

Intro to Interactive Systems

LEAPS Computing Course

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Introductions

- **Lecturer:** Teun Krikke
- **Teaching Assistant:**
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- **Coordinator:** Frank Broz



Today

- Overview of the course
- Form lab groups
 - Work in groups of 3
- Setup
 - Accounts, devices, etc
- Exercises
 - Intro to the robots and their software

Interactive Systems

- From interfaces...

User

Not just text
and buttons!



Other People

Share and communicate

Environment

Sense your surroundings

Information

Retrieve, Visualize,
Manipulate, Create

Cozmo robot

- Used for programming exercises
 - Python SDK
- Documentation and forums online
<https://developer.anki.com/>



Course Content: Programming

- Intro to OOP concepts in Python
 - Classes and inheritance
 - Methods
 - Variables and operators
 - Loops and conditionals
- Working with APIs
- Basics of software design
- Debugging

- Figure 1 displays the Cozmo 3D visualization and camera view. The left panel shows the Cozmo robot in a 3D environment, positioned on a green grid floor. The right panel shows the Cozmo camera view, which includes a list of sensor data (Pose, Rot, Acc, Gyro, Mobile) and three bounding boxes labeled 'Lightcube 1 id:2', 'Lightcube 2 id:1', and 'Lightcube 3 id:3'.

Course Content: Assessment

- Quiz on python programming
 - Weeks 3 and 6
 - Assessed individually
- Presentations in Week 7
 - On your project implementation
 - Assessed by group

Course Content: Project

- Robot competition!
 - Group programming project
 - Program your group's robot to collect more cubes than its opponent
- Week 7: Class championships



Questions?