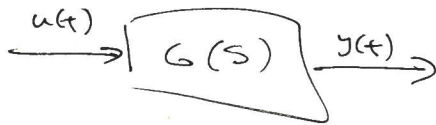


## Frequency Response:

### SISO



$$u(t) = e^{j\omega t}$$

$$\text{If } G(s) \text{ is stable} \Rightarrow y(t) = G(j\omega) e^{j\omega t} + \tau(t)$$

- where  $\tau(t) \rightarrow 0$  exp fast

$$- G(j\omega) e^{j\omega t} = |G(j\omega)| e^{j(\omega t + \angle G(j\omega))}$$

$$\text{i.e. if } u(t) = \sin(\omega t) \Rightarrow y_{ss}(t) = |G(j\omega)| \sin(\omega t + \angle G(j\omega))$$

### MIMO

$$u(t) = \text{vector}$$

- If we assume same freq. for all comp, but different amplitudes & phase.

$$u(t) = \underline{u}_0 e^{j\omega t}$$

$$\text{w/ } \underline{u}_0 = \begin{bmatrix} A_1 e^{j\phi_1} \\ A_2 e^{j\phi_2} \\ \vdots \\ A_k e^{j\phi_k} \end{bmatrix}$$

(All  $k$  inputs are sinusoidal, but w/ different amplitudes  $A_i$  & phases  $\phi_i$ )

$$y_{ss} = G(j\omega) \underline{u}_0 e^{j\omega t} = \underbrace{\begin{bmatrix} A_1 |G(j\omega)| e^{j(\omega t + \phi_1 + \angle G(j\omega))} \\ \vdots \\ A_k |G(j\omega)| e^{j(\omega t + \phi_k + \angle G(j\omega))} \end{bmatrix}}_{\underline{y}_0}$$

$$\underline{y}_0 = \begin{bmatrix} G(j\omega) \end{bmatrix}_{(m \times k)} \begin{bmatrix} \underline{u}_0 \end{bmatrix}_{(k \times 1)} = \begin{bmatrix} \quad \end{bmatrix}_{(m \times 1)}$$

$$y_{0,i} = \sum_{\ell=1}^k g_{i\ell}(j\omega) u_{0,\ell} = \sum_{\ell=1}^k |g_{i\ell}(j\omega)| A_\ell e^{j(\phi_\ell + \angle g_{i\ell}(j\omega))}$$

→ Difficult to look @ individual Bode diagrams for MIMO systems.

— Instead, quantify  $\|y_0\|$  as a function of  $\|u_0\|$

For complex system:  $\|x\|_2^2 = x^* x$

$*$  = complex conj.  
transpose.

$$\|y_0\|_2^2 = y_0^* y_0 = [G(j\omega)u_0]^* G(j\omega)u_0 = u_0^* \underbrace{G(j\omega)^* G(j\omega)}_{H(j\omega)} u_0$$

$$\|y_0\|_2^2 = u_0^* H(j\omega) u_0 \rightarrow \text{freq. dependent quad form w/ symmetric matrix } H(j\omega).$$

$\rightarrow$  E-values of  $H(j\omega)$  are real + non-negative.

$\rightarrow$  use quadratic ~~identity~~ property:

$$0 \leq \lambda_{\min}(H(j\omega)) \|u_0\|_2^2 \leq \|y_0\|_2^2 \leq \lambda_{\max}(H(j\omega)) \|u_0\|_2^2$$

or w/  $\|u_0\|_2 \neq 0$

$$(\lambda_{\min}(H(j\omega)))^{1/2} \leq \frac{\|y_0\|_2}{\|u_0\|_2} \leq \lambda_{\max}(H(j\omega))^{1/2}$$

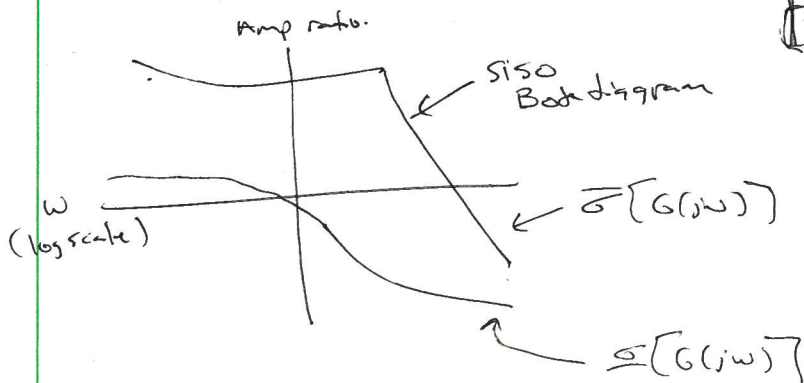
$$\text{Let } \sigma[G(j\omega)] = \max_i \sigma_i(G(j\omega))$$

$$\underline{\sigma}[G(j\omega)] = \min_i \sigma_i(G(j\omega))$$

$$\begin{aligned} &\downarrow \\ &\lambda_{\max}(G^*(j\omega)G(j\omega))^{1/2} \\ &= 2\text{-norm of TFM } G(j\omega) \end{aligned}$$

$$\frac{\|y_0\|_2}{\|u_0\|_2} \rightarrow \text{amplitude ratio for MIMO system}$$

w/  $\sigma[G(j\omega)]$  +  $\underline{\sigma}[G(j\omega)] \rightarrow$  playing a role similar to  $|G(j\omega)|$  for SISO.

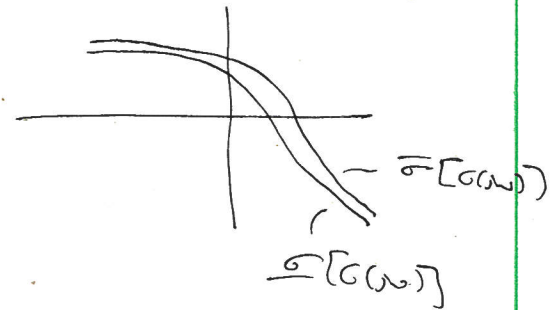


$\rightarrow$  At every freq the amplitude ratio lies between the upper + lower bound.

$\rightarrow$  Direction of the input determining if closer to lower or upper bound.

→ TF is "strongly directional" when there is a large difference between  $\sigma[G(\omega)]$  &  $\underline{\sigma}[G(\omega)]$  over a range of freq.

i.e. → Not Strongly Directional  
(These are more like SISO systems)



→ Direction is specific combination of amplitudes  $A_i$  & phase  $\psi_i$

$$w / u_0 = \begin{pmatrix} A_1 e^{j\psi_1} \\ A_2 e^{j\psi_2} \\ \vdots \\ A_k e^{j\psi_k} \end{pmatrix}$$

→ Use singular value decomposition:

$$G = L \Sigma R^* \quad \text{or} \quad (U \Sigma V^*)$$

Note: works for non-square matrices as well

$$\text{let } q = \min(k, m)$$

$$\begin{cases} \bar{\sigma} = \sigma_i \\ \underline{\sigma} = \begin{cases} \sigma_i & m \geq k \\ 0 & m < k \end{cases} \end{cases} \quad \begin{matrix} \text{(tall)} \\ \text{(wide)} \end{matrix}$$

Partition  $R$  &  $L$  matrices.  
i.e.

$$R = [r_1 \ r_2 \ \dots \ r_k] \quad \begin{matrix} \text{cols are} \\ \text{orthogonal} \end{matrix}$$

$$L = [l_1 \ l_2 \ \dots \ l_m]$$

$$y_0 = \sum_{\ell=1}^k \sigma_{\ell} (r_{\ell}^* u_0) l_{\ell}$$

$$\text{Suppose } u_0 = r_i$$

$$y_0 = \sum_{\ell=1}^k \sigma_{\ell} (r_{\ell}^* r_i) l_{\ell} = \sigma_i l_i$$

→ Input = "right" singular direction  
→ output =  $i^{\text{th}}$  singular value along corresponding left singular direction.

$$\therefore \text{ if } u_0 = r_1 \Rightarrow y_0 = \sigma_1 l_1 = \overline{\sigma}[G] l_1$$

$$\|y_0\|_2 = (y_0^* y_0)^{1/2} = \overline{\sigma}[G] (l_1^* l_1)^{1/2} = \overline{\sigma}[G]$$

Example:

evalfr()

$$G(3j) = \begin{pmatrix} -.284 + 2.58j & -.28 + 1.9j \\ .995 + .59j & .1 - .009j \end{pmatrix}$$

$$[L, \Sigma, R] = \text{svd}(G)$$

$$L(3j) = \begin{pmatrix} \underbrace{-0.0011 + 1j}_{l_1} & \underbrace{.0045 - .0002j}_{l_2} \\ \underbrace{.0039 + .0023j}_{l_1} & \underbrace{-.4739 + .8805j}_{l_2} \end{pmatrix}$$

$$\Sigma(3j) = \begin{pmatrix} 2.58.003 & 0 \\ 0 & 0.1005 \end{pmatrix}$$

$$R(3j) = \begin{pmatrix} 1 & .0013 \\ \underbrace{.0007 - .0011j}_{r_1} & \underbrace{-.5635 + .8261j}_{r_2} \end{pmatrix}$$

Put into mag/angle format:

$$l_1 = \begin{bmatrix} 1 + \angle 1.5719 \\ 0.0045 + \angle 0.5351 \end{bmatrix} \quad r_1 = \begin{bmatrix} 1 \\ 0.0013 + \angle -0.9722 \end{bmatrix}$$

Given input:

$$u = \begin{bmatrix} 1 \sin(3t) \\ 0.0013 \sin(3t + -0.9722) \end{bmatrix}$$

$\swarrow$   $r_1$  amplitude       $\swarrow$   $r_1$  phase

Then

$$y_{ss} = 2.58 \begin{bmatrix} \sin(3t + 1.5719) \\ \underbrace{0.0045 \sin(3t + 0.5351)}_{l_1 \text{ amplitude}} \end{bmatrix}$$

$\nearrow$   $\Sigma(1)$        $\nwarrow$   $l_1$  phase