The six imporatnt communication types

MLOps

Rank 0: master/main

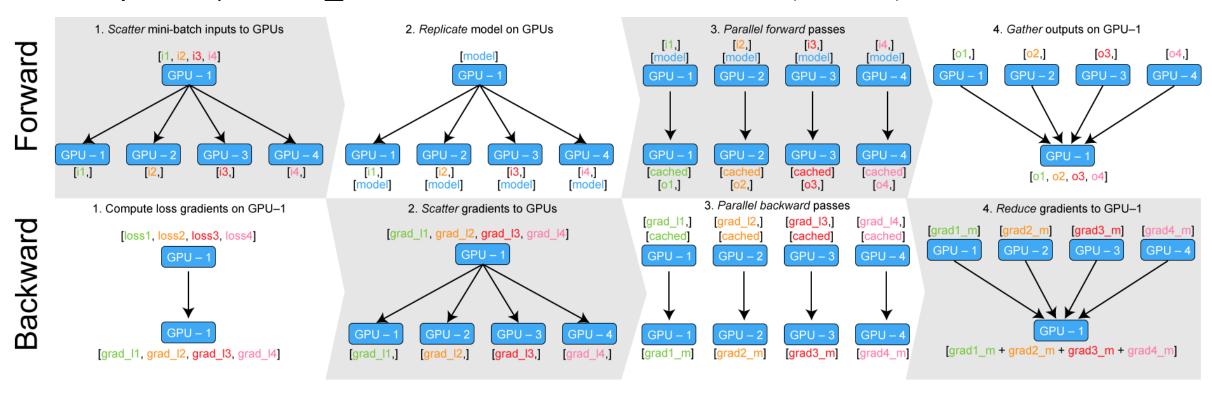
Rank > 0: slave/spawed



## Data Parallel: one process controls all



### Simple as parallel model = torch.nn.DataParallel(model)

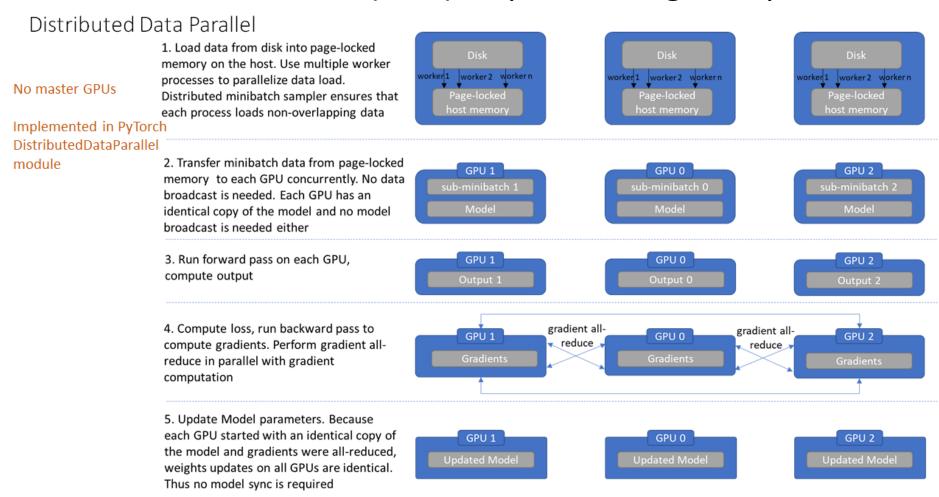


Note that only GPU-1 parameters are updated, the replicas are destroyed after backward

### Distributed Data Parallel



### In Distributed Data Parallel (DDP) all processes gets equal workload

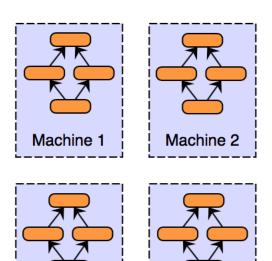


## Model paralliseme



### When your model is too big for one device

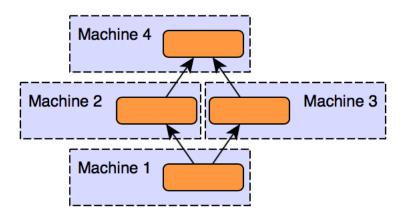
#### **Data Parallelism**



Machine 4

Machine 3

#### Model Parallelism



### How to do this in practise



### DataParallel

parallel\_model = torch.nn.DataParallel(model)

### Distributed Data Parallel

- Set a environment MASTER\_ADDR and MASTER\_PORT
- Init a process group
- parallel\_model = nn.parallel.DistributedDataParallel(model, device\_ids=[gpu]
- Use mp.spawn to spawn multiple processes
- •

### Model parallizeme

• A shit ton of tensor.to('cuda:x') calls

## Seperating engineering and research code



Getting code to run in parallel has somewhat become a research task!

However maybe it should not be like that?

### Research Code

```
11 = nn.Linear(...)
12 = nn.Linear(...)
decoder = Decoder()

x1 = 11(x)
x2 = 12(x2)
out = decoder(features, x)

loss = perceptual_loss(x1, x2, x) + CE(out, x)
```

### Engineering code

```
model.cuda(0)
x = x.cuda(0)

distributed = DistributedParallel(model)

with gpu_zero:
    download_data()

dist.barrier()
```

Spend time on research code and not engineering code!

## Why using a training framework



Spend time on research code and not engineering code

→ Why training frameworks exist!

- Reduce boilerplate = increase turn-around time
- Focus on what is important
- Reproducibility
- Shareability
- Consistency
- Scalability

### Training Fremworks





Many frameworks exist for reducing boilerplate



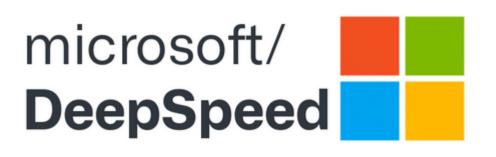




Many frameworks for accelerating training







## Pytorch Lightning



#### PyTorch

```
class MNISTClassifier(nn.Module):
  def __init__(self):
      self.layer 1 = torch.nn.Linear(28 * 28, 128)
      self.layer_2 = torch.nn.Linear(128, 10)
  def forward(self, x):
   x = x.view(x.size(0), -1)
   x = self.layer_1(x)
   x = F.relu(x)
   x = self.layer_2(x)
    return x
# download data
if global rank == 0:
 mnist_train = MNIST(os.getcwd(), train=True, download=True)
 mnist_test = MNIST(os.getcwd(), train=False, download=True)
dist.barrier()
# transforms
transform=transforms.Compose([transforms.ToTensor(),
                           transforms.Normalize((0.1307,), (0.3081,))])
mnist_train = MNIST(os.getcwd(), train=True, transform=transform)
mnist_test = MNIST(os.getcwd(), train=False, transform=transform)
mnist_train, mnist_val = random_split(mnist_train, [55000, 5000])
mnist_test = MNIST(os.getcwd(), train=False, download=True)
# build dataloaders
mnist_train = DataLoader(mnist_train, batch_size=64)
mnist_val = DataLoader(mnist_val, batch_size=64)
mnist_test = DataLoader(mnist_test, batch_size=64)
optimizer = torch.optim.Adam(pytorch_model.parameters(), lr=1e-3)
def cross_entropy_loss(logits, labels):
 return F.nll_loss(logits, labels)
num_epochs = 1
for epoch in range(num_epochs):
  for train_batch in mnist_train:
    x, y = train_batch
    logits = pytorch_model(x)
    loss = cross_entropy_loss(logits, y)
    print('train loss: ', loss.item())
    loss.backward()
    optimizer.step()
   optimizer.zero_grad()
  model.eval()
  with torch.no_grad():
    val_loss = []
    for val_batch in mnist_val:
      x, y = val batch
      logits = pytorch_model(x)
      val_loss.append(cross_entropy_loss(logits, y).item())
    avg_val_loss = torch.stack(val_loss).mean()
  model.train()
```

Its just reorganized Pytorch code!

Two core objects

- Lightning Module
  - Training, validation, test logic
  - Optimizer
- Trainer
  - The "rest"

trainer.fit(model) does the heavy lifting

## What you get for free



#### Multi-GPU, multi-node

```
# 8 GPUs
# no code changes needed
trainer = Trainer(max_epochs=1, gpus=8)
# 256 GPUs
trainer = Trainer(max_epochs=1, gpus=8, num_nodes=32)
```

#### 16 bit precision

```
# no code changes needed
trainer = Trainer(precision=16)
```

#### TPU training

```
# no code changes needed
trainer = Trainer(tpu_cores=8)
```

#### **Experiment managers**

```
from pytorch_lightning import loggers

logger = loggers.TensorBoardLogger('logs/')
logger = loggers.WandbLogger()
logger = loggers.CometLogger()
logger = loggers.MLFlowLogger()
logger = loggers.NeptuneLogger()
# ... and many more

trainer = Trainer(logger=logger)
```

### What you get for free



#### **Early stopping**

```
es = EarlyStopping(monitor='val_loss')
trainer = Trainer(callbacks=[es])
```

#### Model Checkpoint

```
checkpointing = ModelCheckpoint(monitor='val_loss')
trainer = Trainer(callbacks=[checkpointing])
```

#### 40+ tricks and extensions

```
trainer = Trainer(
    max_epochs=10,
    auto_lr_find=True,
    gradient_clip_val=1.0,
    accumulate_grad_batches=10,
    max_steps=1000
    #... 40+ tricks and extensions
)
```

#### **Arbitrary functionality**

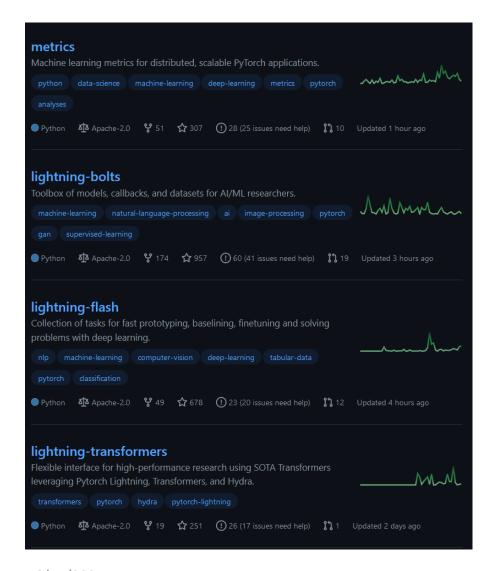
```
# add arbitrary functionality
class MyNotifier(pl.Callback):

    def on_train_epoch_start(trainer, pl_module):
        slack.post('training started!')

notifier = MyNotifier()
trainer = Trainer(callbacks=[notifier])
```

### What else do we offer?





All the metrics you need to measure the quality of your ML model in Pytorch

SOTA implementation of selected models

Easy-to-get-started tasks and models for fast prototyping

Transformer models in Lightning (for all NLP lovers)

## Todays exercises



- Format your code using pytorch-lightning
  - https://pytorch-lightning.readthedocs.io/en/latest/
  - https://pytorch-lightning.readthedocs.io/en/latest/starter/converting.html

Make it run on multi-gpu

## Meme of the day



