

Rotary Encoder

Overview



This lesson will teach you how to use Rotary Encoder module, which can calculate the number of interrupts.

Specification

Please view "Rotary Encoder.pdf"

Path: \Public_materials\Datasheet\ Rotary Encoder.pdf

Pin definition

Rotary Encoder		UNO
GND	->	GND
+	->	+5v
SW	->	D4
DT	->	D3
CLK	->	D2

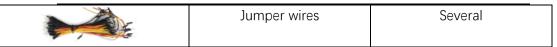
Hardware required

Material diagram	Material name	Number
	Rotary Encoder	1
	LED	2
1113-	10KΩ resistor	2
	USB Cable	1
	UNO R3	1
	Breadboard	1

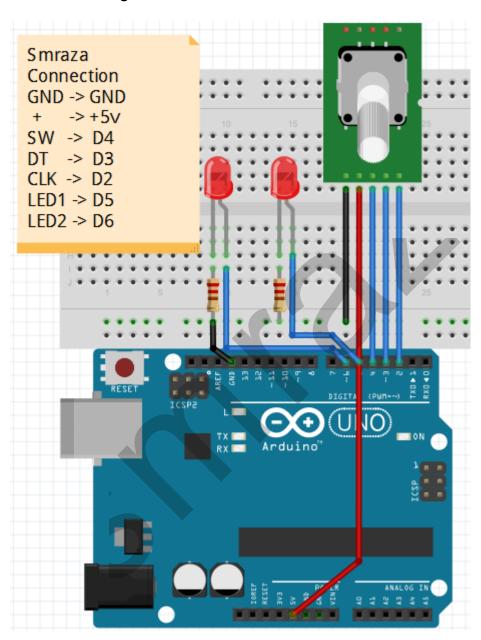
---Designed by Smraza Keen

V1.0





Connection diagram



Sample code

Note: sample code under the **Sample code** folder.

const int interrupt = 0;

int CLK = 2;

int DAT = 3;

int BUTTON = 4;

int LED1 = 5;

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```
V1.0
int LED2 = 6:
int COUNT = 0;
void setup()
{
    attachInterrupt(interrupt, RoteStateChanged, FALLING);
    pinMode(CLK, INPUT);
    digitalWrite(CLK, HIGH); // Pull High Restance
    pinMode(DAT, INPUT);
    digitalWrite(DAT, HIGH); // Pull High Restance
    pinMode(BUTTON, INPUT);
    digitalWrite(BUTTON, HIGH); // Pull High Restance
    pinMode(LED1, OUTPUT);
    pinMode(LED2, OUTPUT);
    Serial.begin(9600);
}
void loop()
  if (!(digitalRead(BUTTON)))
  {
    COUNT = 0;
    Serial.println("STOP COUNT = 0");
    digitalWrite(LED1, LOW);
    digitalWrite(LED2, LOW);
    delay (2000);
  }
  Serial.println(COUNT);
void RoteStateChanged() //When CLK FALLING READ DAT
{
    if (digitalRead(DAT)) // When DAT = HIGH IS FORWARD
      COUNT++;
      digitalWrite(LED1, HIGH);
      digitalWrite(LED2, LOW);
      delay(20);
    }
    else // When DAT = LOW IS BackRote
      COUNT--;
      digitalWrite(LED1, LOW);
      digitalWrite(LED2, HIGH);
      delay(20);
```

}

}

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/*Tips: Open the serial port monitor, you will see the total number of Statistics.

Language reference

Tips: click on the following name to jump to the web page. If you fail to open, use the Adobe reader to open this document. attachlnterrupt

Application effect

When you rotate the encoder, LED lights will be flashing alternately.

