DUO Integration

Integration Projects

DUO works well with common vision and robotics frameworks such as .NET, OpenCV, ROS, Qt and more. Get started with the DUO API, SDK and Code Samples.
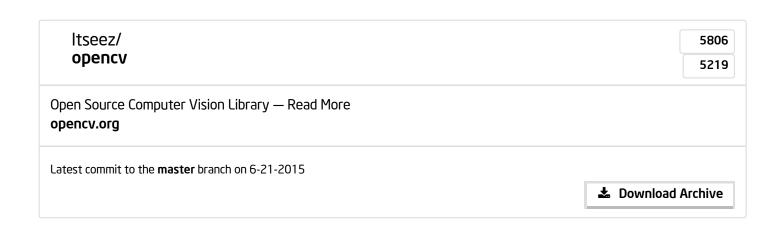
.NET

.NET

Integrating DUO with the Microsoft .NET with provided bindings and samples.

Microsoft/ **dotnet**	5944
	770

dotnet is the official home of .NET on GitHub. It's a great starting point to find many .NET OSS projects from Microsoft and the community, including many that are part of the .NET Foundation. — Read More **http://blogs.msdn.com/dotnet**

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OpenCV

Integrating DUO with OpenCV (Open Source Computer Vision) with provided samples.

Itseez/
opencv

Open Source Computer Vision Library — Read More
opencv.org

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ROS

ROS.org

Integrating DUO with ROS (Robot Operating System) driver module with Module Docs.

l0g1x/
DUO-Camera-ROS

6

5

ROS driver for DUO Stereo camera(s). Specify which camera you are using in your launch file, if it is a custom DUO solution, specify the the camera specifications in the launch parameters. — Read More

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BVS

Integrating DUO with BVS (Broad Versatile Supervisor)

nilsonholger/
bvs-modules

BVS-Modules, computer vision add-ons for BVS. — Read More
https://www.github.com/nilsonholger/bvs

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MRPT

Integrating DUO with MRPT (Mobile Robot Programming Toolkit)

jlblancoc/
mrpt

94

85

The Mobile Robot Programming Toolkit (MRPT) — Read More
http://www.mrpt.org/

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Qt

Integrating DUO with the latest Qt with provided samples.

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qtproject/
qt5

— Read More

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