

The transfer point is in arch/arm/lib/bootm.c

```
1.  /* Subcommand: GO */
2.  static void boot_jump_linux(bootm_headers_t *images, int flag)
3.  {
4.  #ifdef CONFIG_ARM64
5.      void (*kernel_entry)(void *fdt_addr);
6.      int fake = (flag & BOOTM_STATE_OS_FAKE_GO);
7.
8.      kernel_entry = (void (*)(void *fdt_addr))images->ep;
9.
10.     debug("## Transferring control to Linux (at address %lx)...\n",
11.           (ulong) kernel_entry);
12.     bootstage_mark(BOOTSTAGE_ID_RUN_OS);
13.
14.     announce_and_cleanup(fake);
15.
16.     if (!fake)
17.         kernel_entry(images->ft_addr);
18. #else
19.     unsigned long machid = gd->bd->bi_arch_number;
20.     char *s;
21.     void (*kernel_entry)(int zero, int arch, uint params);
22.     unsigned long r2;
23.     int fake = (flag & BOOTM_STATE_OS_FAKE_GO);
24.
25.     kernel_entry = (void (*)(int, int, uint))images->ep;
26.
27.     s = getenv("machid");
28.     if (s) {
29.         strict_strtoul(s, 16, &machid);
30.         printf("Using machid 0x%lx from environment\n", machid);
31.     }
32.
33.     debug("## Transferring control to Linux (at address %08lx)" \
34.           "...\\n", (ulong) kernel_entry);
35.     bootstage_mark(BOOTSTAGE_ID_RUN_OS);
36.     announce_and_cleanup(fake);
37.
38.     if (IMAGE_ENABLE_OF_LIBFDT && images->ft_len)
39.         r2 = (unsigned long)images->ft_addr;
40.     else
41.         r2 = gd->bd->bi_boot_params;
42.
43.     if (!fake)
44.         kernel_entry(0, machid, r2);
45. #endif
46. }
```

①

```
kernel_entry(0, machid, r2);
```

The transfer point!

The following is call stack when running on the transfer point.

`_main()` in `crt0.S`

--> `board_init_r()` in `board.c`

--> `main_loop()` in `main.c`

--> `process_boot_delay()` in `main.c`

--> `run_command_list()` in `main.c`

--> `parse_string_outer()` in `hush.c`

--> `parse_stream_outer()` in `hush.c`

--> `run_list()` in `hush.c`

--> `run_list_real()` in `hush.c`

--> `run_pipe_real()` in `hush.c`

--> `cmd_process()` in `command.c`

--> `cmd_call()` in `command.c`

--> `do_bootm()` in `cmd_bootm.c`

--> `do_bootm_states()` in `cmd_bootm.c`

--> `boot_selected_os()` in `cmd_bootm.c`

--> `do_bootm_linux()` in `bootm.c`

--> `boot_jump_linux()` in `bootm.c`

