The George Washington University

Crowd Counting

Machine Learning II- Deep Learning

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Introduction:

When there is an influx of a large number of people it can cause accidents such as a stampede. During sports events, large stadiums are full of people, this project can be used in order to analyze and predict the number of people in each area and prevent any accidents from taking place. It can also be used to analyze the number of people in a mall in order to prevent overcrowding and avoid mishaps from taking place. The relevance of this project can be seen in 2020, when there is an outbreak of a virus, it is mandatory to remain indoors, this project can be used to alert authorities when the number of people goes above a certain threshold. The goal of this project is to be able to predict the number of people in each image.

In this report, we describe the dataset used, the architecture of the two models, explanations of our results, and finally evaluation of our models.

Dataset:

The <u>dataset</u> consists of a collection of 2000 images, each image has a size of 480x640 pixels and has 3 channels. The images were collected from a still webcam that is located inside a mall. Each image has a different number of people. We are provided with a CSV file containing labels that give the number of people present in each image.

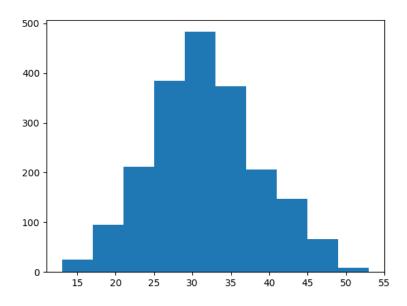


Fig 1. Distribution of labels

The image data is displayed below.





Fig 2. Image data that is input to the training models

Data Cleaning and Preprocessing:

The data is preprocessed and resized to 128x96 in order to store and train the data easily.

Fig 3. Code to pre-process data

As the data is not evenly distributed, we introduce an image generator.

```
76 # add ImageDataGenerator
77 datagen = ImageDataGenerator(
78
     featurewise_center=False,
      samplewise_center=False,
      featurewise_std_normalization=False,
81
     samplewise_std_normalization=False,
82
      zca_whitening=False,
83
      rotation_range=30,
      width_shift_range=0.1,
85
      height_shift_range=0.1,
      horizontal_flip=True,
87
       vertical_flip=False,
       shear_range=0.5)
```

Fig 4. Code for image augmentation

Architecture of the models:

Background:

For this project, we are using CNN and a pre-trained ResNet 50 model. We are using the CNN model mainly because it's a fully connected feed-forward neural network. CNN is very effective in reducing the number of parameters and maintain the image quality at the same time. By adding a regression layer at the end of the network, we are able to fit the model with this regression problem.

A similar reason is used for the pre-trained ResNet 50 model. ResNet 50 is a 50 layers Residual Network. We can also change the output layer to make the model predict the number of people in the image. The ResNet 50 model differs from the ordinary model in that it's using skip or shortcut connections. With the shortcut connections, the model measures the residuals calculate by each layer, and make sure the higher layer performs at least as good as the lower layer, and not worse.

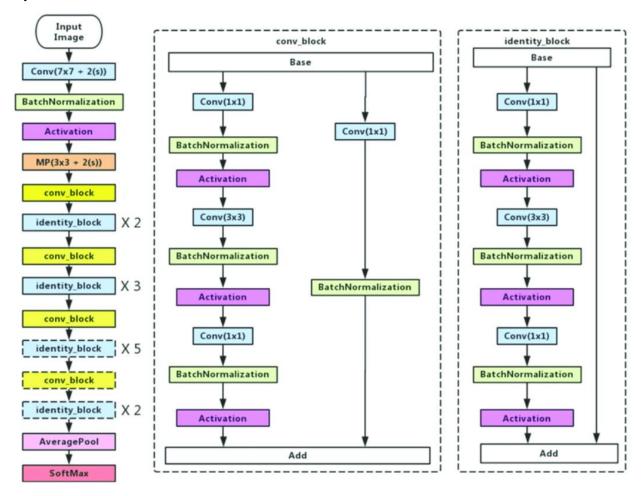


Fig 5. Sample ResNet-50 Architecture

Hyper-parameter selection:

We use various techniques to find the appropriate learning rate, batch size, and numbers of epochs. In order to fine-tune the model, we use a Learning Rate scheduler to find the best learning rate for the model.

```
90 lr_monitor = tf.keras.callbacks.LearningRateScheduler(
        lambda epochs: 1e-8 * 10 ** (epochs / 20))
 93 model check = ModelCheckpoint("1205-CNN.hdf5", monitor="val loss", verbose=1, save best only=True
 95 learning_rate_reduction = ReduceLROnPlateau(
        monitor='val_mean_absolute_error',
        verbose=1,
        factor=0.2,
        min lr=0.000001
101 )
103 epochs = 100
104 datagen.fit(x_train)
105  # fits the model on batches with real-time data augmentation:
106 history = model.fit(datagen.flow(x_train, y_train, batch_size=32),
                      steps_per_epoch=len(x_train) / 32, epochs=epochs,
                       validation data=(x test, v test).
                       callbacks=[lr_monitor, model_check],
                      shuffle=True)
```

Fig 6. Code for finding appropriate learning rate

From this we select the learning rate to be 3e-4, as it gives us the least loss value. We make use of the Learning Rate Scheduler that reduces the learning rate in order to best fit the model.

```
lr_monitor = tf.keras.callbacks.LearningRateScheduler(
         lambda epochs: 1e-8 * 10 ** (epochs / 20))
 93 model_check = ModelCheckpoint("1205-CNN.hdf5", monitor="val_loss", verbose=1, save_best_only=True
 95 learning_rate_reduction = ReduceLROnPlateau(
         monitor='val_mean_absolute_error',
        patience=3,
         verbose=1,
         factor=0.2,
         min lr=0.000001
101 )
103 epochs = 100
104 datagen.fit(x train)
105 # fits the model on batches with real-time data augmentation:
106 history = model.fit(datagen.flow(x_train, y_train, batch_size=32),
                        steps_per_epoch=len(x_train) / 32, epochs=epochs,
                       validation_data=(x_test, y_test),
                       callbacks=[lr_monitor, model_check],
                      shuffle=True)
```

Fig 7. Code for the hyper-parameters

The batch size is selected as 32. As you can see in the figures below the loss value drops quickly and considerably for batch size 32, while for batch size 64 and 128 it takes longer for the loss values to drop.

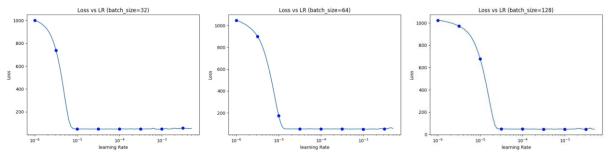


Fig 8. Learning rate vs Loss

Training CNN model:

While training the CNN model we make use of relu as the activation function and Adam as the optimizer function.

```
----- Model Prep
# create CNN model
model = tf.keras.Sequential([
    tf.keras.layers.Conv2D(16, (5, 5), input_shape=(128, 96, 3), activation=tf.keras.activations.
    tf.keras.layers.MaxPool2D(2, 2),
    tf.keras.layers.Conv2D(32, (3, 3), activation=tf.keras.activations.relu),
    tf.keras.layers.MaxPool2D(2, 2),
   tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Flatten(),
    # tf.keras.layers.Dense(400, activation=tf.keras.activations.relu),
    # tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dense(1)
])
model.compile(loss="mean_squared_error", # This is a classic regression score - the lower the be
             metrics=['mean_absolute_error'],
             optimizer=tf.keras.optimizers.Adam(1r=3e-4))
```

Fig 9. Code to compile model

For fitting the model we make use of 100 epochs, increasing the number of epochs cause the model to overfit the data, therefore we chose 100 epochs. The final model was trained on a batch size of 32.

```
97
98 epochs = 100
99 datagen.fit(x_train)
100 # fits the model on batches with real-time data augmentation:
101 history = model.fit(datagen.flow(x_train, y_train, batch_size=32),
102 steps_per_epoch=len(x_train) / 32, epochs=epochs,
103 validation_data=(x_test, y_test),
104 callbacks=[lr_monitor, model_check],
105 shuffle=True)
106
```

Fig 10. Code to fit the model

Training ResNet 50 model:

The data is set up by using the "flow from dataframe" function. The data is split into training and validation.

```
49 datagen = ImageDataGenerator(
      rescale=1. / 255,
       featurewise_center=False,
      samplewise_center=False,
     featurewise_std_normalization=False,
      samplewise_std_normalization=False,
       zca_whitening=False,
     horizontal_flip=True,
       vertical flip=True,
       validation_split=0.2,
       preprocessing_function=resnet50.preprocess_input
61 )
63 flow params = dict(
       directory='/home/ubuntu/Deep-Learning/Final Project/frames/frames',
       x_col="image_name",
       y_col="count",
       weight_col=None,
       target_size=(128, 96),
       color_mode='rgb',
       class_mode="raw",
      batch_size=batch,
       seed=0
75 )
77 # The dataset is split to training and validation sets
78 train_generator = datagen.flow_from_dataframe(
      subset='training',
80
        **flow_params
81 )
82 valid_generator = datagen.flow_from_dataframe(
     subset='validation',
        **flow_params
84
85 )
```

Fig 11. Code snippet for data splitting

Training the model, the top seven layers, the last parts of the pre-trained model, are made untrainable to avoid overfitting and also to fit this regression problem. We add one dense layer and one final output layer that gives out one parameter, the prediction of the number of people in the image.

```
base_model = resnet50.ResNet50(
90
      weights='imagenet',
       include_top=False,
      input_shape=(128, 96, 3),
       pooling='avg'
94 )
96 # Change the top (the last parts) of the network.
97 x = base_model.output
98 x = Dense(1024, activation='relu')(x)
    predictions = Dense(1, activation='linear')(x)
    model = Model(inputs=base model.input, outputs=predictions)
101 k = -7
102 for layer in model.layers[:k]:
       layer.trainable = False
104 print('Trainable:')
105 for layer in model.layers[k:]:
       print(laver.name)
       layer.trainable = True
```

Fig 12. Compiling ResNet 50 model

Finally to compile the model we make use of the Adam optimizer. For training the model, we apply a learning rate monitor that focuses on the validation mean squared error. For every 3 epochs, if the mean squared error doesn't go down, the learning rate will drop by 20%, the lowest learning rate will not go beyond 1e-6.

```
111  optimizer = Adam(learning_rate=3e-4)
113 model.compile(
        optimizer=optimizer.
        loss="mean_squared_error", # This is a classic regression score - the lower the better
        metrics=['mean_absolute_error', 'mean_squared_error']
119 learning rate reduction - ReduceLROnPlateau(
        monitor='val_mean_squared_error',
        patience=3,
        verbose=1,
        min_lr=0.000001
125 )
model_check = ModelCheckpoint('resnet50_cc.hdf5', monitor='val_loss', verbose=2, save_best_only=T
129 # Fit the model
130 history - model.fit(
        train_generator,
        epochs=105,
        validation data=valid generator,
        callbacks=[learning_rate_reduction, model_check]
136 )
```

Fig 13. Optimizer and training code

Evaluation:

Models	Mean Absolute Error	Mean Square Error
CNN	5.55	50.29
ResNet 50	4.92	36.31

Fig 14. Table with metrics evaluations

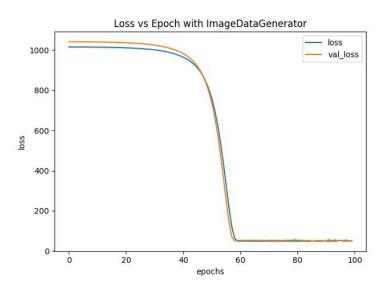


Fig 15. CNN Training loss & validation loss

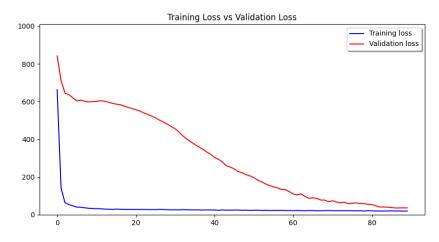


Fig 16. ResNet50 Training loss & validation loss

Prediction results:

- CNN model:



Fig 17. CNN model predict results vs actual results

- ResNet 50 model:

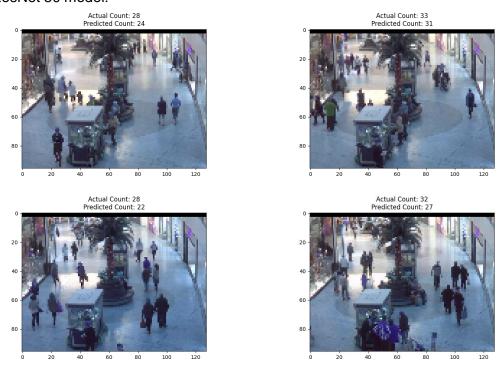


Fig 18. ResNet 50 model predict results vs actual results

Appendix- Code: Resnet train 50: import os import cv2 import random import scipy import numpy as np import pandas as pd import matplotlib.pyplot as plt from keras.optimizers import Adam from keras.models import * from keras.layers import * from sklearn.metrics import mean_squared_error from tensorflow.keras.applications import resnet50 from keras.preprocessing.image import ImageDataGenerator from keras.callbacks import ReduceLROnPlateau from sklearn.model_selection import train_test_split import tensorflow as tf from tensorflow.python.keras.callbacks import ModelCheckpoint SEED = 42os.environ['PYTHONHASHSEED'] = str(SEED) random.seed(SEED) np.random.seed(SEED) tf.random.set_seed(SEED) # references https://www.kaggle.com/rmishra258/counting-crowd-with-cnnsocial-distancing-project # %% ------ Load Data -----

```
DATA_DIR = os.getcwd() + "/frames/"
x, y = [], []
label = pd.read_csv("labels.csv")
label['image_name'] = label['id'].map('seq_{:06d}.jpg'.format)
lb = label['id']
count = label['count']
for path in [f for f in os.listdir(DATA_DIR) if f[-4:] == ".ipg"]:
  x.append(cv2.resize(cv2.imread(DATA_DIR + path), (128, 96)))
  for i in range(len(lb)):
     if lb[i] == int(path[4:-4]):
       y.append(count[j])
x, y = np.array(x), np.array(y)
x_train, x_test, y_train, y_test = train_test_split(x, y, random_state=SEED,
test size=0.2)
x_train, x_test = x_train / 255, x_test / 255
resize = 64
batch = 256
# ImageDataGenerator - with defined augmentaions
datagen = ImageDataGenerator(
  rescale=1. / 255,
  featurewise_center=False,
  samplewise_center=False,
  featurewise_std_normalization=False,
  samplewise_std_normalization=False,
  zca whitening=False,
  horizontal_flip=True,
  vertical_flip=True,
  validation_split=0.2,
  preprocessing_function=resnet50.preprocess_input
```

```
flow_params = dict(
  dataframe=label,
  directory=DATA_DIR,
  x_col="image_name",
  y_col="count",
  weight_col=None,
  target_size=(128, 96),
  color_mode='rgb',
  class mode="raw",
  batch_size=batch,
  shuffle=True,
  seed=0
# The dataset is split to training and validation sets
train_generator = datagen.flow_from_dataframe(
  subset='training',
  **flow_params
valid_generator = datagen.flow_from_dataframe(
  subset='validation',
  **flow_params
batch = next(train_generator)
base_model = resnet50.ResNet50(
  weights='imagenet',
  include_top=False,
  input_shape=(128, 96, 3),
  pooling='avg'
# Change the top (the last parts) of the network.
```

```
x = base_model.output
x = Dense(1024, activation='relu')(x)
predictions = Dense(1, activation='linear')(x)
model = Model(inputs=base_model.input, outputs=predictions)
k = -7
for layer in model.layers[:k]:
  layer.trainable = False
print('Trainable:')
for layer in model.layers[k:]:
  print(layer.name)
  layer.trainable = True
optimizer = Adam(learning_rate=3e-4)
model.compile(
  optimizer=optimizer,
  loss="mean_squared_error",
  metrics=['mean_absolute_error']
learning_rate_reduction = ReduceLROnPlateau(
  monitor='val_mean_absolute_error',
  patience=3,
  verbose=1,
  factor=0.2,
  min_Ir=0.000001
model_check = ModelCheckpoint('resnet50_cc.hdf5', monitor='val_loss',
verbose=2, save_best_only=True)
# Fit the model
history = model.fit(
  train_generator,
```

```
epochs=90,
  validation_data=valid_generator,
  verbose=2,
  callbacks=[learning_rate_reduction, model_check]
print('\nTraining Done')
# Plot the loss and accuracy curves for training and validation
fig, ax = plt.subplots(1, 1, figsize=(10, 5))
ax.plot(history.history['loss'], color='b', label="Training loss")
ax.plot(history.history['val_loss'], color='r', label="Validation loss", axes=ax)
ax.set_ylim(top=np.max(history.history['val_loss']) * 1.2, bottom=0)
legend = ax.legend(loc='best', shadow=True)
ax.set_title('Training Loss vs Validation Loss')
plt.show()
# Predict on entire validation set, to be able to review the predictions
manually
valid_generator.reset()
all_labels = []
all_pred = []
for i in range(len(valid_generator)):
  x = next(valid_generator)
  pred_i = model.predict(x[0])[:, 0]
  labels_i = x[1]
  all_labels.append(labels_i)
  all_pred.append(pred_i)
test_labels = np.concatenate(all_labels)
test_pred = np.concatenate(all_pred)
df_predictions = pd.DataFrame({'True values': test_labels, 'Predicted
values': test_pred})
ax = df_predictions.plot.scatter('True values', 'Predicted values', alpha=0.5,
s=14, figsize=(9, 9))
```

```
# ax.plot(df_predictions['True values'], df_predictions['Predicted values'],
color='r')
ax.grid(axis='both')
ax.set_title('Testing set')
plt.show()
# ----- Evaluation -----
mse = mean_squared_error(*df_predictions.T.values)
pearson r = scipy.stats.pearsonr(*df predictions.T.values)[0]
#print(f'MSE on testing: {mse:.1f}\nPearson r between True Values and
Predicted Values: {pearson_r:.1f}')
print("MSE Train Set Loss value", history.history['loss'][-1])
print("MSE Validation Set Loss value", history.history['val_loss'][-1])
print("MAE Test Set Loss value",history.history['mean_absolute_error'][-1])
print("MAE Validation Set Loss
value", history.history['val_mean_absolute_error'][-1])
Cnn train:
# %% ------ Imports ------
import random
import os
import cv2
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.model_selection import train_test_split
import tensorflow as tf
from keras_preprocessing.image import ImageDataGenerator
```

```
from tensorflow.python.keras.callbacks import ReduceLROnPlateau,
ModelCheckpoint
# references https://www.kaggle.com/rmishra258/counting-crowd-with-cnn-
social-distancing-project
# %% ------ Set-Up ------
SEED = 64
os.environ['PYTHONHASHSEED'] = str(SEED)
random.seed(SEED)
np.random.seed(SEED)
tf.random.set_seed(SEED)
# %% ------ Load-Data ------
# read the labels.cvs to get the labels and set columns name: 'image_id',
'num_of_people'
df_of_labels = pd.read_csv('labels.csv')
df_of_labels.columns = ['image_id', 'num_of_people']
# get the label_num of the people
labels = np.array(df_of_labels['num_of_people'])
print("labels.shape:\n", labels.shape)
# read the data of image, check the dimension
DATA_DIR = os.getcwd()+"/frames/"
# set image size to (128, 96)
X = []
for path in [f for f in os.listdir(DATA DIR) if f[-4:] == ".ipg"]:
  x.append(cv2.resize(cv2.imread(DATA_DIR + path), (128, 96)))
x = np.array(x)
print("x.shape:\n", x.shape)
```

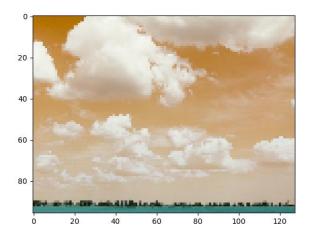
```
# %% ------ Data Prep ------
x_train, x_test, y_train, y_test = train_test_split(x, labels, test_size=0.2)
x_train, x_test = x_train.astype('float') / 255, x_test.astype('float') / 255
print("x_train.shape:\n", x_train.shape, "\nx_test.shape:\n", x_test.shape)
print("y_train.shape:\n", y_train.shape, "\ny_test.shape:\n", y_test.shape)
# %% ------ Model Prep ------
# create CNN model
model = tf.keras.Sequential([
  tf.keras.layers.Conv2D(16, (5, 5), input_shape=(128, 96, 3),
activation=tf.keras.activations.relu),
  tf.keras.layers.MaxPool2D(2, 2),
  tf.keras.layers.Conv2D(32, (3, 3), activation=tf.keras.activations.relu),
  tf.keras.layers.MaxPool2D(2, 2),
  tf.keras.layers.Dropout(0.2),
  tf.keras.layers.Flatten(),
  tf.keras.layers.Dense(1)
])
model.compile(loss="mean_squared_error",
        metrics=['mean_absolute_error'],
        optimizer=tf.keras.optimizers.Adam(lr=3e-4))
# add ImageDataGenerator
datagen = ImageDataGenerator(
  featurewise_center=False,
  samplewise_center=False,
  featurewise_std_normalization=False,
```

```
samplewise_std_normalization=False,
  zca_whitening=False,
  rotation_range=30,
  width_shift_range=0.1,
  height_shift_range=0.1,
  horizontal_flip=True,
  vertical_flip=False,
  shear_range=0.5)
Ir monitor = tf.keras.callbacks.LearningRateScheduler(
  lambda epochs: 1e-8 * 10 ** (epochs / 20))
model check = ModelCheckpoint("keras-CNN-128-96.hdf5",
monitor="val_loss", verbose=1, save_best_only=True)
learning_rate_reduction = ReduceLROnPlateau(
  monitor='val_mean_absolute_error',
  patience=3,
  verbose=1,
  factor=0.2,
  min Ir=0.000001
epochs = 100
datagen.fit(x_train)
# fits the model on batches with real-time data augmentation:
history = model.fit(datagen.flow(x_train, y_train, batch_size=32),
           steps_per_epoch=len(x_train) / 32, epochs=epochs,
           validation_data=(x_test, y_test),
           callbacks=[lr_monitor, model_check],
           shuffle=True)
# %% ------ Training Loop ------
# plot loss
```

```
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.legend(['loss', 'val_loss'])

plt.xlabel('epochs')
plt.ylabel('loss')
plt.title('Loss vs Epoch with ImageDataGenerator')
plt.show()
print("MSE Train Set Loss value", history.history['loss'][-1])
print("MSE Validation Set Loss value", history.history['val_loss'][-1])
print("MAE Test Set Loss value", history.history['mean_absolute_error'][-1])
print("MAE Validation Set Loss
value",history.history['val_mean_absolute_error'][-1])
```

Appendix- added on Professors suggestion



The true label: 0 Predicted Label: 27

From this we can see that the model fails when there are no people in the image. We believe this is because the image was not trained to recognize these images, we could improve this by adding more images with 0 people.

Correctly predicted values:

ResNet:24/400 CNN: 31/400

From this we can see that our inference was wrong the CNN model performs much better which means that our loss values do not give us much information and we should use accuracy, precision and recall for future comparisions.

Conclusion:

It can be seen from the results that the CNN model designed this time can successfully predict the number of people in the picture. However, from the picture shown in Fig 17. CNN model predicts results vs actual results, we can also find that the predicted results still have partial deviations, so this model has room for improvement. This improvement can be used as a future research direction.

We can see that the ResNet50 model performed better than the CNN model in Fig 18, but there is still room for improvement. In the future, we would look to collect more data and improve the performance of our model. As of now, we are limited because the data collected does not have any images for more than 55 people, our next step would be to find such data points. Also, for future improvements, the MCNN (Multi-Scale Convolutional Neural Networks) model could be a better model because it's designed to count a small number of people inside an image. Since this dataset is predicting numbers of people in the mall from one camera, we can also see from the distribution of the labels, the counts are not very big. Therefore, the MCNN model might be a better fit for the dataset.

References:

- Optimized Deep Convolutional Neural Networks for Identification of Macular Diseases from Optical Coherence Tomography Images - Scientific Figure on ResearchGate. Retrieved December 07, 2020, from https://www.researchgate.net/figure/Left-ResNet50-architecture-Blocks-with-dotted-line-represents-modules-that-might-be-fig3_331364877
- 2. T, S. (2020, August 18). Crowd Counting Keras pretrained ResNet50 CNN. Retrieved December 07, 2020, from https://www.kaggle.com/shovalt/crowd-counting-keras-pretrained-resnet50-cnn

3.	Mishra, R. (2020, June 18). Counting crowd with CNN- social distancing project. Retrieved December 07, 2020, from https://www.kaggle.com/rmishra258/counting-crowd-with-cnn-social-distancing-project
4.	DAGNetwork. (n.d.). Retrieved December 07, 2020, from https://www.mathworks.com/help/deeplearning/ref/resnet50.html