

CMPT 300
Operating System I
Midterm Review

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Admin notes

- Midterm date (June 20 from 1:30 -2:20 pm)
 - 50 min exam
 - In person exam only.
 - No cheat sheets. No sample midterm exam. I will provide some sample questions.
- Content: All lecture and material covered prior to June 17.
- Suggested way to Study
 - Start with the post-lecture slides (special attention to the list of Learning Goals.
 - Textbook (focus on the lecture notes)
 - Go through Quizzes, In-class activities, Clickers

Tentative Number of Problems (subject to change)

4-5 True or False

- Choosing T or F, no explanation needed or allowed
- Full credit or zero credit

4-5 Multiselect questions

Full credit or zero credit

3-4 Short questions.

- Write outcome of a code piece
- Short explanation require
- Partial credit

Midterm Topic

- Coverage
 - Chapter 1 : Introduction
 - Chapter 2 : OS Structure
 - Chapter 3: Process
 - Chapter 4: Threads
 - Chapter 5 : Scheduling

Midterm Review Suggestions

NOTE: This is not guaranteed to be exhaustive!

Chapter 1

- Organization of Computer System
- Role of interrupts
- User mode vs kernel mode
- What is Operating System

Interrupts/DMA

- Basic concept of interrupt
 - Signals sent by devices to the CPU when some event happens
- CPU runs much faster than other devices
- Using interrupts allows the CPU to do other tasks while an I/O is in progress
 - Steps of handling an interrupt ✓
- Two ways of doing I/O operations
 - Busy waiting - wastes CPU cycles
 - Interrupts - better than busy waiting, but also depends on the frequency CPU is interrupted
- DMA operations allow I/O devices to transfer data to/from memory without CPU intervention

Chapter 2

- Services provided by OS
- System Calls
- OS Structure

OS Structures

- Monolithic
- Layered
- Microkernel
- Modular
- Hybrid

Pros and Cons?

- Modern OSes are often hybrids ✓
 - Exhibit properties from multiple structures

Chapter 3

- Process Operations
- Process States
- Process Control Block ✓
- Context switch
 - switch from one process to another
 - Need to save and restore process states
 - Pure overhead
 - fork() *exec()*
 - Signals
- Inter Process Communications (IPC) Mechanisms (Shared Memory, Message Passing , Pipe)

Chapter 4

- Thread
- User and Kernel Threads
- Pthreads

Processes and threads

- Similarities and differences?
- What's shared between threads
- How do processes/threads communicate with each other?

Process and Threads

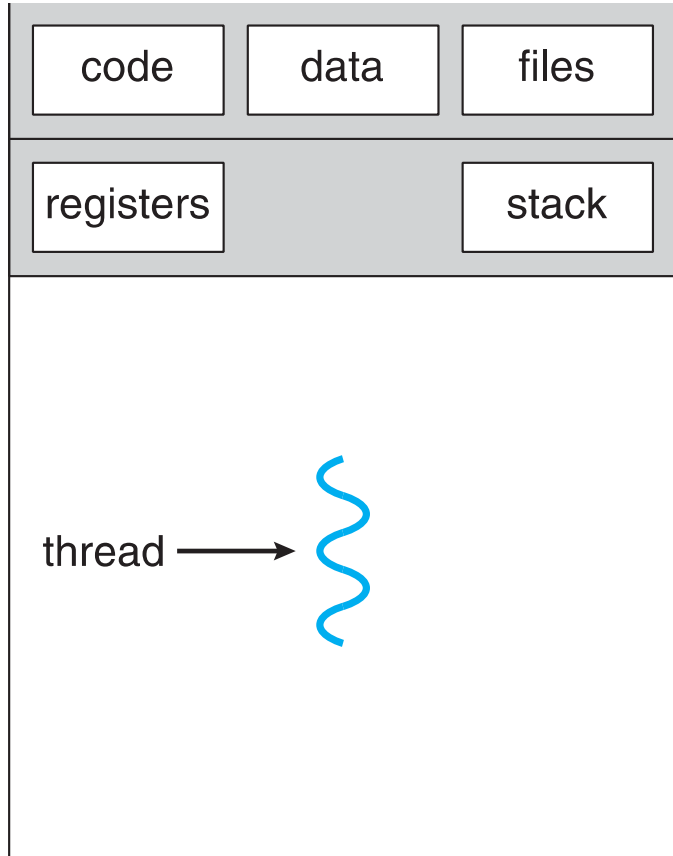
Process: program in execution

- Program on disk (file) is not a process, until it is loaded in memory and required OS structures are created
- Terms “job” and “process” are interchangeable

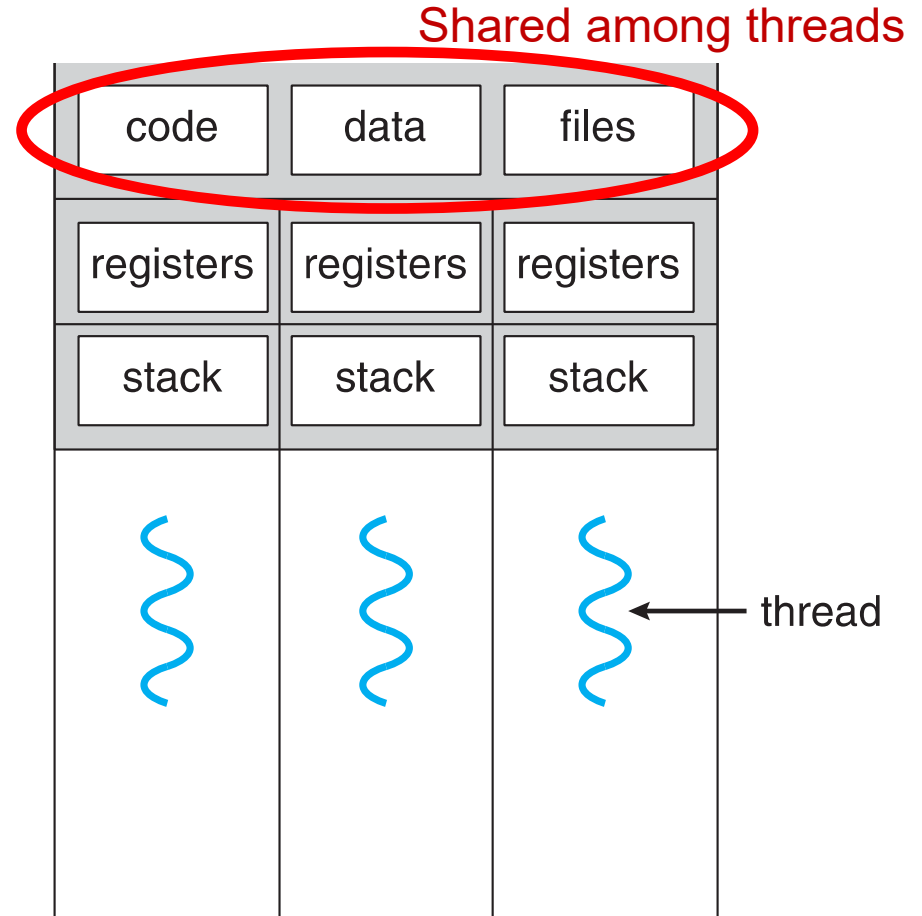
Threads: a basic unit of CPU utilization

- Threads in the same process share certain resources
 - What are they?
- But not everything is shared
 - What are the things that are not shared?

Single and Multithreaded Processes

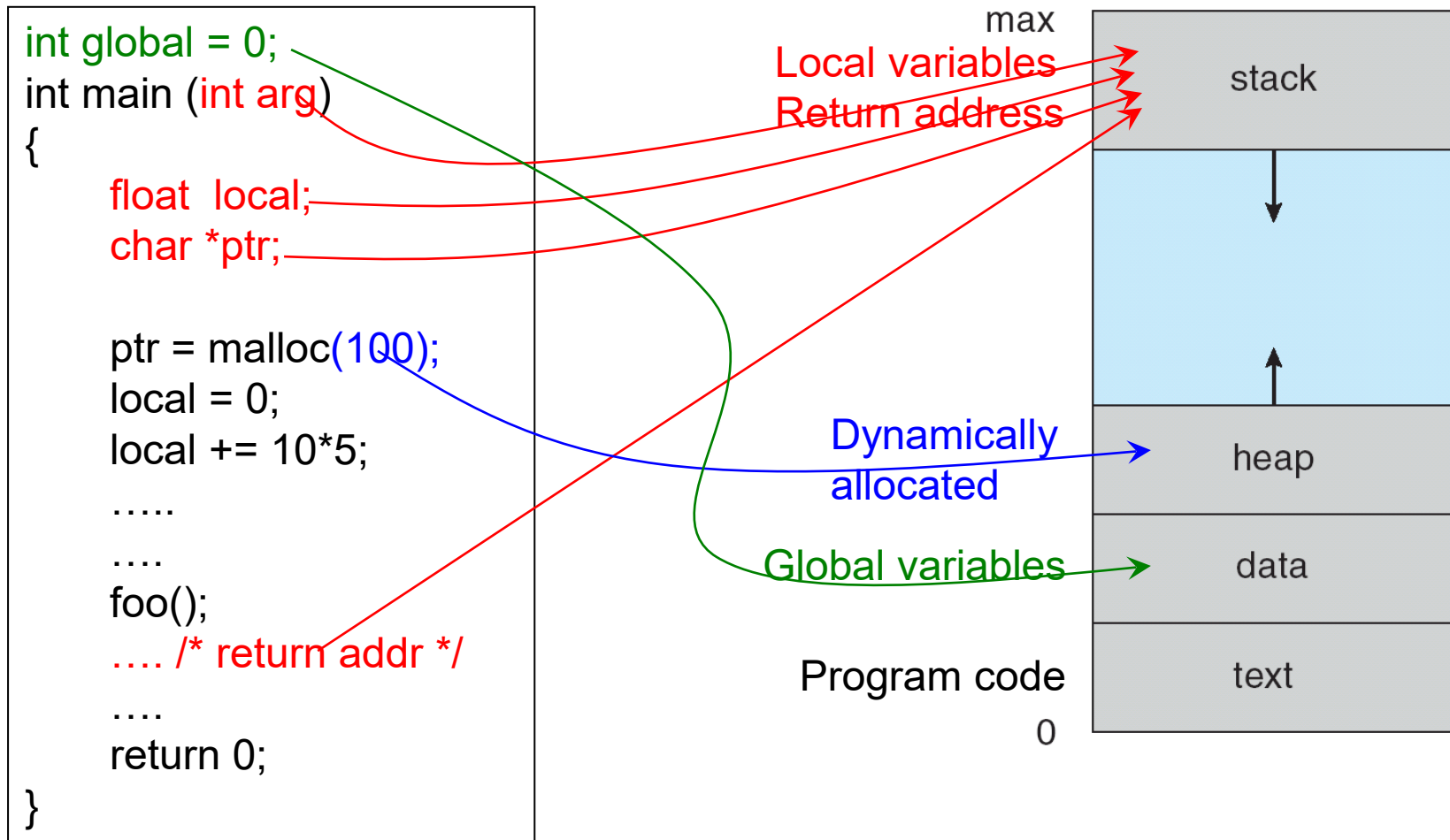


single-threaded process



multithreaded process

Process in Memory

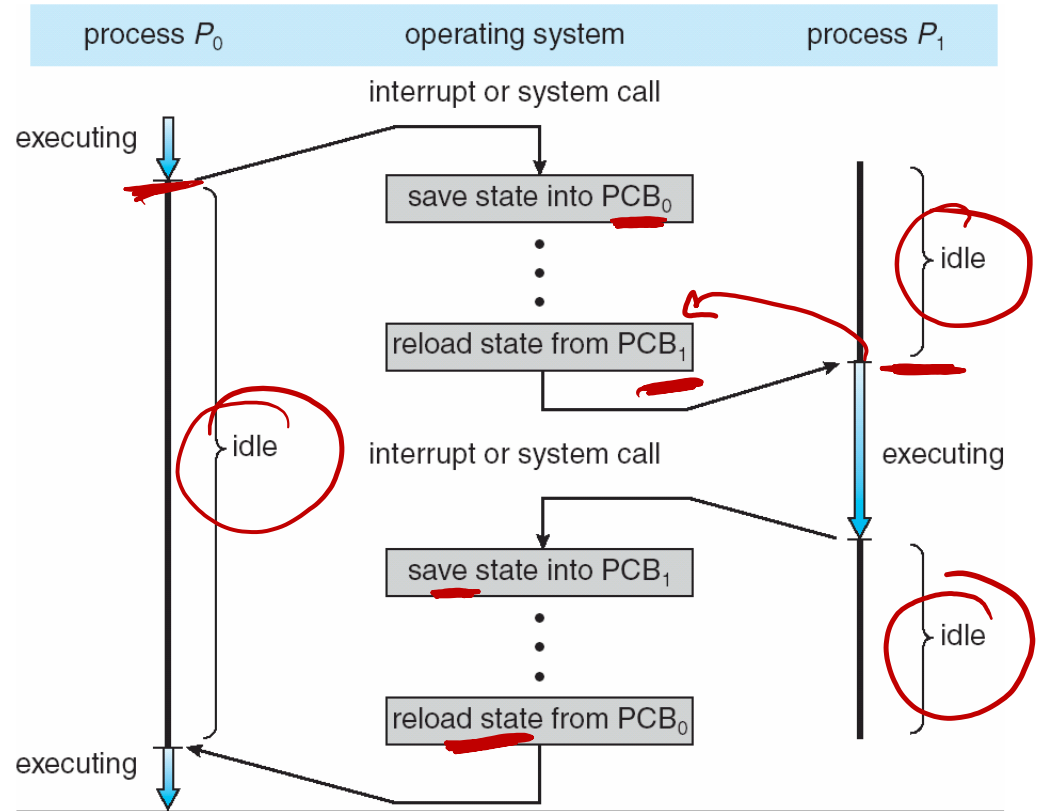


Processes: Context Switch

Switch the CPU core from one process to another

- When switching occurs, the OS kernel:
 - Saves state of P_0 in PCB₀ (in memory)
 - Loads state of P_1 from PCB₁ into registers

State: values of the CPU registers (program counter, stack pointer, etc.)



C Program Forking a Child Process

```
int main() {  
    pid_t  var_pid;  
    → var_pid = fork();  
    if (var_pid < 0) {  
        fprintf (stderr, "fork Failed");  
        exit(-1);  
    }  
    [ else if (var_pid == 0) { /* child process */  
        execvp ("/bin/ls", "ls", NULL);  
    }  
    else { /* parent process */  
        /* parent will wait for child to complete */  
        wait (NULL);  
        printf ("Child %d Completed", var_pid);  
        exit(0);  
    }  
}
```

fork returns twice

exec does not return if succeeded

Note: fork returns 0 to child and the pid of the new process to parent.

Example: Pthreads

```
#include <pthread.h>
```

```
int sum;
```

```
void* runner(void* param) {  
    int i, upper = atoi(param); sum = 0;  
    for (i = 1; i <= upper; i++)  
        sum += i;  
    pthread_exit(0);  
}
```

string to integer


```
int main(int argc, char* argv[]) {  
    pthread_t tid; pthread_attr_t attr;
```

```
    pthread_attr_init(&attr); // default attributes  
    pthread_create(&tid, &attr, runner, argv[1]);  
    pthread_join(tid, NULL);
```

```
    printf("Sum = %d\n", sum);  
    return 0;
```

```
}
```

Chapter 5

- Goals of scheduling (What to maximize? What to minimize?)
 - Process Cycles (CPU Burst and I/O Burst)
 - Process Queues (Ready and I/O)
 - Context Switching
 - Thread Scheduling
 - Preemptive and Non-preemptive Scheduling
 - First Come First Serve Scheduling
 - Shortest Job First Scheduling
 - Shortest Remaining Time First Scheduling
 - Priority Scheduling
 - Round Robin Scheduling
 - Multiple Queues Scheduling and Multiple queue feedback Scheduling
- 

Scheduling

- Process/thread types
 - I/O-bound: spend more time on I/O
 - CPU-bound: spend more time on CPU
 - Examples?
- Scheduling can be
 - Preemptive: OS scheduler can force a process to give up CPU
 - Non-preemptive: process only voluntarily leaves the CPU
- Algorithms
 - FCFS, SJF, Priority, Round-Robin, Queue based
 - Properties of each algorithm

Scheduling Metrics

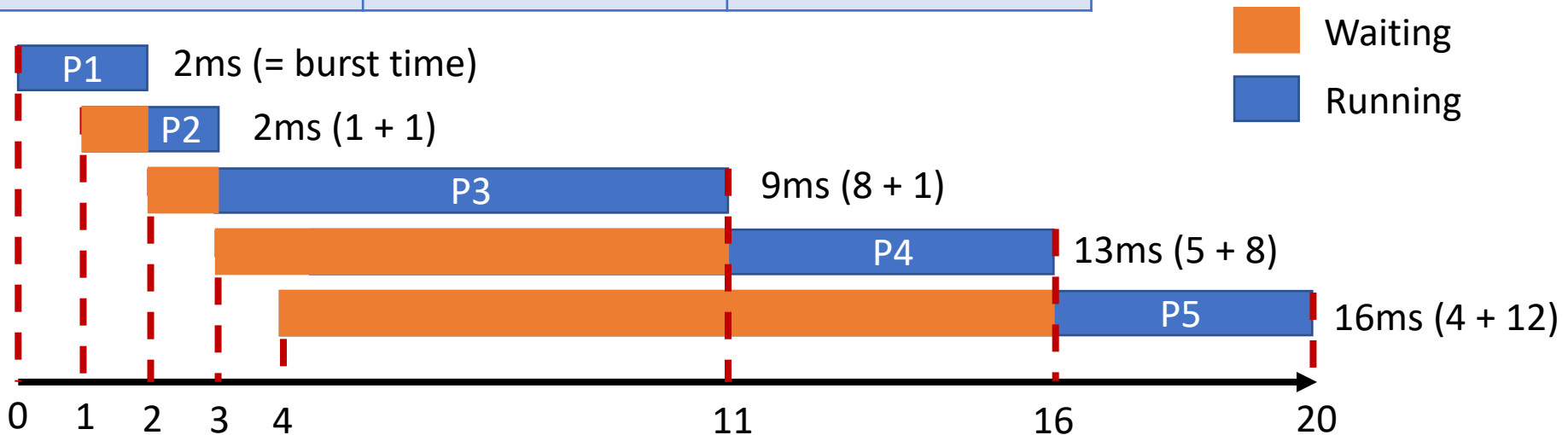
- Maximize (higher = better)
 - CPU utilization - keep the CPU as busy as possible
 - Throughput - # of processes that complete their execution per time unit
- Minimize (lower = better)
 - Turnaround time - amount of time to execute a particular process (time from submission to termination)
 - Waiting time - amount of time a process has been waiting in ready queue
 - Response time - amount of time it takes from when a request is submitted until the first response is produced

Scheduling Examples

Process	Burst Time (ms)	Arrival Time (AT)
P1	2	0
P2	1	1
P3	8	2
P4	5	3
P5	4	4

Turnaround time for each process under FCFS?

Burst time + wait time

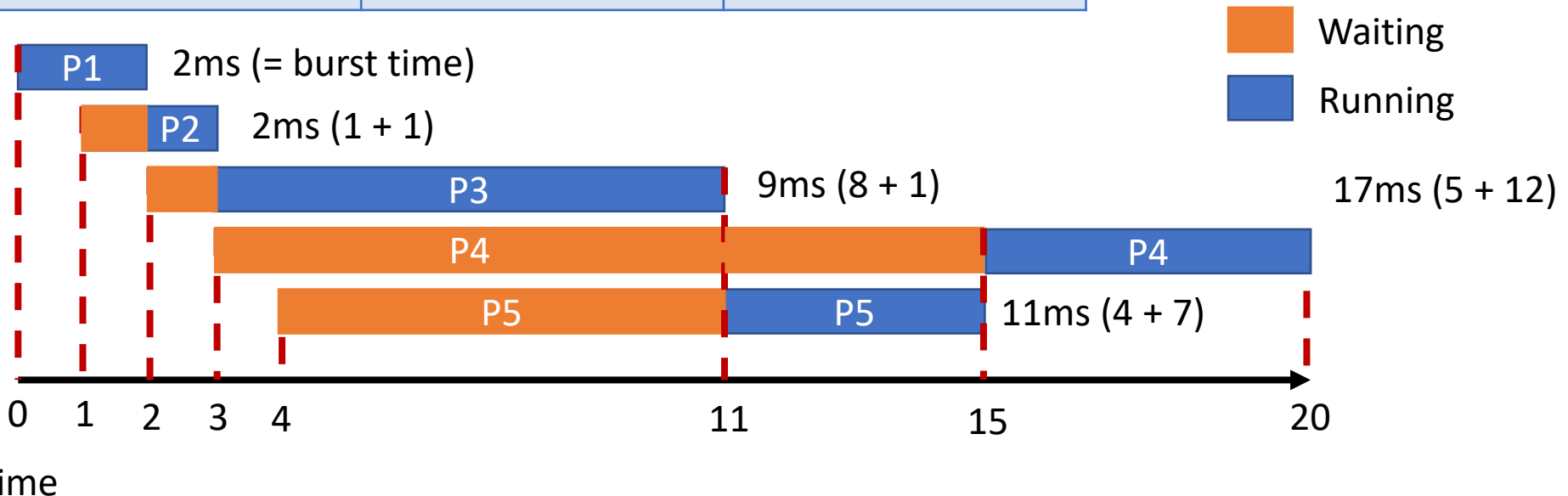


Gantt chart: put all "running" parts together

Scheduling Examples

Process	Burst Time (ms)	Arrival Time (AT)
P1	2	0
P2	1	1
P3	8	2
P4	5	3
P5	4	4

Turnaround time for each process under Shortest-Job-First?
Burst time + wait time



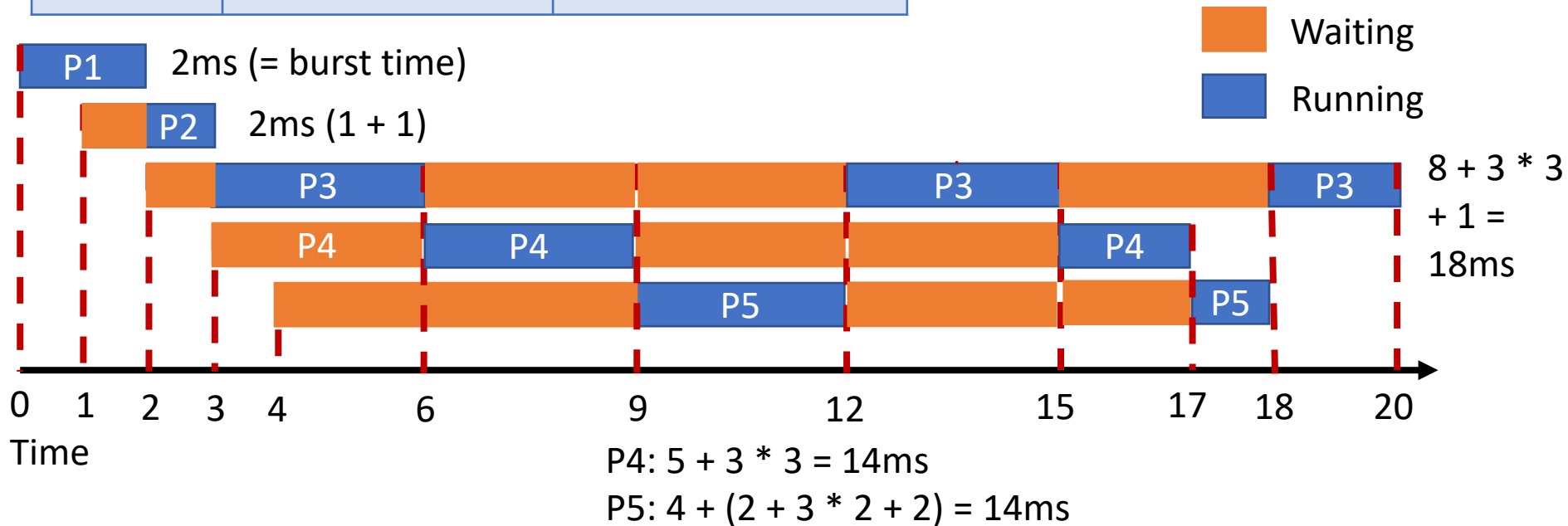
Scheduling Examples

Process	Burst Time (ms)	Arrival Time (AT)
P1	2	0
P2	1	1
P3	8	2
P4	5	3
P5	4	4

Turnaround time for each process under Round-Robin?

Assume: time quantum (q) = **3ms**

Burst time + wait time



Sample questions

- What are the roles of the OS?
- What does it mean to share the resources of the system?
- What is a context switch?
- Define Interrupts.
- Define preemption.
- What is a process?
- What is the difference between a process and a program?
- What is contained in a process?
- What is PID?
- What information does PCB contain?
- How is it used in a context switch?
- What different states can a process be in?
- When does a process change state?
- What does fork()? ✓
- What does it return?
- What does exec() do?

Sample questions

- How is `exec()` different from the `fork`? ✓
- When you type `ls -l` at a bash prompt, how do `ls` get the `-l` argument?
- What are system calls, and how are they handled?
- What are interrupts, and how are they handled?
- What is a thread?
- What is the difference between a thread and a process?
- How are they related?
- Why are threads useful? ✓
- Why does each thread have its own stack? ←
- How are threads managed by the system?
- What is a thread control block? TCB
- User-level and kernel-level threads
 - What's the difference?
 - What are the advantages/disadvantages of one over another?
 - Different user-level kernel-level thread mapping models

Sample questions

Consider the following code snippet

```
int value = 10;

int main ( ) {
    //...
    if ( fork() == 0 )
        value += 15;
    else {
        wait(NULL);
        printf ("\n value = %d \n", value);    /*Line A */
    }
    // ...
}
```

- (a) What will be the output of Line A?
- (b) If we remove the statement `wait(NULL)`, what will be the output?

Sample questions

Consider the following set of processes:

Process	Arrival Time	Burst Time	Priority
P1	0	10	3
P2	1	1	1
P3	1	2	2
P4	2	1	4
P5	4	5	1

Consider a preemptive priority CPU scheduling policy. Note that a smaller number implies higher priority.

- (a) Draw a Gantt chart showing the execution of these processes.
- (b) Compute the average waiting time and average turnaround time.

Finally, DON'T PANIC!

The best advice I can give about what to do during an exam is “DON'T PANIC”.

When you panic, your mind freezes up, everything seems harder (even the easy stuff), and you get nothing done, which is the worst-case scenario in an exam setting.

Unfortunately, we all panic from time to time. It will happen.

So, it will be very useful to practice not panicking.

Some Tips

- Take some time to relax, calm down, and give yourself a silent pep-talk.
 - You've prepared for this exam.
 - You've already done some of it (or practice questions, clickers like it), and you can do more.
 - Part marks are your friend.
 - Even the worst-case scenario is not unrecoverable; **EVERYTHING WILL BE ALRIGHT.**