```
1.
      struct pxa_i2c {
              spinlock_t
                                       lock;
              wait_queue_head_t
 3.
                                       wait;
              struct i2c_msg
                                       *msg;
 4.
 5.
              unsigned int
                                       msg_num;
              unsigned int
 6.
                                       msg_idx;
 7.
              unsigned int
                                       msg_ptr;
8.
 9.
10.
11.
      };
```

```
1. struct i2c_msg *msg;
```

当前正在处理的i2c_msg

还剩多少i2c_msg没处理。当msg_num为0,表示所有i2c_msg都处理完了。也就是处理了msg[msg_num] array.

相对要处理的msg[msg_num] array,msg_idx表示正在处理的msg的index。

```
1.
     struct i2c_msg {
                                                                     */
2.
             __u16 addr; /* slave address
3.
             _u16 flags;
                                                                             */
             __u16 len;
                                    /* msg length
4.
             __u8 *buf;
                                    /* pointer to msg data
                                                                             */
5.
6.
     };
```

每个i2c_msg指向[buf, buf + len)的buffer,而msg_ptr则指向buf中当前正在处理的位置,即当前正在发送/接收 buf + msg_ptr。

比如在i2c_pxa_do_xfer()中开始transfer以前

```
1.
              i2c->msg = msg;
              i2c->msg_num = num;
              i2c->msg_idx = 0;
 3.
4.
              i2c->msg_ptr = 0;
              i2c->irqlogidx = 0;
6.
              i2c_pxa_start_message(i2c);
8.
              spin_unlock_irq(&i2c->lock);
9.
10.
11.
              /*
12.
               * The rest of the processing occurs in the interrupt handler.
13.
14.
              timeout = wait_event_timeout(i2c->wait, i2c->msg_num == 0, HZ * 5);
15.
              i2c_pxa_stop_message(i2c);
```

(1)

初始化这4个field

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transfer结束的判断标志是i2c->msg_num == 0,即所有i2c_msg都处理了。