

回归分析

Regression

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■ 主要内容

- 相关分析
- 线性回归
 - 一元线性回归
 - 多元线性回归
 - 多项式回归
- 非线性回归
- 回归分析的统计特性

■参考教材

- 《数理统计学习教程》 陈希孺2009
- (Statistical Model)
 David Freedman 2010
- 《Statistical Inference》
 George Casella 2002
- 《Linear Regression Analysis》
 George Seba 2003



- ■基础知识
 - 研究变量之间的两种关系
 - 确定性关系: 变量之间存在确定性的因果关系, 可用函数关系表达
 - 相关性关系: 变量之间存在非确定性的依赖关系, 又称统计相关关系



■ 统计相关关系

- 变量之间存在非确定性的依赖关系, 但具有统计意义上的相关性
- 涉及的变量是随机变量

例1: 身高和体重, 不存在准确的函数可以由身高计算出体重, 但从统计意义上来说, 它们之间存在相关性, 身高者, 体也重

例2: **父母的身高与子女的身高**之间也有一定联系, 通常父母高, 子女也高



■ 回归分析: Regression Analysis

回归分析:一种研究变量间统计相关关系的统计分析方法.

(研究相关性关系的最基本, 应用最广泛的方法)



■回归模型

- $X = (x_1, x_2, ..., x_k)$: 非随机变量, **自变量** (independent variable)
- y: 受 $x_1, x_2, ..., x_k$ 的随机影响, 随机变量, 因变量 (dependent variable)
- y 对 $x_1, x_2, ..., x_k$ 相关关系的数学模型: $y=f(x_1, x_2, ..., x_k)+\varepsilon$ 称 y 对 $x_1, x_2, ..., x_k$ 的回归模型, ε 随机误差
- $y=f(x_1, x_2, ..., x_k)$ 称 y 对 $x_1, x_2, ..., x_k$ 的回归方程, 函数 $f(x_1, x_2, ..., x_k)$ 称为回归函数, y 对 X 的回归函数



■回归分析

- 回归分析: 根据变量 $x_1, x_2, ..., x_k$ 和 y 的具体观察值去估计回归函数 f
- 一元线性回归分析: 只有一个自变量的回归分析 (i.e. k=1): y=ax+b

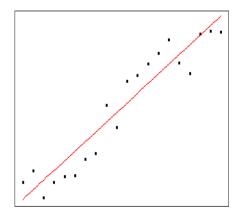


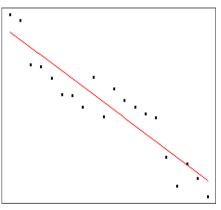
Analysis of Correlation 相关分析

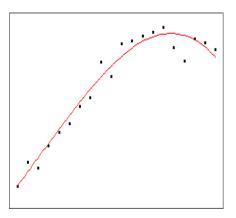


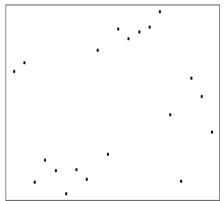
■ 1. 散点图

- 散点图是描述变量之间关系的一种直观方法.
- 我们用坐标的横轴代表自变量 x, 纵轴代表因变量 y, 每组数据 (x_i, y_i) 在坐标系中用一个点表示, 由这些点形成的散点图描述了两个变量之间的大致关系, 从中可以直观地看出变量之间的关系形态及关系强度.











■ 2. 相关系数

- 相关系数是对变量之间关系密切程度的度量
- 总体相关系数
 - 若相关系数是根据总体全部数据计算的,称为**总体相关系数**,记为 ρ
- 样本相关系数
 - 若相关系数是根据样本数据计算的, 则称为**样本相关系数**, 记为 r
 - 样本相关系数简称为相关系数



- 2. 相关系数
 - 总体相关系数

$$\rho = \frac{COV(X,Y)}{\sqrt{D(X)}\sqrt{D(Y)}}$$

COV(X,Y) 为变量 X 和 Y 的协方差 D(X) 和 D(Y) 分别为 X 和 Y 的方差

• 样本相关系数

$$r = \frac{\sum_{i=1}^{n} (x_i - \overline{x})(y_i - \overline{y})}{\sqrt{\left(\sum_{i=1}^{n} (x_i - \overline{x})^2\right) \left(\sum_{i=1}^{n} (y_i - \overline{y})^2\right)}}$$

一般情况下,总体相关系数 ρ 是未知的. 通常是将样本相关系数r作为 ρ 的近似估计值.



■ 相关系数r的性质

- 1) 相关系数的取值范围: $-1 \le r \le 1$. 若 $0 < r \le 1$, 表明 X = 1 与 $Y \ge 1$ 之间存在**正线性相关关系**; 若 $-1 \le r < 0$, 表明 X = 1 之间存在**负线性相关关系**.
- 2) 若 r = 1, 表明 X = 1 之间为完全正线性相关关系; 若 r = -1, 表明 X = 1 之间为完全负线性相关关系; 若 r = 0, 说明二者之间**不存在**线性相关关系.



■ 相关系数r的性质

• 3) 当 -1 < r < 1 时, 为说明两个变量之间的线性关系的密切程度, 通常将相关程度分为以下几种情况:

```
当 |r| \ge 0.8 时, 可视为高度相关; 当 0.5 \le |r| < 0.8 时, 可视为中度相关; 当 0.3 \le |r| < 0.5 时, 可视为低度相关;
```

建立在对相关系数进行显著性检验的基础之上

当 |r| < 0.3 时, 说明两个变量之间的相关程度极弱, 可视为不相关.



- 3. 相关系数的显著性检验
 - 检验总体相关系数 ρ 是否显著为 0
 - 通常采用费歇尔 (Fisher) 提出的 t 分布检验, 可用于小样本, 也可用于大样本



1) 提出假设:

假设样本是从一个不相关的总体中随机抽取的, 即 H_0 : $\rho = 0$; H_1 : $\rho \neq 0$

2) 由样本观测值计算检验统计量:

$$t = |r| \sqrt{\frac{n-2}{1-r^2}} \sim t(n-2)$$

的观测值 t_0 和衡量观测结果极端性的 P值 (P-value): P-value = $P\{|t| \ge |t_0|\} = 2P\{t \ge |t_0|\}$

3) 进行决策:

比较 P值 和显著性水平 α 作判断: 若 $P < \alpha$, 拒绝原假设 H_0 ; 若 $P \ge \alpha$, 不能拒绝原假设 H_0 .



■ 相关系数的显著性检验

- 若 P>0.05, 接受 H_0 , 相关不显著, 即总体 x 与 y 间不存在相关关系
- 若 0.01 < P < 0.05, 拒绝 H_0 , 相关显著, 即总体 x 与 y 间存在显著相关 关系
- 若 P < 0.01, 拒绝 H_0 , 相关极显著, 即总体 x 与 y 间存在极显著的相关关系



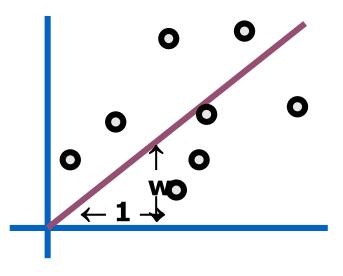
Linear Regression 线性回归



- Linear Regression (线性回归)
 - Linear regression is a linear approach for modelling the relationship between a *scalar* dependent variable y (一个因变量) and one or more <u>explanatory variables</u> (or <u>independent variables</u>, 一个或多个自变量) denoted X.
 - In linear regression, the relationships are modeled using <u>linear predictor functions</u> whose unknown model <u>parameters</u> are *estimated from the data*.
 - 线性回归分析是研究一个因变量 y 与一个或多个自变量 X 间关系的统计方法



■ Linear Regression (线性回归)



inputs	outputs
$x_1 = 1$	$y_1 = 1$
$x_2 = 3$	$y_2 = 2.2$
$x_3 = 2$	$y_3 = 2$
$x_4 = 1.5$	$y_4 = 1.9$
$x_5 = 4$	$y_5 = 3.1$

- Linear regression assumes that the expected value $\hat{y} = E[y|x]$: $y \forall x \Leftrightarrow \Box$ of the output given an input, E[y|x], is **linear**.
- Simplest case: out(x) = wx for some unknown w.
- Given the data, we can estimate w.

- 归函数, 简称回归
- *x*是一维: 一元回归
- *x*是*p*维向量: *p*元回归



Linear Regression

• In linear regression, the case of one independent variable (一个自变量) is called <u>simple linear regression</u> (一元线性回归).

• For more than one independent variable (多个自变量), the process is called <u>multiple linear regression</u> (多元线性回归).



■ 1. Simple Linear Regression (一元线性回归)

Assume that the data is formed by a linear equation:

$$y_i = wx_i + noise_i$$

where...

- the noise signals are independent
- the noise has a normal distribution with mean 0 and unknown variance σ^2

p(y|w,x) has a normal distribution with

- mean wx
- variance σ^2



Bayesian Linear Regression

$$p(y|w,x) = N(wx, \sigma^2)$$

We have a set of data points (x_1,y_1) (x_2,y_2) ... (x_n,y_n) which are evidence about w.

We want to infer w from the data.

$$p(w|x_1, x_2, ...x_n, y_1, y_2, ...y_n)$$

- We can use BAYES rule to work out a posterior distribution for w given the data.
- Or we could do Maximum Likelihood Estimation.



- Maximum a Posterior Estimation
 - In Bayesian statistics, a **maximum a posteriori probability (MAP) estimation** is an estimate of an unknown quantity, that equals the mode of the posterior distribution.
 - The MAP can be used to obtain a point estimate of an unobserved quantity on the basis of empirical data.



- Maximum a Posterior Estimation
 - MAP estimation

$$p(w|\{x_i, y_i\}) = \frac{p(\{y_i\}|w, \{x_i\})p(w)p(\{x_i\})}{p(\{x_i, y_i\})}$$

$$\arg \max_{w} p(w|\{x_i, y_i\}) = \arg \max_{w} p(\{y_i\}|w, \{x_i\})p(w)$$

需要知道被估计参数w的先验分布概率



- Maximum Likelihood Estimation
 - In statistics, maximum likelihood estimation (MLE) is a method of estimating the parameters of a statistical model, given observations.
 - MLE attempts to find the parameter values that **maximize the likelihood function**, given the observations.



Maximum Likelihood Estimation

Asks the question:

"For which value of w is this data most likely to have happened?"

For what w is $p(y_1, y_2, ..., y_n | x_1, x_2, ..., x_n, w)$ maximized?

$$\arg \max_{w} p(w|\{x_i, y_i\}) = \arg \max_{w} p(\{y_i\}|w, \{x_i\})$$



Maximum Likelihood Estimation

Asks the question:

"For which value of w is this data most likely to have happened?"

For what w is $p(y_1, y_2, ..., y_n | x_1, x_2, ..., x_n, w)$ maximized?

For what w is $\prod_{i=1}^{n} p(y_i|w,x_i)$ maximized?



Maximum Likelihood Estimation

For what
$$w$$
 is $\prod_{i=1}^{n} p(y_i|w,x_i)$ maximized?

For what
$$w$$
 is $\prod_{i=1}^{n} \exp\left(-\frac{(y_i - wx_i)^2}{2\sigma^2}\right)$ maximized?

For what
$$w$$
 is $\sum_{i=1}^{n} -\frac{(y_i - wx_i)^2}{2\sigma^2}$ maximized?

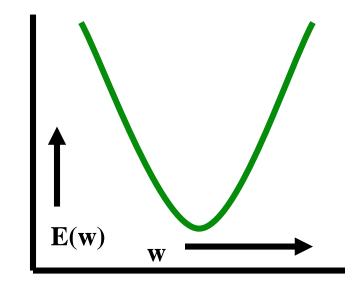
For what w is $\sum_{i=1}^{n} (y_i - wx_i)^2$ minimized?

This is also called least square regression (最小二乘估计/回归)



Linear Regression

The maximum likelihood w is the one that minimizes sum-of-squares of residuals



$$E = \sum_{i} (y_{i} - wx_{i})^{2} = \sum_{i} y_{i}^{2} - (2\sum_{i} x_{i}y_{i})w + (\sum_{i} x_{i}^{2})w^{2}$$

We want to minimize a quadratic function of w.



Linear Regression

Easy to show that the sum of squares is minimized when

$$w = \frac{\sum x_i y_i}{\sum x_i^2}$$

The Maximum Likelihood model is

$$\operatorname{out}(x) = wx$$

We can use it for prediction.

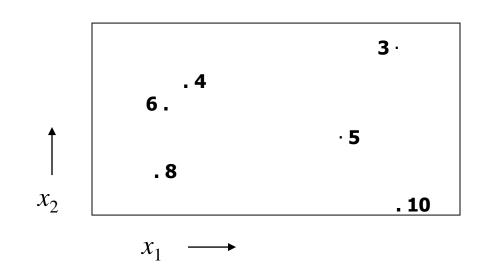


■ 2. Multiple Linear Regression (多元线性回归)

What if the inputs are vectors?

Dataset has the form

\mathbf{x}_1	\mathcal{Y}_1
\mathbf{x}_2	\mathcal{Y}_2
\mathbf{X}_3	y_3
•••	•••
\mathbf{X}_{R}	y_R



2-d input example



Multiple Linear Regression

$$\mathbf{X} = \begin{bmatrix} \dots \mathbf{x}_1 \dots \\ \dots \mathbf{x}_2 \dots \\ \vdots \\ \dots \mathbf{x}_R \dots \end{bmatrix} = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1m} \\ x_{21} & x_{22} & \dots & x_{2m} \\ \vdots & & \vdots & & \\ x_{R1} & x_{R2} & \dots & x_{Rm} \end{bmatrix} \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_R \end{bmatrix}$$

Write the \mathbf{X} matrix and \mathbf{y} vector as above:

- There are R data points, and each input has m components.
- The linear regression model assumes a vector w such that:

$$out(\mathbf{x}) = \mathbf{w}^{\mathrm{T}}\mathbf{x} = w_1x_1 + w_2x_2 + \dots + w_mx_m$$

• The maximum likelihood \mathbf{w} is $\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} (\mathbf{X}^T \mathbf{y})$



Multiple Linear Regression

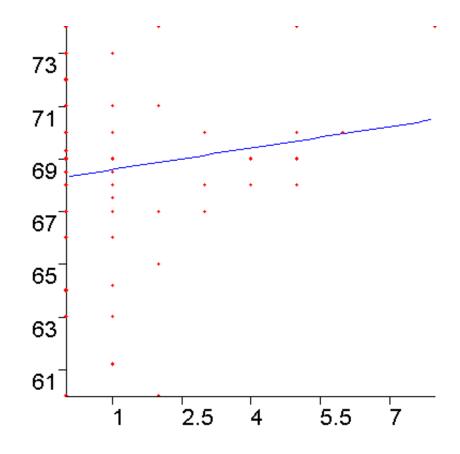
- The maximum likelihood w is $\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} (\mathbf{X}^T \mathbf{y})$
- $\mathbf{X}^{\mathrm{T}}\mathbf{X}$: an $m \times m$ matrix with the $(i,j)^{\mathrm{th}}$ term being $\sum_{k=1}^{R} x_{ki} x_{kj}$
- $\mathbf{X}^{\mathrm{T}}\mathbf{y}$: an m-element vector with the i^{th} term being $\sum_{k=1}^{R} x_{ki} y_k$



■ 3. Constant Term in Linear Regression (常数项, y截距)

We may expect linear data that does not go through the origin.

Statisticians and Neural Net Folks all agree on a simple obvious hack.





■ The Constant Term

• The trick is to create a fake input " x_0 " that always takes the value 1

x_1	x_2	y
2	4	16
3	4	17
5	5	20

Before:

$$y=w_1x_1+w_2x_2$$

A poor model

In this example, you should be able to see the MLE w_0 , w_1 and w_2 by inspection.

x_0	x_1	x_2	y
1	2	4	16
1	3	4	17
1	5	5	20

After:

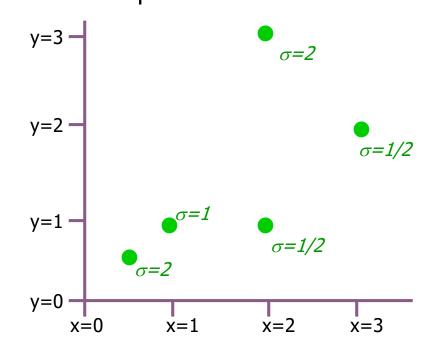
$$y = w_0 x_0 + w_1 x_1 + w_2 x_2$$

$$= w_0 + w_1 x_1 + w_2 x_2$$



4. Regression with Varying Noise

 Suppose you know the variance of the noise that was added to each data point



x_i	\mathcal{Y}_{i}	σ_{i}^{2}
1/2	1/2	4
1	1	1
2	1	1/4
2	3	4
3	2	1/4

Assume $y_i \sim N(wx_i, \sigma_i^2)$

What's the MLE estimate of w?

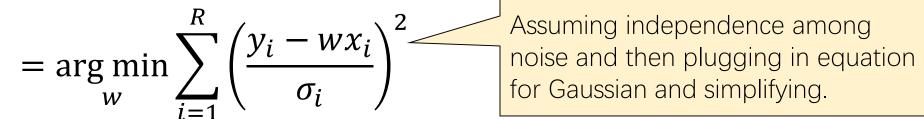


Setting

ML Estimation with Varying Noise

Recall: ML estimation: arg max $p(\{y_i\}|w,\{x_i\})$

$$\arg\max_{w} \log p(y_1, y_2, ..., y_R | x_1, x_2, ..., x_R, \sigma_1^2, \sigma_2^2, ..., \sigma_R^2, w)$$



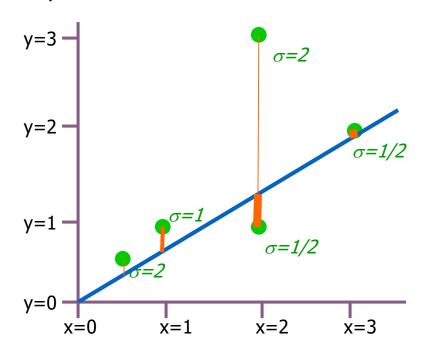


This is Weighted Regression

We are minimizing the weighted sum of squares of noises

$$\underset{w}{\operatorname{arg\,min}} \sum_{i=1}^{R} \frac{(y_i - wx_i)^2}{\sigma_i^2}$$

where weight for i^{th} data point is $\frac{1}{\sigma_i^2}$





■ 5. Polynomial Regression (多项式回归)

- Polynomial regression is a form of linear regression in which the relationship between the <u>independent variable</u> x and the <u>dependent variable</u> y is modeled as an qth degree polynomial.
- Polynomial regression fits a nonlinear relationship between the value of x and the corresponding conditional mean of y, denoted E(y|x).

$$\hat{y} = w_0 + w_1 x_1 + w_2 x_2 + w_3 x_1^2 + w_4 x_1 x_2 + w_5 x_2^2$$

Why polynomial regression is linear regression?



■ 5. Polynomial Regression (多项式回归)

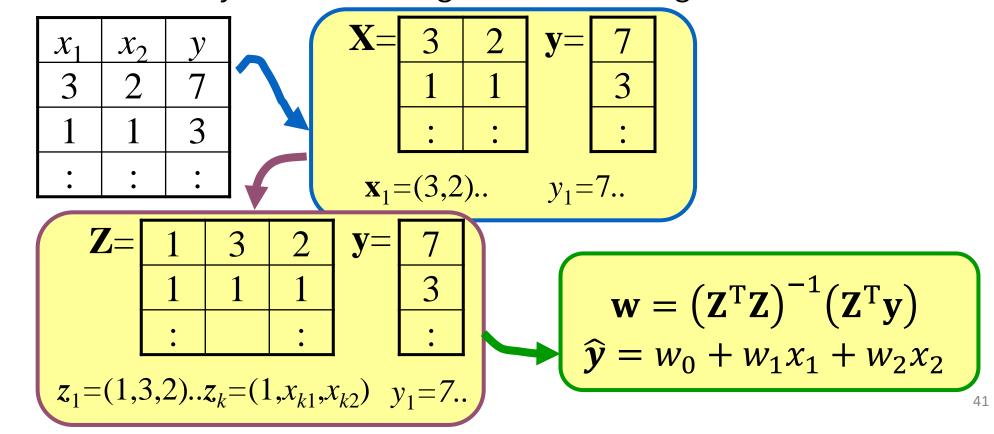
Why polynomial regression is linear regression?

- Although polynomial regression *fits a nonlinear model to the data*, as a statistical estimation problem it is linear, in the sense that the regression function E(y|x) is **linear in the unknown parameters** w that are estimated from the data.
- Polynomial regression is considered to be a special case of multiple linear regression.



Polynomial Regression

So far we've mainly been dealing with linear regression





Quadratic Regression

• It's trivial to do linear fits of fixed nonlinear basis functions

x_1	x_2	у		X=	3	2	$\mathbf{y}=$	7	
3	2	7			1	1		3	
1	1	3	×		•	•		•	
•	•	•		X ₁ =	=(3,2	()	$y_1 =$	7	

$$\mathbf{Z} = \begin{bmatrix}
1 & 3 & 2 & 9 & 6 & 4 \\
1 & 1 & 1 & 1 & 1 & 1 \\
\vdots & \vdots & \vdots & \vdots & \vdots
\end{bmatrix}$$

$$\mathbf{z} = (1, x_1, x_2, x_1^2, x_1 x_2, x_2^2)$$

$$\mathbf{w} = (\mathbf{Z}^{T}\mathbf{Z})^{-1}(\mathbf{Z}^{T}\mathbf{y})$$

$$\widehat{\mathbf{y}} = w_{0} + w_{1}x_{1} + w_{2}x_{2} + w_{3}x_{1}^{2} + w_{4}x_{1}x_{2} + w_{5}x_{2}^{2}$$



Quadratic Regression

- Each component of a z vector is called a term.
- Each column of the Z matrix is called a term column.
- How many terms in a quadratic regression with m inputs?
 - 1 constant term
 - *m* linear terms
 - (m+1)-choose-2 = m(m+1)/2 quadratic terms
 - (m+2)-choose-2 terms in total = $O(m^2)$
- Note that solving $\mathbf{w} = (\mathbf{Z}^{\mathrm{T}}\mathbf{Z})^{-1}(\mathbf{Z}^{\mathrm{T}}\mathbf{y})$ is thus $O(m^6)$



Qth-degree Polynomial Regression

x_1	x_2	y	X=	3	2	y=	7	
3	2	7		1	1		3	
1	1	3		•	•		•	
•	•	•	\mathbf{x}_1 =	=(3,2	2)	$y_1 =$	7	

$$z = \begin{bmatrix} 1 & 3 & 2 & 9 & 6 & 4 & y = 7 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ \vdots & & & & & \vdots \end{bmatrix}$$
 $z = (all \ products \ of \ powers \ of \ inputs \ in \ which \ sum \ of \ powers \ is \ Q \ or \ less)$

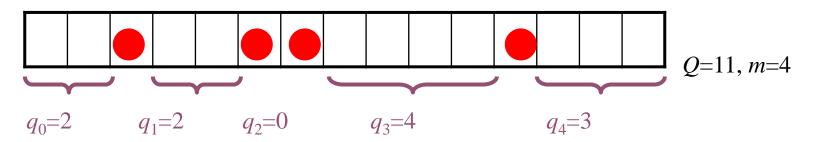
$$\mathbf{w} = (\mathbf{Z}^{\mathrm{T}}\mathbf{Z})^{-1}(\mathbf{Z}^{\mathrm{T}}\mathbf{y})$$

$$\widehat{\mathbf{y}} = w_0 + w_1x_1 + w_2x_2 + w_3x_1^Q + \dots + w_kx_2^Q$$



\blacksquare m inputs, degree Q: how many terms?

- = the number of unique terms of the form $x_1^{q_1}x_2^{q_2}...x_m^{q_m}$ where $\sum_{i=1}^{n}q_i \leq Q$
- = the number of unique terms of the form $1^{q_0} x_1^{q_1} x_2^{q_2} ... x_m^{q_m}$ where $\sum_{i=0}^m q_i = Q$
- = the number of lists of non-negative integers $[q_0,q_1,q_2,...q_m]$ in which $\Sigma q_i = Q$
- = the number of ways of placing m disks on a row of squares of length Q+m
- = (Q+m)-choose-Q



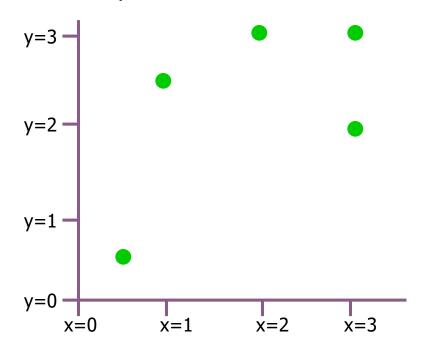


Nonlinear Regression 非线性回归



Nonlinear Regression

• Suppose you know that y is related to a function of x in the way that the predicted values have a **non-linear dependence on** w



Xi	y _i
1/2	1/2
1	2.5
2	3
3	2
3	3



Assume
$$y_i \sim N(\sqrt{w + x_i}, \sigma^2)$$



Nonlinear Regression

- Nonlinear regression is a form of regression analysis in which observational data are modeled by a function which is a nonlinear combination of the model parameters and depends on one or more independent variables.
- Examples of nonlinear functions include exponential functions, logarithmic functions, etc.



Nonlinear ML estimation

Recall: ML estimation: arg max $p(\{y_i\}|w,\{x_i\})$

arg max $\log p(y_1, y_2, ..., y_R | x_1, x_2, ..., x_R, \sigma^2, w)$ W

Assuming i.i.d. among noise and then plugging in equation for Gaussian and simplifying.

$$= \underset{w}{\operatorname{arg\,min}} \sum_{i=1}^{R} (y_i - \sqrt{w + x_i})^2$$

$$= \arg\min_{w} \sum_{i=1}^{R} (y_i - \sqrt{w + x_i})^2$$

$$\Leftrightarrow \text{ select } w \text{ such that } \sum_{i=1}^{R} \frac{y_i - \sqrt{w + x_i}}{\sqrt{w + x_i}} = 0$$
Setting dLL/dw=0



Nonlinear ML estimation

arg max $\log p(y_1, y_2, ..., y_R | x_1, x_2, ..., x_R, \sigma^2, \sqrt{\text{Common (but not only) approach:}}$

$$= \underset{w}{\operatorname{arg\,min}} \sum_{i=1}^{R} (y_i - \sqrt{w + x_i})^2$$

 \Leftrightarrow select w such that

Iterative approach:

- Start with an initial guess of w
- Update w in each iteration until convergence

How to select *w*?

Numerical Solutions:

- Line Search
- Simulated Annealing
- Gradient Descent
- Conjugate Gradient
- Levenberg Marquart
- Newton's Method

Also, special statistical-optimizationspecific tricks such as EM



■ Linearization (线性化)

- Sometimes, it may be possible to transform a nonlinear regression function to a linear one.
- Example: $\mu_y(x) = \beta_1 e^{-\beta_2 x}$
 - $\bullet \ln \mu_y(x) = \ln \beta_1 \beta_2 x$
 - Given $\{(y_1, x_1), \dots, (y_n, x_n)\}$, let $z_i = \ln y_i$
 - Apply linear regression to $\{(z_1,x_1),\cdots,(z_n,x_n)\}$ and estimate $\ln \hat{\beta}_1$ and $\hat{\beta}_2$



Linearization (cont'd)

• Example:
$$\mu_y(x) = \frac{1}{\beta_1 - \beta_2 x}$$

$$\bullet \ \mu_y^{-1}(x) = \beta_1 - \beta_2 x$$

- Apply linear regression to $\{(y_i^{-1}, x_i)\}$
- Example: $\mu_{\mathcal{Y}}(x) = \frac{\beta_1 x}{\beta_2 + x}$

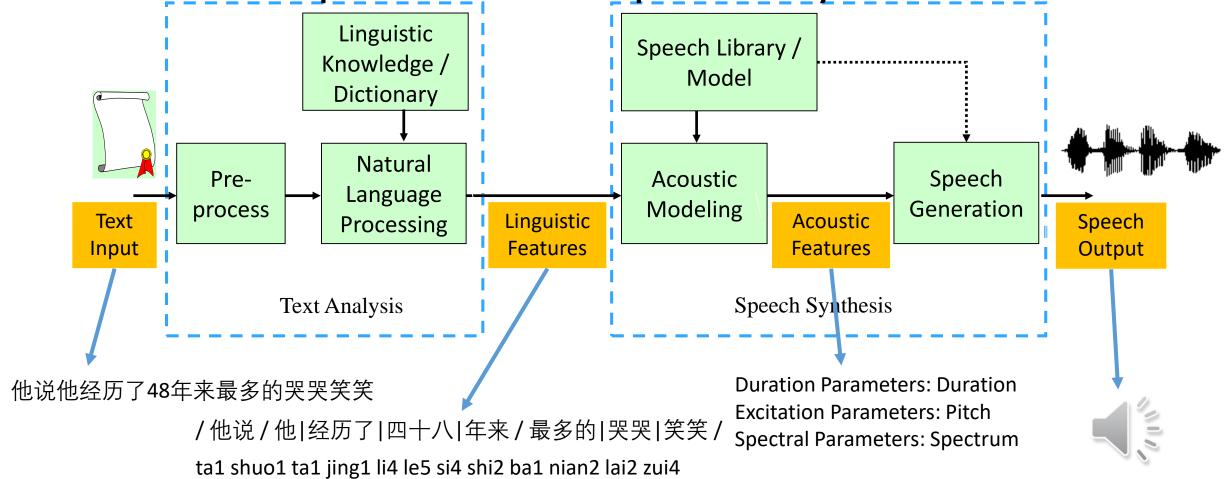
•
$$\mu_y^{-1}(x) = \frac{1}{\beta_1} + \frac{\beta_2}{\beta_1} x^{-1}$$

• Apply linear regression to $\{(y_i^{-1}, x_i^{-1})\}$



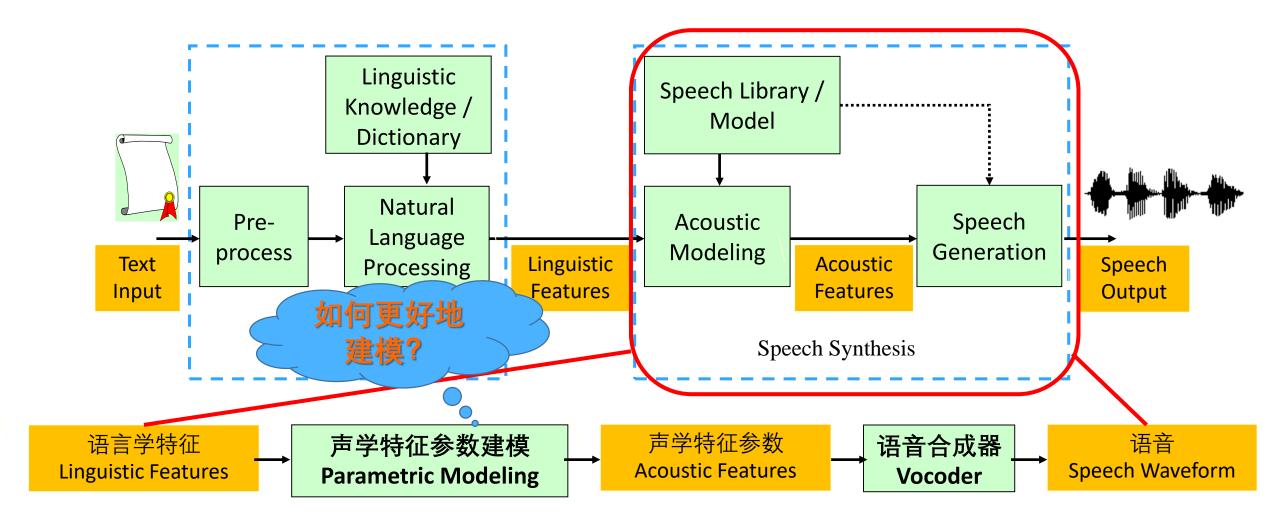
An Example: Text-to-Speech Synthesis

duo1 de5 ku1 ku1 xiao4 xiao4



53

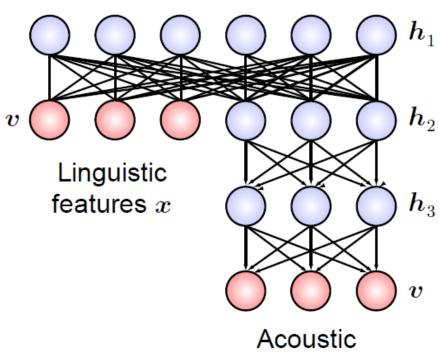






- Speech Synthesis with DBN (Tsinghua-CUHK)
 - DBN represents joint distribution of linguistic & acoustic features
 - P(x, y)
 - State-level modeling

- The acoustic features modeled:
 - Cepstral: spectrum
 - F0: pitch



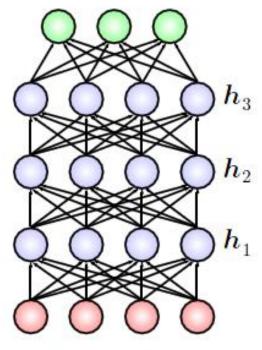
features y



- Speech Synthesis with DNN (Google)
 - DNN represents conditional distribution of acoustic feature given linguistic feature
 - P(y | x)
 - State-level modeling

- The acoustic features modeled:
 - Cepstral: spectrum
 - F0: pitch

Acoustic features y



Linguistic features x



Detailed Analysis and Insights 回归分析的统计特性



Parameter Estimation

- An (unknown) parameter θ to be estimated
 - A point estimator $\hat{\theta}(x)$
 - $\hat{\theta}(x)$: estimate for the observed dataset x
- Unbiased estimator (无偏估计量): $E[\hat{\theta}(x)] = \theta$
- Consistent estimator (一致估计量):
 - A sequence of estimators $\{\hat{\theta}_n\}$ is a consistent estimator of θ iff $\forall \epsilon > 0$, $\lim_{n \to \infty} [|\hat{\theta}_n \theta| < \epsilon] = 1$
 - The estimator converges in probability to the true values as the number of data points increases.



Unbiased Estimators

Given independently drawn observations $\{X_i\}$ of random variable X and $\{Y_i\}$ of random variable Y

- Sample mean: $\bar{X} = \frac{1}{n}(X_1 + X_2 + \dots + X_n)$
 - Degree of freedom: *n*
- Sample variance: $S_X^2 = \frac{1}{n-1} \sum_i (X_i \bar{X})^2$
 - Bessel correction: use *n*-1 but not *n*
 - D.f.: n-1 (constraint on \bar{X})
- Sample covariance: $S_{XY} = \frac{1}{n-1} \sum_{i} (X_i \bar{X})(Y_i \bar{Y})$
 - D.f.: *n*-1



Linear Regression

- Given $\{(X_i,Y_i)\}$, find a straight line $\hat{Y}=b_0+b_1X$ to approximate their relationship
 - Fitted value \hat{Y}_i and residual (残差) $e_i = Y_i \hat{Y}_i$
 - MLE (LSE): $\underset{b_0,b_1}{\operatorname{arg \, min}} \sum_i e_i^2$

$$\frac{\partial \sum_{i} (Y_{i} - \hat{Y}_{i})^{2}}{\partial b_{0}} = 0 \Rightarrow \frac{\sum_{i} e_{i}}{n} = 0$$

$$\frac{\partial \sum_{i} (Y_{i} - \hat{Y}_{i})^{2}}{\partial b_{1}} = 0 \Rightarrow \frac{\sum_{i} e_{i} X_{i}}{n} = 0 \Leftrightarrow \begin{cases} Cov(X, e) = 0 \\ Cov(\hat{Y}, e) = 0 \end{cases}$$

The residual has zero sample mean and is uncorrelated to X and therefore \hat{Y} .



Least Square Estimation

• Intercept:

$$\bar{e} = 0 \Leftrightarrow \bar{Y} = b_0 + b_1 \bar{X}$$

- The center of mass $(\overline{X}, \overline{Y})$ is on the regression line.
- LS finds the center of mass and rotates the line through that point until getting the "right" slope.
- Slope:

$$Cov(X, e) = 0 \Leftrightarrow b_1 = \frac{S_{XY}}{S_X^2} = r_{XY} \times \frac{S_Y}{S_X}$$

• So, the right slope is the sample correlation coefficient times a scaling factor that ensures the proper units for b_1 .



Decomposing the Sum of Squares

• How well does the least square line explain the variation in Y? $Y_i = \hat{Y}_i + e_i$

• Given $\bar{e} = 0$ and $Cov(\hat{Y}, e) = 0$, we have

$$\underbrace{\sum_{i} (Y_{i} - \overline{Y})^{2}}_{\text{Soft SST}} = \underbrace{\sum_{i} (\widehat{Y}_{i} - \overline{Y})^{2}}_{\text{Regression SS}} + \underbrace{\sum_{i} e_{i}^{2}}_{\text{Error SS}}$$

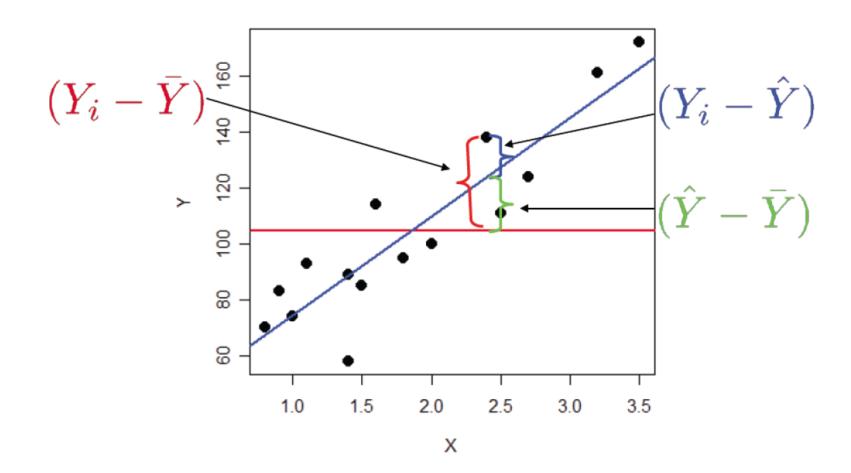
SSR: variation in Y explained by the regression line (回归平方和)

SSE: variation in Y that is left unexplained (残差平方和)

SST: total variation (总变差平方和) SSR = SST → perfect fit



On A Scatter Plot





■ SSE: Error Sum of Squares (残差平方和)

$$SSE = \sum_{i} e_i^2 = \sum_{i} (Y_i - \hat{Y}_i)^2$$

- 反映了除去Y与X间线性关系之后,其他因素引起的数据 $Y_1,Y_2,...,Y_n$ 的波动
 - 如SSE=0, 则每个观测值可由线性关系精确拟合;
 - SSE越大, 观测值与线性拟合的偏差也越大.



■ SSR: Regression Sum of Squares (回归平方和)

$$SSR = \sum_{i} (\widehat{Y}_{i} - \overline{Y})^{2}$$

- 反映了拟合值与其平均值的总偏差, 即由变量 $X_1, X_2, ..., X_n$ 的变化引起的 $Y_1, Y_2, ..., Y_n$ 的波动
 - 如SSR=0, 则每个拟合值均相等, 即 Y_i (i=1,2,...,n)不随 X_i 的变化而变化.



■ SST: Total Sum of Squares (总变差平方和)

$$SST = \sum_{i} (Y_i - \bar{Y})^2$$

• 反映了数据 $Y_1, Y_2, ..., Y_n$ 本身波动性的大小

$$SST = SSR + SSE$$

• SSR越大, 说明由线性回归关系描述的 Y_i 波动的比例就越大, 即 Y_i 与 X 之间的线性关系就越显著



A Goodness of Fit Measure

• The coefficient of determination (判定系数), denoted by \mathbb{R}^2 , measures goodness of fit:

$$R^2 = \frac{SSR}{SST} = 1 - \frac{SSE}{SST}$$

- $0 \le R^2 \le 1$
- The closer \mathbb{R}^2 is to 1, the better the fit.
- 可以解释为 y_i 的总变化量SST中被线性回归方程所描述的比例
- 反映了回归方程对数据的拟合程度, 是衡量拟合优劣的重要统计量



An Interesting Fact

• $R^2 = r^2_{XY}$ (R^2 is squared correlation coefficient)

$$R^{2} = \frac{\sum_{i} (\hat{Y}_{i} - \bar{Y})^{2}}{\sum_{i} (Y_{i} - \bar{Y})^{2}}$$

$$= \frac{\sum_{i} (b_{0} + b_{1}X_{i} - b_{0} - b_{1}\bar{X})^{2}}{\sum_{i} (Y_{i} - \bar{Y})^{2}}$$

$$= \frac{b_{1}^{2} \sum_{i} (X_{i} - \bar{X})^{2}}{\sum_{i} (Y_{i} - \bar{Y})^{2}} = \frac{b_{1}^{2} S_{X}^{2}}{S_{Y}^{2}} = r_{XY}^{2}$$

• No surprise: the higher the sample *correlation coefficient* between *X* and *Y*, the better we can do in our regression.



- Prediction and the Modeling Goal
 - The LS line: a prediction rule $\hat{Y} = b_0 + b_1 X$
 - \hat{Y} is not a perfect prediction
 - Forecast accuracy:
 - What value of *Y* can we expect for a new *X*?
 - How sure are we about his forecast?
 - Our goal is to measure the accuracy of (or equivalently, the uncertainty in) our forecasts.

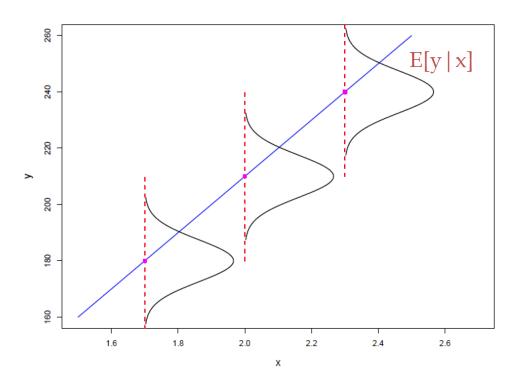


- Prediction and the Modeling Goal
 - **Key Insight**: To construct a prediction interval, we will have to build a probability model, and assess the likely range of error values corresponding to a *Y* value that has not yet been observed.
 - We need to work with the notion of a "true line" and a probability distribution that describes deviation around the line.



Simple Linear Regression Model

- Assume $Y = \beta_0 + \beta_1 X + \varepsilon$, ε i. i. d. $\sim N(0, \sigma^2)$
 - 3 parameters: β_0 and β_1 : (linear pattern), σ (variation around the line)

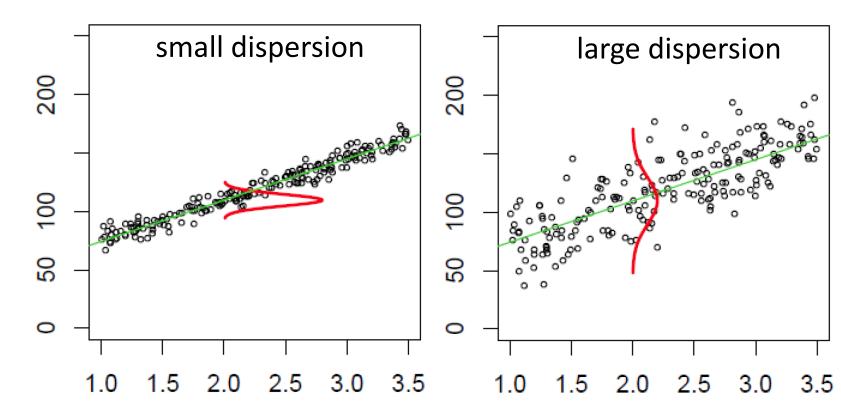


- $\beta_0 + \beta_1 X$ represents the "true line"; the part of Y that depends on X
- The error term ε is independent "noise"; the part of Y not associated with X



Conditional Distributions

- $(Y|X=x)\sim N(\beta_0+\beta_1x,\sigma^2)$
- With prob. 95%, given *x*,





Estimation of the SLR Model

• We use least squares to estimate eta_0 and eta_1 $\hat{\ensuremath{\mathcal{S}_{\!\scriptscriptstyle V}}}$

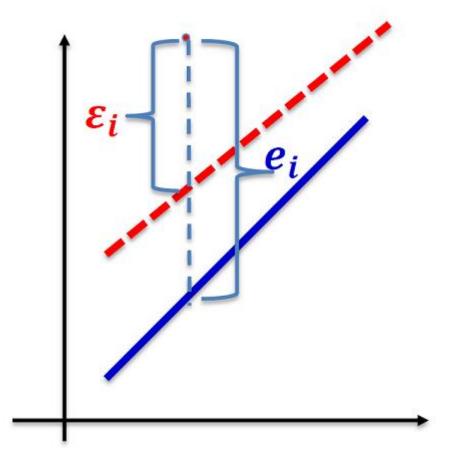
$$\hat{\beta}_1 = b_1 = r_{XY} \times \frac{S_Y}{S_X}$$

$$\hat{\beta}_0 = b_0 = \overline{Y} - b_1 \overline{X}$$

Tue line: $E[Y|X] = \beta_0 + \beta_1 X$

Least square line: $\hat{Y} = b_0 + b_1 X$

NOTE: $b_0 \neq \beta_0$, $b_1 \neq \beta_1$, $e_i \neq \varepsilon_i$





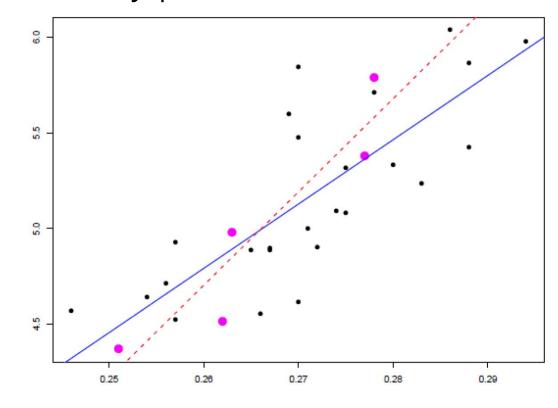
Prediction and the Modeling Goal

• Note that the "fitted" line may be fooled by particular realization

of the residuals.

 Dashed line: fits the purple points only

- Solid line: fits all points
- Which line is better?

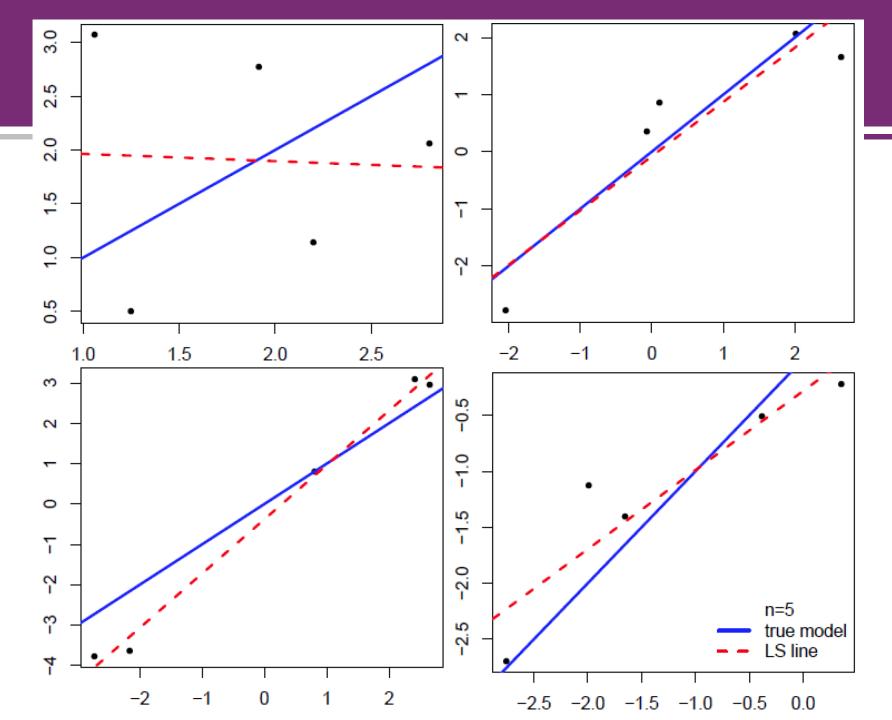




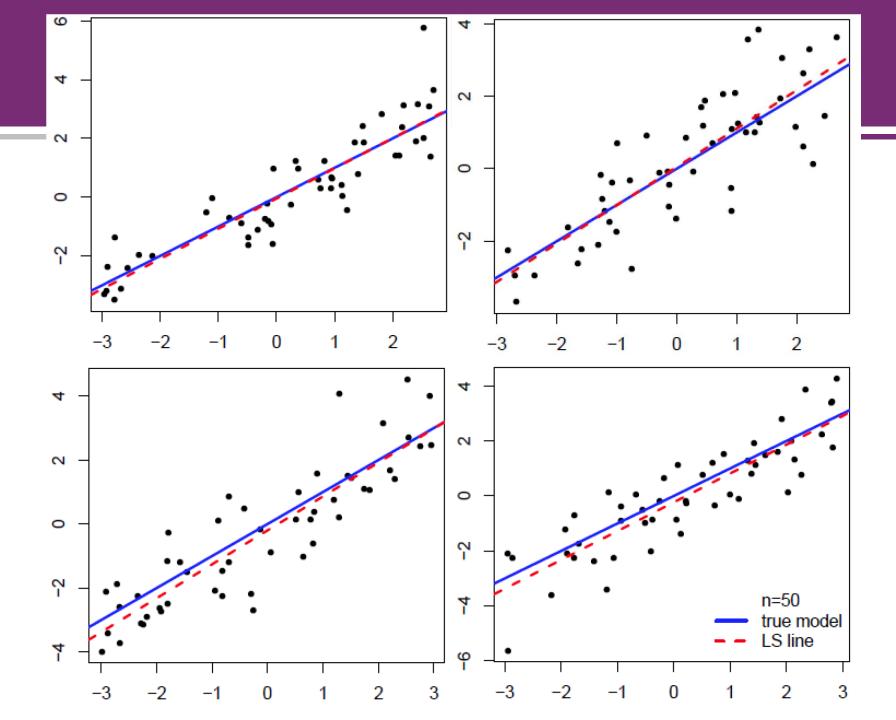
Sampling Distribution of LSE

- How much do our estimates depend on the particular random sample that we observe?
- Randomly draw different samples of the same size, and compute the estimated parameters for each sample.
- If the estimates do not vary much from sample to sample, then it does not matter which sample to choose. Vice versa.











Sampling Distribution of LSE

- The LS lines are much closer to the true line with larger sample size.
- When n=5, some lines are close, others are not. We need to get "lucky".

- Also notice that the LS lines are, more often than not:
 - Closer to the true line near middle of the data cloud
 - They get farther apart away from the middle of the cloud



Q&A?