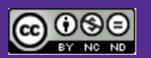


DS-GA 1003 Machine Learning

Week 2: Lecture 2

Model Selection - Classification and Loss Functions





How can we put machine learning into practice?

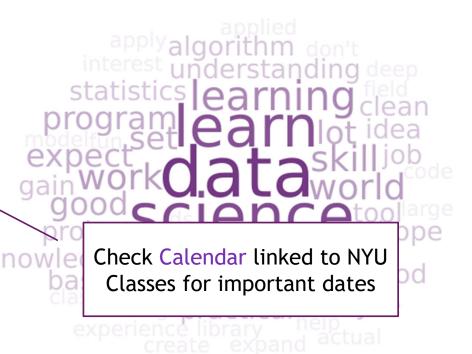
DS-GA 1003 Machine Learning

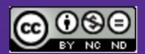
Week 2: Lecture 2

Model Selection - Classification and Loss Functions

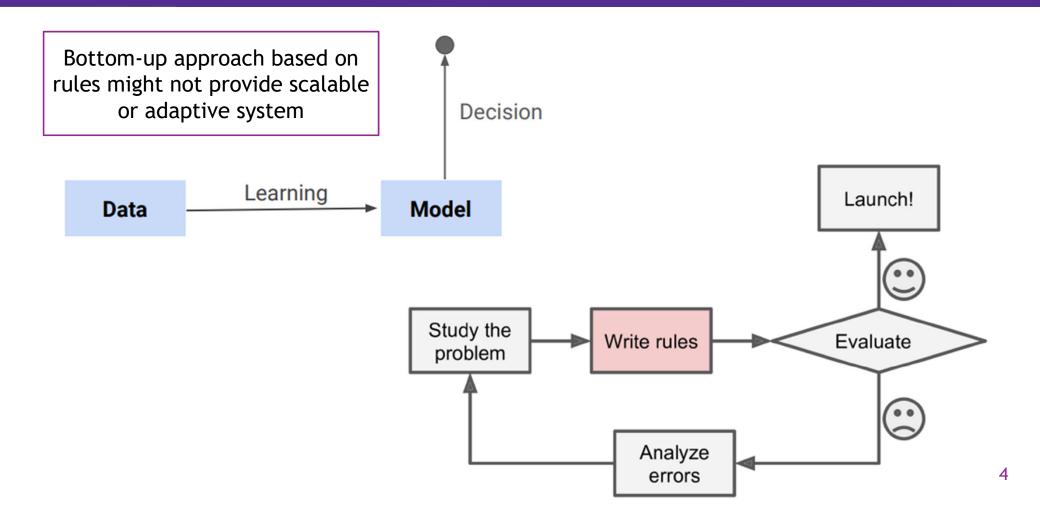
Announcements

- ▶ Please check Week 2 agenda on NYU Classes
 - ► Homework 1
 - ► Survey 1
 - ► Section, Tutoring Session, Office Hours
- Remember to post to Piazza

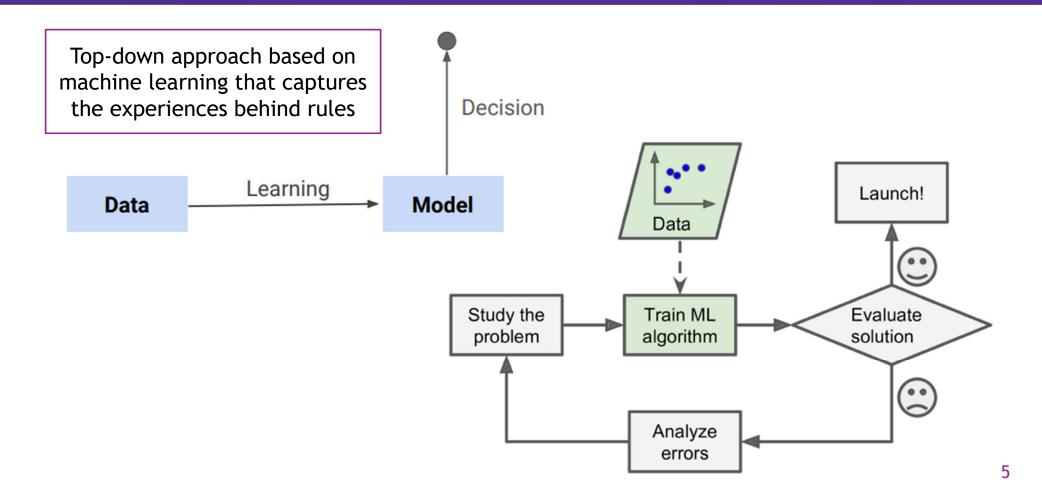




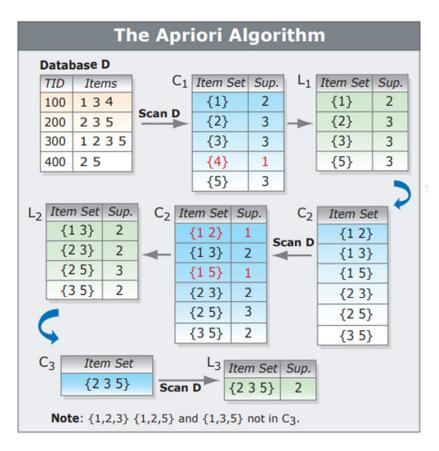
Review: What is machine learning?

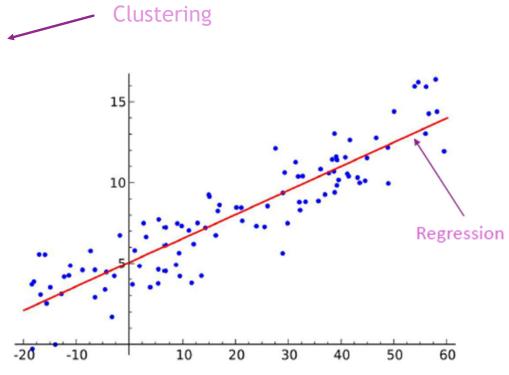


Review: What is machine learning?

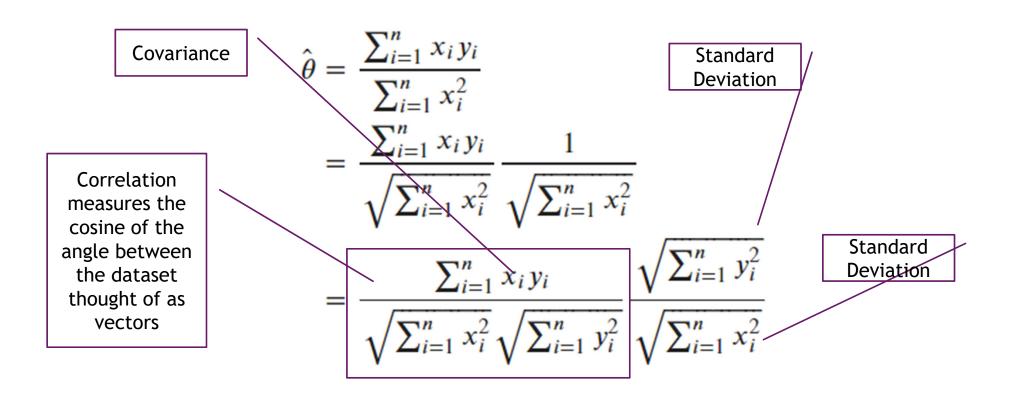


Review: Regression and Clustering





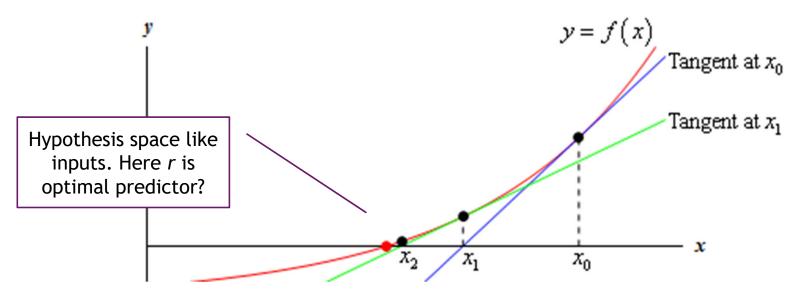
Review: Regression and Clustering



Steps for Machine Learning

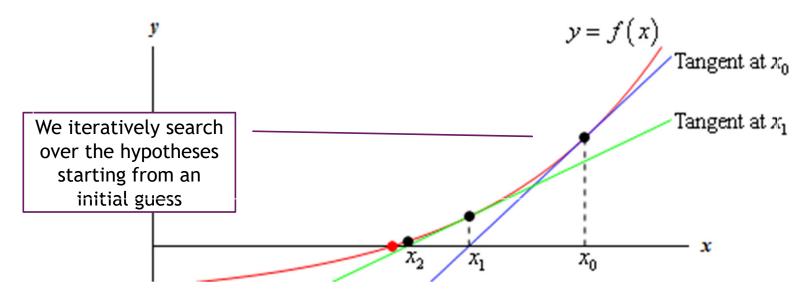
- ► Loss Function l(x)
 - ► Set f(x) = l'(x) derivative
 - Find r such that f(r) = 0





Steps for Machine Learning

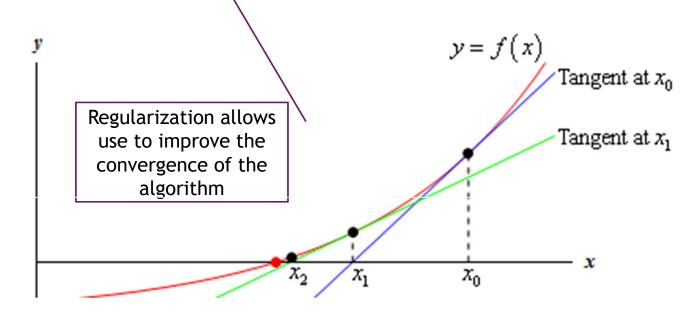
- ▶ Optimization
 - $\blacktriangleright \operatorname{Set} g(x) = x (f(x) / f'(x))$
 - ► Take $x_{t+1} = g(x_t)$





Steps for Machine Learning

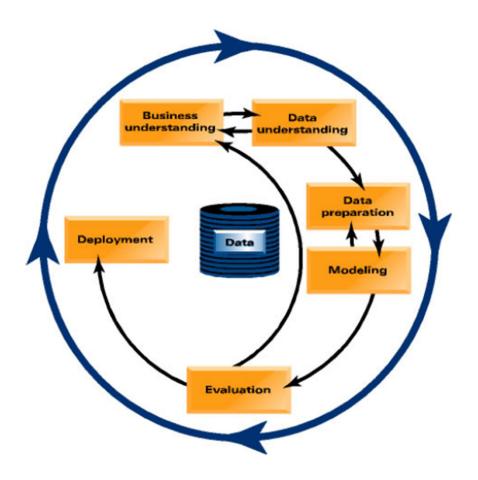
- ► Regularization
 - ightharpoonup Set g(x) = x m (f(x) / f'(x))
 - ► Take $x_{t+1} = g(x_t)$





Agenda

- ► Steps for Machine Learning
 - ► Hypothesis Space
 - **▶** Loss Functions
 - ▶ Optimization
 - ▶ Regularization
- ► Putting Steps into Practice
 - ▶ Data
 - ► Features and Labels
 - ► Experimentation
 - **▶** Evaluation



Data

- **▶** Data
 - **►**Split
 - ► Training set
 - Held out set (sometimes call Validation set)
 - ▶Test set
 - ► Randomly allocate to these three, e.g. 60/20/20

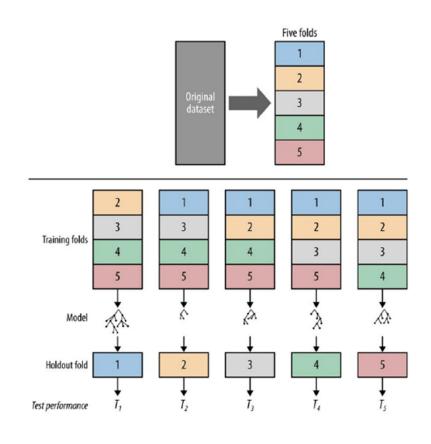
Test Data

Validation Set

Training Data

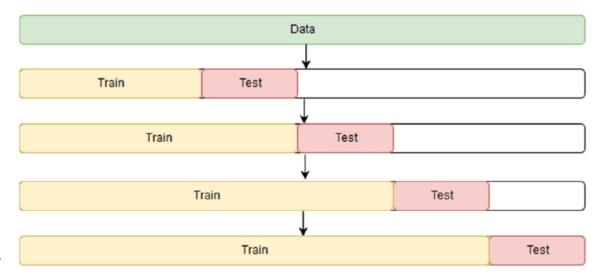
Data

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Data

- **▶** Data
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 - ► Randomly allocate to these three, e.g. 60/20/20



Features and Labels

- ▶ Features
 - Data comes in different forms
 - **►**Text
 - ► Recordings
 - **►** Images
 - ► Translate into features amenable to model
- ▶ Labels
 - ► For supervised learning, we have labels
 - ► Spam or Not Spam



Dear Sir.

First, I must solicit your confidence in this transaction, this is by virture of its nature as being utterly confidencial and top secret. ...



TO BE REMOVED FROM FUTURE MAILINGS, SIMPLY REPLY TO THIS MESSAGE AND PUT "REMOVE" IN THE SUBJECT.

99 MILLION EMAIL ADDRESSES FOR ONLY \$99



Ok, Iknow this is blatantly OT but I'm beginning to go insane. Had an old Dell Dimension XPS sitting in the corner and decided to put it to use, I know it was working pre being stuck in the corner, but when I plugged it in, hit the power nothing happened.

Features and Labels

| | id | subject | email | spam |
|---|----|--|--|------|
| 0 | 0 | Subject: A&L Daily to be auctioned in bankrupt | url: http://boingboing.net/#85534171\n date: n | 0 |
| 1 | 1 | Subject: Wired: "Stronger ties between ISPs an | url: http://scriptingnews.userland.com/backiss | 0 |
| 2 | 2 | Subject: It's just too small | <html>\n <head>\n </head>\n <body>\n <font siz<="" th=""><th>1</th></body></html> | 1 |
| 3 | 3 | Subject: liberal defnitions\n | depends on how much over spending vs. how much | 0 |
| 4 | 4 | Subject: RE: [ILUG] Newbie seeks advice - Suse | hehe sorry but if you hit caps lock twice the | 0 |

Experimentation

Experimentation

- ► Select a hypothesis *f*
 - Usually depends on numbers called parameters
 - ► Fit parameters to model on training set. Compute accuracy of test set.
- ► Tune hyperparameters on validation set
 - Usually arise from regularization
 - ► For example early stopping
- ▶ Data Snooping

| Example | x_1 | x_2 | x_3 | x_4 | y |
|---------|-------|-------|--------|-------|---|
| 1 | 0 | 0 | 1 0 | 0 | 0 |
| 2 | 0 | 1 | 0 | 0 | 0 |
| 3 | 0 | 0 | 1. | 1 | 1 |
| 4 | 1 | 0 | 0 | 1 | 1 |
| 5 | 0 | 1 | 1 | 0 | 0 |
| 6 | 1 | 1 | 0 | 0 | 0 |
| 7 | 0 | 1 | 0 | 1 | 0 |

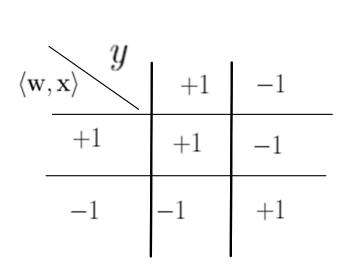
Experimentation

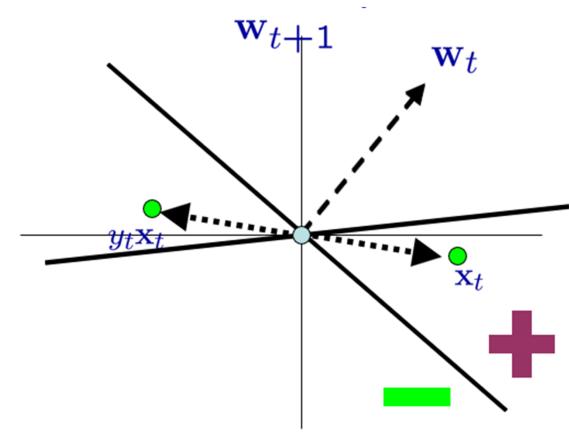
Experimentation

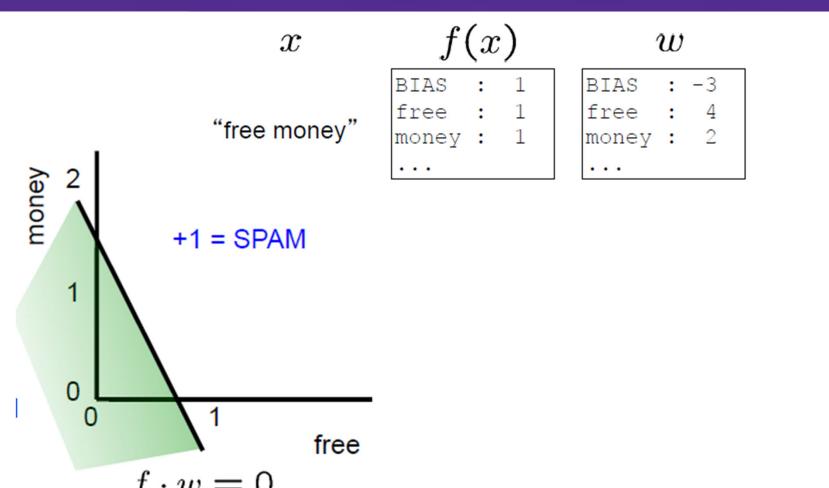
- ► Select a hypothesis *f*
 - Usually depends on numbers called parameters
 - ► Fit parameters to model on training set. Compute accuracy of test set.
- ► Tune hyperparameters on validation set
 - Usually arise from regularization
 - ► For example early stopping
- ▶ Data Snooping

| x_1 | x_2 | x_3 | x_4 | y |
|-------|-------|-------|-------|-------------|
| 0 | 0 | 0 | 0 | ? |
| 0 | 0 | 0 | 1 | ? |
| 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 1 | 1 |
| 0 | 1 | 0 | 0 | 0 |
| 0 | 1 | 0 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 | |
| 1 | 0 | 0 | 0 | ? |
| 1 | 0 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | ? |
| 1 | 0 | 1 | 1 | ? |
| 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 0 | 1 | 0 ? ? |
| 1 | 1 | 1 | 0 | ? |
| 1 | 1 | 1 | 1 | ? |

| Rule | Counterexample | | | |
|--|----------------|--|--|--|
| $\Rightarrow y$ | 1 | | | |
| $x_1 \Rightarrow y$ | 3 | | | |
| $x_2 \Rightarrow y$ | 2 | | | |
| $x_3 \Rightarrow y$ | 1 | | | |
| $x_4 \Rightarrow y$ | 7 | | | |
| $x_1 \wedge x_2 \Rightarrow y$ | 3 | | | |
| $x_1 \wedge x_3 \Rightarrow y$ | 3 | | | |
| $x_1 \wedge x_4 \Rightarrow y$ | 3 | | | |
| $x_2 \wedge x_3 \Rightarrow y$ | 3 | | | |
| $x_2 \wedge x_4 \Rightarrow y$ | 3 | | | |
| $x_3 \wedge x_4 \Rightarrow y$ | 4 | | | |
| $x_1 \wedge x_2 \wedge x_3 \Rightarrow y$ | 3 | | | |
| $x_1 \wedge x_2 \wedge x_4 \Rightarrow y$ | 3 | | | |
| $x_1 \wedge x_3 \wedge x_4 \Rightarrow y$ | 3 | | | |
| $x_2 \wedge x_3 \wedge x_4 \Rightarrow y$ | 3 | | | |
| $x_1 \wedge x_2 \wedge x_3 \wedge x_4 \Rightarrow y$ | 3 | | | |
| | | | | |







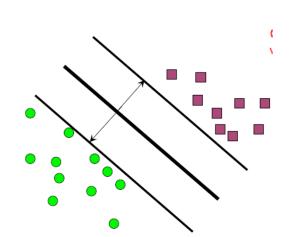
$$sign (\langle \mathbf{w}, \mathbf{f}(x) \rangle - threshold) = \begin{cases} 1 & then spam \\ -1 & then not spam \end{cases}$$

► Step 2 (Combine)

$$f_{N+1}(x) \equiv 1$$

$$w_{N+1} = -$$
threshold

Step 3 (Output)
$$\operatorname{sign}(\langle \mathbf{w}, \mathbf{f}(x) \rangle) = \begin{cases} 1 & \text{then spam} \\ -1 & \text{then not spam} \end{cases}$$



```
input: A training set (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)

initialize: \mathbf{w}^{(1)} = (0, \dots, 0)

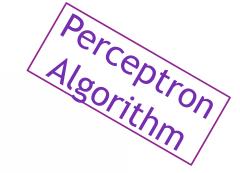
for t = 1, 2, \dots

if (\exists i \text{ s.t. } y_i \langle \mathbf{w}^{(t)}, \mathbf{x}_i \rangle \leq 0) then

\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + y_i \mathbf{x}_i

else

output \mathbf{w}^{(t)}
```



input: A training set $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)$ initialize: $\mathbf{w}^{(1)} = (0, \dots, 0)$ for $t = 1, 2, \dots$ if $(\exists i \text{ s.t. } y_i \langle \mathbf{w}^{(t)}, \mathbf{x}_i \rangle \leq 0)$ then $\mathbf{w}^{(t+1)} = \mathbf{w}^{(t)} + y_i \mathbf{x}_i$ else

output $\mathbf{w}^{(t)}$

Perceptron Algorithm

$$y \langle w_t, x \rangle$$
$$y \langle w_{t+1}, x \rangle = y \langle w_t, x \rangle + ||x||^2$$

Exercise

Fix x (vector), w (vector) and b (number). Assume absolute value of w is 1. Determine v that minimizes

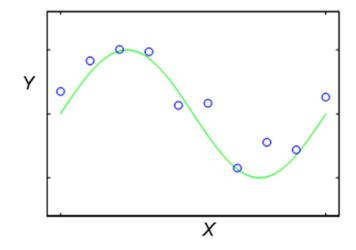
$$\min\{\|\mathbf{x} - \mathbf{v}\| : \langle \mathbf{w}, \mathbf{v} \rangle + b = 0\}$$

Hint: Consider

$$\mathbf{v} = \mathbf{x} - (\langle \mathbf{w}, \mathbf{x} \rangle + b)\mathbf{w}$$

Tuning Hyperparameters

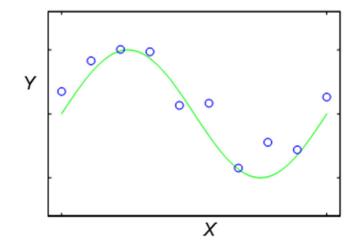
Dataset: 10 (X,Y) points generated from a sin function, with noise

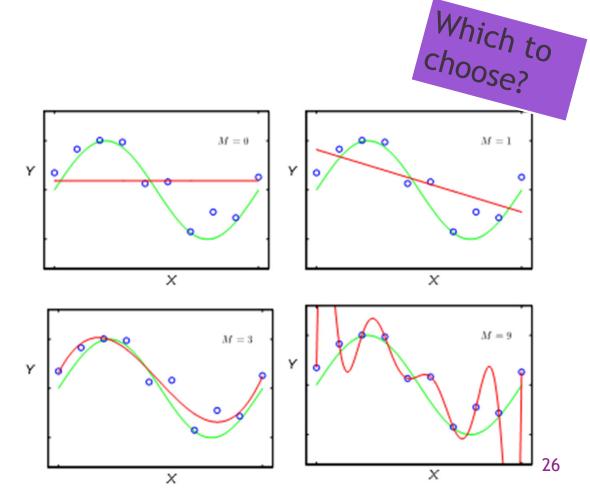


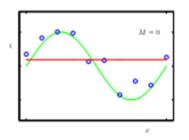
Think about the nonlinear transformation that allowed us to model an inverse relationship between mpg and horsepower using linear regression

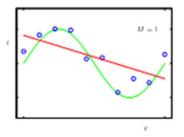
Tuning Hyperparameters

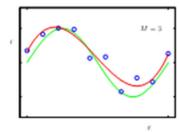
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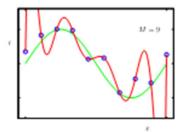












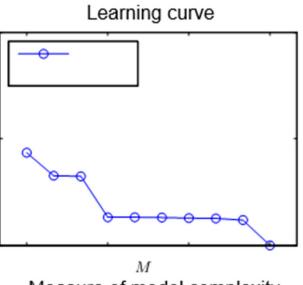
We measure error using a loss function $L(y, \hat{y})$

For regression, a common choice is squared loss:

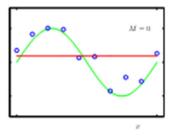
$$L(y_i, f(x_i)) = (y_i - f(x_i))^2$$
 Squared error

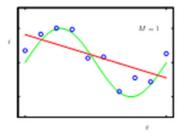
The *empirical loss* of the function *f* applied to the training data is then:

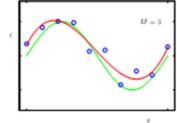
$$\frac{1}{N} \sum_{i=1}^{N} L(y_i, f(x_i)) = \frac{1}{N} \sum_{i=1}^{N} (y_i - f(x_i))^2$$

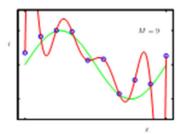


Measure of model complexity









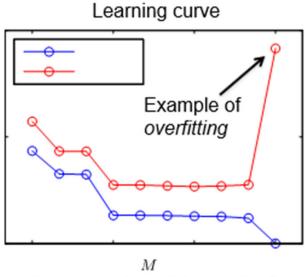
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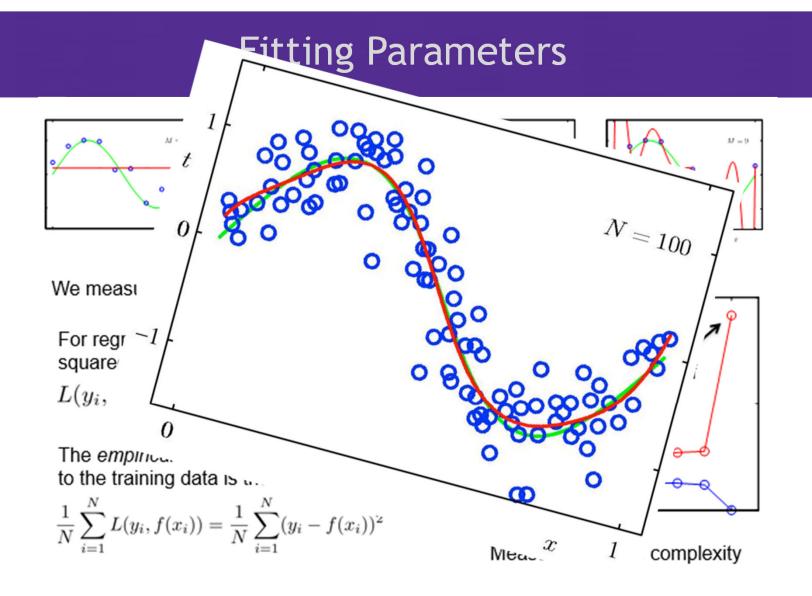
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 Squared error

The *empirical loss* of the function *f* applied to the training data is then:

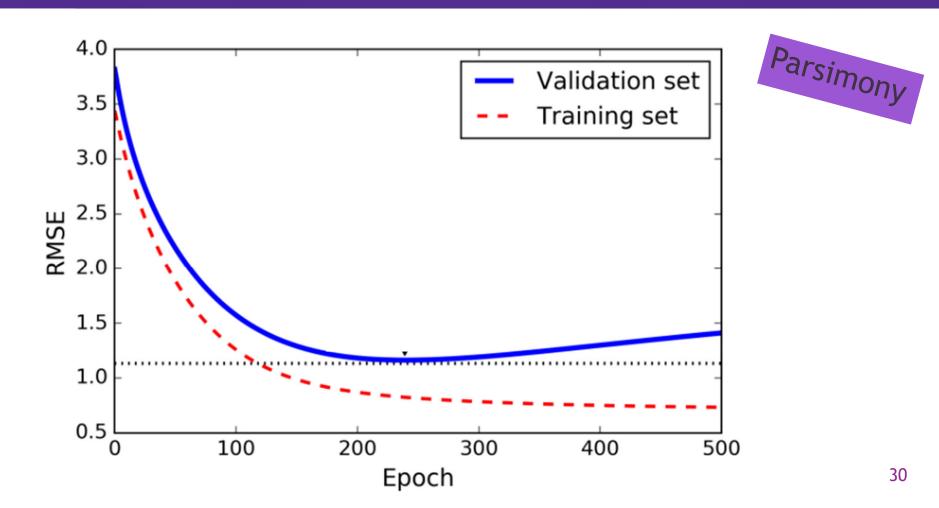
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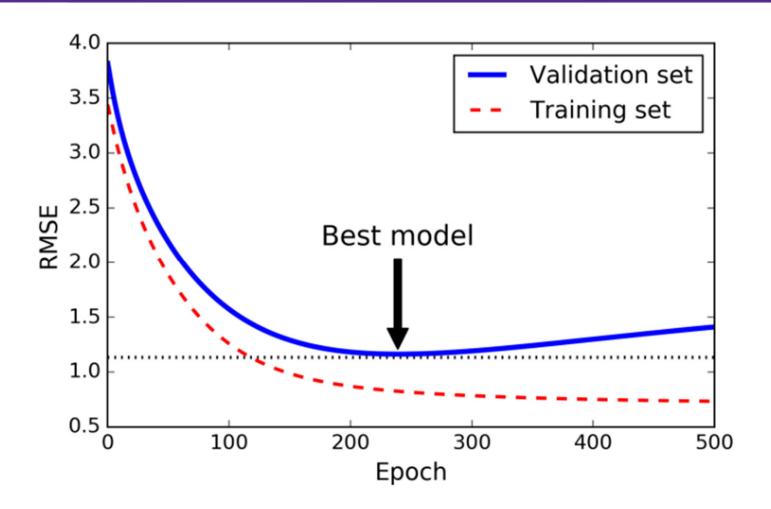
Measure of model complexity



Regularization



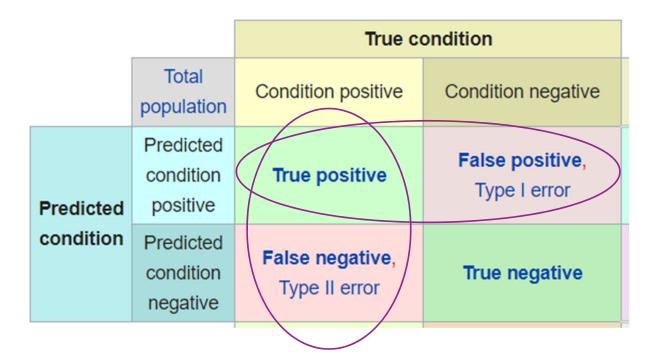
Regularization



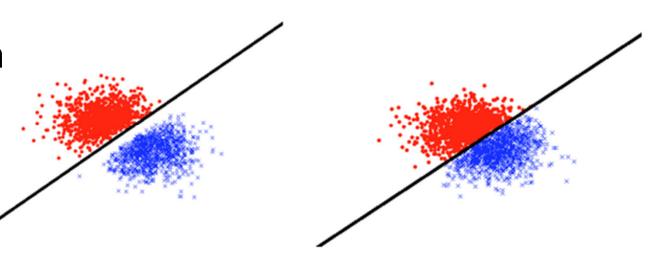
Evaluation

► Evaluation

- Metrics measure the accuracy according to different criteria
- Often accuracy refers to fraction of instances predicted correctly
 - ▶0-1 loss function



- ▶ Advantages
 - ▶Error Bound
 - ► Online Algorithm
- ▶ Disadvantages
 - Many Decision Boundaries
 - ▶Overfitting
 - ► Separable Data



- Advantages
 - ► Error Bound
 - ► Online Algorithm
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```
1 \mathbf{w}_1 \leftarrow \mathbf{w}_0 > typically \mathbf{w}_0 = \mathbf{0}

2 \mathbf{for} \ t \leftarrow 1 \ \mathbf{to} \ T \ \mathbf{do}

3 \mathbf{RECEIVE}(\mathbf{x}_t)

4 \widehat{y}_t \leftarrow \mathrm{sgn}(\mathbf{w}_t \cdot \mathbf{x}_t)

5 \mathbf{RECEIVE}(y_t)

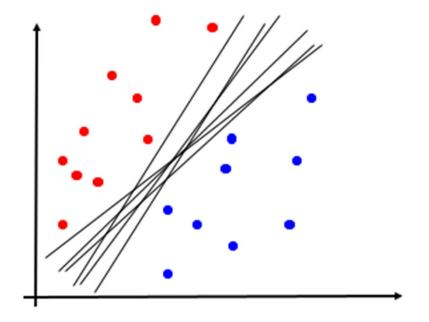
6 \mathbf{if} \ (\widehat{y}_t \neq y_t) \ \mathbf{then}

7 \mathbf{w}_{t+1} \leftarrow \mathbf{w}_t + y_t \mathbf{x}_t > more generally \eta y_t \mathbf{x}_t, \eta > 0.

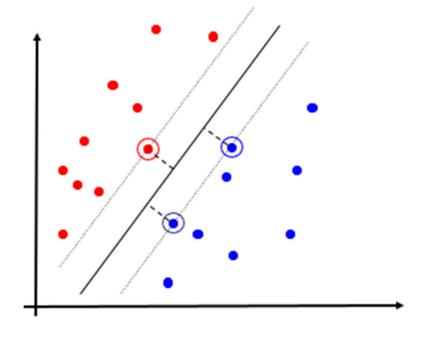
8 \mathbf{else} \ \mathbf{w}_{t+1} \leftarrow \mathbf{w}_t

9 \mathbf{return} \ \mathbf{w}_{T+1}
```

- ▶ Advantages
 - ▶Error Bound
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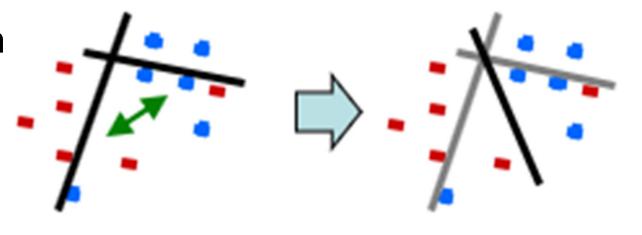
- ▶ Advantages
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- ▶ Advantages
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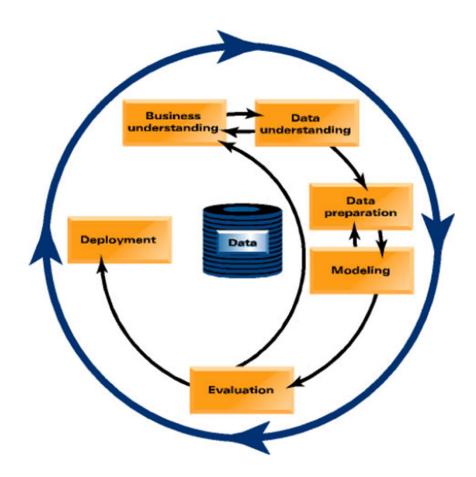


- ▶ Advantages
 - **Error Bound**
 - ► Online Algorithm
- ▶ Disadvantages
 - Many Decision Boundaries
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 - ► Separable Data



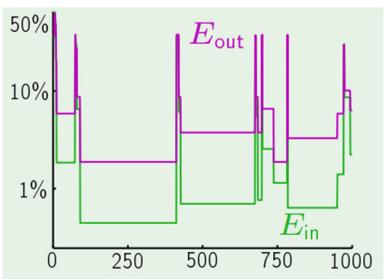
Summary

- ► Steps for Machine Learning
 - ► Hypothesis Space
 - **▶** Loss Functions
 - ▶ Optimization
 - ► Regularization
- ▶ Putting Steps into Practice
 - ▶ Data
 - ► Features and Labels
 - ► Experimentation
 - **▶** Evaluation



Questions

- ▶ Questions on Piazza?
- ▶ Question for You!
 - ► Can you think of another way to use Perceptron for nonseparable data







Questions

Pocket Algorithm

- ▶ Questions on Piazza?
- ▶ Question for You!
 - ► Can you think of another way to use Perceptron for nonseparable data

