

```
% Jesse Wynn  
% Robotics HW 3
```

```
clc  
% clear
```

```
% Problem 8-2 from the book
```

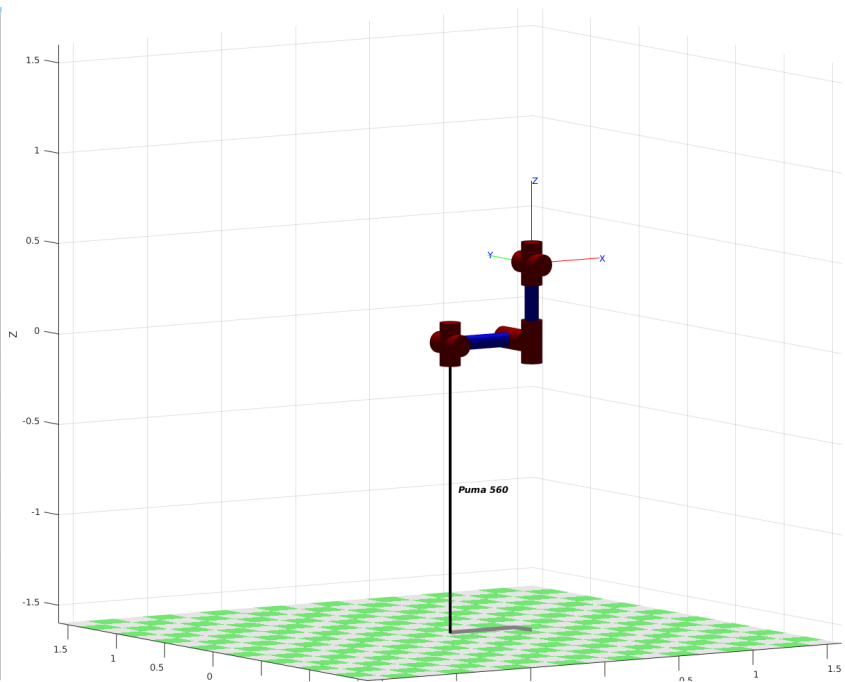
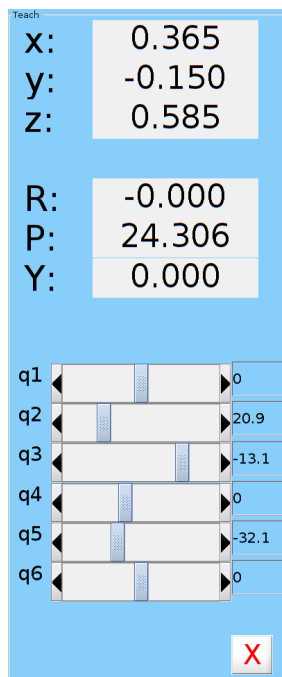
```
% for the puma560 robot, can you devise an situation where three axes  
are  
% parallel?
```

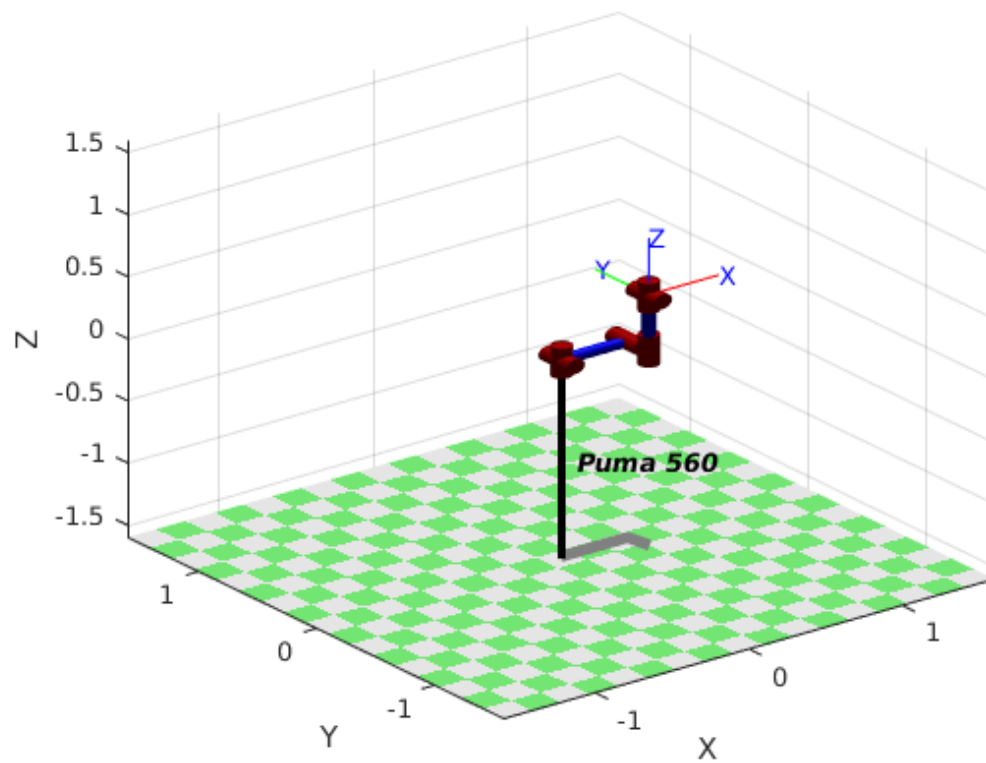
```
mdl_puma560  
bot = p560;
```

```
q = [0 0 0 0 0 0];  
bot.plot(q)
```

```
disp 'yes. In the zero-angle pose, axes q2,q3, and q5 are parallel'
```

Warning: arrow option requires arrow3 from FileExchange
yes. In the zero-angle pose, axes q2,q3, and q5 are parallel





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