The results:

```
Air Cargo: [Load(C1, P1, SF0), Fly(P1, SF0, JFK), Load(C2, P2, JFK),

Romania: [Drive(Sibiu, Fagaras), Drive(Fagaras, Bucharest)]

Robot delivery, part 1: [Move(Robert, MyOffice, Floor), Move(Robert, Robot delivery, part 2: [Move(Robert, MailOffice, Floor), Move(Robert, Move(Robert, MailOffice, Floor), Move(Robert, MailOffice, F
```

The result means, first drive from Sibiu to Fagaras, then drive from Fagaras to Bucharest and achieve the goal state.

To solve another problem such as a dinner date example:
Initial Conditions
:(and (garbage) (cleanHands) (quiet))

Goal
:(and (dinner) (present) (not (garbage))

Actions:

Cook :precondition (cleanHands)
:effect (dinner)

Wrap :precondition (quiet)
:effect (present)

Carry :precondition
:effect (and (not (garbage)) (not (cleanHands))

:effect (and (not (garbage)) (not (quiet)))

Then develop a graph plan such like:

Dolly:precondition

