arm中对kgdb breakpoint的支持是通过"undefined instruction" trap来实现的。

kgdb breakpoint在arm中分为2种

这两条在arm中都是"undefined instruction".前者是用户动态设置breakpoint时使用的,而后者 是静态编译在code中的。

in arch/arm/include/asm/kgdb.h

```
1. static inline void arch_kgdb_breakpoint(void)
2. {
3. asm(__inst_arm(0xe7ffdeff));
4. }
```

arch_kgdb_breakpoint()即产生一条KGDB_COMPILED_BREAK instruction.

所以在kernel code(driver code)中可以调用该函数来嵌入一个breakpoint.

Note: 需要include如下文件

```
1. #include <linux/kgdb.h>
```

in kernel/debug/debug core.c

```
1.
 2.
       * kgdb_breakpoint - generate breakpoint exception
       * This function will generate a breakpoint exception. It is used at the
5.
       * beginning of a program to sync up with a debugger and can be used
       * otherwise as a quick means to stop program execution and "break" into
6.
       * the debugger.
8.
9.
      noinline void kgdb_breakpoint(void)
10.
11.
          atomic_inc(&kgdb_setting_breakpoint);
12.
          wmb(); /* Sync point before breakpoint */
13.
          arch_kgdb_breakpoint();
          wmb(); /* Sync point after breakpoint */
14.
15.
          atomic_dec(&kgdb_setting_breakpoint);
16.
      EXPORT SYMBOL GPL(kgdb breakpoint);
17.
```

使用该AP可能更合理。只需要

```
#include <linux/kgdb.h>
```