Physics based animation

Grégory Leplâtre

Introduction

Assessmen

References

# Physics based animation Lecture 01 - Introduction

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References

# **Objectives**

Programme of the module

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# Objectives

- ► Programme of the module
- Administration

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References

### **Outline**

- 1 Introduction
  - 2 Assessment
- 3 References

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Introduction

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Animation techniques

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- Animation techniques
  - By hand (keyframe animation)

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- Animation techniques
  - By hand (keyframe animation)
  - Data driven (motion capture)

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References





### Animation techniques

- By hand (keyframe animation)
- Data driven (motion capture)
- Procedural
  - non-physically based
  - physically-based

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References



# Relevant topics

- Rigid/soft bodies
- Particles
- ► Fluids
- Hair
- Cloth

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 Gain experience in physics-based simulation development, particularly the technical aspects (e.g., achieving real-time performance) Assessmer

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### Module aims

- Gain experience in physics-based simulation development, particularly the technical aspects (e.g., achieving real-time performance)
- Examine some of the fundamental techniques used in physics animation development such as the underpinning maths, performance bottlenecks, particles, collisions, constraints, numerical issues

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- Gain experience in physics-based simulation development, particularly the technical aspects (e.g., achieving real-time performance)
- Examine some of the fundamental techniques used in physics animation development such as the underpinning maths, performance bottlenecks, particles, collisions, constraints, numerical issues
- Put together various physics-based simulations

Assessment

Reference:

# **Learning Outcomes**

| Learning Outcomes   | Supported by                          | Assessed by              |
|---|---------------------------------------|--------------------------|
| LO1: Develop insight into the design and implementation process that occurs within modern physics-based animation software development. | Lectures & Practicals                 | Coursework               |
| LO2: Consider the different physics-based techniques.   | Lectures, practi-<br>cals & tutorials | Coursework & class tests |
| LO3: Produce a physics-based simulation utilising a development environment by applying relevant design and development processes.      | Practicals                            | coursework               |
| LO4: Demonstrate a practi-<br>cal understanding of the funda-<br>mental mathematics underpin-<br>ning physics based development         | Tutorials                             | Class tests              |

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# **Timetable**



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#### Lectures:

- physics principles, design, technology, and algorithms
- Practicals:
  - Development of physics-based simulations
  - Clear, computationally fast, elegant code (beyond prints)
  - Use of Visual Studio as a development environment
- Tutorials:
  - Fundamental mathematical principles
  - Three class tests

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- You WILL have to work around 12-13 hours a week on the module:
  - 5 hours contact (lectures, practical, tutorial)
  - 7-8 hours self study
- Coursework will require some organisation outside class time
  - Use the Games Lab, it's what it is there for
- Keep up with practical work! There is one every week
  - We won't be pausing so falling behind at any stage means it will be difficult to catch up

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# Working through practicals

- Run by Sam Serrels (s.serrels@napier.ac.uk)
- Regularly check in your work to BitBucket
- Make videos of your working practical simulations
  - put the course title, simulate on title and your name at the start of the video
- Write modular, readable code
- Experiment

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# Equipment and resources

- Games lab equipped with high-end PCs
  - 8am-9pm weekdays, 9am-5pm week-ends
  - All software you need is there
- JKCC has Visual Studio installed
- Visual Studio available from Dreamspark for home use
- Using your own wired physical controller is an option to be considered

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### Develop a physics-simulation

- Must be buildable on the PCs in the Games Lab
- Can use any control mechanism you like
- Expand on what you learn during the module (e.g., cloth animation control)
- Three parts
  - 1 Pitch presentation (week 5)
  - 2 Design document (week 8)
  - 3 Implementation, report and demonstration (week 14)

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# Report submissions

- Reports have a purpose (technical document)
- Use SIGGRAPH template
- Submit PDF (not docx, txt, bmp, png)
  - Name & Student Number (First Page)
  - Title
  - Page Numbers
  - Sections (Introduction, Overview, Summary)
  - Figures (captions and referenced in text)
  - Tables (captions and referenced in text)
- Naming convention: LastName\_FirstName\_Matric\_ReportName.pdf
- ► See past projects/reports
  http://games.soc.napier.ac.uk/physics.html

Reference

### Class tests

- Mathematics covered in tutorials is assessed in three class tests
  - Week 6: Vectors, matrices, transformations, FK, IK, etc
  - Week 10: Motion, derivatives, Newton's laws, projectile motion, etc
  - Week 13: Energy, momentum and collisions, rotational motion, etc

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- Game Physics Engine Development, by David Bourg (2001)
- ► Game Physics, by David Eberly (2010)
- ➤ Real-Time Collision Detection, by Christer Ericsson (2004)
  - Essential for the collision detection part of the module

### To do this week

- ► Take a look at last year's materials to form a better idea of the contents of the module.
- Take a look at past projects (link from Moodle)
- Bring pen and paper to every class.
- Read Tutorial 1 notes for Wednesday