VM 250 Computational Lab Sessions Lab #3

Virtual Manufacturing with UniGraphics (UG)

Prepared by TA Group





Contents



1. Setup

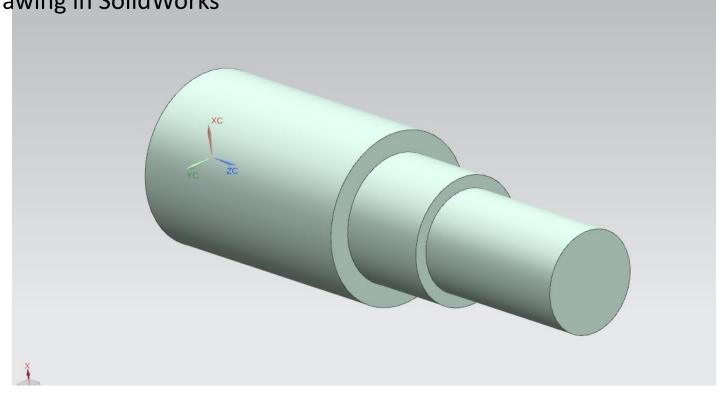
- Import a Parasolid file in UG from a drawing in SolidWorks
- Go to the manufacturing module
- Analyze the part.
 - Length (Analysis)
- Define geometry
 - Verify the coordinate systems
 - > Define the blank
 - Define part geometry
- Create avoidance geometry
- Create tools

2. Program

- Create operation
- Stepover's cut depth
- Simulate machine

3. Output

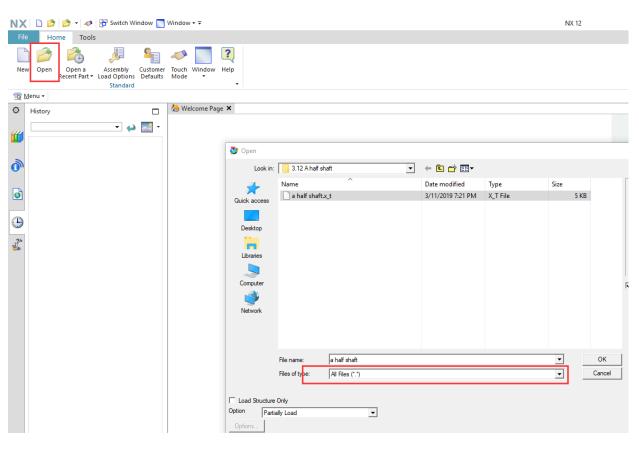
Post process

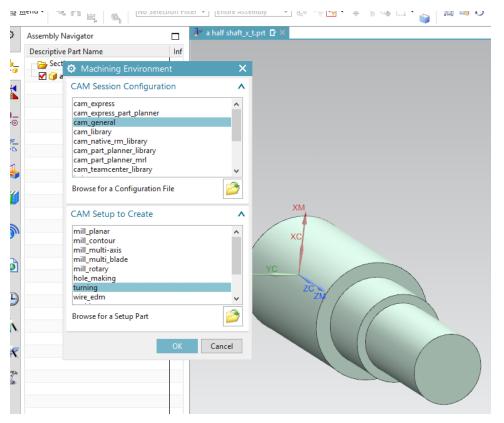


Import a Parasolid file in UG from a drawing in SolidWorks



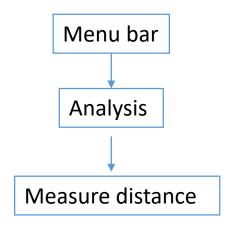
- Import a Parasolid file in UG from a drawing in SolidWorks
 - A. Save the previous shaft created in SolidWorks as Parasolid (*.x_t)
 - B. Open this file (*.x_t) in UG.
 - C. Go to the manufacturing module and choose cam_general and turning on the Machining Environment.

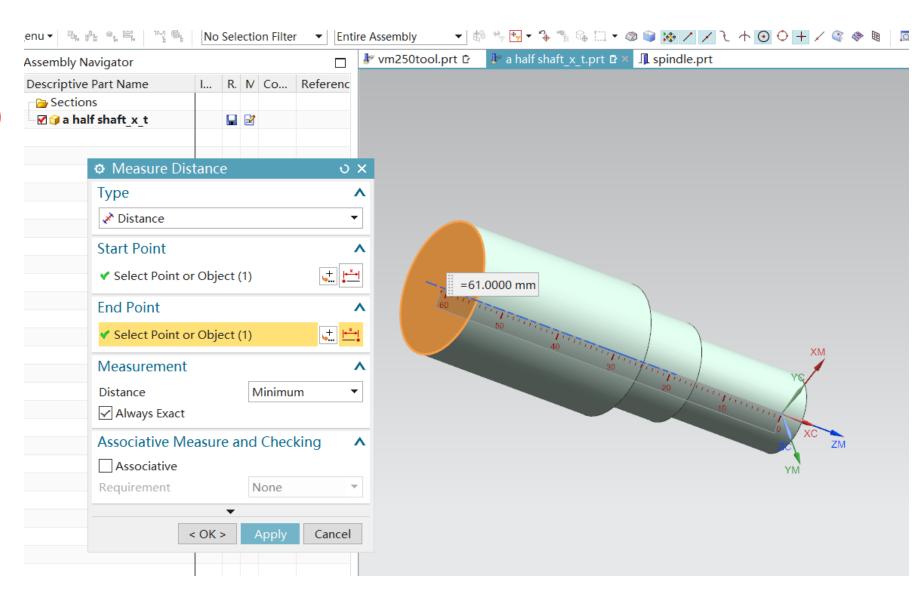






- Analyze the part.
 - Length (Analysis)

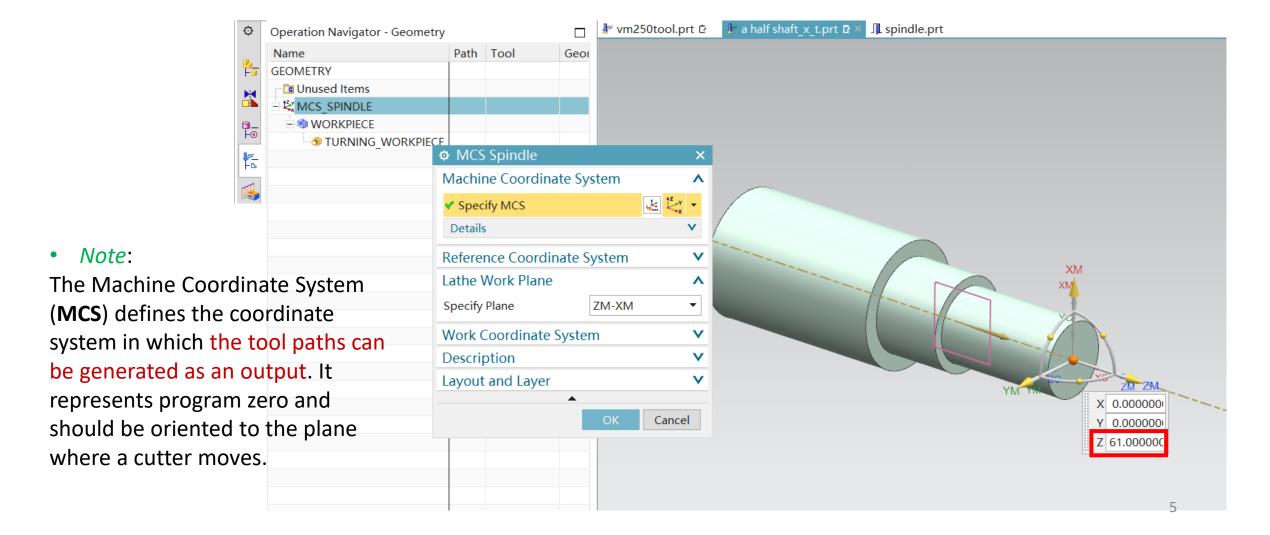






Define geometry

Verify the machine coordinate systems (MCS)





Define geometry

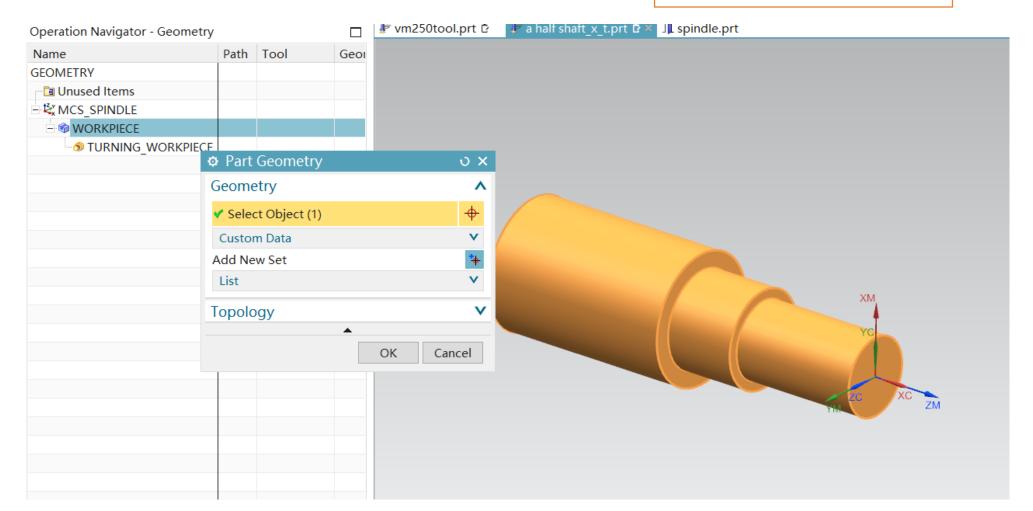
Define part geometry

1. Right click Workpiece

2.Edit

3. Part Geometry

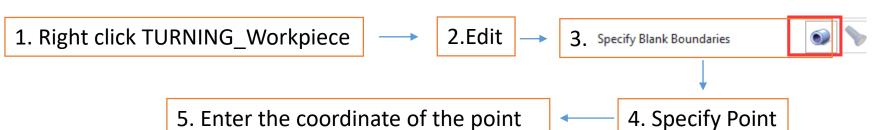
4. Select the shaft as object

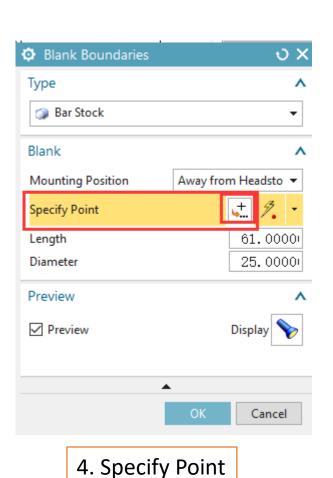


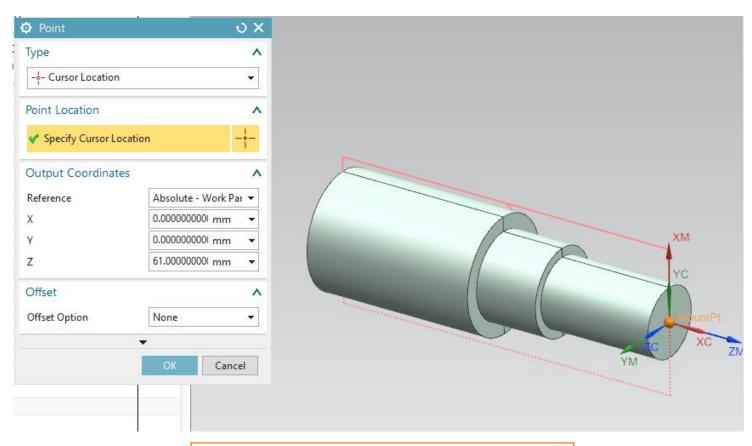


Define geometry

Define the blank







5. Enter the coordinate of the point

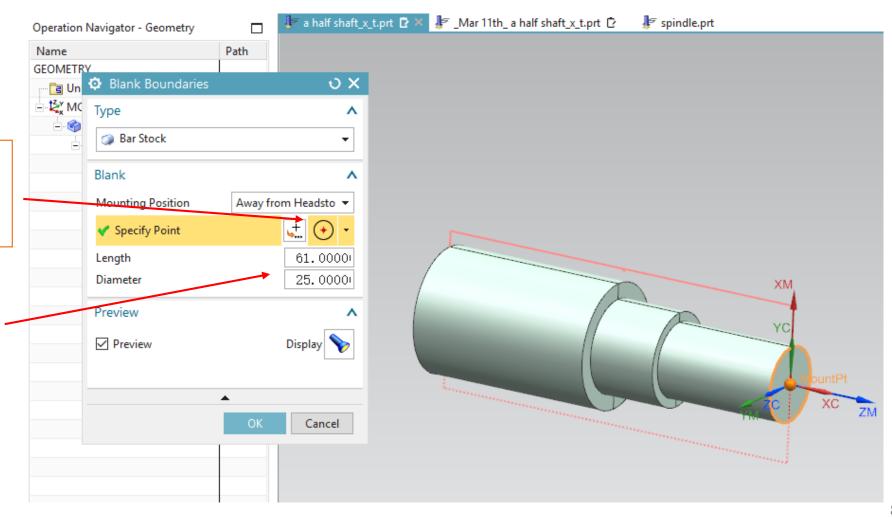


Define geometry

• Define the blank

6. Set a point as Arc/Ellipse/Sphere center

7. Modify parameters





Create avoidance geometry

Define start and return points

1. Right click "Turning _ Workpiece"

2. Insert |

3. Geometry

Avoidance Legend From Point (FR) Motion to Start Point (ST) Motion Type Point Option ✓ Specify Point Approach (AP) υX Point Motion to Start of Engage ∠ Direct Motion Type X=12 - - Cursor Location Departure (DP) Point Location Motion to Return Point / Clearance (... Specify Cursor Location None Motion Type Coordinates Motion to Gohome Point (GH) Reference Clearance Planes Preview Display 📎 ✓ Preview Offset Offset Option Cancel Cancel

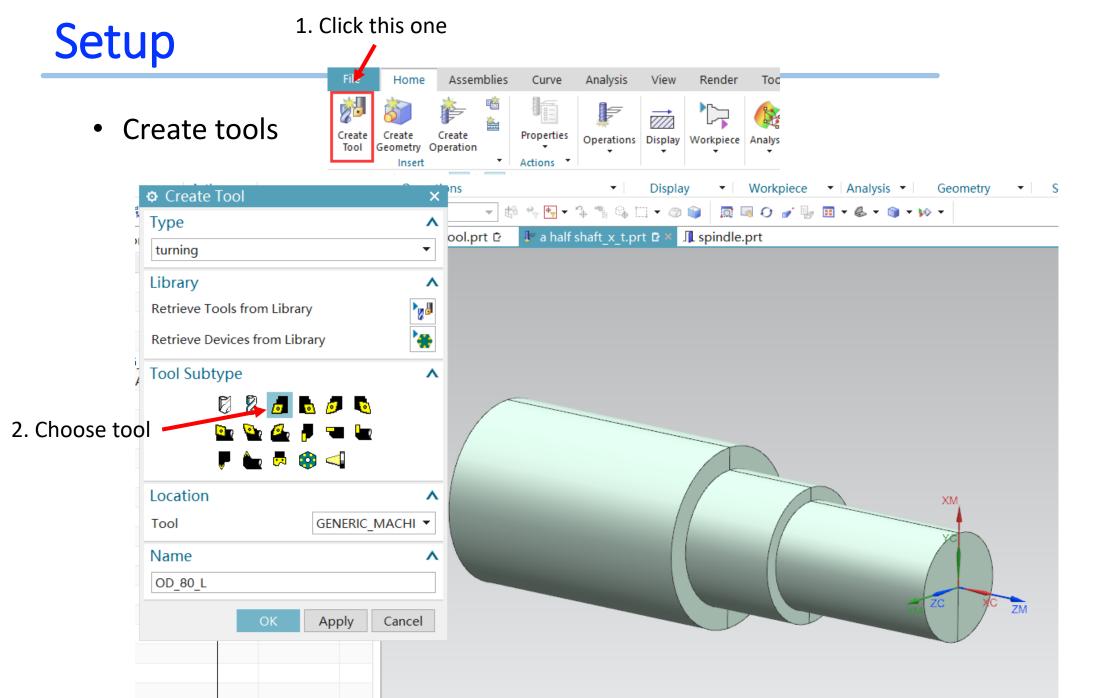
Legend From Point (FR) Motion to Start Point (ST) ✓ Direct Motion Type Point Option Point ✓ Specify Point Approach (AP) Motion to Start of Engage Motion Type ∠ Direct Departure (DP) Motion to Return Point / Clearance (... Motion Type ∠. Direct Point Option Same as Start Motion to Gohome Point (GH) Clearance Planes Preview Display 📎 ✓ Preview Cancel

Avoidance

4. Choose AVOIDANCE as Geometry Subtype

5. Set the motion type and specify point

6. Same start and return point





And click OK



Create tools

Turning Tool-Standard

Tool Holder Tracking More Insert Analysis ▼ ISO Insert Shape C (Diamond 80) Topside Insert Position ool.prt 🖸 🧦 a half shaft x t.prt 🗈 × 🎵 spindle.prt Legend Dimensions Nose Angle 80.0 1. 2000 (R) Nose Radius 5. 0000 (OA) Orient angle R4 R3 Insert Size Verify these parameters **Cutting Edge** Measurement 15.0000 Length More Description R1_P3_0 Ļ Material: CARBIDE Numbers 0 Tool Number Information Librai Preview ✓ Preview Display 📎 Cancel Translate origin

Application

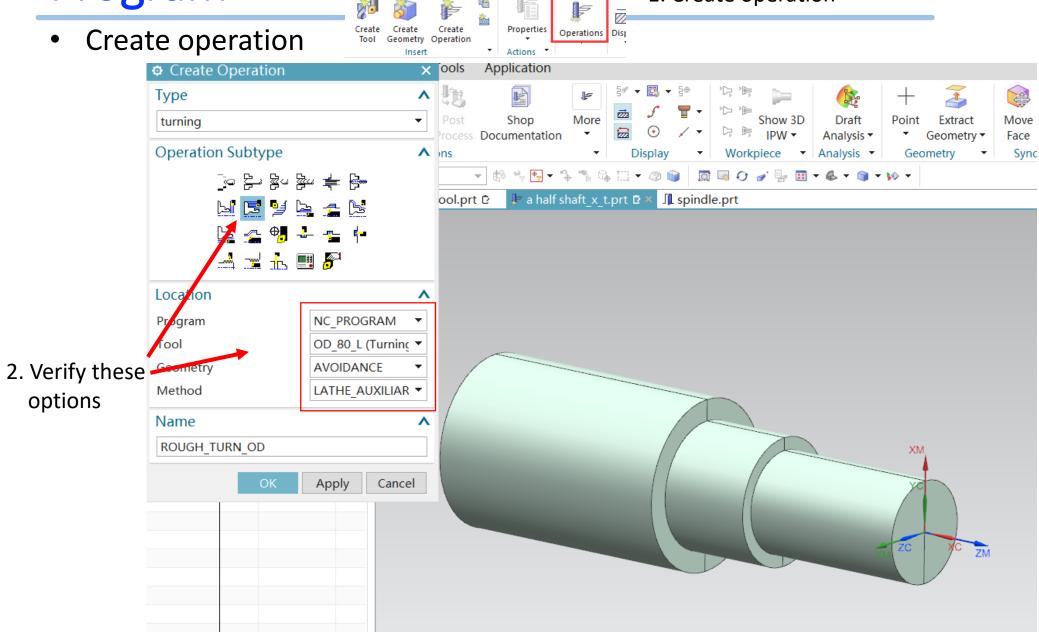
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Program





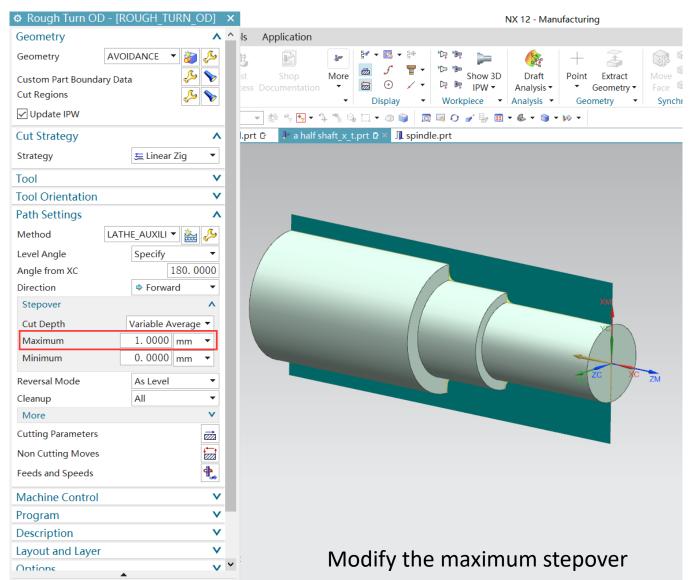


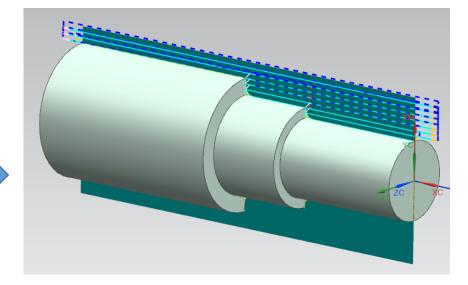


Program



Set stepover's maximum cut depth



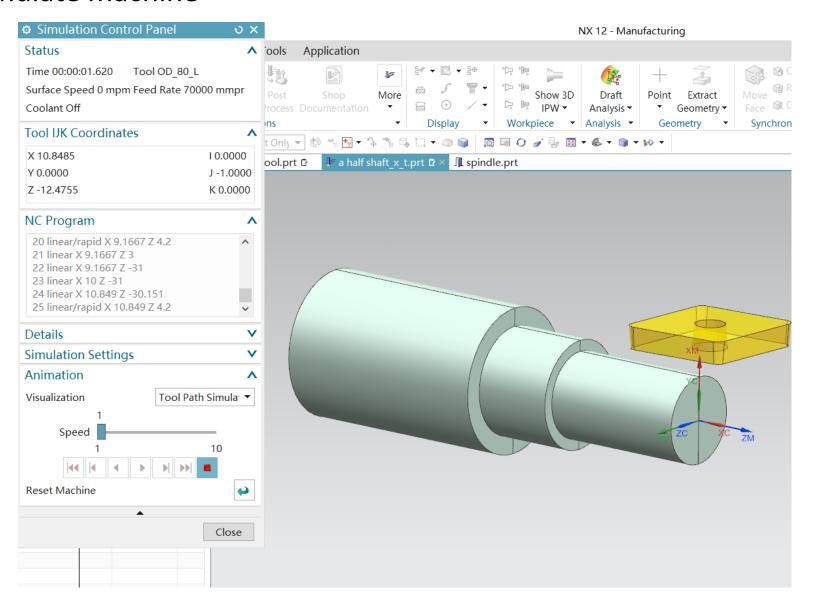


Generate the operation

Program



Simulate machine



Output



Post process

