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Preface

This manual describes the following:

- Recommended modeling practices to use when performing analog simulation with Cadence[®] products.
- Applications that are useful to use with the Virtuoso Analog Design Environment and the Spectre Circuit Simulator.
- Simple and powerful examples of different ways to model devices in your designs.

The information presented in this manual is intended for integrated circuit designers and assumes that you are familiar with analog design and simulation. You should also be familiar with the Component Description Format (CDF).

This preface contains the following topics:

- Scope
- Licensing Requirements
- Related Documentation
- Additional Learning Resources
- Customer Support
- Feedback about Documentation
- Typographic and Syntax Conventions

Scope

Unless otherwise noted, the functionality described in this guide can be used in both mature node (for example, IC6.1.8) and advanced node and methodologies (for example, ICADVM20.1) releases.

Label Meaning	
---------------	--

(ICADVM20.1 Only)	Features supported only in the ICADVM20.1 advanced nodes and advanced methodologies release.
(IC6.1.8 Only)	Features supported only in mature node releases.

Licensing Requirements

For information about licensing in the Virtuoso design environment, see <u>Virtuoso Software</u> <u>Licensing and Configuration Guide</u>.

Related Documentation

Installation, Environment, and Infrastructure

- <u>Virtuoso Design Environment User Guide</u>
- Cadence Application Infrastructure User Guide

Virtuoso Tools

- Virt uoso Analog Design Environment L User Guide
- <u>Virtuoso Analog Design Environment XL User Guide</u>
- <u>Virtuoso Analog Design Environment GXL User Guide</u>
- Component Description Format User Guide

Spectre Circuit Simulator

- Spectre Circuit Simulator and Accelerated Parallel Simulator User Guide
- Spectre Circuit Simulator Reference

Additional Learning Resources

Video Library

The <u>Video Library</u> on the Cadence Online Support website provides a comprehensive list of videos on various Cadence products.

To view a list of videos related to a specific product, you can use the *Filter Results* feature available in the pane on the left. For example, click the *Virtuoso Layout Suite* product link to view a list of videos available for the product.

You can also save your product preferences in the Product Selection form, which opens when you click the *Edit* icon located next to *My Products*.

Virtuoso Videos Book

You can access certain videos directly from Cadence Help. To learn more about this feature and to access the list of available videos, see <u>Virtuoso Videos</u>.

Rapid Adoption Kits

Cadence provides a number of <u>Rapid Adoption Kits</u> that demonstrate how to use Virtuoso applications in your design flows. These kits contain design databases and instructions on how to run the design flow.

To explore the full range of training courses provided by Cadence in your region, visit Cadence Training or write to training_enroll@cadence.com.

Note: The links in this section open in a separate web browser window when clicked in Cadence Help.

Help and Support Facilities

Virtuoso offers several built-in features to let you access help and support directly from the software.

■ The Virtuoso *Help* menu provides consistent help system access across Virtuoso tools and applications. The standard Virtuoso *Help* menu lets you access the most useful help and support resources from the Cadence support and corporate websites directly from the CIW or any Virtuoso application.

■ The Virtuoso Welcome Page is a self-help launch pad offering access to a host of useful knowledge resources, including quick links to content available within the Virtuoso installation as well as to other popular online content.

The Welcome Page is displayed by default when you open Cadence Help in standalone mode from a Virtuoso installation. You can also access it at any time by selecting *Help – Virtuoso Documentation Library* from any application window, or by clicking the *Home* button on the Cadence Help toolbar (provided you have not set a custom home page).

For more information, see <u>Getting Help</u> in *Virtuoso Design Environment User Guide*.

Customer Support

For assistance with Cadence products:

Contact Cadence Customer Support

Cadence is committed to keeping your design teams productive by providing answers to technical questions and to any queries about the latest software updates and training needs. For more information, visit https://www.cadence.com/support.

■ Log on to Cadence Online Support

Customers with a maintenance contract with Cadence can obtain the latest information about various tools at https://support.cadence.com.

Feedback about Documentation

You can contact Cadence Customer Support to open a service request if you:

- Find erroneous information in a product manual
- Cannot find in a product manual the information you are looking for
- Face an issue while accessing documentation by using Cadence Help

You can also submit feedback by using the following methods:

- In the Cadence Help window, click the *Feedback* button and follow instructions.
- On the Cadence Online Support <u>Product Manuals</u> page, select the required product and submit your feedback by using the <u>Provide Feedback</u> box.

Typographic and Syntax Conventions

The following typographic and syntax conventions are used in this manual.

text	Indicates names of manuals, menu commands, buttons, and fields.
text	Indicates text that you must type as presented. Typically used to denote command, function, routine, or argument names that must be typed literally.
z_argument	Indicates text that you must replace with an appropriate argument value. The prefix (in this example, z_{-}) indicates the data type the argument can accept and must not be typed.
	Separates a choice of options.
{ }	Encloses a list of choices, separated by vertical bars, from which you must choose one.
[]	Encloses an optional argument or a list of choices separated by vertical bars, from which you may choose one.
[?argName t_arg]	
	Denotes a <i>key argument</i> . The question mark and argument
	name must be typed as they appear in the syntax and must be followed by the required value for that argument.
• • •	* * * * * * * * * * * * * * * * * * * *
•••	followed by the required value for that argument.
•••	followed by the required value for that argument. Indicates that you can repeat the previous argument. Used with brackets to indicate that you can specify zero or more
····	followed by the required value for that argument. Indicates that you can repeat the previous argument. Used with brackets to indicate that you can specify zero or more arguments. Used without brackets to indicate that you must specify at least
····	followed by the required value for that argument. Indicates that you can repeat the previous argument. Used with brackets to indicate that you can specify zero or more arguments. Used without brackets to indicate that you must specify at least one argument. Indicates that multiple arguments must be separated by

If a command-line or SKILL expression is too long to fit within the paragraph margins of this document, the remainder of the expression is moved to the next line and indented. In code excerpts, a backslash (\) indicates that the current line continues on to the next line.

1

Modeling for Direct Simulation

Cadence strongly recommends that you use the modeling practices described in this document. Cadence is committed to these modeling practices, and these practices are fully supported by the Virtuoso Analog Design Environment, the Spectre Circuit Simulator, and the Spectre interface.

By employing the direct modeling practices described in this document, you can use different types of models without making any design changes. For example, you can model an *npn* device as

- a simple simulator model statement,
- a simple subckt definition,
- an advanced subckt definition, or
- a behavioral definition.

Neither the design nor the component description format (CDF) of the *npn* component in analogLib needs to change. You can change the model complexity without design or CDF edits.

Modeling Strategies

This document gives you information about the implementation and advisability of the following modeling strategies:

- <u>Simple Device Models</u> describes how to use the simplest device models which do not contain expressions, user-defined parameters, or instance parameters.
- <u>Built-In Geometric Models</u> describes how to specify parameters in addition to those included in simple device models. This method is convenient when the unmodified instance parameters provided by the simulator are adequate, such as when the simulator performs geometric scaling internally.

Modeling for Direct Simulation

- External Models describes how to define models that are based on the models provided by the simulator but which have slightly different behavior or interface. The modifications are implemented outside the simulator, as opposed to internally, and defined in a file.
- Standard Model Binning describes how to select a different model for each range of device geometries.
- Custom Model Binning describes how to select a different model for different ranges of certain parameters, but in contrast to standard binning, this capability is not built into the model. Instead, it is a general simulator capability.
- Process Modeling describes how to include, or not include, process and geometry effects in your simulation.
- Corners Modeling describes how to create one library that places the worst, typical, and best cases in one model file.
- Monte Carlo Modeling describes how to use statistical quantities in your models.
- Package Modeling points to a discussion of package modeling in the Spectre Circuit Simulator and Accelerated Parallel Simulator RF Analysis User Guide.
- Behavioral Modeling describes how to use behavioral models to abstract parts of a design to shorten the simulation time.
- Miscellaneous Modeling Techniques summarizes several other modeling techniques used in analog simulation. The usefulness of each technique is discussed, as is the degree of support for each technique available from Cadence tools.
- <u>Libraries</u> explains how devices are created for simulation in a Cadence library.

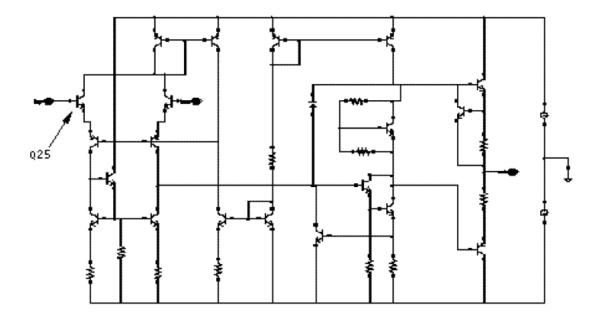
Simple Device Models

In analog simulation, components frequently reference models. For example, a bjt component requires both an instance and a definition of the model it references. The instances and the model definitions can be complex or simple.

This section describes the use of the simplest device models. With simple device models, no expressions, no user-defined parameters, and no instance parameters are used.

An example of a simple device model is the instance Q25 in the schematic view of the opamp cell from the aExamples library which is shown in Figure 1-1.

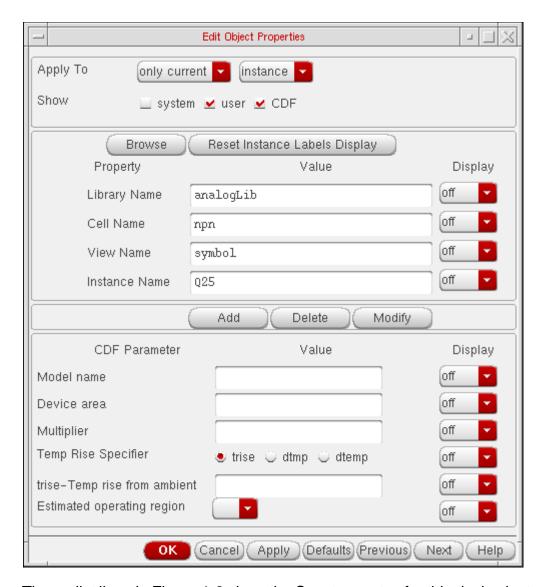
Figure 1-1 opamp Cell from the aExamples Library Showing Q25



You can find the aExamples library in the directory tools/dfII/samples/artist in your Cadence installation directory.

In the Edit Object Properties form shown in the following figure, the model parameter, Model name is for the instance Q25 and is npn. This makes this instance a reference to the npn model.

Figure 1-2 Edit Object Properties Form for Instance Q25 of the aExamples opamp



The netlist lines in Figure $\underline{1-3}$ show the Spectre syntax for this device instance along with the model npn it references shown in Figure $\underline{1-4}$. The model defines both the device type (bjt) and the parameters associated with the device.

The model npn is included from the file tools/dfII/samples/artist/models/spectre/models.scs.

The opamp cell in Figure <u>1-1</u> is used by the lowpass schematic cell view in the same library. When you simulate this cell view in the <u>Virtuoso Analog Design Environment</u>, you specify models.scs as the model file by typing this filename in the <u>Setup Model Libraries</u> form.

Modeling for Direct Simulation

Figure 1-3 File: lowpass.scs for Simple Device Models

```
simulator lang=spectre
...
include "models.scs"
...
Q25 (net39 inp net80) npn
```

Figure 1-4 File: bipolar.scs for Simple Device Models

```
model npn bjt type=npn is=3.26E-16 va=60 bf=100 \
br=6 nc=2 ikr=100m rc=1 vje=0.7 \
cjc=1e-12 fc=0.5 cje=0.7p \
tr=200e-12 tf=25e-12 itf=0.03 vtf=7 xtf=2
```

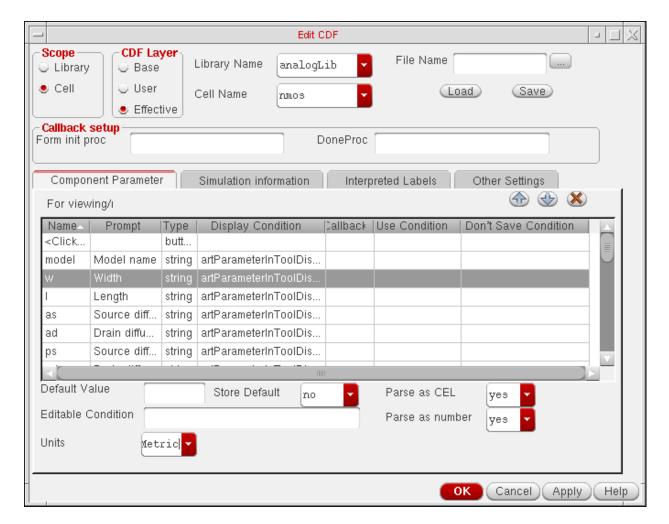
Built-In Geometric Models

For most device primitives, you can specify additional parameters besides those included in the model. For example, with the $\mathbb 1$ and $\mathbb w$ parameters, you can change the size of specific instances of Spectre MOS devices that are otherwise identical and described by a single model statement. This method is convenient when the unmodified instance parameters provided by the simulator are adequate for your simulation needs, such as when the simulator performs geometric scaling internally.

In the <u>Virtuoso Analog Design Environment</u>, the developer of the library adds parameter definitions to the CDF for such components as shown in Figure <u>1-5</u>. The developer also adds the parameter names, such as 1 and w, to the list of instance parameters in the simulator information section for each simulator of interest. For the nmos cell of the <code>analogLib</code> library, you define the 1 and w parameters in the CDF with the prompts Length and Width respectively. These parameters are referenced in the <code>instParameters</code> section of the Edit Simulation Information form.

Modeling for Direct Simulation

Figure 1-5 Edit CDF Form for the nmos Cell



The instances M14 and M15 in the schematic view of the foldedCascode cell in the aExamples library, shown in Figure 1-6, demonstrate this technique. Both instances have identical values for 1 and w. The instances M2 and M4 also use this technique, and although these instances differ in size, both reference model nmos24 as shown in Figure 1-7.

Figure 1-6 foldedCascode Cell From the aExamples Library

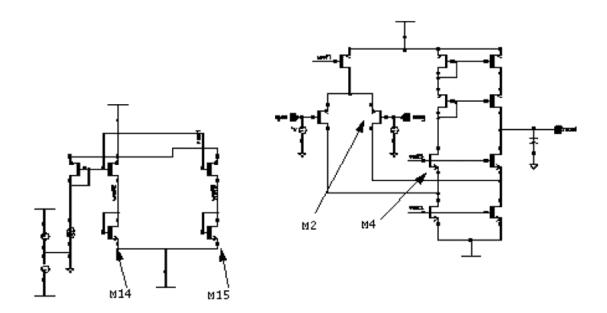


Figure 1-7 File: foldedCascode.scs for Built-In Geometric Models

```
simulator lang=spectre
...
include "basicMos.scs"
...
M2 (2 1 0 0) nmos24 l=3u w=40u
...
M4 (2 1 0 0) nmos24 l=1.8u w=20u
...
```

The basicMos.scs file in Figure 1-8 is selected as the model file on the <u>Setup Model</u> <u>Libraries</u> form in the <u>Virtuoso Analog Design Environment</u>.

Figure 1-8 File: basicMos.scs for Built-In Geometric Models

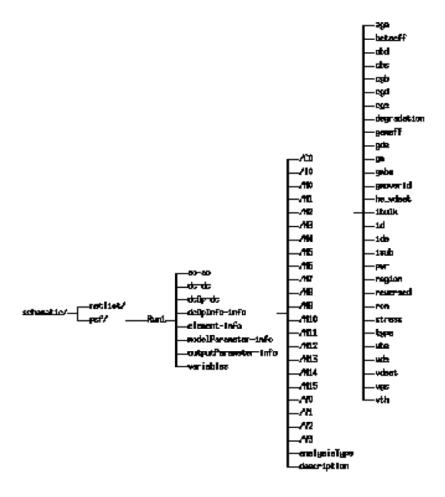
```
model nmos24 mos2 type=n vto = 0.775 tox = 400e-10 nsub = 8e+15 + xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e+5 uexp = 0.125
```

Modeling for Direct Simulation

```
+ vmax = 5.1e+4 neff = 4.0 delta = 1.4 rsh = 36 cgso = 1.95e-10
+ cgdo = 1.95e-10 cj = 195u cjsw = 500p mj = 0.76 mjsw = 0.30
+ pb = 0.8
```

After simulation, the operating-point results for the instance appear in the Results Browser as shown in Figure <u>1-9</u>.

Figure 1-9 Operating Points for the Built-In Geometric Models Example



Modeling for Direct Simulation

External Models

In some cases, specifying different parameter values for the instances of built-in models, as is shown in the previous example, <u>Built-In Geometric Models</u>, is not a satisfactory solution. External modeling might be a preferred procedure.

With external modeling, you define models that are based on the models provided by the simulator but that have slightly different behavior or interfaces. The modifications are implemented outside the simulator, as opposed to internally, and are defined in a file that is normally provided by the foundry developer. This file might contain parameter definitions, function definitions, and an extra layer of computation, as well as the modified model.

You can also further modify the behavior of an individual device with your own instance parameters. For example, the length and width are often user-specified for bipolar devices, but these parameters might not be available in a particular simulator. The following features or effects might be modeled in an externally created model:

- Geometry
- Temperature
- Process parameters
- Device mismatch
- Parameter correlation
- Radiation

You can accomplish external modeling by making instance parameter and model parameter values functions of the quantity of interest, such as geometry. This approach is available within the <u>Virtuoso Analog Design Environment</u> for any component you choose.

Compare the netlist in Figure 1-10 to the example shown in Figure 1-7 that also utilizes the M2 and M4 instances in the foldedCascode circuit shown in Figure 1-6. In both examples, the M2 and M4 instances reference the same model nmos24 but specify instance values for the 1 and w parameters.

The two examples differ in the choice of the model file. The external modeling example uses <code>externalMos.scs</code> in Figure 1-11 instead of <code>basicMos.scs</code> shown in Figure 1-8. Without any changes to the <code>foldedCascode</code> schematic in Figure 1-6, a more powerful modeling approach is used by specifying a different filename. For external modeling, the file in Figure 1-10 is the netlist created by the Virtuoso Analog Design Environment:

Figure 1-10 File: foldedCascode.scs for External Models

Modeling for Direct Simulation

```
// Using direct netlister
simulator lang=spectre
...
include "externalMos.scs"
...
M2 (2 1 0 0) nmos24 l=3u w=40u
...
M4 (2 1 0 0) nmos24 l=1.8u w=20u
```

This example demonstrates modeling of geometry with process effects. The externalMos.scs model file in Figure 1-11 is located in the samples directory tools/dfII/samples/artist/models/spectre.

In the <code>externalMos.scs</code> model file, the variables <code>mos24LengthOffset</code> and <code>mos24WidthOffset</code>, as well as the functions <code>mos24LengthCorrection</code> and <code>mos24WidthCorrection</code>, are defined for the <code>nmos24</code> model. The variable values <code>nmos24LengthOffset</code> and <code>nmos24WidthOffset</code> (.1 μ , .015 μ) are called process parameters. These process parameters are used in both a function and an algebraic expression where they are combined with the user-defined instance parameters 1 and <code>w</code> to determine the effective length and width. The 1 and <code>w</code> parameters of instance <code>_mos</code> in the <code>nmos24</code> and <code>pmos24</code> inline <code>subckt</code> definitions use the functions <code>mos24LengthCorrection</code> and <code>mos24WidthCorrection</code> to determine their values.

The externalMos.scs file shown in Figure 1-11 includes an inline subckt definition which replaces the nmos24 model card of the basicMos.scs file shown in Figure 1-8. The inline subckt contains a single instance of a device as well as a model definition. The terminals are identical to those of the Spectre mos2 model.

The parameters 1 and w for the foldedCascode example in Figure $\underline{1-10}$ are also defined in the inline subckt definition of Figure $\underline{1-11}$. The inline subckt definition transparently replaces the model statement from Figure $\underline{1-10}$. Inside the inline subckt definition, the length and width of the instance are replaced with corrected values.

The example in Figure <u>1-11</u> shows alteration of the instance parameters. Of course, the model parameters can be altered.

Figure 1-11 File: externalMos.scs for External Models

```
simulator lang=spectre

parameters mos24LengthOffset=.1u mos24WidthOffset=.015u

real mos24WidthCorrection( real w, real offset ) {
```

Modeling for Direct Simulation

```
return w + offset
real mos24LengthCorrection( real 1, real offset ) {
   return 1 + offset
}
inline subckt nmos24 (d g s b)
parameters w=1 l=1
nmos24 (d g s b) mos l=mos24LengthCorrection( 1, mos24LengthOffset )
+ w=mos24WidthCorrection( w, mos24WidthOffset )
model mos mos2 type=n vto = 0.775 tox = 400e-10 nsub = 8e+15
+ xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e+5 uexp = 0.125
+ \text{ vmax} = 5.1e+4 \text{ neff} = 4.0 \text{ delta} = 1.4 \text{ rsh} = 36 \text{ cqso} = 1.95e-10
+ \text{ cqdo} = 1.95 \text{e} - 10 \text{ cj} = 195 \text{u cjsw} = 500 \text{p mj} = 0.76 \text{ mjsw} = 0.30
8.0 = dq +
ends
inline subckt pmos24 (d g s b)
parameters w=1 l=1
pmos24 (d g s b) mos l=mos24LengthCorrection( l, mos24LengthOffset )
+ w=mos24WidthCorrection( w, mos24WidthOffset )
model mos mos2 type=p vto = -0.75 tox = 400e-10 nsub = 6e+15
+ xj = 0.05u ld = 0.20u uo = 255 ucrit = 0.86e+5 uexp = 0.29
+ \text{ vm} = 3.0\text{e} + 4 \text{ neff} = 2.65 \text{ delta} = 1.0 \text{ rsh} = 101 \text{ cgso} = 1.90\text{e} - 10
+ \text{ cqdo} = 1.90e-10 \text{ cj} = 250\text{u} \text{ cjsw} = 350\text{p} \text{ mj} = 0.535 \text{ mjsw} = 0.34
+ pb = 0.8
ends
```

Note: You must define the global parameters nmos24LengthOffset and mos24WidthOffset before you reference them.

An inline subckt definition is used instead of a subckt definition to make the simulation results appear similar to mos2 results. With inline subcircuits, no extra hierarchy is introduced by the use of subcircuits. The inline subckt contains a single instance whose instance name is identical to the name of the inline subckt, nmos24.

After simulation, you can display the operating points for M2 in the Results Browser. Compare the operating-point results with those shown in Figure 1-9. The operating-point names are identical to those of the model card although the values might differ because of the offsets of width and length in externalMos.scs.

Modeling for Direct Simulation

For more information about inline subcircuits, see the *Spectre Circuit Simulator Reference*.

Standard Model Binning

When you specify the stdbinMos.scs file for the foldedCascode example shown in Figure 1-12 on the Setup Model Libraries form, different model sections are used for instances M2 and M4. This modeling style is again different from that in the previous two examples in Figure 1-7 and Figure 1-10 while the schematic shown in Figure 1-6 is the same.

The resulting netlist is shown below:

Figure 1-12 File: foldedCascode.scs for Standard Model Binning

```
// Using direct netlister
simulator lang=spectre
...
include "stdbinMos.scs"
...
M2 (2 1 0 0) nmos24 l=3u w=40u
...
M4 (2 1 0 0) nmos24 l=1.8u w=20u
```

The following is a section of the sample model file:

Figure 1-13 File: stdbinMos.scs for Standard Model Binning

```
simulator lang=spectre
...
model nmos24 mos2 {
1: type=n vto = 0.775 tox = 400e-10 nsub = 8e+15
+ xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e+5 uexp = 0.125
+ vmax = 5.1e+4 neff = 4.0 delta = 1.4 rsh = 36 cgso = 1.95e-10
+ cgdo = 1.95e-10 cj = 195u cjsw = 500p mj = 0.76 mjsw = 0.30
+ pb = 0.8 lmin=0.1u lmax=2u wmin=1u wmax=30u
2: type=n vto = 0.775 tox = 400e-10 nsub = 8e+15
+ xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e+5 uexp = 0.125
+ vmax = 5.1e+4 neff = 4.0 delta = 1.4 rsh = 36 cgso = 1.95e-10
+ cgdo = 1.95e-10 cj = 195u cjsw = 500p mj = 0.76 mjsw = 0.30
+ pb = 0.8 lmin=2u lmax=10u wmin=30u wmax=100u
}
```

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. . .

Custom Model Binning

As is the case with standard binning, a different model is selected for different ranges of certain parameters, but in contrast to standard binning, the custom binning capability is not built into the model. Instead, it is a general simulator capability.

In this example, the appropriate model is selected by the simulator for each device or subcircuit instance based on the values of the subcircuit parameters for the area of that instance. The model selection can be based on any parameter, not just on geometry parameters.

Unlike standard binning, which is limited to the 1 and w parameters for mos devices, custom binning can be used for any parameter or design variable of any device type, including bipolar devices. In Spectre, custom binning is achieved using the structural if statement, as shown in cstbinMos.scs in Figure 1-15 on page 23, and the conditional expressions used in the if statements can reference any netlist parameter, subcircuit parameter, or design variable.

The cstbinMos.scs file in Figure 1-15 is located in the samples directory tools/dfII/samples/artist/models/spectre.

When you specify the cstbinMos.scs model file on the model setup form for the foldedCascode example shown in Figure <u>1-14</u>, different model sections are again used for instances M2 and M4. The resulting netlist is shown in Figure <u>1-14</u>:

Figure 1-14 File: foldedCascode.scs for Custom Model Binning

```
// Using direct netlister
simulator lang=spectre
...
include "cstbinMos.scs"
...
M2 (2 1 0 0) nmos24 l=3u w=40u
...
M4 (2 1 0 0) nmos24 l=1.8u w=20u
```

Figure <u>1-15</u> is a section of the sample model file.

Figure 1-15 File: cstbinMos.scs for Custom Model Binning

simulator lang=spectre

Modeling for Direct Simulation

```
inline subckt nmos24 (d g s b)
parameters l=1u w=1u area=1*w
     if (area < 4e-12) {
          nmos24 (d g s b) small l=l w=w
     } else {
          nmos24 (d g s b) large l=l w=w
     }
model small mos2 type=n vto = 0.775 tox = 400e-10 nsub = 8e+15
+ xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e+5 uexp = 0.125
+ \text{ vmax} = 5.1e+4 \text{ neff} = 4.0 \text{ delta} = 1.4 \text{ rsh} = 36 \text{ cgso} = 1.95e-10
+ \text{ cqdo} = 1.95\text{e}-10 \text{ cj} = 195\text{u} \text{ cjsw} = 500\text{p} \text{ mj} = 0.76 \text{ mjsw} = 0.30
+ pb = 0.8
model large mos2 type=n vto = 0.775 tox = 400e-10 nsub = 8e+15
+ xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e + 5 uexp = 0.125
+ \text{ vmax} = 5.1e+4 \text{ neff} = 4.0 \text{ delta} = 1.4 \text{ rsh} = 36 \text{ cgso} = 1.95e-10
+ \text{ cgdo} = 1.95 \text{e} - 10 \text{ cj} = 195 \text{u cjsw} = 500 \text{p mj} = 0.76 \text{ mjsw} = 0.30
+ pb = 0.8 lmin=2u lmax=10u wmin=30u wmax=100u
ends nmos24
inline subckt pmos24 (d g s b)
parameters l=1u w=1u area=1*w
     if (area < 4e-12) {
          mos (d g s b) small l=l w=w
     } else {
          mos (d g s b) large l=l w=w
     }
model small mos2 type=p vto = 0.775 tox = 400e-10 nsub = 8e+15
+ xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e+5 uexp = 0.125
+ \text{ vmax} = 5.1e+4 \text{ neff} = 4.0 \text{ delta} = 1.4 \text{ rsh} = 36 \text{ cgso} = 1.95e-10
+ \text{ cqdo} = 1.95e-10 \text{ cj} = 195u \text{ cjsw} = 500p \text{ mj} = 0.76 \text{ mjsw} = 0.30
+ pb = 0.8
model large mos2 type=p vto = 0.775 tox = 400e-10 nsub = 8e+15
+ xj = 0.15u ld = 0.20u uo = 650 ucrit = 0.62e+5 uexp = 0.125
+ \text{ vmax} = 5.1e+4 \text{ neff} = 4.0 \text{ delta} = 1.4 \text{ rsh} = 36 \text{ cgso} = 1.95e-10
+ \text{ cgdo} = 1.95e-10 \text{ cj} = 195u \text{ cjsw} = 500p \text{ mj} = 0.76 \text{ mjsw} = 0.30
+ pb = 0.8 lmin=2u lmax=10u wmin=30u wmax=100u
```

Modeling for Direct Simulation

ends pmos24

In this example, model binning is performed for MOS devices within the inline subcircuit definition. The devices $\tt M2$ and $\tt M4$ in the foldedCascode example in Figure $\tt 1-14$ reference the same model $\tt nmos24$. The values of the 1 and w parameters, which are passed from the $\tt M2$ and $\tt M4$ instances, determine the appropriate model definition. No instance or model names change in the result files.

Process Modeling

Successful IC design requires accurate modeling of the fabrication process. Many of the techniques described in previous sections are used in the netlist below. This section shows a Spectre simulator example of a complete process modeling approach. The example shows you how to create a netlist that lets you include, or not include (plain simulation), process and geometry effects in your simulation.

- To include process and geometry effects in your simulation, include the Process.scs file in the diffamp.ckt netlist instead of the Plain.h file.
- To perform a plain simulation which does not model the process and geometry effects, include the Plain.h file in the diffamp.ckt netlist instead of the Process.scs file.

The diffamp schematic cell view in Figure 1-16 from the aExamples library is a simple differential amplifier with two resistors and two npn bipolar transistors. The resistor and bipolar models are defined in the ProcessSimple.scs file. Both process and geometry effects are also modeled in this file.

When you include the Process.scs file shown in Figure 1-19 in the netlist, you specify geometric parameters to model bjt and resistor devices. Certain non-ideal process effects are also modeled in this file.

The Plain.scs file shown in Figure 1-20 is not used in this example, but it gives you an interface in which the parameters that you specify are the electrical parameters used by the simulator.

Figure 1-16 diffamp Schematic from the aExamples Library

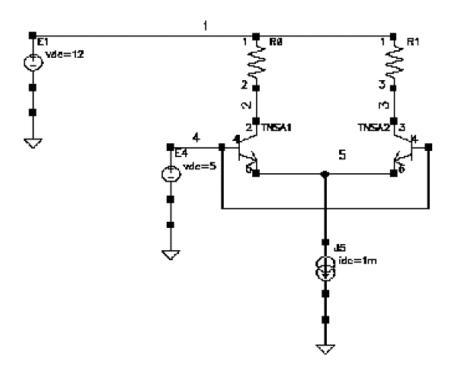


Figure 1-17 File: diffamp.scs for Process Modeling

```
// A differential amplifier, biased with a 1mA current source
simulator lang=spectre
include "ProcessSimple.scs"
include "Process.scs"
E1 (1 0) vsource dc=12
// Pullup resistors, 4k ohms nominal
R1 (1 2) RPLR Rnom=4k WB=5 // 5 units wide, model calcs required length
R2 (1 3) RPLR Rnom=4k WB=10
                             // 10 units wide, model calcs required length
// The input pair
TNSA1 (2 4 5 0) TNSA WE=10 LE=10
TNSA2 (3 4 5 0) TNSA WE=10 LE=10
// No differential input voltage, both inputs tied to same source
E4 (4 0) vsource dc=5
// current source biasing
J5 (5 0) isource dc=1m
dcop dc
```

Modeling for Direct Simulation

Figure 1-18 File: ProcessSimple.scs for Process Modeling

```
simulator lang=spectre
// Define process parameters, including mismatch effects
parameters RSHSP=200 RSHPI=5k
                                     // sheet resistance, pinched sheet res
          SPDW=0 SNDW=0
                                     // etching variation from ideal
         XISN=1 XBFN=1 XRSP=1
                                    // device "mismatch" parameters
           XISNafac=100m XISNbfac=1m
                                       // IS scaling factors for mismatch egns
                                                    **
                                                          **
        XBFNafac=100m XBFNbfac=1m // BF
                                                    **
         XRSPafac=100m XRSPbfac=1m // RS "
           RSHSPnom=200 RSHPInom=5k
                                     // sheet resistance nominal values
                                       // ratio of PI sheet res to nominal
           FRSHPI=RSHPI/RSHPInom
   Define "simple" bipolar and resistor devices...
//
    Define a "base" TNSA subckt i.e
    Define a simple "TNSA" bipolar transistor subcircuit, with model // card
inline subckt TNSA B (C B E S)
 parameters MULT=1 IS=1e-15 BF=100
 model modX bjt type=npn is=IS bf=BF  // a model card
                                 // "inline" device instance
 TNSA B (C B E S) modX m=MULT
ends TNSA B
// Define a "base" resistor
// A simple "RPLR" resistor subcircuit
inline subckt RPLR B (A B)
 parameters R MULT=1
 RPLR B (A B) resistor r=R m=MULT
                                  // "inline" device
ends RPLR B
//
    Define process/geometry dependent bipolar and resistor devices..
   Define a "geometrical/process" TNSA subckt
//
//
  Define BJT subcircuit, with process and geometry effects modeled
// Bipolar model parameters IS and BF are functions of the
// effective emitter area/perimeter taking process factors
//
     (e.g non-ideal etching) into account
inline subckt TNSA PR (C B E S)
 parameters WE LE MULT=1 dIS=0 dBF=0
          WEA=WE+SNDW
                            // effective or "Actual" emitter width
         LEA=LE+SNDW
                           // effective or "Actual" emitter length
                             // effective emitter area
           AE=WEA*LEA
            IS=1e-18*FRSHPI*AE* (1+ (XISNafac/sqrt (AE) +XISNbfac)
                             *(dIS/2+XISN-1)/sqrt(MULT))
            BF=100*FRSHPI*(1+(XBFNafac/sqrt(AE)+XBFNbfac)
```

Modeling for Direct Simulation

```
*(dBF/2+XBFN-1)/sqrt(MULT))
 TNSA PR (C B E S) TNSA B IS=IS BF=BF MULT=MULT // "inline"
ends TNSA PR
// Define a "geometrical/process" RPLR resistor subckt
// Resistance is function of effective device geometry, taking
// process factors (e.g non-ideal etching) into account
inline subckt RPLR PR (A B)
 parameters Rnom WB MULT=1 dR=0
           LB=Rnom*WB/RSHSPnom
           AB=LB*(WB+SPDW)
 RPLR PR (A B) RPLR B R=RSHSP*LB/(WB+SPDW)*(1+(XRSPafac/sqrt(AB)+XRSPbfac)
                              *(dR/2+XRSP-1)/sqrt(MULT))
ends RPLR PR
Figure 1-19 File: Process.scs for Process Modeling
// Provides the designer with "geometrical" device interface
simulator lang=spectre
// Call to the geometrical TNSA model
inline subckt TNSA (C B E S)
 parameters WE=1u LE=1u MULT=1 dIS=0 dBF=0
 TNSA (C B E S) TNSA PR WE=WE LE=LE \
                MULT=MULT dIS=dIS dBF=dBF // call TNSA PR
ends TNSA
// Call to the geometrical RPLR model
inline subckt RPLR (A B)
 parameters Rnom=1 WB=10u MULT=1 dR=0
 RPLR (A B) RPLR PR Rnom=Rnom WB=WB \
            MULT=MULT dR=dR
                                               // call RPLR PR
ends RPLR
Figure 1-20 File: Plain.scs for Process Modeling
//
// Provides designer with "plain" device interface (i.e.
// no geometrical or process modeling)
```

simulator lang=spectre

Modeling for Direct Simulation

```
// Plain TNSA, no geometrical or process modeling
inline subckt TNSA (C B E S)
  parameters MULT=1 IS=1e-15 BF=100
  TNSA (C B E S) TNSA_B IS=IS BF=BF MULT=MULT // call TNSA_B
ends TNSA
// Plain RPLR no geometrical or process modeling
inline subckt RPLR (A B)
  parameters R=1 MULT=1
  RPLR (A B) RPLR_B R=R MULT=MULT
ends RPLR
```

The number of process variables and functions might be large for realistic processes and designs. Using many expressions, like increasing design size, can slow the simulation, and tasks such as reading in user-defined functions and process variables might have an impact on performance.

Corners Modeling

You can create one library that places the worst, typical, and best cases in one models file. The foldedCascode schematic view shown in Figure 1-6 in the aExamples library is used as an example of this practice. The cornersMos.scs models file contains worst, typical, and best case models. The Setup Model Library form provides a convenient way to specify the section with the model file of interest.

The method shown below is the preferred approach. You place all the models in one file and then include the models you want to use.

The netlist created for this design from the <u>Virtuoso Analog Design Environment</u> is shown in foldedCascode.scs in Figure 1-21.

Figure 1-21 File: foldedCascode.scs for Corners Modeling

```
simulator lang=spectre
...
include "cornersMos.scs" section=FCS
...
File: cornersMos.scs
library vti_2u
section TNTP
simulator lang=spice
```

Modeling for Direct Simulation

```
* VTI-derived Level=2 nominal model
.model nmos24 nmos level=2 vto = 0.775 tox = 400e-10 nsub = 8e+15 xj = 0.15U ld = 0.20U u0 = 650 ucrit = 0.62e+5 uexp = 0.125 vmax = 5.1e+4 neff = 4.0 delta = 1.4 rsh = 36 cgso = 1.95e-10 cgdo = 1.95e-10 cj = 195U cjsw = 500P mj = 0.76 mjsw = 0.30 pb = 0.8

.model pmos24 pmos level=2 vto = -0.75 tox = 400e-10 nsub = 6e+15 xj = 0.05U ld = 0.20U u0 = 255 ucrit = 0.86e+5 uexp = 0.29 vmax = 3.0e+4 neff = 2.65 delta = 1.0 rsh = 101 cgso = 1.90e-10 cgdo = 1.90e-10 cj = 250U cjsw = 350P mj = 0.535 mjsw = 0.34 pb = 0.8

endsection
```

Monte Carlo Modeling

With Monte Carlo analysis, you can use statistical quantities in your models by applying statistical variations to the process parameters. Monte Carlo analysis determines the parameter values by generating randomly distributed numbers according to the distributions (means and standard deviations) of process parameters. You then implement these process parameters as design variables.

You model all of the statistical quantities such as mismatch, deterministic tracking, and correlations through these process parameters. The parameters are typically physical, measurable values from silicon such as sheet rho, island depth, and oxide thickness. The process parameters are different for each manufacturing process. The modeling equations use these process parameters to calculate the final model parameters that are used by the simulator.

You can use Monte Carlo modeling with the diffamp example shown in Figure 1-16 from the Process Modeling section. The monteProcess.scs file in Figure 1-22 is an example of a model file you might want to include.

Figure 1-22 File: monteProcess.scs for Monte Carlo Modeling

```
simulator lang=spectre
include "processSimple.scs"
include "process.scs"
statistics {
   process {
     vary RSHSP dist=gauss std=5
     vary RSHPI dist=lnorm std=0.15
     vary SPDW dist=gauss std=0.25
     vary SNDW dist=gauss std=0.25
```

Modeling for Direct Simulation

```
correlate param=[RSHSP RSHPI] cc=0.6
mismatch {
   vary XISN dist=gauss std=1
   vary XBFN dist=gauss std=1
   vary XRSP dist=gauss std=1
}
```

Note: The monteProcess.scs model file includes both the process.scs file shown in Figure 1-19 and the processSimple.scs file shown in Figure 1-18. Both files and the relevant process parameters are discussed in the Process Modeling section.

Package Modeling

With package modeling, you can simulate the effects of the package on the IC. The design is simulated along with the package model. See the *SpectreRF User Guide* for a discussion of package modeling.

Behavioral Modeling

You usually use behavioral models to abstract parts of a design, which shortens the simulation time. Behavioral modeling is usually not appropriate for low-level modeling, for example, the implementation of transistor models. However, you can use it to prototype such models.

You can write behavioral models in behavioral languages like the Verilog®-A language without using the compiled model interface (CMI). If the behavioral modeling language is a standard language, you can use the model with other tools. The parameter \mathbf{r} can be passed in form the instand of the Verilog-A model.

Miscellaneous Modeling Techniques

This section summarizes other modeling techniques used in analog simulation. The usefulness of each technique is discussed, as is the degree of support for each technique available from Cadence tools.

Modeling for Direct Simulation

Passed Model Names

You can use a subcircuit with a device whose model name has the value of pPar("model"). This helps you model a device as a schematic. You can add other components to the schematic. The additional components can be used to model for effects not built-in in the simulation primitive. You have the flexibility to specify the model name of the core device while creating instance of the symbol for the schematic model.

The library developer specifies the model name for the core device M0 as pPar("model"). He also creates a parameter *model* in the CDF with prompt *Model Name*, *parseasCEL* as *yes* and *parseAsNumber* set to *no*

Figure 1-23 Cell nch_sub showing M0 Instance.

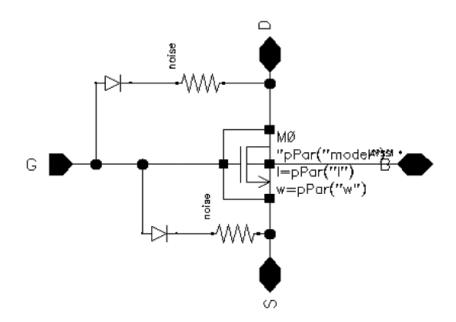
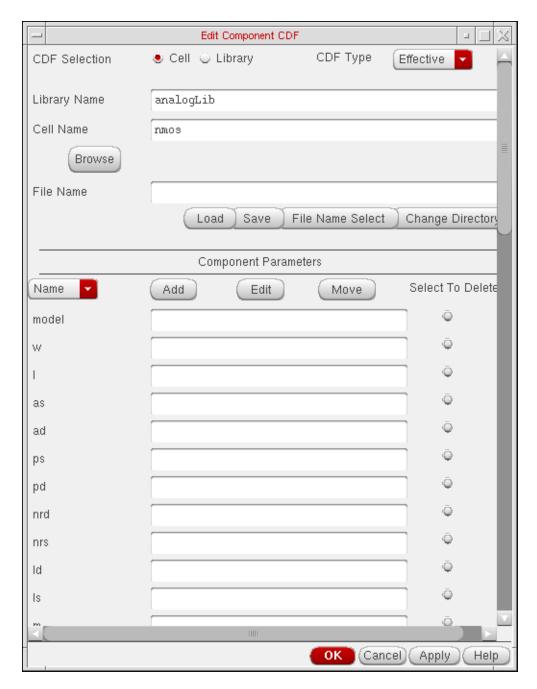


Figure 1-24 Edit Object Properties Form for Instance M0



The designer can now place the symbol for the schematic and can specify the model name of the core device at instance creation time.

For direct interface, both the netlister and the simulator should support passed model names. The analogmodel device is netlisted in the netlist and the model name is passed through the hierarchy.

Modeling for Direct Simulation

Figure 1-25 Direct netlist

Figure 1-26 Contents of file samplelib_nch_sub_schematic.s

```
subckt &1 d g s inh_mn_b
m0 (d g s inh_mn_b) &2 w=(&3) l=(&4)
...
simulator lang=\spice
USEM &2 &2
```

Using the AEL iPar Function

When using the iPar function, you use component description format (CDF) to calculate the length and width of the simulator device from the length and the width you specify on the schematic. This calculation uses the Analog Expression Language (AEL) iPar function.

For example, a CDF parameter Luser with prompt Physical length is accessible for a foundry MOS device through the Virtuoso® schematic composer <u>Edit Object Properties</u> form. The parameter 1 is not shown on that form, but rather is given the value iPar("Luser"). You also specify the parameter 1 as one of the instance parameters for the Spectre netlist. When the component is netlisted, the netlister substitutes the value of Luser for the value of 1.

The drawback of this technique is the substitution performed by the netlister for the iPar expression. After substitution, the relationships between the parameter values on the schematic and those in the netlist are no longer straightforward.

For these reasons, use of the iPar function is discouraged. Instead, you should use the method described in the <u>External Models</u> section.

Modeling for Direct Simulation

CDF Callbacks

Note: You should avoid using this technique as it has many drawbacks.

Multiplier Techniques

In this approach, the devices used have fixed geometries, but a different, related quantity modifies the specification. Such a quantity might be one of the following:

- Number of emitters
- Number of rows and or number of columns or both for the emitter layout
- A multiplier

You add parameters to the schematic to specify the number of emitters and the number of rows or columns in the emitter layout.

In the <u>Virtuoso Analog Design Environment</u>, the multiplier parameter \mathfrak{m} is a special parameter for devices. In a Spectre netlist, you cannot declare \mathfrak{m} in the subcircuit parameter statement. The netlister handles the \mathfrak{m} parameter explicitly for Spectre simulation.

Shared Models

The term *shared models* refers to device models with passed parameters. Instances of models within a subcircuit that have identical model parameter values can share the same model. Sharing models saves some memory in the simulator.

The shared models technique works well for circuits that have many models in a single subcircuit, but the technique offers no improvement if only a few devices are instantiated within a subcircuit.

Model sharing is accomplished with a subcircuit definition. The efficiency aspects described above are handled by the simulator. No special netlisting is performed. Both the netlister and the simulator support passed model parameters. Sharing of models, however, depends entirely on the capabilities of the simulator.

Libraries

This section explains how devices are created in a Cadence library for simulation.

Modeling for Direct Simulation

Defining Netlisting Attributes for Components With CDF

This procedure is explained in the Component Description Format User Guide.

Defining Netlisting Attributes for Components Without CDF

You can define the netlisting attributes using the following documented SKILL procedures:

- almGetModuleName/almSetModuleName
- almGetNamePrefix/almSetNamePrefix
- almGetParameterList/almSetParameterList
- almGetTerminalList/almSetTerminalList
- almGetTerminalMap/almSetTerminalMap
- almGetOpPointParamMap/almSetOpPointParamMap
- almGetNetlistProcedure/almSetNetlistProcedure
- almGetViewInfoNameList
- almGetNetlistType

almHasViewInformation

To use these procedures, use *?noCdf* arguments with a nil value.

Bulk terminals

Note: You can use this technique for devices with or without CDF.

A device might have extra terminals that are not on the symbol, for example, the bulk terminal (B) on MOS devices or the substrate terminal (S) on bipolar devices. In 4.4.3 and later releases, inherited connections are used. The *npn* spectre cellview in analogLib is an example of using inherited connections. In this cellview, the terminal S has a net expression.

Examples

This section presents several specific examples.

Modeling for Direct Simulation

Example: pmos Device

Terminal B in the pmos spectre cellview from the sample library has a net expression. The default is vdd!, and the parameter is bulk B.

The following code sets the netlist attributes for this device:

```
lib = "sample"
cell = "pmos"
view = "spectre"
    cv=(dbOpenCellViewByType lib cell view nil "a")
    (almSetTerminalList
    lib cell '( D G S B ) ?view view ?useCdf nil)
    (almSetTerminalMap lib cell 'D 'd ?view view ?useCdf nil)
    (almSetTerminalMap lib cell 'G 'g ?view view ?useCdf nil)
    (almSetTerminalMap lib cell 'S 's ?view view ?useCdf nil)
    (almSetTerminalMap lib cell 'S 's ?view view ?useCdf nil)
    (almSetTerminalMap lib cell 'B 'b ?view view ?useCdf nil)
    (almSetParameterList
    lib cell
    '( w l as ad ps pd nrd nrs ld ls m trise region degradation )
    ?view view ?useCdf nil)
    dbSave( cv )
```

The lib variable is set to sample, and the view variable is set to spectre.

Example: nmos Device

Terminal B in the spectre view of the nmos device has a net expression. The default is gnd!, and the parameter of the net expression is bulk B.

```
lib = "sample"
cell = "nmos"
view = "spectre"
    cv=(dbOpenCellViewByType lib cell view nil "a")
    (almSetTerminalList lib cell '( D G S B ) ?view "spectre" ?useCdf nil)
    (almSetTerminalMap lib cell 'D 'd ?view "spectre" ?useCdf nil)
    (almSetTerminalMap lib cell 'G 'g ?view "spectre" ?useCdf nil)
    (almSetTerminalMap lib cell 'S 's ?view "spectre" ?useCdf nil)
    (almSetTerminalMap lib cell 'S 'b ?view "spectre" ?useCdf nil)
    almSetTerminalMap lib cell 'B 'b ?view "spectre" ?useCdf nil)
    almSetParameterList
    lib cell
    '( w l as ad ps pd nrd nrs ld ls m trise region degradation )
    ?view "spectre" ?useCdf nil)
```

Modeling for Direct Simulation

```
dbSave ( cv )
```

Example: Resistor

Example: Voltage Source

```
cell = "vsrc"
(almSetModuleName lib cell "vsource" ?view "spectre" ?useCdf nil)
(almSetTerminalList lib cell '(N\+ N ) ?view "spectre" ?useCdf nil)
(almSetTerminalMap lib cell 'N\+ ":p" ?view "spectre" ?useCdf nil)
(almSetTerminalMap lib cell 'N "(FUNCTION minus(root('N+')))"
      ?view "spectre" ?useCdf nil)
(almSetParameterList
lib cell
' (
dc type
;; Pulse waveform parameters:
    delay val0 val1 period rise fall
    width
;; PWL waveform parameters:
    file wave offset scale stretch
    allbrkpts pwlperiod twidth
;; Sinusoidal waveform parameters:
    sinedc ampl freq sinephase ampl2
    freq2 sinephase2 fundname
    other fundname2 fmmodindex fmmodfreq
    ammodindex ammodfreq
    ammodphase damp
;; Exponential waveform parameters:
    td1 tau1 td2 tau2
;; Noise Parameters:
```

Modeling for Direct Simulation

```
noisefile noisevec
;; Small signal parameters:
    mag phase xfmag pacmag pacphase
;; Multiplication factor parameters:
    m
;;Temperature effects parameters:
    tc1 tc2 tnom)
        ?view "spectre" ?useCdf nil)
    dbSave( cv )
```

Netlist procedures

You can write netlist procedures using documented methods. In most situations, the netlisting of components is adequately addressed by specifying entities such as parameter lists.

In certain situations, however, more advanced control is required. This control can be obtained through netlist procedures. By default, the netlist procedure is specified as nil, and the *nlPrintInst* method from the formatter is used. If you specify a netlisting procedure, that procedure is used instead.

You can define attributes to customize components by using the procedures in the <u>Defining Netlisting Attributes for Components Without CDF</u> section.

The principal reason for customizing netlisting is to use special parameters. To maintain consistency, Cadence discourages customization of other aspects of the netlist. Customization affects netlisting performance in the following ways:

- Modifying comments affects the look of the netlist. A modified component looks different from components from other sources. Designers look at the netlist and the simulator input file, so such presentation differences deserve caution.
- Modifying only the indent string changes the look of the netlist. Do not modify it to customize libraries.
- Changing the formatter instance name can create name mapping errors.

 These errors result in unresolved names during the simulation or results display. The formatter guarantees correct name mapping. It also ensures that signals are printed according to the connectivity in the design and in the order specified.
- Changing the default model name causes serious design flow problems. The default model name follows conventions used throughout the Virtuoso Analog Design Environment and the major OSS interfaces.

Modeling for Direct Simulation

The netlisting procedure does not print the end of the line. End-of-line printing is the responsibility of the nlPrintInstEnd method, which is called by the netlister after the netlist procedure is called. This practice permits a netlist procedure to be called from another netlist procedure.

In the following example, a netlist procedure prints a parameter that is enclosed by double quotes.

For completeness, the following example shows a netlist procedure that has identical functionality to the nlPrintInst method of the nlAnalogFormatter class:

```
(defun myNetlistProc (inst)
    ;; Print any comments
    (nlPrintInstComments formatter inst)

;; Print the indentation
    (nlPrintIndentString netlister)

;; Print the instance name
    (nlPrintInstName formatter inst)

;; Print the signals
    (nlPrintInstSignals formatter inst)

;; Print the model name
    (nlPrintModelName formatter inst)

;; Print the instance parameters
    (nlPrintInstParameters formatter inst)
```

t)

Modeling for Direct Simulation

The following example shows modifications required in nlPrintModelName method for your simulator to support model name passing:

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