CMPT 300 Operating System I Synchronization Tools

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Summer 2022

Admin

A2 regrading request due date is July 6.

A3 submission date is July 11.

A2 reflection

I did not learn much on things relating to this course to be completely honest. This felt more like a C general assignment than something relating to this course.

I would say this assignment was rather challenging and it tested me more on my C language skills than testing me out on my Operating Systems knowledge.

I learned a lot through this assignment. I got a general idea of how shells work. I learned how to use threads and pipes appropriately. Also learned about I/O redirection, and although I had trouble with the implementation of the system call, I understood how they worked.

I learned about handling child processes with fork() and wait(), managing arrays of structs, and splitting an array of strings into tokens. I also learned how to use the tm struct to display the current time in a formatted way.

This assignment was very fun and had a lot of interesting elements to learn from. It was a very satisfactory experience as we got to build our own c shell.

Clicker

's' can be initialized to any integer value.

(A) True

(B) False

5<0 blocked on 5 non-ne gative non-ne gative

Readers-Writers Solution

Shared data:

- Data set
- Binary Semaphore rw_mutex initialized to 1
 - 1 = no readers/writers;
 - 0 = a writer or some number of readers
- Integer read_count initialized to 0
 - Number of processes actively reading the data set
- Binary Semaphore mutex initialized to 1
 - Protects read_count from being accessed/modified by more than one process

Solution Case 1: R-W

read count= 0

Semaphore rw_mutex =1

Semaphore mutex =1

```
Reader
do {
wait(mutex);
read_count++; // one more reader
if (read_count == 1)
    wait(rw_mutex); // First reader

signal(mutex);

...
/* reading is performed */
...

wait(mutex);
read_count--; // one less reader
if (read_count == 0)
    signal(rw_mutex);
    signal(mutex);
} while (true);
```

```
Writer
do {
    wait(rw_mutex);
    ...
    /* writing is performed */
    ...
    signal(rw_mutex);
} while (true);
```

- Reader 1 comes first.
- Mutex = $\frac{1}{4}$ 0
- RC++ = we have one reader. That's why its incremented
- If (read_count==1) True, So now,rw_mutex is 0.
- Mutex =1 (signal(mutex))
- Reader 1 in cs
- Now, writer comes. The entry code of writer will try to decrement rw_mutex(which is 0). These are binary semaphores so not possible. So, Writer will get block.

Solution Case 2: W-R

read count= 0

Semaphore rw_mutex =1

Semaphore mutex = 1

```
Reader
do {
wait (mutex);
read_count++; // one more reader
if (read_count == 1)
    wait (rw_mutex); // First reader
    signal (mutex);

...
/* reading is performed */
...

wait (mutex);
read_count--; // one less reader
if (read_count == 0)
    signal (rw_mutex);
signal (mutex);
} while (true);
```

```
Writer
do {
   wait(rw_mutex);
   ...
   /* writing is performed */
   ...
   signal(rw_mutex);
} while (true);
```

W1 comes first.

rw_mutex = 4 0

Writer in CS

Ques Can reader enter in CS?

Lets check:

mutex = 4 0

RC++ = we have one reader. That's why its incremented If (read_count==1) → True. So now, it will try to decrement rw_mutex (which is 0). These are binary semaphores so not possible. So, Reader will get block.

Solution Case 3: W-W

read_count= 0

Semaphore rw_mutex = 1

Semaphore mutex = 1

```
Reader
do {
wait(mutex);
read_count++; // one more reader
if (read_count == 1)
    wait(rw_mutex); // First reader
    signal(mutex);
...
/* reading is performed */
...

wait(mutex);
read_count--; // one less reader
if (read_count == 0)
    signal(rw_mutex);
signal(mutex);
} while (true);
```

```
writer

do {
    wait(rw_mutex);
    ...

/* writing is performed */
    ...

signal(rw_mutex);
} while (true);
```

W1 comes first. rw_mutex = 4 0 Writer1 in CS

Ques Can Writer 2 enter in CS?

Lets check:

The entry code of writer2 will try to decrement rw_mutex(which is 0). These are binary semaphores so not possible. So, Writer2 will get block.

Solution Case 4: R-R

Semaphore rw_mutex =1 Semaphore mutex = 1 read count= 0 Reader Writer do { do { wait(mutex); read count++; // one more reader wait(rw mutex); if (read count == 1) wait(rw mutex); // First reader signal (mutex); /* writing is performed */ /* reading is performed */ . . . signal(rw mutex); wait(mutex); } while (true); read count--; // one less reader if (read count == 0) Reader1 comes first. signal(rw mutex); signal(mutex); Mutex = 10} while (true); RC++ = we have one reader. That's why its incremented If $(read_count==1) \rightarrow True$. So now,rw_mutex is 0. Mutex =1 (signal(mutex)) Reader1 in cs Now, R2 comes. Wait(mutex), so Mutex now is 0. Read_count=2. If condition is False. So now Mutex =1

Reader 2 is in cs

Solution Case 4: R-R

read_count= 0 Semaphore rw_mutex = 1 Semaphore mutex = 1

```
do {
    wait(mutex);
    read_count++; // one more reader
    if (read_count == 1)
        wait(rw_mutex); // First reader
        signal(mutex);

    /* reading is performed */
    ...

wait(mutex);

read_count--; // one less reader
    if (read_count == 0)
        signal(rw_mutex);

signal(mutex);

y while (true);
```

Reader

```
do {
                  wait(rw mutex);
                  /* writing is performed */
                   . . .
                   signal(rw mutex);
                   } while (true);
So now Mutex =1
Read_count =2
Reader 2 want to exit the cs. It will execute the exit code.
mutex = \frac{1}{2}
Read count =\frac{2}{1}
If condition is false
Signal(mutex) will execute and mutex will be again
```

Writer

Reader- Writer

Specifically, two rules must be enforced:

1. A reader is permitted to join other readers currently in the CS only when no writer is waiting. When the last reader exits the CS, the writer is allowed to enter.

Rule 1 guarantees that writers cannot starve

2. All readers that have arrived while a writer is in the CS must be allowed to enter before the next writer.

Rule 2 guarantees that readers cannot starve.

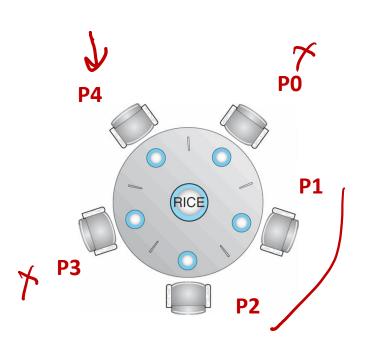
mat con arroncy of readers.

- Five philosophers spend their lives thinking and eating while sitting at a round table around a bowl of rice
- A chopstick is placed between each philosopher
- Philosophers cannot interact with their neighbours
- Each philosopher will think and occasionally eat
 - When ready to eat, a philosopher will try to pick up two chopsticks (one at a time) so he can eat some rice
 - A philosopher needs 2 chopsticks to eat
 - When done eating, a philosopher will put down each chopstick, one at a time
- How can the philosophers sit and eat together without anyone starving?
 - Think of each chopstick as a semaphore

Clicker

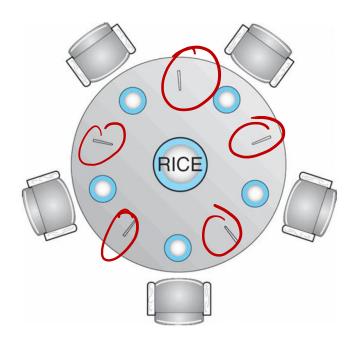
When P4 is eating then _____ can eat concurrently.

- (A) Only P1
- (B) P0 or P1
- (C) P1 or P2



Shared data

- Bowl of rice (data set)
- Semaphore chopstick [5] initialized to 1

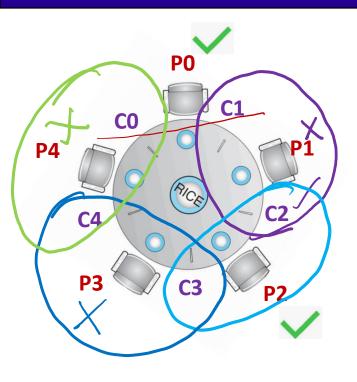


Possible Solution?

Instruct each philosopher to behave as follows:

- Think until the left chopstick is available; when it is pick it up
- Think until the right chopstick is available; when it is pick it up
- Eat some rice
- Put the left chopstick down
- Put the right chopstick down
- Go back to thinking





P0 comes in and grab C1 and C0 and start eating.

P1 comes in and grabs C2 and tries to grab C1 (which is with P0). So, get blocked.

P2 comes in, C3 and C2 are both available so P2 grabs both and starts eating.

P3 comes in, grabs C4 and tries to grab C3 (which is with P2), so get blocked.

P4 comes in, C0 is with P1 so get blocked.



```
do {
                       left
     ( chopstick[i] );
wait
wait (chopStick[ (i + 1) % 5] ); Right
// eat
signal ( chopstick[i] );
signal (chopstick[ (i + 1) % 5] );
// think
  while (TRUE);
```

Each philosopher will grab left chopstick first



Ques. What is the problem with this algorithm?

If each philosopher picks up his left chopstick at the same time, then they all sit waiting for the right chopstick forever (i.e. deadlock)

How do we solve this?

How do we solve the deadlock problem?

- Option 1: at most 2 philosophers can eat at the same time (using 4 chopsticks)
- Option 2: if we can prevent all five of the philosophers from picking up the first chopstick simultaneously, then we can guarantee that at least one can pick up the second chopstick

- Introduce another common semaphore. Call it flag.
- Initialize to 4
- Before picking up the first chopstick, the philosophers must wait on the flag.
- Once done with their chopsticks, they must signal the flag.

```
fly ~ 9
do {
   wait (flag) ;
   wait (chopstick[i] );
   wait (chopStick[ (i + 1) % 5] );
               // eat
   signal (chopstick[i]);
   signal (chopstick[ (i + 1) % 5] );
   signal (flag);
               // think
} while (TRUE);
```

Deadlock

 Deadlock: two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes

Let S and Q be two semaphores initialized to 1

```
P_0 P_1 wait(S); wait(Q); wait(S); ... signal(S); signal(Q); signal(S);
```

Starvation: Indefinite blocking

- A process may never be removed from the semaphore queue in which it is suspended
- The semaphore/mutex might still be released, but another waiting process can get it first

Next topic: Deadlock

- Definition
- Techniques for preventing

Learning Objectives

- To develop a description of deadlocks, which prevent sets of concurrent processes from completing their tasks
- To present a number of different methods for preventing or avoiding deadlocks in a computer system

The Deadlock Problem

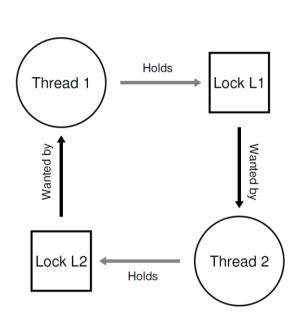
A set of processes each holding a resource and waiting to acquire a resource held by another process

Example: two threads running simultaneously on two cores

```
Thread 1:

pthread_mutex_lock(L1);  pthread_mutex_lock(L2);  pthread_mutex_lock(L1);  pthread_mu
```

- Thread 1 waits for Thread 2 to release L2
- Thread 2 waits for Thread 1 to release L1
- Two threads wait for each other



Necessary Conditions for Deadlock

Deadlock may arise if four conditions hold simultaneously

- 1. Mutual exclusion: threads require exclusive control of resources
- 2. Hold and wait: threads are already holding resources but also are waiting for additional resources being held by other threads
- 3. No preemption: resource released only voluntarily by the thread holding it
- 4. Circular wait: there exists a set {P0, P1, ..., Pn} of processes such that P0 is waiting for a resource that is held by P1, P1 is waiting for P2, ..., Pn-1 is waiting for Pn, and Pn is waiting for P0

corder emplies hold & wait situation

^{* &}quot;Threads" and "processes" used interchangeably here

Deadlock detection

- Deadlock detection is when we try to find deadlocks after they have occurred and then try to take corrective action.
 - E.g., killing one of the threads that are in deadlock.
- Deadlock detection isn't typically done by the OS, but instead, it is done by the user or in a library.
- Deadlocks can be detected on-the-fly, by running cycle detection algorithms on the graph that defines the current use of resources.

System model

- resource types: R₁, R₂, ..., R_n
- each resource R has W_i instances
- each process utilizes a resource as follows:

of medicics

ned Request > use > release (lose())

signed

interpt

sess will block if the resource is ret (

Process will block if the resource is not free

Any instance of a resource type can be used to satisfy a request of that resource.

Deadlock

Given the graph, we can run any cycle detection algorithm.

