

(8.13)

$$(W_{\underline{t_1}}, \dots, W_{\underline{t_n}})$$

$$\text{Cov}(W_{t_i}, W_{t_{i'}})$$

$$(W_{t_1}, W_{t_2} - W_{t_1}, W_{t_3} - W_{t_2}, \dots, W_{t_n} - W_{t_{n-1}})$$

$X_1 \quad X_2 \quad X_3 \quad X_n$

$$Y_1 = X_1, \quad Y_2 = X_1 + X_2, \quad \dots, \quad Y_n = X_1 + \dots + X_n$$

$$\mathbb{E}[f(Y_1, \dots, Y_n)] = \int_{\mathbb{R}^n} f(y_1, \dots, y_n) \underbrace{\psi(y_1, \dots, y_n)}_{\text{joint density}} dy_1 \dots dy_n$$

$$\mathbb{E}[f(X_1, X_1 + X_2, \dots, X_1 + \dots + X_n)]$$

$$\int_{\mathbb{R}^n} f(\underbrace{x_1}_{y_1}, \underbrace{x_1 + x_2}_{y_2}, \dots, \underbrace{x_1 + \dots + x_n}_{y_n}) \underbrace{\phi(x_1, \dots, x_n)}_{\text{joint density}} dx_1 \dots dx_n$$

$$x_1 \sim y_1 \quad x_2 \sim (y_2 - y_1) \quad x_3 = y_3 - x_1 - x_2 = y_3 - y_1 - y_2 + y_1$$

$$\frac{1}{\sqrt{2\pi}t_1} e^{-\frac{y_1^2}{2t_1}} \frac{1}{\sqrt{2\pi}(t_2 - t_1)} e^{-\frac{(y_2 - y_1)^2}{2(t_2 - t_1)}} \quad x_4 = y_4 - y_3$$

(8.21)

 W_t L^2

$$\left[\underbrace{\{X_\alpha : \alpha \in A\}}_{L^2} \right] \subseteq L^2$$

$$\mathbb{E}[W_t] = 0$$

$$\mathbb{E}[W_s W_t] = s \wedge t$$

(8.25)

(8.24)

$$\mathbb{E} \left[\underbrace{|W_{t+h} - W_t|^\alpha}_{\substack{\forall t \\ \forall h}} \right] \leq C h^{\frac{\alpha}{1+\beta}}$$

$$\alpha, \beta, C \in \mathbb{R}_{++}$$

$$\alpha = 2, 4, 6, 8, \dots$$

$$\mathbb{E} \left[\underbrace{(W_{t+h} - W_t)^4}_{\substack{C=3 \\ \alpha=4 \\ \beta=1}} \right] = 3 h^{1+1}$$

$$W_{t_i} - W_{t_{i-1}}$$

$$\underbrace{W_t - W_s}_{\text{var} = t-s}$$

$$\underline{s \leq t}$$

$$\mathbb{E} \left[(W_{t+h} - W_t)^4 \right]$$



$$\mathbb{E}[X_1 X_2 X_3 X_4]$$

$$\mathbb{E}[X_i] = 0$$

$$= \mathbb{E}[X_1 X_2] \mathbb{E}[X_3 X_4] + \mathbb{E}[X_1 X_3] \mathbb{E}[X_2 X_4] + \mathbb{E}[X_1 X_4] \mathbb{E}[X_2 X_3]$$

$$\underline{\underline{E[X^4] = 3E[X^2]^2}}$$

$$E[X] = 0$$

$$X(\omega, t)$$

ω

$$\boxed{X(\omega, t)}$$

X_ω

contin. function
of time
 $\forall \underline{t}$

$$\tilde{W}_t(\omega) = W_t(\omega) \text{ for a.e. } \omega$$

modification

$$\tilde{W}_t$$

$$W_t$$