



Md Jahidul Islam

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About Me

I am an avid practitioner of artificial intelligence with a passion for robot vision and deep learning. I also explore challenging problems in the domains of applied machine learning and 3D computer vision.

Domain Knowledge

Robot Vision

- Visual attention modeling
- Visual tracking & servoing
- Autonomous following

Deep Visual Perception

- Object detection & segmentation
- Image enhancement/restoration
- Image super-resolution

Applied Machine Vision

- Design of computationally light detection/classification models
- Low-powered meta-learning

Education

Ph.D. in Computer Science

Fall 2015 - Today

University of Minnesota (UMN), Twin Cities

🔬 My ongoing Ph.D. research work focuses on the design and development of robust perception modules for visually-guided underwater robots. More at: <https://xahidbuffon.github.io/projects.html>.

Dissertation: "Machine Vision for Improved Human-Robot Cooperation in Adverse Underwater Conditions"

Advised by: Prof. Junaed Sattar

Major courses: Field Robotics; 3D Computer Vision; Advanced Machine Learning; Matrix Theory; Non-linear Optimization; Artificial Intelligence II; Sensing/Estimation in Robotics; Probability and Stochastic Processes.

M.Sc. / B.Sc. in Computer Science & Engineering

Spring 2012-15 / Fall 2007-12

Bangladesh University of Engineering and Technology (BUET)

🔬 My research focused on designing a smart dynamic spectrum access (DSA) technique for cognitive radio networks (CRNs) by integrating the benefits of bio-inspired algorithms and stochastic processes.

Thesis: "Intelligent DSA by Exploiting a Synergy between Genetic Algorithm and Local Search"

Advised by: Prof. Md. Monirul Islam and Prof. A. B. M. Alim Al Islam

Major courses: Structured Programming Languages; Linear Algebra; Machine Learning; Artificial Intelligence; Neural Networks; Microprocessors; Wireless Networks; Concrete Mathematics; Differential Equations.

Academic Enrollments

Graduate Research Assistant

Fall 2020/18, Summer 2020/17

Interactive Robotics and Vision Lab (IRVLab)

🔧 My primary role involves working on sponsored research projects and assisting in the robotic field trials.

Graduate Teaching Assistant

Spring 2018, Fall 2017/16

Dept. of CSE, University of Minnesota (UMN), Twin Cities

👤 I was involved in preparing/grading tests. I also held office-hours and conducted occasional lectures.

Courses: Introduction to Intelligent Robotic Systems; Introduction to C/C++ Programming.

Assistant Professor and Lecturer

May 2012 - August 2015

Dept. of CSE, United International University (UIU), Dhaka

Major courses: Artificial Intelligence; Structured Programming Languages; Algorithms; Numerical Methods; Microprocessors and Microcontrollers; Data Communications; Electronic Devices and Circuits.

Industry Experiences

Qualcomm

2019 Summer Internship, R&D

Qualcomm Technologies, Inc.
Santa Clara, CA, USA.

📁 I worked with the Glance team on design/customization of various vision-based models for faster processing and better portability on ultra-low powered systems.

3M

2018 Summer Internship, R&D

Corporate Research Systems Lab, 3M.
Maplewood, MN, USA

📁 I worked with the AI group (Orthodontics team) on visual and corpus data analysis, and also building multiple features of a virtual assistant app.

Skill Sets

🔧 Programming Languages

- Python, C++/C
- Java, MATLAB, Unix Shell

📊 Deep NN Libraries

- TensorFlow 1.14+ (Keras 2.2.0+)
- PyTorch 1.5.1+

🔌 Embedded AI devices

- Nvidia Jetson Xavier, TX2, Nano
- Google Coral Edge TPU

⚙️ Operating Systems

- Linux (Ubuntu), Windows

🔧 Vision Tool-kits

- OpenCV 3.0, ROS (Kinetic/Melodic)

🐾 Robotic platforms

- AQUA 8, TurtleBot 2, OpenROV

Research Highlights and Publications

Saliency-guided Visual Attention Modeling (SVAM)

[In review at IEEE T-RO]

Designed a holistic deep visual model: SVAM-Net, which integrates bottom-up and top-down learning within an efficient end-to-end architecture to facilitate fast saliency estimation by visually-guided robots.

📄 <https://arxiv.org/pdf/2011.06252.pdf>

📄 <https://github.com/xahidbuffon/SVAM-Net>

Simultaneous Enhancement and Super-Resolution (SESR)

[Published in RSS 2020]

Introduced the SESR problem and developed a robust solution: Deep SESR, a residual-in-residual network model that can learn to restore perceptual image qualities for up to 4x higher spatial resolution.

📄 <http://www.roboticsproceedings.org/rss16/p018.pdf>

📄 https://github.com/xahidbuffon/Deep_SESR

Fast Underwater Image Enhancement (FUnIE)

[Published in RA-L 2020]

Designed a generative adversarial network model: FUnIE-GAN, which provides state-of-the-art performance for perceptual image enhancement and offers real-time inference on single-board embedded devices.

📄 <https://ieeexplore.ieee.org/document/9001231>

📄 <https://github.com/xahidbuffon/FUnIE-GAN>

Semantic Segmentation of Underwater Imagery (SUIM)

[To appear at IROS 2020]

Presented the first large-scale dataset for semantic segmentation of underwater imagery, performed comprehensive benchmark evaluation of state-of-the-art approaches for general-purpose robotic applications.

📄 <https://arxiv.org/pdf/2004.01241.pdf>

📄 <https://github.com/xahidbuffon/SUIM>

Autonomous Person Following

[Published in IJRR 2019 and RA-L 2018]

Developed and benchmarked various visual servoing modules for autonomous person-following by ground, underwater, and aerial robots. In particular, developed a robust diver-following module by addressing the inherent challenges of underwater human-robot cooperative missions.

📄 <https://journals.sagepub.com/doi/10.1177/0278364919881683>

📄 <https://ieeexplore.ieee.org/document/8543168>

Robot-to-robot Relative Pose from Human Body-Pose (R2R-OpenPose)

[In review at AuRo]

We propose a method to estimate the 3D relative poses of pairs of communicating robots by using human pose (OpenPose)-based key-points as geometric correspondences.

📄 <https://arxiv.org/pdf/1903.00820.pdf>

Selected Awards

2019-20	Doctoral Dissertation Fellowship (DDF), Dept. of CSE, University of Minnesota.
2019	RAS travel grant for ICRA 2019 in Montreal, Canada.
2017	IEEE/RSJ travel grant for IROS 2017 in Vancouver, Canada.
2015-16	ADC graduate fellowship, Digital Technology Center (DTC), University of Minnesota.
2012-13	Runner-up. International Robotics Challenge (IRC) grand finale, Techfest, IIT-Bombay, India.
2012	Champion. Bangladesh regional of IRC, IEEE student branch, BUET, Bangladesh.

Community and Volunteering Work

👤 Member / Student Member

- IEEE, IEEE RAS, TinyML, 3D-VR
- Self-Driving Car Club, UMN
- Grad Student Panel, UMN

👤 Conference & Journal Reviewer

- ICRA 2016-20, IROS 2016-20,
- ICCV 2019, CRV 2018-20
- IEEE Transactions, RA-L, Elsevier

👤 Volunteer / Activist

- Clean Energy and Climate
- One-Taka-Meal Project
- Oceanic Preservation Society

Extracurricular Activities

👤 Math / Puzzle Nerd

- Keen explorer of century-old math problems and puzzles

🏏 Cricket Player

- Semi-professional cricketer, played in major leagues of MN, CA, and TX

📷 Travel Photographer

- Self-taught photographer, like to travel and capture memories

📄 References are available on request. For more information, please visit: <https://xahidbuffon.github.io/>.