Detection of Ellipses

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Project Target

To detect ellipses in the images/videos.



Figure: Input



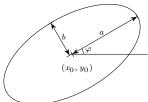
Figure: Output

Ellipse

To describe an ellispe we need 5 parameters:

$$Ax^{2} + Bxy + Cy^{2} + Dx + Ey + F = 0$$
, where $B^{2} - 4AC < 0$.

Or in another way, we need the coordinates of ellipse's center (x_0, y_0) , semi-major/semi-minor axes (a, b), and a rotation angle (φ) .



Two major ways

Hough Transform

- Slow
- Sacrifice accuracy for efficiency

Edge Following

- Derived from Arc-support LS
- use greyscale image (gradient)
- Greedy for efficiency

Methods

- To detect the arc segements;
- (To form arcs;)
- To predict the 5 parameters for ellipses;
- Co-clustering;
- Validation.

LSD: A Fast Line Segment Detector with a False Detection Control

IEEE TRANSACTIONS ON PATTERN ANALYSIS AND MACHINE INTELLIGENCE

- Finding line-support region (region growing algorithm)
- Rectangular Approximation of Regions
- Validation

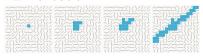


Figure: Region generation

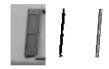


Figure: Rectangular Approximation

Arc segments' result

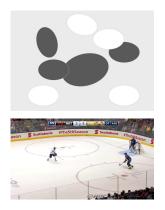


Figure: Source Images

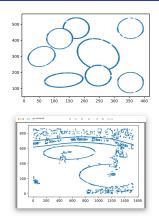


Figure: Arc Detection Results

Arc Segments' Result



Figure: Arc Segment Example

$$x^{2} + bxy + cy^{2} + dx + ey + f = 0;$$

$$(x \quad y \quad 1) \begin{pmatrix} 1 & \frac{b}{2} & \frac{d}{2} \\ \frac{b}{2} & c & \frac{e}{2} \\ \frac{d}{2} & \frac{e}{2} & f \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} = O_{3\times 3};$$

$$\begin{pmatrix} x_1 & y_1 & 1 \\ \vdots & \vdots & \vdots \\ x_n & y_n & 1 \end{pmatrix} \begin{pmatrix} 1 & \frac{b}{2} & \frac{d}{2} \\ \frac{b}{2} & c & \frac{e}{2} \\ \frac{d}{2} & \frac{e}{2} & f \end{pmatrix} \begin{pmatrix} x_1 & \dots & x_n \\ y_1 & \dots & y_n \\ 1 & \dots & 1 \end{pmatrix} = O_{3\times 3}.$$