

### Text-to-Concept (and back) via Cross-Model Alignment

Concept Activation Vectors \*Directly from Text

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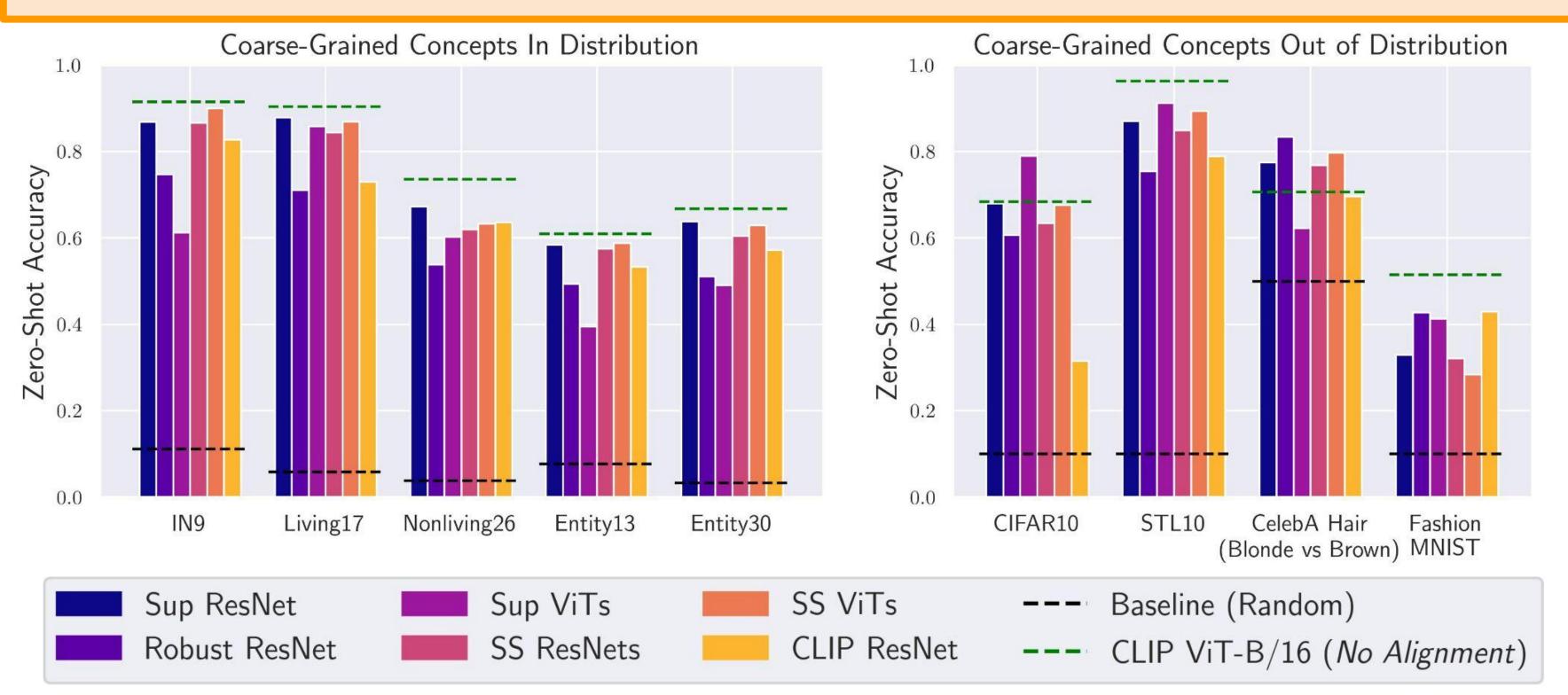
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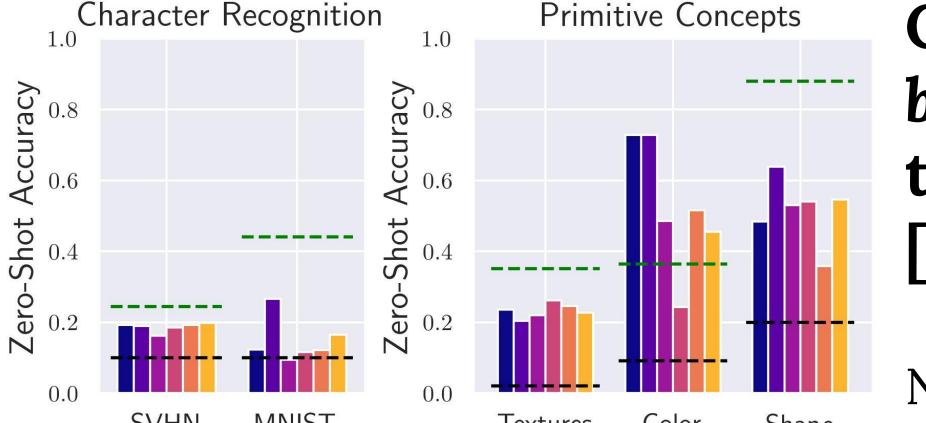
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VANCOUVER, CANADA

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### Application 1: Converting off-the-shelf Vision Encoders into Zero-shot Classifiers





Competitive, and at times better, zero-shot accuracy than CLIP, for various [much simpler] encoders.

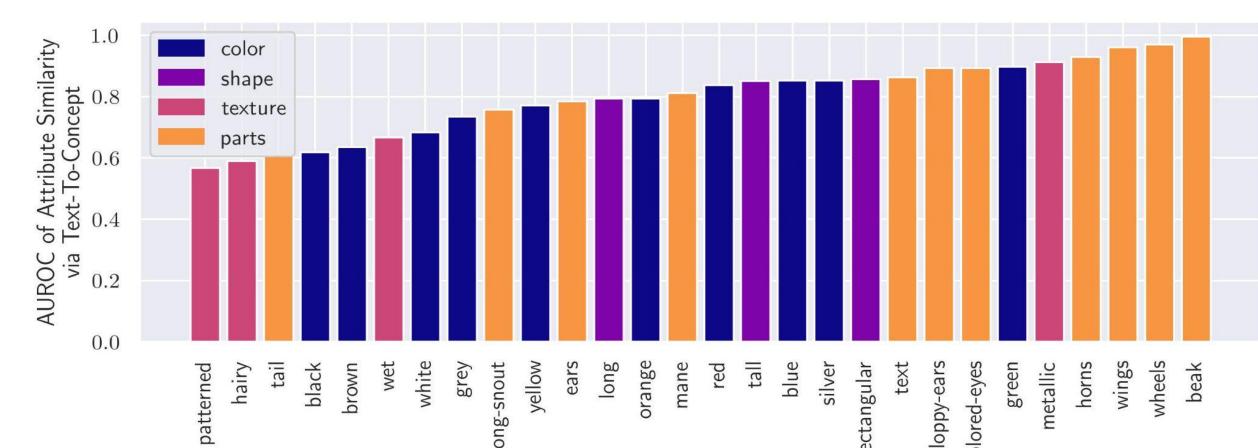
Notable gains over CLIP occur for tasks that involve color recognition.

## Application 2: Concept-Bottleneck Models with no concept supervision



CBMs are white box models w.r.t. concept predictions, but they require costly extra concept supervision.

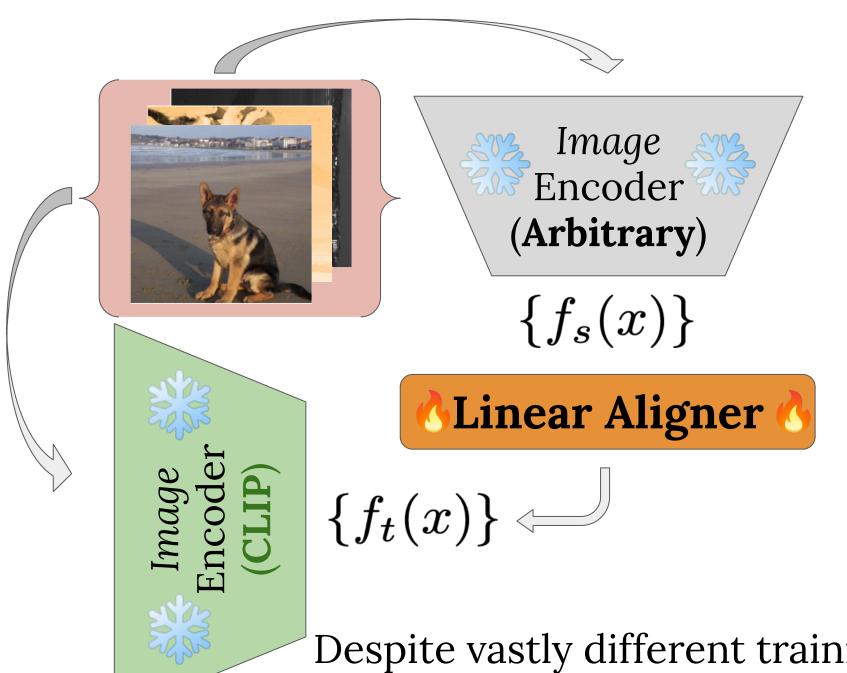




Text-to-Concept yields concept vectors for free → via training only two linear layers (aligner + final head), you can easily convert an encoder into a CBM.

Shown: interpretable inferences using RN50 fit on RIVAL10 data. (bottom) RIVAL10 Attributes are predicted reasonably well by similarity of aligned features to Text-to-Concept vectors.

# **W** Key Insight: **A linear layer can map across P representation spaces of diverse vision models**



#### Cross-Model Linear Alignment

For the source and target image encoders,

- 1. Take a dataset of unlabeled images
- 2. Cache their representations
- 3. Solve regression [very efficient] to obtain linear aligner parameters.

$$\min_{W,b} \sum_{x \in \mathcal{D}} \|W^T f_s(x) + b - f_t(x)\|^2$$

Despite vastly different training procedures, using a linear layer to predict representations of one encoder given those of another is surprisingly effective.

We achieve high R<sup>2</sup> for this regression task, and can even use the classification head for one model on aligned features of another with minimal drop in accuracy.

## Implication: Aligning to a CLIP vision encoder → **Multimodal access for your Unimodal Model \***

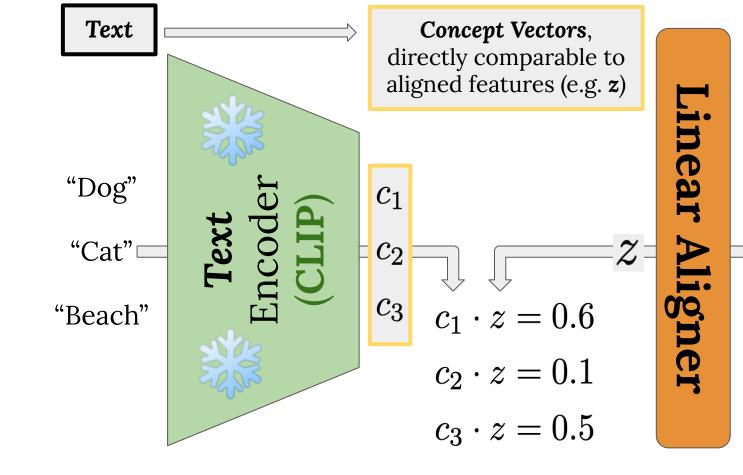
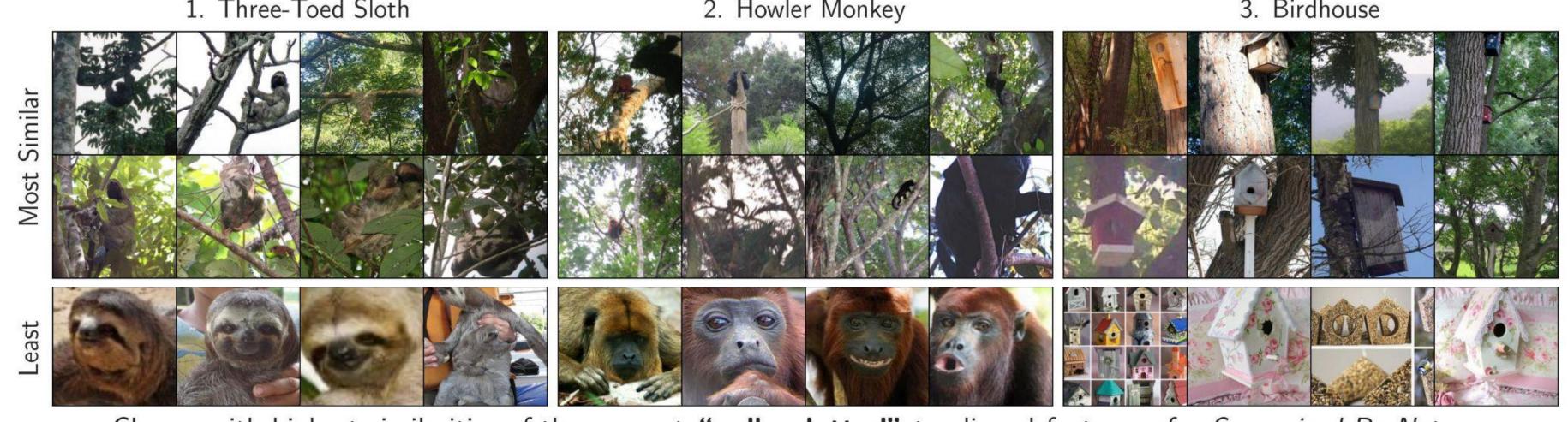


Image Encoder (Arbitrary)

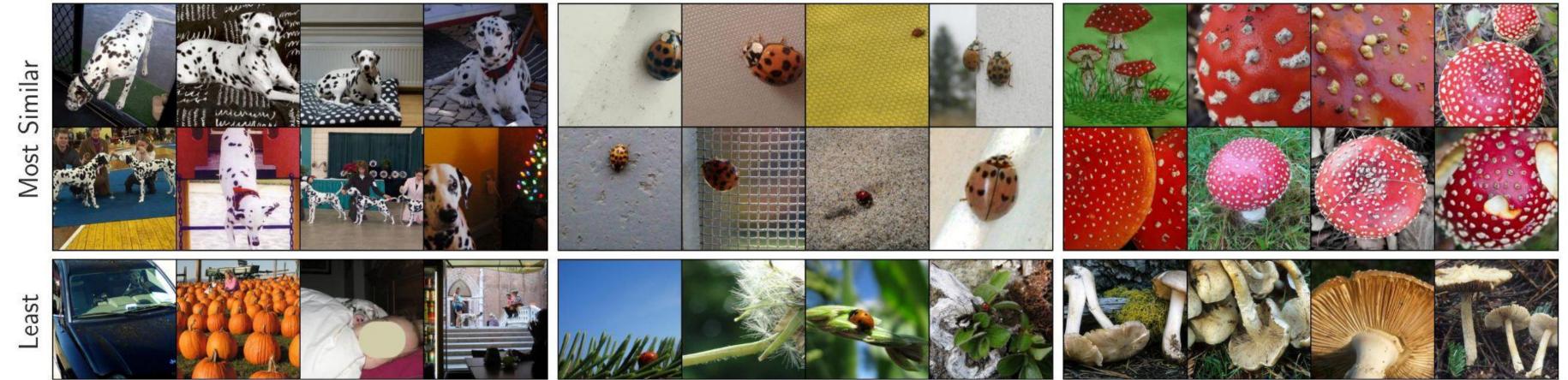
After training the aligner once, you can **use CLIP's text encoder to get concept vectors in constant time** w.r.t. typical cost of collecting exemplar data for every concept.

An aligned representation from the source encoder compares directly to **CLIP** text embeddings, yielding high similarity when a concept is present. See examples below.

#### Classes with highest similarities of the concept **"in a tree"** to aligned features of a *Self-Supervised* (via Dino) ResNet. 1. Three-Toed Sloth 2. Howler Monkey 3. Birdhouse



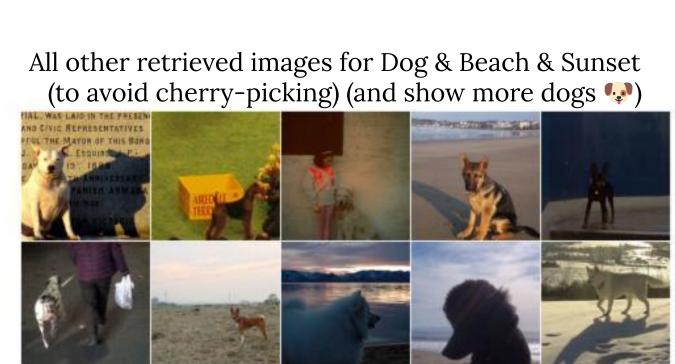
Classes with highest similarities of the concept **"polka-dotted"** to aligned features of a *Supervised ResNet*1. Dalmatian
2. Ladybug
3. Agaric

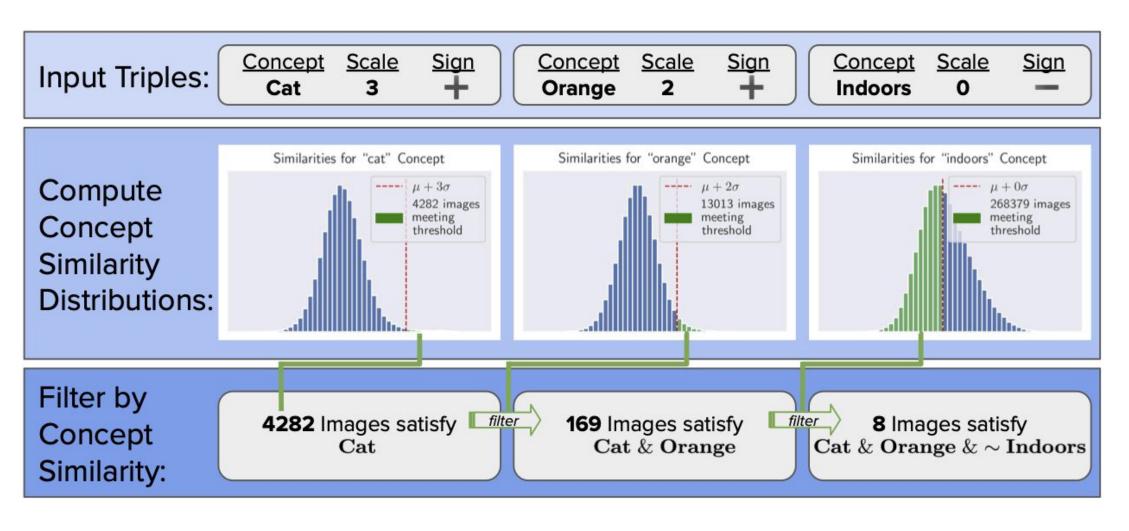


# Application 3: **Image Retrieval** using the embeddings of your choice via **Concept Logic**

Extends CLIP's ability to retrieve images with text to arbitrary encoders.

Concept Logic is a simple way to somewhat side step text encoder limitations with negation and long queries.





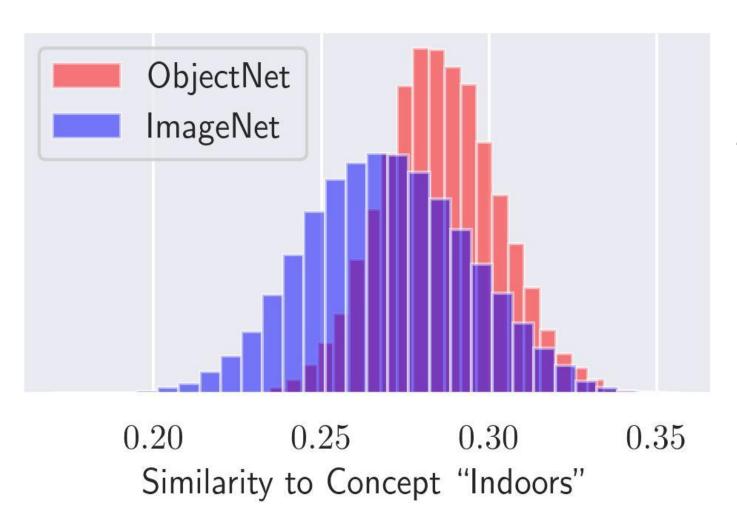
Dog & Beach & Sunset Skis &  $\sim$ Snow &  $\sim$ Human Cat & Orange &  $\sim$ Indoor Dino ResNet50 Dino ViTs16 ResNet50







### Application 4: Diagnosing Distribution Shifts



By maintaining a bank of concept vectors (cheap via Text-to-Concept), one can track concept similarities as data (e.g. from a new deployment environment) streams in, and automatically **detect and describe data drifts** w.r.t human notions.

Example: Detecting that ObjectNet images were taken indoors, which contributes to reduced performance.

### Application 5: Decoding Latent Vectors to text

992	Swin (S)	ResNet-50	Dino ViTs8
	94.48%	95.14%	92.18%

Using CLIP decoders, we can map latent vectors for arbitrary vision encoders to text.

Shown: ImageNet classification head vectors for diversely trained vision encoders are decoded to words that adequately describe images from the class (based on human judgements). Current challenge: Decodings are generally coarse-grain. We hope this will improve as CLIP decoders do.

### Parting Thoughts

Many efforts focus on **how** we train models.

It might be time to shift more attention to **what** we train our models on.

Existing models may be capable of more than what we use them for.

How else can we allow the models we already have to work together?