CONCURRENCY: LOCKS

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RECAP: THREADS

Threads enable concurrency within the same process

Each thread has its own

- Thread ID (TID)
- Set of registers, including program counter and stack pointer
- Stack for local variables and return addresses
 - There are now multiple stacks in same address space

EXAMPLE: CONCURRENT INCREMENT

Data

balance at 0x9cd4 = 100

Code (C)
balance = balance + 1;

Code (Assembly)

0x195 mov 0x9cd4, %eax
0x19a add \$0x1, %eax
0x19d mov %eax, 0x9cd4

thread 1 Thread 2

thread %eax %eax ... %rip %rip

Registers are virtualized by OS; Each thread "thinks" it has own

- Both threads run the above code
- Many possible execution timelines due to concurrency

PROBLEM: NON-DETERMINISM

Concurrency can lead to non-deterministic results

- Different results even with same inputs
- Race conditions

Whether bug manifests depends on CPU schedule!

How write concurrent programs: pretend scheduler is malicious

- Processes/threads can be stopped and resumed at any point
- Processes/threads might execute at different "speeds"

ATOMIC EXECUTION

We want instructions to execute as an uninterruptible group That is, we want them to be atomic

mov 0x123, %eax add %0x1, %eax mov %eax, 0x123

More general: Need mutual exclusion for critical sections if one thread is in critical section C, other threads cannot (okay if other threads do unrelated work)

LOCKS

Goal: Provide mutual exclusion (mutex)

Allocate and Initialize

```
pthread_mutex_t mylock;
pthread_mutex_init(&mylock, NULL);
```

Acquire (or Lock)

- Acquire exclusive access to lock
- Wait if lock is not available (some other process in critical section)
- Spin or block (relinquish CPU) while waiting
- pthread_mutex_lock(&mylock);

Release (or Unlock)

- Release exclusive access to lock; let another process enter critical section
- pthread_mutex_unlock(&mylock);

EXECUTION TIMELINE WITH LOCKING

Thread 1 Thread 2 mutex_lock() mutex_lock() mov 0x9cd4, %eax Thread 2 waits while add %0x1, %eax thread 1 holds the lock mov %eax, 0x9cd4 Time mutex unlock() mov 0x9cd4, %eax Once thread 1 is done, add %0x1, %eax thread 2 can enter the mov %eax, 0x9cd4 critical section mutex_unlock()

OTHER EXAMPLES

Consider multi-threaded applications that do more than incrementing a single integer value

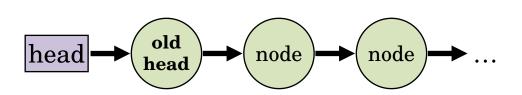
Multi-threaded application with shared linked-list

- All concurrent:
 - Thread A inserting element a
 - Thread B inserting element b
 - Thread C looking up element c

EXAMPLE: SHARED LINKED LIST

```
void list insert(list t *1, int key) {
  typedef struct node t {
                                         node t *new = malloc(sizeof(node t));
      int key;
      struct node t *next;
                                         assert(new);
                                         new->key = key;
  } node t;
                                         new->next = 1->head;
  typedef struct list t {
                                         1->head = new;
      node t *head;
  } list t;
                                     int list lookup(list t *1, int key) {
  void list init(list t *L) {
                                         for(node t *curr = 1->head; curr;
      L->head = NULL;
                                                 curr = curr->next) {
                                             if (curr->key == key) {
                                                 return 1;
What can go wrong?
Find schedule that leads to problem?
                                         return 0;
```

LINKED-LIST RACE



Thread 1

Thread 2

```
new->key = key
new->next = L->head
```

```
new->key = key
new->next = L->head
L->head = new
```

1->head = new

LOCKING LINKED LISTS

```
typedef struct   node t {
                                  void list insert(list t *1, int key) {
                                      node t *new = malloc(sizeof(node t));
    int key;
    struct node t *next;
                                      assert(new);
                                      new->key = key;
} node t;
                                      new->next = 1->head;
typedef struct list t {
                                      1->head = new;
    node t *head;
} list t;
                                  int list lookup(list t *1, int key) {
void list init(list t *1) {
                                      for(node t *curr = 1->head; curr;
    1->head = NULL;
                                               curr = curr->next) {
                                           if (curr->key == key) {
                                               return 1;
How to add locks?
```

return 0;

A SIMPLE THREAD-SAFE LINKED LIST

```
typedef struct   node t {
    int key;
    struct __node_t *next;
} node t;
typedef struct list t {
    node t *head;
    pthread mutex t lock;
} list t;
void list init(list t *1) {
    1->head = NULL;
    pthread mutex init(&1->lock,
        NULL);
```

A SIMPLE THREAD-SAFE LINKED LIST (CONT.)

```
void list_insert(list_t *1, int key) { int list_lookup(list_t *1, int key) {
    pthread mutex lock(1);
                                            pthread mutex lock(1);
                                            for (node t *curr = 1->head;
    node t *new =
        malloc(sizeof(node t));
                                                 curr!=NULL; curr = curr->next) {
    new->key = key;
                                                 if (curr->key == key) {
    new->next = 1->head;
                                                     pthread mutex unlock(1);
    1->head = new;
                                                     return 1;
    pthread mutex unlock(1);
                                            pthread mutex unlock(1);
                                            return 0;
```

What is the impact of critical section size?

SYNCHRONIZATION PRIMITIVES

- OS provides higher-level synchronization primitives
- Rely on hardware features if possible

Motivation: Build them once and get them right

High-Level Userspace API Monitors Locks Semaphores
Condition Variables

Hardware-Specific Implementation

Loads Stores Test&Set

Disable Interrupts

LOCK IMPLEMENTATION GOALS

Correctness

- *Mutual exclusion:* Only one thread in critical section at a time
- *Progress:* If several simultaneous requests, must allow one to proceed

Performance:

- CPU is not used unnecessarily (e.g., no spin-waiting or busy-waiting)
- Fast to acquire lock if no contention with other threads (common case!)

Fairness: Each thread eventually gets a turn

- Wait times are *bounded* (starvation-free)
- Must eventually allow each waiting thread to enter (assuming others eventually exit)

APPROACH 1: DISABLE INTERRUPTS

```
void acquire_lock() {
    disable_interrupts();
}
void release_lock() {
    enable_interrupts();
}
```

Turn off interrupts while in a critical section

- Prevent scheduler from running another thread
- Code between interrupts executes atomically

Problems:

- Only works on systems with a single CPU
- OS yields control to the process
 - What if the process is malicious? What if it runs forever?
- Not fair: process might disable interrupts for a long time

APPROACH 2: USE LOAD AND STORE

```
void acquire_lock(lock_t *1) {
    while (l->flag != 0) {}
    l->flag = 1;
}
void release_lock(lock_t *1) {
    l->flag = 0;
}
```

Approach

- Each lock has a single flag indicating its state
- acquire_lock spins until the lock is available

Does this work? What situation can cause this to not work?

PROBLEMS WITH APPROACH 2

	Thread 1	Thread 2	Thread 3
Time	l->flag = 1;	<pre>while (l->flag != 0) {} section]</pre>	
	<pre>[critical section] l->flag = 0;</pre>		
			while (1->flag != 0) {}
			1->flag = 1;
			[critical section]
			1->flag = 0;

When T1 releases lock, both T2 and T3 acquire it

THE NEED FOR HARDWARE SUPPORT

Software-based solutions exist but do not well on modern hardware

• See "Dekker's and Peterson's Algorithms" in the book

Better: Use a hardware primitive that can load and store atomically

- test_and_set(&val, 1) sets val to 1 and returns previous value
- Also called atomic exchange
- Specific instruction differs depending on CPU-architecture
 - e.g., xchg on x86

APPROACH 3: USE TEST-AND-SET

```
typedef struct lock t {
                                      int test and set(int *var,
   int flag;
                                          int new value) {
} lock t;
                                        int old value = *var;
                                        *var = new value;
void init(lock t *lock) {
                                        return old value;
   lock->flag = 0;
void acquire(lock t *lock) {
   while (test and set(&lock->flag, 1) == 1) {}
void release(lock t *lock) {
   lock->flag = 0;
```

OTHER POSSIBLE HARDWARE INSTRUCTIONS

```
int compare_and_swap(int *val, int cmp, int new)
```

- Set val to new if val==cmp
- Otherwise, does nothing
- Always returns val's previous value

```
int fetch_and_add(int *val)
```

Increments val and returns its previous value

USE SPINNING WITH CAUTION

Consider the following scenario:

- Thread 1 is holding a lock for five time slices
- Ten other threads want to acquire the lock and spin
- The scheduler is Round-Robin with time slice length 10ms

What is the worst-case time spent on spinning? 500ms!

We need to avoid spinning as much as possible! What could we do instead of spinning?

APPROACH 4: YIELD

Idea: Introduce a new system call yield() that voluntarily gives up CPU control

```
void acquire_lock(lock_t *1) {
    while ((test_and_set(&l->flag,1) == 1) {
        yield();
    }
}

void release_lock(lock_t *1) {
    l->flag = 0;
}
```

LOCK IMPLEMENTATION GOALS REVISITED

Yield-based locks (Approach 4)

- Correctness: Yes (only one thread can be in the CS)
- Performance: Better (still too many context switches)
- Fairness: No (scheduler does not know/respect wait order)

APPROACH 5: USE A QUEUE

Intuition: Two-step approach

- First lock a wait-queue and add current thread to it
 - Queue-lock is only held for a very short time
- When calling release(), pick the first thread from queue
- Needs to more system class
 - park() pauses/deschedules the current thread
 - unpark(int thread_id) resumes/schedules the specified thread

APPROACH 5: ACQUIRING LOCKS

```
typedef struct __lock_t {
                              void acquire(lock t *1) {
                                  while(test_and_set(&l->guard,1) == 1)
    int flag;
                                      ; //acquire guard lock by spinning
    int guard;
                                   if (1->flag == 0) {
   queue t *q;
                                      1->flag = 1; // lock is acquired
} lock t;
                                      1->guard = 0;
                                   } else {
void init(lock t *1) {
                                      queue add(l->q, gettid());
    1 \rightarrow flag = 0;
                                      1->guard = 0;
    1->guard = 0;
                                      park();
   queue_init(l->q);
```

APPROACH 5: RELEASING LOCKS

```
void release(lock_t *1) {
typedef struct lock t {
                                  while(test and set(&l->guard,1) == 1)
    int flag;
                                      ; //acquire quard lock by spinning
    int guard;
                                  if (queue empty(1->q)) {
   queue t *q;
                                      // let go of lock; no one wants it
} lock t;
                                      1->flag = 0;
                                  } else {
void init(lock_t *1) {
                                      // hold lock (for next thread!)
    1 \rightarrow flag = 0;
                                      unpark(queue remove(m->q));
    1->guard = 0;
                                      1->guard = 0;
   queue_init(l->q);
```

SUMMARY

- Locks are a fundamental building block for concurrent applications and data structures
- Efficient locking mechanism require hardware and OS support
 - compare_and_swap(), atomic exchange, etc.
 - yield(), park(), etc.