Exploring Discrete Approximations of Manifolds in Computational Geometry

Biber

1 Introduction

In this paper, we delve into the relationship between continuous manifolds and their discrete approximations, particularly focusing on the mesh functor g_{θ} and its role in computational geometry.

2 Mesh Functor g_{θ} and its Properties

The mesh functor g_{θ} , given a parameter θ , discretizes a continuous manifold M into a finite triangular mesh P. This process is crucial in computational applications where exact manifold representations are infeasible.

2.1 Definition and Continuity

The functor g_{θ} can be formally defined as follows:

$$g_{\theta}: \mathbf{Man} \to \mathbf{SimpCplx}$$

where Man denotes the category of 3-dimensional manifolds and $\mathbf{SimpCplx}$ the category of simplicial complexes. This functor preserves essential topological and geometric features of M, albeit in a discretized form.

2.2 Error Analysis

An important aspect of g_{θ} is the error introduced during the discretization. The Gromov-Hausdorff distance provides a measure of this error, offering insights into the fidelity of P as an approximation of M.

3 Comparative Analysis

3.1 Manifold M versus Mesh P

The fidelity of P in representing M is crucial for algorithms in computational geometry. Despite the inherent approximation, P maintains most of the critical geometric properties of M, allowing for effective algorithmic processing.

3.2 Algorithmic Considerations

The discrete nature of P introduces unique computational challenges and opportunities. Algorithms must be adapted to handle the discrete structure efficiently, balancing accuracy and computational complexity.[1]

4 Conclusion

Our exploration underscores the significance of the mesh functor g_{θ} in bridging the gap between theoretical manifolds and their practical computational counterparts. This understanding is pivotal for advancing methods in computational geometry and related fields. [2]

References

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