

Linux中已经支持了大部分I2C EEPROM的read / write.

drivers/misc/eeprom/at24.c

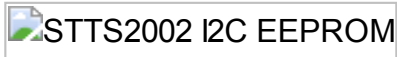
at24.c - handle most I2C EEPROMs

Gemstone2 TOC board上的两块I2C EEPROM可以被该driver support.

M24C64 I2C EEPROM



STTS2002 I2C EEPROM



```
1. static const struct i2c_device_id at24_ids[] = {
2.     /* needs 8 addresses as A0-A2 are ignored */
3.     { "24c00", AT24_DEVICE_MAGIC(128 / 8, AT24_FLAG_TAKE8ADDR) },
4.     /* old variants can't be handled with this generic entry! */
5.     { "24c01", AT24_DEVICE_MAGIC(1024 / 8, 0) },
6.     { "24c02", AT24_DEVICE_MAGIC(2048 / 8, 0) },
7.     /* spd is a 24c02 in memory DIMMs */
8.     { "spd", AT24_DEVICE_MAGIC(2048 / 8,
9.         AT24_FLAG_READONLY | AT24_FLAG_IRUGO) },
10.    { "24c04", AT24_DEVICE_MAGIC(4096 / 8, 0) },
11.    /* 24rf08 quirk is handled at i2c-core */
12.    { "24c08", AT24_DEVICE_MAGIC(8192 / 8, 0) },
13.    { "24c16", AT24_DEVICE_MAGIC(16384 / 8, 0) },
14.    { "24c32", AT24_DEVICE_MAGIC(32768 / 8, AT24_FLAG_ADDR16) },
15.    { "24c64", AT24_DEVICE_MAGIC(65536 / 8, AT24_FLAG_ADDR16) },
16.    { "24c128", AT24_DEVICE_MAGIC(131072 / 8, AT24_FLAG_ADDR16) },
17.    { "24c256", AT24_DEVICE_MAGIC(262144 / 8, AT24_FLAG_ADDR16) },
18.    { "24c512", AT24_DEVICE_MAGIC(524288 / 8, AT24_FLAG_ADDR16) },
19.    { "24c1024", AT24_DEVICE_MAGIC(1048576 / 8, AT24_FLAG_ADDR16) },
20.    { "at24", 0 },
21.    { /* END OF LIST */ }
22. };
23. MODULE_DEVICE_TABLE(i2c, at24_ids);
```

这两块EEPROM分别对应上表中的"24c64" (64 Kbit, 8 KByte)和"spd" (2Kb and 256 Byte)

这里的关键是要为这两个EEPROM device创建I2C device,完成at24 driver与i2c device的"match".

in drivers/i2c/i2c-core.c

```

1. struct bus_type i2c_bus_type = {
2.     .name      = "i2c",
3.     .match     = i2c_device_match,
4.     .probe     = i2c_device_probe,
5.     .remove    = i2c_device_remove,
6.     .shutdown  = i2c_device_shutdown,
7.     .pm        = &i2c_device_pm_ops,
8. };

```

```

1. static int i2c_device_match(struct device *dev, struct device_driver *drv)
2. {
3.     struct i2c_client *client = i2c_verify_client(dev);
4.     struct i2c_driver *driver;
5.
6.     if (!client)
7.         return 0;
8.
9.     /* Attempt an OF style match */
10.    if (of_driver_match_device(dev, drv))
11.        return 1;
12.
13.    /* Then ACPI style match */
14.    if (acpi_driver_match_device(dev, drv))
15.        return 1;
16.
17.    driver = to_i2c_driver(drv);
18.    /* match on an id table if there is one */
19.    if (driver->id_table)
20.        return i2c_match_id(driver->id_table, client) != NULL;
21.
22.    return 0;
23. }

```

i2c bus上完成driver和device配对的是 `i2c_device_match()`。

由于at24.c没有支持device tree，所以使用的是driver中的 `id_table` 来match i2c device.

```

1.     /* match on an id table if there is one */
2.     if (driver->id_table)
3.         return i2c_match_id(driver->id_table, client) != NULL;

```

```
1. static const struct i2c_device_id *i2c_match_id(const struct i2c_device_id *
2.                                     const struct i2c_client *client)
3. {
4.     while (id->name[0]) {
5.         if (strcmp(client->name, id->name) == 0)
6.             return id;
7.         id++;
8.     }
9.     return NULL;
10. }
```

代表i2c device的i2c_client的 `name` field必须与at24.c中的 `id_table` 中的成员相等。
即client->name为"24c64"或"spd"。

struct i2c_client - represent an I2C slave device

in drivers/i2c/i2c-boardinfo.c

```

1.  /**
2.   * i2c_register_board_info - statically declare I2C devices
3.   * @busnum: identifies the bus to which these devices belong
4.   * @info: vector of i2c device descriptors
5.   * @len: how many descriptors in the vector; may be zero to reserve
6.   *       the specified bus number.
7.   *
8.   * Systems using the Linux I2C driver stack can declare tables of board info
9.   * while they initialize. This should be done in board-specific init code
10.  * near arch_initcall() time, or equivalent, before any I2C adapter driver i
11.  * registered. For example, mainboard init code could define several device
12.  * as could the init code for each daughtercard in a board stack.
13.  *
14.  * The I2C devices will be created later, after the adapter for the relevant
15.  * bus has been registered. After that moment, standard driver model tools
16.  * are used to bind "new style" I2C drivers to the devices. The bus number
17.  * for any device declared using this routine is not available for dynamic
18.  * allocation.
19.  *
20.  * The board info passed can safely be __initdata, but be careful of embedde
21.  * pointers (for platform_data, functions, etc) since that won't be copied.
22.  */
23. int __init
24. i2c_register_board_info(int busnum,
25.     struct i2c_board_info const *info, unsigned len)
26. {
27.     int status;
28.
29.     down_write(&__i2c_board_lock);
30.
31.     /* dynamic bus numbers will be assigned after the last static one */
32.     if (busnum >= __i2c_first_dynamic_bus_num)
33.         __i2c_first_dynamic_bus_num = busnum + 1;
34.
35.     for (status = 0; len; len--, info++) {
36.         struct i2c_devinfo *devinfo;
37.
38.         devinfo = kzalloc(sizeof(*devinfo), GFP_KERNEL);
39.         if (!devinfo) {
40.             pr_debug("i2c-core: can't register boardinfo!\n");
41.             status = -ENOMEM;
42.             break;
43.         }
44.
45.         devinfo->busnum = busnum;
46.         devinfo->board_info = *info;
47.         list_add_tail(&devinfo->list, &__i2c_board_list);
48.     }
49.
50.     up_write(&__i2c_board_lock);

```

```

51.
52.     return status;
53. }

```

i2c_register_board_info()把填写在struct i2c_board_info中的i2c slave device信息生成node , 挂到 `__i2c_board_list` list上。

in drivers/i2c/i2c-core.c

```

1.  static void i2c_scan_static_board_info(struct i2c_adapter *adapter)
2.  {
3.      struct i2c_devinfo *devinfo;
4.
5.      down_read(&__i2c_board_lock);
6.      list_for_each_entry(devinfo, &__i2c_board_list, list) {
7.          if (devinfo->busnum == adapter->nr
8.              && !i2c_new_device(adapter,
9.                                  &devinfo->board_info))
10.             dev_err(&adapter->dev,
11.                     "Can't create device at 0x%02x\n",
12.                     devinfo->board_info.addr);
13.      }
14.      up_read(&__i2c_board_lock);
15.  }

```

i2c_scan_static_board_info()扫描 `__i2c_board_list` list , 把上面的node生成i2c device。而 `i2c_scan_static_board_info()` 则是在 `i2c_register_adapter()` 中被调用。即每当有新的i2c bus注册 , 则会扫描 `__i2c_board_list` list,看一下上面是否由该bus管理的device,是则create i2c device。

所以kernel支持M24C64和STTS2002 EEPROM的关键是create两个struct i2c_board_info , 填写上对应的hardware parameters , 然后调用 `i2c_register_board_info()` 。

```

1.  /**
2.   * I2C_BOARD_INFO - macro used to list an i2c device and its address
3.   * @dev_type: identifies the device type
4.   * @dev_addr: the device's address on the bus.
5.   *
6.   * This macro initializes essential fields of a struct i2c_board_info,
7.   * declaring what has been provided on a particular board.  Optional
8.   * fields (such as associated irq, or device-specific platform_data)
9.   * are provided using conventional syntax.
10.  */
11. #define I2C_BOARD_INFO(dev_type, dev_addr) \
12.     .type = dev_type, .addr = (dev_addr)

```

I2C_BOARD_INFO macro用于帮组create struct i2c_board_info。

比如

```
1. struct i2c_board_info i2c_eeprom[2] = {
2.     I2C_BOARD_INFO("24c64", 0x50),
3.     I2C_BOARD_INFO("spd", 0x53),
4. };
5.
6. i2c_register_board_info(0, i2c_eeprom, 2);
```

在gemstone2 toc board上，M24C64和STTS2002都挂在第一个i2c bus上。在原理图上是I2C1，但在Programmer Guide上是I2C0。

Note:

必须enable CONFIG_I2C_BOARDINFO。

How to support i2c eeprom in kernel?

add following code into arch/arm/mach-pegmatite/pegmatite.c

```
1. static int __init i2c_eeprom_init(void)
2. {
3.     struct i2c_board_info i2c_eeprom[] =
4.     {
5.         {
6.             I2C_BOARD_INFO("24c64", 0x50),
7.             I2C_BOARD_INFO("spd", 0x53),
8.         },
9.     };
10.
11.     i2c_register_board_info(0, i2c_eeprom, 2);
12.
13.     return 0;
14. }
15. arch_initcall(i2c_eeprom_init);
```

make i2c_eeprom_init() before i2c-pxa driver init and after init-core driver init.

```

1. root@granite2:/sys/class/i2c-adapter/i2c-0# pwd
2. /sys/class/i2c-adapter/i2c-0
3. root@granite2:/sys/class/i2c-adapter/i2c-0# ls -l
4. drwxr-xr-x    3 root    root          0 May 23 06:41 0-0050
5. drwxr-xr-x    3 root    root          0 May 23 06:41 0-0053
6. --w-----    1 root    root        4096 May 23 06:43 delete_device
7. lrwxrwxrwx    1 root    root          0 May 23 06:43 device -> ../../d40
   11000.i2c
8. -r--r--r--    1 root    root        4096 May 23 06:43 name
9. --w-----    1 root    root        4096 May 23 06:43 new_device
10. drwxr-xr-x    2 root    root          0 May 23 06:43 power
11. lrwxrwxrwx    1 root    root          0 May 23 06:41 subsystem -> ../../
   ../bus/i2c
12. -rw-r--r--    1 root    root        4096 May 23 06:41 uevent

```

这里的0-0050 and 0-0053就是两个eeprom device

```

1. root@granite2:/sys/class/i2c-adapter/i2c-0/0-0050# ls -l
2. lrwxrwxrwx    1 root    root          0 May 23 06:41 driver -> ../../../
   ../bus/i2c/drivers/at24
3. -rw-----    1 root    root        8192 May 23 06:51 eeprom
4. -r--r--r--    1 root    root        4096 May 23 06:43 modalias
5. -r--r--r--    1 root    root        4096 May 23 06:43 name
6. drwxr-xr-x    2 root    root          0 May 23 06:43 power
7. lrwxrwxrwx    1 root    root          0 May 23 06:41 subsystem -> ../../
   ../../bus/i2c
8. -rw-r--r--    1 root    root        4096 May 23 06:41 uevent

```

可以对eeprom进行read / write