

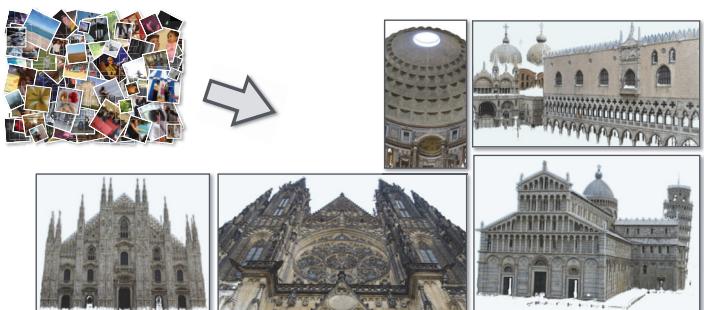
# Pixelwise View Selection for Unstructured Multi-View Stereo

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## Overview

This work presents an **open source Multi-View Stereo** system for **robust** and **efficient** dense modeling from **unstructured image collections**. Experiments on benchmarks and large-scale Internet photo collections demonstrate **state-of-the-art performance** in terms of accuracy, completeness, and efficiency.



## Contributions

### Joint depth - normal - occlusion inference

embedded in improved PatchMatch sampling scheme

### Pixelwise view selection

using photometric and geometric priors

### Multi-view geometric consistency

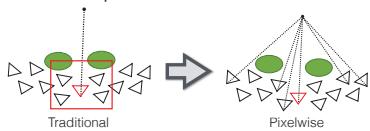
for simultaneous refinement and image-based fusion

### Graph-based filtering and fusion

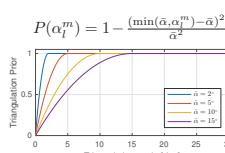
of depth and normal maps

## Pixelwise View Selection

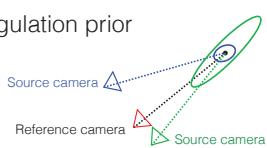
### Occlusion prior



$$P(X_l^m | Z_l^m, \theta_l) = \begin{cases} \frac{1}{N\Lambda} \exp\left(-\frac{(1-\rho_l^m(\theta))^2}{2\sigma_p^2}\right) & \text{if } Z_l^m = 1 \\ \frac{1}{N\mathcal{U}} & \text{if } Z_l^m = 0 \end{cases}$$

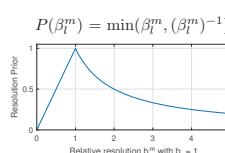


### Triangulation prior

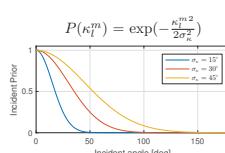


$$P(\alpha_l^m) = 1 - \frac{(\min(\bar{\alpha}, \alpha_l^m) - \bar{\alpha})^2}{\bar{\alpha}^2}$$

### Resolution prior



### Incident prior



## Joint Depth - Normal - Occlusion Inference

### Joint likelihood function $P(\mathbf{X}, \mathbf{Z}, \boldsymbol{\theta}, \mathbf{N})$

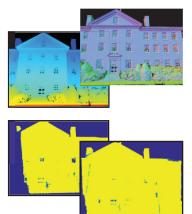


Normals

Depth

Occlusion

Images



### Generalized Expectation Maximization (GEM)

- E-Step:* Infer  $\mathbf{Z}$  using variational inference

- M-Step:* Infer  $\boldsymbol{\theta}, \mathbf{N}$  using PatchMatch sampling

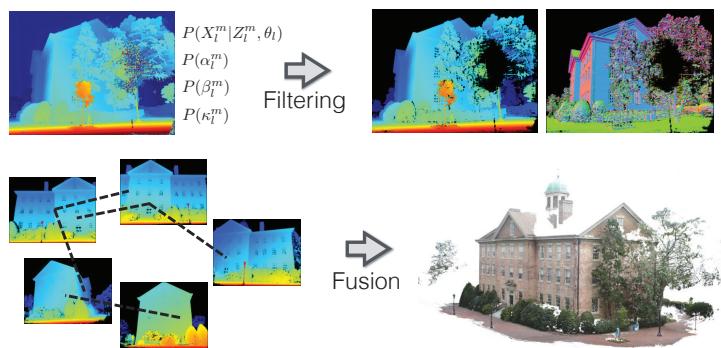
## Multi-View Geometric Consistency

### Cost function

$$\xi_l^m = 1 - \rho_l^m + \eta \min_{\psi_l^m} \frac{1}{|\mathcal{S}|} \sum_{m \in \mathcal{S}} \xi_l^m(\theta_l^*, n_l^*)$$

$$\text{Optimization} \quad \arg\min_{\theta_l^*, n_l^*} \frac{1}{|\mathcal{S}|} \sum_{m \in \mathcal{S}} \xi_l^m(\theta_l^*, n_l^*)$$

## Filtering and Fusion



## Results

