# **Machine Problem 2**

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## **Color Transformations**

The goal of the machine problem is to apply the concepts of color transformations, specifically using histogram equalization and gamma correction techniques. You are to submit two files for this activity: (1) a Jupyter notebook containing the solutions to the action items. Ensure you provide comments, discussions, and proper section divisions for your code. Please also include your answer to the Guide Questions in the Jupyter Notebook; (2) a PDF version of your Jupyter Notebook. You can provide a link to your submission resources or a zip file. The instructor will run it on their local machine, so make sure the codes and files are accessible and functional.

```
In [1]: import os
    import cv2 as cv
    import numpy as np
    import matplotlib.pyplot as plt
    import random
```

## 1. Information Extraction

## 1a. Reshape Images

Given the image dataset, reshape the images to (100,100,3).

## 1b. Saving resized images

Save the transformed images as JPEG files in a separate directory.

```
input_directory = '../media/dataset2'
output_directory = 'dataset2_resized'

if not os.path.exists(output_directory):
    os.makedirs(output_directory)

# Reshape images to (100, 100, 3)
for filename in os.listdir(input_directory):
    if filename.endswith('.png') or filename.endswith('.jpg'):
        img_path = os.path.join(input_directory, filename)
        img = cv.imread(img_path)

# Resize the image to 100x100 pixels
    img_resized = cv.resize(img, (100, 100))

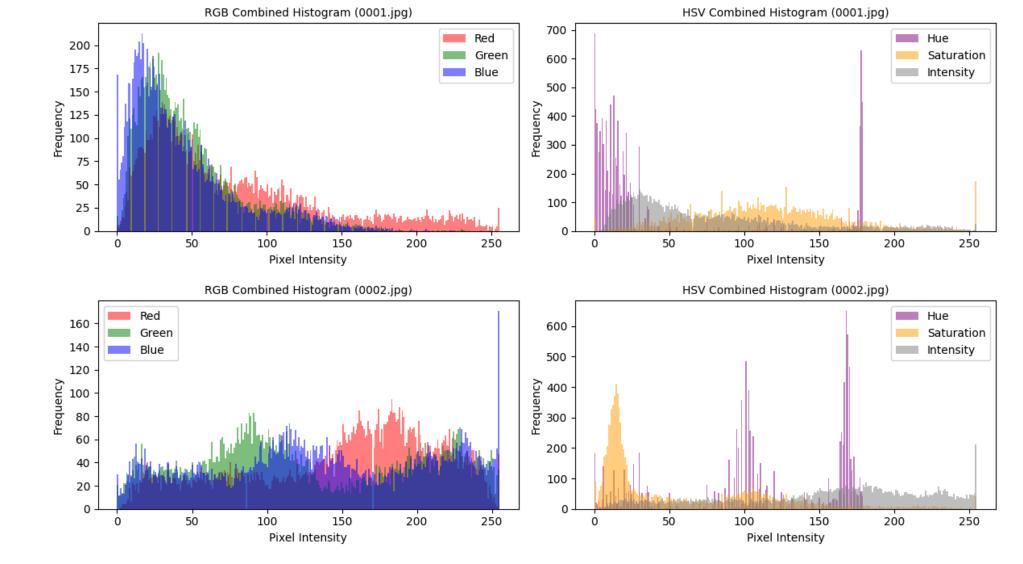
# Save the resized image as JPEG in a separate directory
```

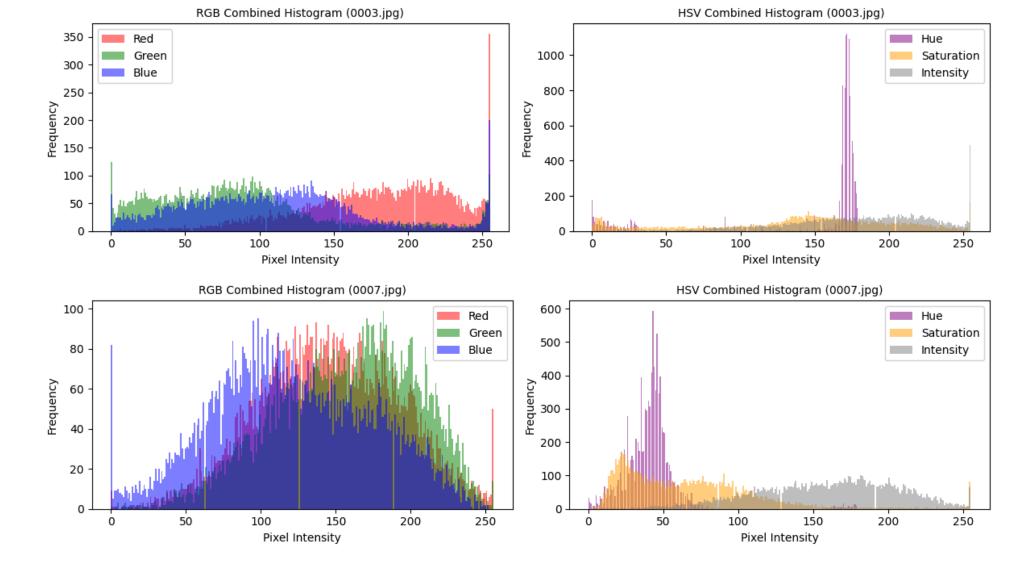
```
output_filename = os.path.join(output_directory, filename)
cv.imwrite(output_filename, img_resized)
```

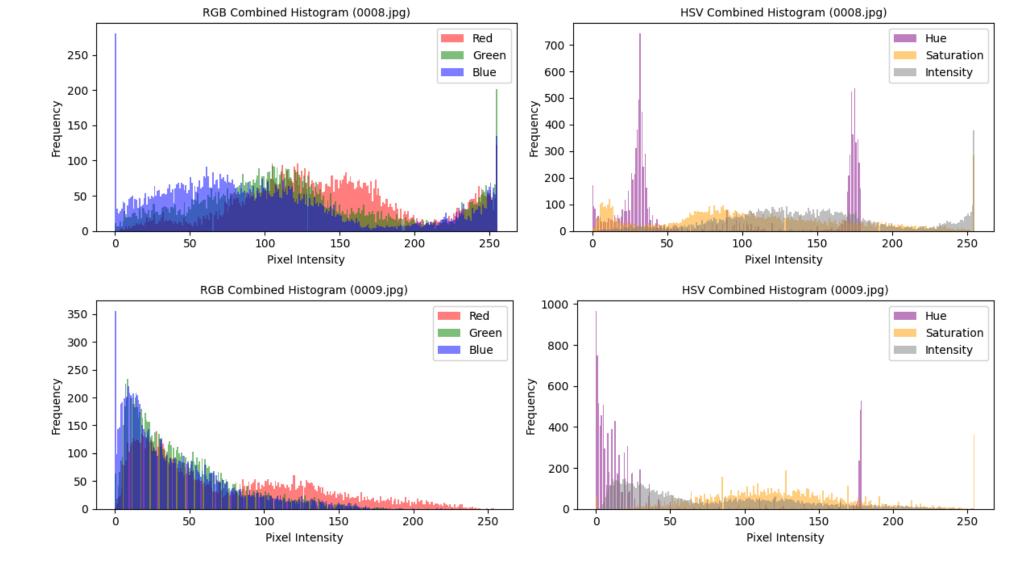
## 1c. Color Channels Histogram

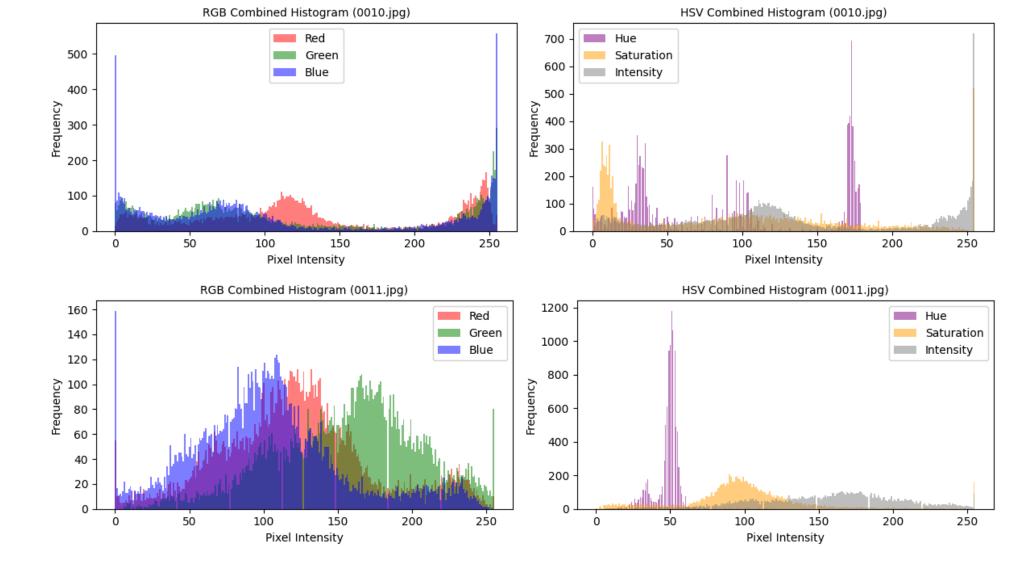
Create a histogram for the following channels: Reds, Greens, Blues, Hues, Saturations, Intensities

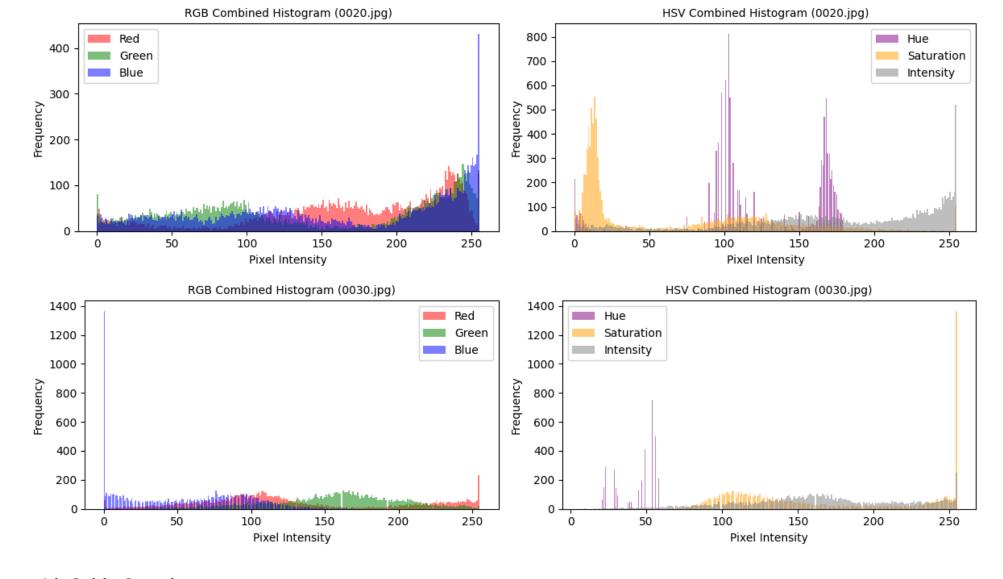
```
In [3]: def plot combined histograms(img, img name):
            # Split the channels for RGB
            b_channel, g_channel, r_channel = cv.split(img)
            # Convert the image to HSV for Hue, Saturation, and Intensity
            hsv img = cv.cvtColor(img, cv.COLOR BGR2HSV)
            h_channel, s_channel, v_channel = cv.split(hsv_img)
            # Create a figure with two subplots side by side for each image
            fig, axes = plt.subplots(1, 2, figsize=(12, 3.5)) # 1 row, 2 columns (side by side histograms)
            # Plot combined RGB histograms
            axes[0].hist(r_channel.ravel(), bins=256, color='red', alpha=0.5, label='Red')
            axes[0].hist(g_channel.ravel(), bins=256, color='green', alpha=0.5, label='Green')
            axes[0].hist(b channel.ravel(), bins=256, color='blue', alpha=0.5, label='Blue')
            axes[0].set title(f'RGB Combined Histogram ({img name})',fontsize=10)
            axes[0].set_xlabel('Pixel Intensity')
            axes[0].set ylabel('Frequency')
            axes[0].legend()
            r channel.ravel()
            # Plot combined HSV histograms
            axes[1].hist(h_channel.ravel(), bins=256, color='purple', alpha=0.5, label='Hue')
            axes[1].hist(s channel.ravel(), bins=256, color='orange', alpha=0.5, label='Saturation')
            axes[1].hist(v channel.ravel(), bins=256, color='gray', alpha=0.5, label='Intensity')
            axes[1].set_title(f'HSV Combined Histogram ({img_name})', fontsize=10)
            axes[1].set xlabel('Pixel Intensity')
            axes[1].set ylabel('Frequency')
            axes[1].legend()
            # Adjust Layout
            plt.tight_layout()
            plt.show()
In [4]: for filename in os.listdir(output directory):
            if filename.endswith('.jpg'):
                img_path = os.path.join(output_directory, filename)
                img = cv.imread(img path)
                plot_combined_histograms(img, filename)
```











## 1d. Guide Questions

#### 1. In the RGB space, which channel is most likely to be observed for all images?

Blue is the channel most frequently observed across all the images. In almost all of the RGB histograms, the blue channel has a strong peak near 0 intensity (darker values) and another significant peak near 255 (brighter values), indicating its dominance.

#### 2. In the HSV space, which top three hues are most likely to be observed for all images?

The top three most observed hues across the images, based on the histograms for hue, appear to be concentrated around:

- 0 to 50 (Reddish tones)
- 100 to 150 (Greenish to yellowish tones)

• 150 to 200 (Bluish tones)

# 2. Data Cleaning

Develop a function that attains the following activities:

- Remove all images that are taken during the night.
- Remove all images that are not pink flowers.

```
In [5]: # Function to display an image
def display_image(image, title="Image"):
    img_rgb = cv.cvtColor(image, cv.COLOR_BGR2RGB)
    plt.imshow(img_rgb)
    plt.title(title)
    plt.axis('off')
    plt.show()
```

## 2a. Removing images taken during the night

```
In [6]: input directory = 'dataset2 resized'
        output_directory = 'non_night_images'
        def is_night_image(image, dark_pixel_percentage_threshold=0.5):
            # Convert the image to grayscale to analyze pixel values
            gray_image = cv.cvtColor(image, cv.COLOR_BGR2GRAY)
            # Compute the histogram
            histogram, _ = np.histogram(gray_image, bins=256, range=(0, 256))
            # Calculate the total number of pixels
            total pixels = gray image.size
            # Calculate the number of dark pixels (e.g., pixel value < 50)
            dark_pixel_count = np.sum(histogram[:50]) # Sum the counts of dark pixels
            dark_pixel_percentage = dark_pixel_count / total_pixels
            # Determine if the image is taken at night
            return dark_pixel_percentage > dark_pixel_percentage_threshold
        def save non night images(input directory, output directory):
            # Create the output directory if it doesn't exist
            if not os.path.exists(output directory):
                os.makedirs(output directory)
            for filename in os.listdir(input_directory):
                if filename.endswith('.jpg'):
                    img path = os.path.join(input directory, filename)
                    img = cv.imread(img_path)
```

```
if img is None:
    print(f"Error: Unable to load {img_path}")
    continue

# Check if the image is taken during the night
if not is_night_image(img):
    output_path = os.path.join(output_directory, filename)
    cv.imwrite(output_path, img) # Save the non-night image
else:
    print(f"Skipping night image: {filename}")
    display_image(img)

save_non_night_images(input_directory, output_directory)
```

Skipping night image: 0001.jpg

#### lmage



Skipping night image: 0009.jpg

#### lmage



## 2b. Removing images of non-pink flowers

```
In [7]: input_directory = 'dataset2_resized'
        output_directory = 'pink_flower_images'
        def is_pink_flower(image, lower_hue=160, upper_hue=180, saturation_threshold=50, value_threshold=50):
            # Convert the image to HSV color space
            hsv_image = cv.cvtColor(image, cv.COLOR_BGR2HSV)
            # Create a mask for pink color (using defined HSV range)
            lower_color = np.array([lower_hue, saturation_threshold, value_threshold])
            upper color = np.array([upper hue, 255, 255])
            # Generate mask
            mask = cv.inRange(hsv_image, lower_color, upper_color)
            # Calculate the percentage of pink pixels
            pink_pixel_count = np.sum(mask > 0)
            total_pixel_count = mask.size # Total number of pixels
            # Calculate the percentage of pink pixels in the image
            pink pixel percentage = pink pixel count / total pixel count
            return pink_pixel_percentage > 0.1 # Adjust the threshold as needed
        # Function to save pink flower images and display non-pink images
        def save_pink_flower_images(input_directory, output_directory):
```

```
# Create the output directory if it doesn't exist
    if not os.path.exists(output_directory):
        os.makedirs(output directory)
   for filename in os.listdir(input_directory):
        if filename.endswith('.jpg'):
            img_path = os.path.join(input_directory, filename)
            img = cv.imread(img_path)
            if img is None:
                print(f"Error: Unable to load {img_path}")
                continue
            # Check if the image contains pink flowers
            if is_pink_flower(img):
                output_path = os.path.join(output_directory, filename)
                cv.imwrite(output_path, img) # Save the pink flower image
            else:
                print(f"Displaying non-pink flower image: {filename}")
                display_image(img, title=f"Non-Pink Image: {filename}")
save_pink_flower_images(input_directory, output_directory)
```

Displaying non-pink flower image: 0007.jpg





Displaying non-pink flower image: 0011.jpg

Non-Pink Image: 0011.jpg



Displaying non-pink flower image: 0030.jpg



2c. Guide Questions

#### 1. What mathematical or statistical bases have you considered when developing your function?

The functions for detecting night images and removing non-pink flower images utilize several mathematical and statistical concepts centered around histogram and color space analysis. The night image detection function constructs a histogram of pixel intensity values from the grayscale version of an image, allowing for the quantification of dark pixels by summing those below a specified threshold (e.g., 50). The dark pixel percentage is calculated by dividing the dark pixel count by the total number of pixels, which is then compared against a user-defined threshold (e.g., dark\_pixel\_percentage\_threshold) to classify the image as night or non-night. In contrast, the function for removing non-pink flower images converts images from BGR to HSV color space to isolate specific colors more intuitively. It generates a mask based on defined lower and upper hue thresholds to capture pixels within the pink color range, calculating the percentage of pink pixels by dividing the count of pink pixels by the total pixel count. This percentage is then compared against a predetermined threshold (e.g., 10%) to determine whether the image contains a sufficient proportion of pink flowers. By applying these techniques, both functions effectively filter images based on pixel intensity distributions and color content, ensuring that only relevant images are retained for further use.

#### 2. What are the challenges in re-orienting the images in this action item?

Re-orienting images poses several challenges, primarily related to orientation detection and processing consistency. Accurately determining an image's orientation can be complex, as different images may have varying degrees of rotation or tilt, necessitating robust algorithms. Reliance on EXIF metadata for orientation can be problematic if it's missing or incorrect, and maintaining or updating this metadata during rotation is essential. Consistency in processing is crucial, as variability in image sources can lead to inconsistencies in output. Additionally, rotating images may introduce artifacts that affect quality, particularly in high-fidelity applications. Performance considerations are also significant for large datasets, requiring efficient algorithms to avoid delays. Edge cases, such as abstract images with minimal distinct features, can complicate detection, and complex backgrounds may hinder accurate orientation. Addressing these challenges requires a combination of advanced algorithms, careful metadata handling, and a focus on maintaining quality and efficiency.

#### 3. What can you suggest for automating such a task?

To automate the tasks of re-orienting images and filtering out non-pink flower images while detecting night images, a structured approach can be taken. First, leveraging image processing libraries like OpenCV or PIL is essential for efficient image manipulation. Developing algorithms that detect image orientation using feature detection methods or machine learning models trained on specific datasets can enhance accuracy.

For efficiency, implementing batch processing to handle multiple images simultaneously will significantly speed up the workflow. Additionally, creating scripts to read and update EXIF metadata ensures that orientation information remains accurate. Utilizing parallel processing frameworks can further improve performance, especially when dealing with large volumes of images.

Incorporating a calibration phase allows for fine-tuning parameters related to detecting pink flowers and dark pixels, which is crucial for achieving reliable results. Including logging will help monitor the process, while establishing a user feedback loop can validate any necessary orientation corrections.

Then, integrating the automation into a larger data processing pipeline using tools like Apache Airflow can enhance workflow management. Implementing automated quality control checks will also ensure the accuracy of the outputs. Combining these strategies will lead to a more efficient and effective image processing system.

## 3. Data Enhancement

From the cleaned dataset, develop and apply a function that:

• Adjusts the exposure of the images based on the brightest image. (Hint: You may manually select the representative image and apply Gamma Correction)

• Adjusts the saturation of the images to match the saturation of the most saturated image. (Hint: You may manually select the representative image and apply Histogram Equalization and Channel Arithmetic)

## 3a. Adjust exposure

```
In [8]: def find brightest image(output directory):
            brightest image name = None
            max brightness = -1 # initialize
            for filename in os.listdir(output_directory):
                if filename.endswith('.jpg'):
                    img_path = os.path.join(output_directory, filename)
                    img = cv.imread(img path)
                    # calculate average brightness
                    gray_image = cv.cvtColor(img, cv.COLOR_BGR2GRAY)
                    brightness = np.mean(gray_image)
                    # update when found
                    if brightness > max brightness:
                        max brightness = brightness
                        brightest_image_name = filename
            return brightest image name
        def adjust exposure(output directory):
            bright image name = find brightest image(output directory)
            bright image path = os.path.join(output directory, bright image name)
            # calculate average brightness
            bright_image = cv.imread(bright_image_path)
            bright gray = cv.cvtColor(bright image, cv.COLOR BGR2GRAY)
            bright brightness = np.mean(bright gray)
            target_brightness = bright_brightness
            # adjust exposure based on the brightest image
            for filename in os.listdir(output directory):
                if filename.endswith('.jpg'):
                    img_path = os.path.join(output_directory, filename)
                    img = cv.imread(img_path)
                    # calculate the brightness and gamma of each image
                    gray image = cv.cvtColor(img, cv.COLOR BGR2GRAY)
                    current_brightness = np.mean(gray_image)
                    gamma = current_brightness / target_brightness
                    # clamp the gamma value to avoid over-darkening or over-brightening
                    gamma = max(0.5, min(gamma, 2.0))
```

```
# gamma correction
inv_gamma = 1.0 / gamma
table = np.array([((i / 255.0) ** inv_gamma) * 255 for i in np.arange(0, 256)]).astype("uint8")
adjusted_image = cv.LUT(img, table)

# display
print(f"Displaying image: {filename}")
display_image(adjusted_image, title=f"Adjusted Image: {filename}")

adjust_exposure(output_directory)
```

Displaying image: 0001.jpg

Adjusted Image: 0001.jpg



Displaying image: 0002.jpg

Adjusted Image: 0002.jpg



Displaying image: 0003.jpg

Adjusted Image: 0003.jpg



Displaying image: 0008.jpg

Adjusted Image: 0008.jpg



Displaying image: 0009.jpg





Displaying image: 0010.jpg

Adjusted Image: 0010.jpg



Displaying image: 0020.jpg

Adjusted Image: 0020.jpg



3b. Adjust saturation

```
In [9]: def adjust saturation(output directory):
            most saturated image name = find most saturated image(output directory)
            most saturated image path = os.path.join(output directory, most saturated image name)
            # calculate average saturation
            most saturated image = cv.imread(most saturated image path)
            hsv image = cv.cvtColor(most saturated image, cv.COLOR BGR2HSV)
            most_saturated_value = np.mean(hsv_image[:, :, 1])
            target saturation = most saturated value
            for filename in os.listdir(output directory):
                if filename.endswith('.jpg'):
                    img path = os.path.join(output directory, filename)
                    img = cv.imread(img path)
                    hsv img = cv.cvtColor(img, cv.COLOR BGR2HSV)
                    current_saturation = np.mean(hsv_img[:, :, 1])
                    scaling factor = target saturation / current saturation
                    # adjust the saturation by multiplying the scaling factor
                    hsv_img[:, :, 1] = np.clip(hsv_img[:, :, 1] * scaling_factor, 0, 255)
                    # apply histogram equalization to enhance saturation contrast
                    hsv_img[:, :, 1] = cv.equalizeHist(hsv_img[:, :, 1])
                    # convert back after saturation adjustment
                    adjusted_img = cv.cvtColor(hsv_img, cv.COLOR_HSV2BGR)
                    print(f"Displaying image: {filename}")
                    display image(adjusted img, title=f"Adjusted Image: {filename}")
        def find most saturated image(output directory):
            most_saturated_image_name = None
            max_saturation = -1 # initialize
            for filename in os.listdir(output directory):
                if filename.endswith('.jpg'):
                    img path = os.path.join(output directory, filename)
                    img = cv.imread(img path)
                    # convert image to HSV and calculate average saturation
                    hsv img = cv.cvtColor(img, cv.COLOR BGR2HSV)
                    avg_saturation = np.mean(hsv_img[:, :, 1])
                    # update when most saturated is found
                    if avg saturation > max saturation:
                        max_saturation = avg_saturation
                        most saturated image name = filename
            return most saturated image name
```

adjust\_saturation(output\_directory)

Displaying image: 0001.jpg

Adjusted Image: 0001.jpg



Displaying image: 0002.jpg

Adjusted Image: 0002.jpg



Displaying image: 0003.jpg





Displaying image: 0008.jpg

Adjusted Image: 0008.jpg



Displaying image: 0009.jpg

Adjusted Image: 0009.jpg



Displaying image: 0010.jpg

Adjusted Image: 0010.jpg



Displaying image: 0020.jpg





# 4. Modified Data Augmentation

Reuse the data augmentation functions from MP2 on geometric transformations and add the following augmentation techniques:

Increase or decrease the saturation.

Reused data augmentation functions from MP1

• Randomly put a black patch over a portion of the image

```
In [10]: def random_black_patch(img):
    h, w, _ = img.shape
    patch_size = np.random.randint(10, 30) # randomly selects the size of the black patch, currently set between 10 to 30 pixels
    x1 = np.random.randint(0, w - patch_size)
    y1 = np.random.randint(0, h - patch_size)
    img[y1:y1+patch_size, x1:x1+patch_size] = 0 # sets the pixels in the selected area to black
    return img
```

• Shift an image sideward or upwards

```
In [11]: def shift_image(img, shift_x, shift_y):
    h, w = img.shape[:2]

# creates a transformation matrix for shifting
# [1, 0, shift_x] shifts the image by 'shift_x' pixels horizontally
# [0, 1, shift_y] shifts the image by 'shift_y' pixels vertically
M = np.float32([[1, 0, shift_x], [0, 1, shift_y]])
shifted_img = cv.warpAffine(img, M, (w, h)) # apply the shifting using the affine transformation
return shifted_img
```

Rotate an image either for

```
In [12]: def rotate_image(img, angle):
    h, w = img.shape[:2]
    center = (w // 2, h // 2) # determines the center of the image
    M = cv.getRotationMatrix2D(center, angle, 1.0) # positive angle -> counter clockwise rotation, negative angle -> clockwise rotation
    rotated_img = cv.warpAffine(img, M, (w, h)) # apply the rotation using the affine transformation
    return rotated_img
```

Flip an image either vertically or horizontally

```
In [13]: def flip_image(image, value):
    return cv.flip(image, value) # 0 -> vertical, 1 -> horizontal
```

## 4a. Adjusting saturation

```
In [14]: def adjust saturation(img, saturation scale=1.0):
             # Convert BGR to HSV
             hsv img = cv.cvtColor(img, cv.COLOR BGR2HSV)
             # Scale the saturation channel (S)
             hsv img[:, :, 1] = np.clip(hsv img[:, :, 1] * saturation scale, 0, 255)
             # Convert back to BGR
             img_with_adjusted_saturation = cv.cvtColor(hsv_img, cv.COLOR_HSV2BGR)
             return img with adjusted saturation
In [15]: def combine augmentations(image, aug func1, aug func2):
             # Apply the first augmentation
             img_aug1 = aug_func1(image.copy())
             # Apply the second augmentation
             img aug2 = aug func2(img aug1)
             return img aug2
         input directory = 'dataset2 resized'
         augmented output dir = 'modified dataset2 augmented'
         if not os.path.exists(augmented output dir): # creates directory if does not exist
             os.makedirs(augmented output dir)
         image_count = 0
         augmentations = [
             (random black patch, 'random black patch'),
             (lambda img: shift image(img, 20, 0), 'shift right 20px'),
             (lambda img: shift_image(img, 0, -20), 'shift_up_20px'),
             (lambda img: rotate image(img, 45), 'rotate 45 degrees'),
             (lambda img: flip image(img, 0), 'flip vertically'),
             (lambda img: flip_image(img, 1), 'flip_horizontally'),
             (lambda img: adjust saturation(img, 1.5), 'increase saturation 1.5'),
             (lambda img: adjust_saturation(img, 0.5), 'decrease_saturation_0.5'),
         for filename in os.listdir(input directory):
             if filename.endswith('.jpg'):
                 img_path = os.path.join(input_directory, filename)
                 image = cv.imread(img path)
                 # Save the original resized image
                 cv.imwrite(os.path.join(augmented output dir, filename), image)
                 image count += 1
                 # Save the augmented images (single and combined)
                 for i in range(len(augmentations)):
                     # Single augmentations
                     aug_func, aug_desc = augmentations[i]
                     output filename = f'{filename.split(".")[0]}_{aug_desc}.jpg'
                     cv.imwrite(os.path.join(augmented output dir, output filename), aug func(image.copy()))
                     image count += 1
```

```
# Combine augmentations
for j in range(i + 1, len(augmentations)):
    aug_func2, aug_desc2 = augmentations[j]
    combined_image = combine_augmentations(image, aug_func, aug_func2)
    output_filename_combined = f'{filename.split(".")[0]}_{aug_desc}_{aug_desc2}_{jpg'}
    cv.imwrite(os.path.join(augmented_output_dir, output_filename_combined), combined_image)
    image_count += 1

if image_count >= 370:
    break

if image_count >= 370:
    break
```

## **Sample Output**

```
In [16]: image_files = os.listdir(augmented_output_dir)

image_files = [f for f in image_files if f.endswith('.jpg')]

for i in range(min(5, len(image_files))):
    img_path = os.path.join(augmented_output_dir, image_files[i])
    image = cv.imread(img_path)
    display_image(image, title=image_files[i])
```

## 0001.jpg



0001\_decrease\_saturation\_0.5.jpg



0001\_flip\_horizontally.jpg



0001\_flip\_horizontally\_decrease\_saturation\_0.5.jpg



0001\_flip\_horizontally\_increase\_saturation\_1.5.jpg

