

Image Processing **Image Filters: Part**

This technical document introduces the idea of image processing from the basics. The topic covered in this document is image filters, which aids in achieving a stable image. Image filters can also bring out details that may help make the inspection easier and more robust.

Image filter effects

Various types of image filters are available to meet the needs of different applications. To successfully stabilise inspections, it is important to be familiar with the different types of filters and their effects on an image.

■ Inspection of foreign particles on mesh -

Ignore the gridline caused by the mesh and only bring out the thing flaw



Original image

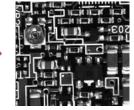
After image filter

■ Emphasis of PCB components -

Increase contrast and emphasise edges of the components mounted on PCB for presence/ absence inspection







■ Inspection of foreign particles in a cup

Detect any foreign particles inside the cup while ignoring the contour of the cup and the shape of the cup against the background







After image filter

Inspection of cylindrical metal part -

Ignore uneven lighting and texture on the surface and bring out the defect



Original image



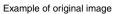
After image filter

2. Image filter basics

This section explains four types of image filters that are most commonly used. A 3 x 3 pixel array is used to find the value of the centre pixel and is applied to every pixel in the image.

3 x 3 pixel array

2	5	9
4	7	3
0	1	2



Image

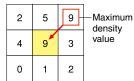


Principle of a 3 x 3 pixel

Filtered image

Expansion filter

In this filtering process, the centre pixel of the 3×3 pixel array becomes the maximum value found within the array. The expansion filter is effective in removing dark noise.





Shrink filter

In this filtering process, the centre pixel of the 3×3 pixel array becomes the minimum value found within the array. This filter is effective at enhancing black pixels.

	2	5	9
	4	0	3
Minimum	0	1	2



Averaging filter

In this filtering process, the centre pixel of the 3×3 array is replaced with the average value of the array. This filter is effective at reducing noise and adds blur to the image.

2	5	9
4	3	3
0	1	2



Median filter

In this filtering process, the centre pixel of the 3×3 array is replaced with the median value of the array. This filter is effective at reducing noise and adds blur to the image.

2	5	9	
4	3 ←	3	Median value
0	1	2	

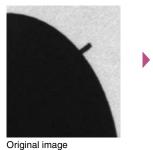


Filtering needs are different for every application, but having an understanding of how these image filters work can be advantageous.

Filtering Tips / Filtering techniques

Example 1 Outline smoothing Expand and shrink

By applying expand and shrink the same number of times, it can remove the burr on the edge while leaving the original shape of the target.





Filtered image

$oldsymbol{3}.$ Edge extraction filters

Edge extraction filters are useful for bringing out the edge when the details of the edge are low. There are numerous edge extraction and enhancement filters which can help increase the contrast of an edge. Each type of filter has different benefits.



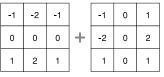
Original image

[Sobel and Prewitt filters]

Both the Sobel and Prewitt filters work by extracting edges by separately filtering in the X (horizontal) and Y (vertical) directions, then combining the two results.

A 3 x 3 central pixel is replaced with the combined density value after multiplying each of the nine pixels by a set coefficient. The Sobel filter is better at enhancing edges with less contrast than the Prewitt filter, because the pixel at the centre is multiplied by 2. Although these filters are good at extracting edges, unwanted noise may also be enhanced.







Prewitt filter

-1	-1	-1		-1	0	1
0	0	0	+	-1	0	1
1	1	1		-1	0	1



Edge-extraction filter in a specified direction

Some edge extraction filters can be applied in just the X or Y direction. This can help bring out flaws that occur in a certain direction.

Sobel in X

-1	0	1
-2	0	2
-1	0	1

Sobel in Y

-1	- 2	-1
0	0	0
1	2	1



[Edge extraction filters]

	Derivation	Horizontal direction	Vertical direction	Diagonal	Others
Prewitt filter	Firstderivation	0	0	Δ	
Sobel filter	Firstderivation	0	0	0	
Roberts filter	Firstderivation	Δ	Δ	0	
Laplacian filter	Second derivation	Δ	Δ	Δ	Direction-independent

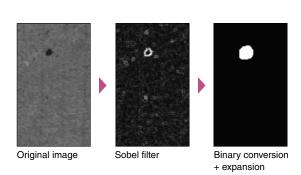
Symbols: ⊚=best ○=good △=fair

\Filtering Tips / Technique for using image filters

Example 2 Emphasis of small surface flaws

Sobel filter + binary conversion + expansion

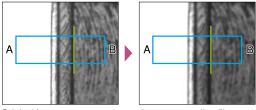
Flaws are enhanced while minimising noise



Example 3 Stable measurement by noise reduction

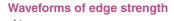
Averaging and median

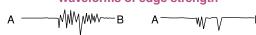
By applying the averaging and median filter together, the surface roughness is minimised for stable measurement



Original image

Average + median filter





An introduction to lineup of image processing

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All of lineup of cameras including line scan cameras, high speed using distributed processing on multicore DSP, a wide variety of flexible inspection tools, interface that allows users to create on their own make a precise response to customers' needs.

CV-X100 Series

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The "Auto-teach inspection tool" which recognises those items that are different from conforming items as non-conforming items is incorporated into the series. This tool allows human-like inspection. This series can be globally deployed and used by anyone by setting and operating by just selecting and clicking.

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