

$$(iii) \quad x_1(n) = -5 \left(\frac{1}{2}\right)^n u(-n-1)$$

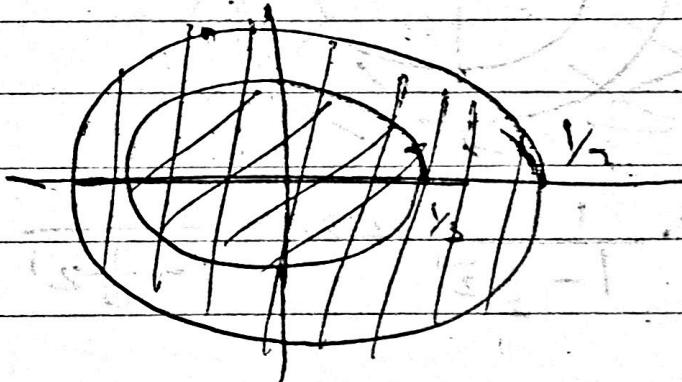
$$x_2(n) = -2 \left(\frac{1}{3}\right)^n u(-n-1)$$

$$X_1(z) = \frac{5}{1 - \frac{1}{2}z^{-1}}$$

$$X_2(z) = 2 \frac{1}{1 - \frac{1}{3}z^{-1}}$$

ROC of $x_1(z)$, $|z| < \frac{1}{2}$

ROC of $x_2(z)$, $|z| < \frac{1}{3}$



ROC of $x(z) \Rightarrow |z| < \frac{1}{3}$

$$X(z) = \frac{5}{1 - \frac{1}{2}z^{-1}} + \frac{2}{1 - \frac{1}{3}z^{-1}} ; |z| < \frac{1}{3}$$

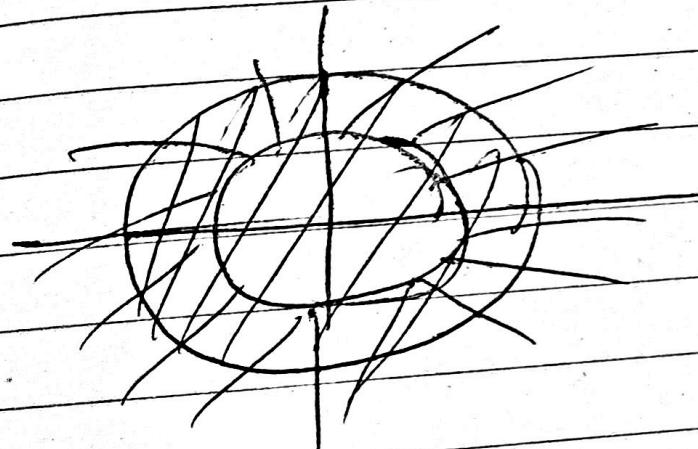
$$(iv) \quad x_1[n] = -5 \left(\frac{1}{2}\right)^n u(-n-1)$$

$$x_2[n] = 2 \left(\frac{1}{3}\right)^n u[n]$$

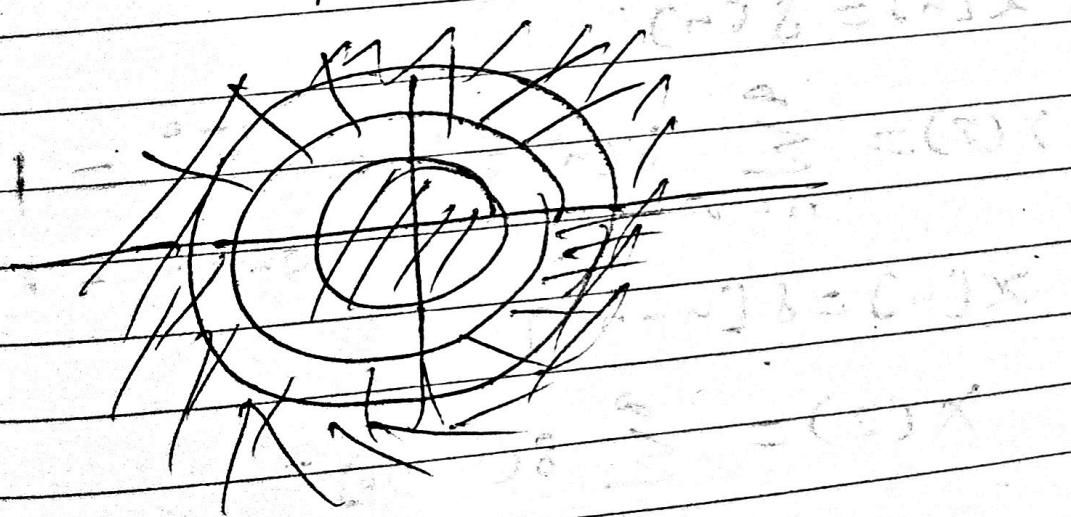
$$x_1(z) = \frac{5}{1 - \frac{1}{2}z^{-1}} \quad |z| < \frac{1}{2}$$

$$x_2(z) = \frac{2}{1 - \frac{1}{3}z^{-1}} \quad |z| > \frac{1}{2}$$

ROC $\rightarrow \frac{1}{3} < |z| < \frac{1}{2}$



(v)

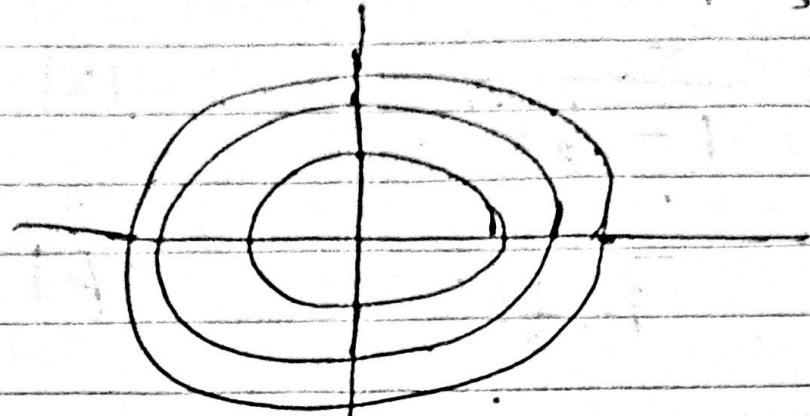


$$|z| < \frac{1}{2}$$

$$|z| > \frac{1}{3}$$

$$(vi) X[n] = 3 \left(\frac{1}{2}\right)^n u(-n-1) + 5 \left(\frac{1}{3}\right)^n u(n) + \left(\frac{1}{5}\right)^n u(n)$$

$$|z| > \frac{1}{5}$$



$$(vii) x[n] = \delta[n]$$

$$X(z) = \sum_{n=-\infty}^{\infty} \delta(n) z^n = \bar{z}^0 = 1$$

entire z -plane.

$$\underline{(viii)} \quad x[n] = \delta[n - n_0]$$

$$X(z) = \sum_{n=-\infty}^{\infty} \delta(n - n_0) z^n$$

$$= \frac{-n_0}{z} = \frac{1}{z^{n_0}}$$

Roc \rightarrow entire z -plane except $\underline{|z|=0}$

$$x[n] = s(n+n_0)$$

$$X(z) = \sum_{n=-\infty}^{n_0} s(n+n_0) z^{-n}$$

$$= z^{n_0}$$

$\text{ROC} \Rightarrow$ Entire z -plane except $|z|=\infty$

$$x[n] = u[n]$$

$$X(z) = \sum_{n=0}^{\infty} u[n] z^{-n}$$

$$= \frac{z}{z-1}$$

$$= \frac{z}{z-1}$$

$$\text{ROC} \Rightarrow |z| > 1$$

Properties of ROC

- ① ROC of $X(z)$ is circular strip centered at origin.
- ② ROC of $X(z)$ does not contain any pole of $X(z)$.
- ③ If $x[n]$ is right handed sequence then its ROC lie outside the outermost pole of $X(z)$.

- ④ If $x[n]$ is left handed sequence then its ROC lies inside the innermost pole of $X(z)$.
- ⑤ If $x[n]$ is algebraic sum of left handed and right handed sequences then ~~then~~ ROC of $X(z)$, area of ~~the~~ overlap of ROCs of individual sequence.
- ⑥ If $x[n]$ is of finite duration then its ROC is entire z -plane which may or may not include $z=0 \geq z=\infty$.

Inverse Z-Transform:-

$$x[n] = \frac{1}{2\pi j} \int_{-\pi}^{\pi} X(z) z^{n-1} dz$$

$$\stackrel{\stackrel{\leftrightarrow}{z}}{\int} \leftrightarrow \stackrel{\stackrel{\leftrightarrow}{z}}{\int}$$

Q:

Find the Inverse Z-transform of the function $x(z)$ if

$$(i) X(z) = \frac{3 - \frac{5}{6}z^{-1}}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 - \frac{1}{3}z^{-1}\right)}$$

$$ROC: |z| > \frac{1}{3}$$

$$= \frac{A}{(1 - \frac{1}{4}z^{-1})} + \frac{B}{(1 - \frac{1}{3}z^{-1})}$$

$$= \frac{1}{(1 - \frac{1}{4}z^{-1})} + \frac{2}{(1 - \frac{1}{3}z^{-1})}$$

Inverse z-transform

$$x(n) = \left(\frac{1}{4}\right)^n u(n) + 2\left(\frac{1}{3}\right)^n u(n)$$

(ii) Find the Inverse-z transform of function

$$X(z) \text{ if } X(z) = \frac{3 - \frac{5}{6}z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})} ; |z| < \frac{1}{4}$$

$$X(z) = \frac{3 - \frac{5}{6}z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})}.$$

$$= \frac{1}{(1 - \frac{1}{4}z^{-1})} + \frac{2}{(1 - \frac{1}{3}z^{-1})}$$

$$= -\left(\frac{1}{4}\right)^{n-1} u(-n) + 2\left(\frac{1}{3}\right)^{n-1} u(-n-1)$$

$$(iii) \text{ R.O.C: } \frac{1}{4} < |z| < \frac{1}{3}$$

$$x(n) = \left(\frac{1}{4}\right)^n u(n) - 2\left(\frac{1}{3}\right)^n u(-n-1)$$

$$\text{ROC: } 1 < |z| < 2$$

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Q3 Find the Inverse Z-transform of function

$$X(z) \text{ if }$$

$$X(z) = \frac{(1 - z^{-1} + z^{-2})}{(1 - \frac{1}{2}z^{-1})(1 - 2z^{-1})(1 - z^{-1})}$$

$$X(z) = \frac{A}{(1 - \frac{1}{2}z^{-1})} + \frac{B}{(1 - 2z^{-1})} + \frac{C}{(1 - z^{-1})}$$

$$= \frac{1}{(1 - \frac{1}{2}z^{-1})} + \frac{2}{(1 - 2z^{-1})} - \frac{2}{(1 - z^{-1})}$$

$$\therefore = \left(\frac{1}{2}\right)^n u(n) - 2(2)^n u(-n-1) - 2(1)^n u(n)$$

Q4 Find the inverse Z-transform for the function $X(z)$ if

$$X(z) = z^4 + z^2 + 2 + 5z^{-1} + 6z^{-2} + 3z^{-3}$$

$$x[n] = \delta[n+4] + \delta[n+2] + \delta[n+1]$$

$$+ 5\delta[n] + 6\delta[n-1] + 3\delta[n-3]$$

$$x[n] = \{1, 0, 1, 1, 5, 6, 0, 3\}$$

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

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Q) Find the inverse -z transform of the signal $x(z)$ if

$$x(z) = e^{\frac{1}{z}}$$

Soln

$$= 1 + \frac{\left(\frac{1}{z}\right)}{1!} + \frac{\left(\frac{1}{z}\right)^2}{2!} + \frac{\left(\frac{1}{z}\right)^3}{3!} + \dots$$

$$= \sum_{n=0}^{\infty} \frac{1}{1^n} \left(\frac{1}{z}\right)^n$$

$$= \sum_{n=0}^{\infty} \frac{1}{1^n} z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} \frac{1}{1^n} u[n] z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

Where $x[n] = \frac{1}{1^n} u[n]$

$$x[n] = \frac{1}{1^n} u[n]$$

$$x[n] = z^{-n} u[n] = e^{-n} u[n]$$

$$x[n] = z^{-n} u[n] = (1+z^{-1})^n u[n]$$

$$x[n] = z^{-n} u[n] = (1+z^{-1})^n u[n]$$

Properties of Z-Transform :-

① Linearity :-

$$Z\{x_1[n] + x_2[n]\} = X_1(z) + X_2(z); R \rightarrow R_1 \cap R_2$$

② Time shifting :-

a) Time delay :-

$$Z\{x(n-k)\} = z^{-k} X(z) + \sum_{m=1}^{K-m} x[-m] z^{m-k}$$

$$\star Z\{x(n-1)\} = z^{-1} X(z) + x[-1]$$

$$\star Z\{x(n-2)\} = z^{-2} X(z) + x[-1] z^{-1} + x[-2]$$

$$Z\{x(n-3)\} = z^{-3} X(z) + x[-1] z^{-2} + x[-2] z^{-1} + x[-3]$$

b) Time Advance :-

$$Z\{x(n+k)\} = z^k X(z) - \sum_{m=0}^{K-1} x[m] z^{K-m}$$

$$\star Z\{x(n+1)\} = z X(z) - x(0) z$$

$$\star Z\{x(n+2)\} = z^2 X(z) - x(0) z^2 - x(1) z$$

③ Time Scaling:

$$z \{ \alpha^n x[n] \} = X\left[\frac{z}{\alpha}\right]$$

④ Time reversal:

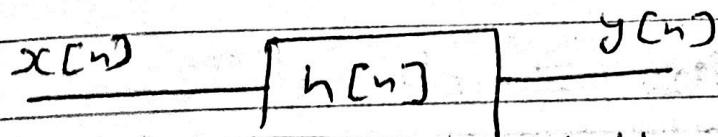
$$z \{ x(-n) \} = x(z')$$

⑤ Conjugation property:

$$z \{ x^*[n] \} = X^*(z^*)$$

⑥ Convolution Property:

$$z [x_1[n] * x_2[n]] = X_1(z) X_2(z)$$



Application of convolution property to LTI system

$$y[n] = h[n] * x[n]$$

$$Y(z) = H(z) X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = \text{Transfer function}$$

④ Time Scaling:

$$z \{x[n]\} = X\left[\frac{z}{a}\right]$$

⑤ Time Reversal:

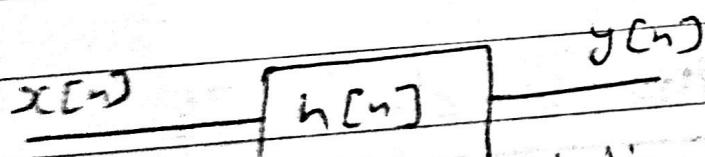
$$z \{x(-n)\} = x(z^1)$$

⑥ Conjugation Property:

$$z \{x^*[n]\} = X^*(z^*)$$

⑦ Convolution Property:

$$z [x_1[n] * x_2[n]] = X_1(z) X_2(z)$$



Application of convolution property to LTI system

$$y[n] = h[n] * x[n]$$

$$Y(z) = H(z)X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = \text{Transfer function}$$

$$\text{Q3} \quad T_0 = \left\{ X(n) : x(n) = \left(\frac{1}{1 - \frac{1}{3}z} \right)^n, |z| < \frac{1}{3} \right\}$$

Then find $x(n) = ?$

$$Z\{X(n)\} = X(z)$$

$$X(z) = \left(\frac{1}{1 - \frac{1}{3}z} \right)^2$$

$$X(z) = \frac{1}{(1 - \frac{1}{3}z)^2}$$

$$X(z) = \frac{1}{z^2} \left(\frac{1}{1 - \frac{1}{3}z} \right)^2 = \frac{1}{z^2} \cdot \left(\frac{1}{1 - \frac{1}{3}z} \right)^2$$

⑦ Differentiation in z-domain

$$Z\{n^k x(n)\} = (-1)^k \frac{d^k}{dz^k} X(z)$$

$$\underline{\underline{G3}} \quad \underline{\underline{x[n] = n u[n]}}$$

$$\underline{\underline{\underline{SOL}}} \quad = (-1)^k \frac{d^k}{dz^k} U(z)$$

$$= (-1)^k \frac{d}{dz} \frac{z}{z-1}$$

$$= -\frac{(z-1)1 \cdot -2}{(z-1)^2} = \frac{2}{(z-1)^2}$$

$$= \frac{-2}{(1-z)^2}$$

⑧ Initial & Final value Theorems

Initial value:

$$x[0] = \lim_{n \rightarrow 0} x[n] = \lim_{z \rightarrow \infty} X(z)$$

Final value Theorem:

$$x[\infty] = \lim_{n \rightarrow \infty} x[n] = \lim_{z \rightarrow 1} [1 - z^{-1}] X(z)$$

$$= \lim_{z \rightarrow 1} (z-1) X(z)$$

⑨ Multiplication in Time domain :

$$z \{ x_1[n] x_2[n] \} = \frac{1}{2\pi j} \oint x_1(\omega) x_2\left(\frac{z}{e^{j\omega}}\right) e^{j\omega} d\omega$$

$$(\bar{z}) + (\bar{z}') \xrightarrow{L^{-1}} = \frac{\bar{z}'}{1-\bar{z}'} = \frac{\bar{z}}{1-\frac{1}{\bar{z}}}$$

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(10) Z-transform of real part of signal

$$Z[\operatorname{Re}\{x[n]\}] = \frac{1}{2} [x(z) + x^*(z^*)]$$

$$Z[\operatorname{Im}\{x[n]\}] = \frac{1}{2} [x(z) - x^*(z^*)]$$

Z-Transform of important signals :-

$$\textcircled{1} \quad Z[\delta[n]] = 1$$

$$\textcircled{2} \quad Z[\delta[n-k]] = z^{-k}$$

$$\textcircled{3} \quad Z[\delta[n+k]] = z^k$$

$$\textcircled{4} \quad Z[U[n]] = \frac{z}{z-1} = \frac{1}{1-z^{-1}}$$

Q3 Find the z transform of $x[n]$ if

$$x[n] = u[-n]$$

$$x[z] = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} u(-n) z^{-n}$$

$$\begin{aligned}
 &= \sum_{n=-\infty}^{\infty} z^{-n} \\
 &\quad \rightarrow \text{Replacing } n \text{ by } -n \\
 &= \sum_{n=\infty}^{\infty} z^n \\
 &= \sum_{n=0}^{\infty} z^n
 \end{aligned}$$

$$\begin{aligned}
 &= 1 + z + z^2 + z^3 + \dots \\
 &= \frac{1}{1-z} = \frac{1}{(1-\bar{z}^*)} \\
 &= -\frac{1}{z-1}
 \end{aligned}$$

(Q) $x[n] = u[-n-1]$

$$\begin{aligned}
 X(z) &= \sum_{n=-\infty}^{\infty} x(n) z^{-n} \\
 &= \sum_{n=-\infty}^{\infty} u[-n-1] z^{-n}
 \end{aligned}$$

$$\begin{aligned}
 &= \sum_{n=-\infty}^{-1} z^{-n}
 \end{aligned}$$

$$\begin{aligned}
 &= \sum_{n=0}^{\infty} z^n
 \end{aligned}$$

$$\begin{aligned}
 &= \sum_{n=1}^{\infty} z^n
 \end{aligned}$$

$$\begin{aligned}
 &= \cancel{z} + z^2 + \dots \\
 &= \frac{z}{1-z} = -\frac{1}{1-\bar{z}^*}
 \end{aligned}$$

$$\begin{aligned}
 x[n] &= \cos(\omega_0 n) u[n] \\
 &= \left[\frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{2} \right] u[n] \\
 &= \left[\frac{1}{2} \alpha^n + \frac{1}{2} \bar{\alpha}^n \right] u[n]
 \end{aligned}$$

$$X(z) = \frac{1 - \bar{z}^{-1} \cos \omega_0}{1 - 2 \bar{z}^{-1} \cos \omega_0 + \bar{z}^2}$$

$$x[n] = \sin(\omega_0 n) u[n]$$

$$X(z) = \frac{z^{-1} \sin \omega_0}{1 - 2 z^{-1} \cos \omega_0 + z^2}$$

$$x[n] = \alpha^n \cos(\omega_0 n) u[n]$$

$$X(z) = \frac{1 - \alpha z^{-1} \cos \omega_0}{1 - 2 \alpha z^{-1} \cos \omega_0 + \alpha z^2}$$

$$x[n] = \alpha^n \sin(\omega_0 n) u[n]$$

$$X(z) = \frac{\alpha z^{-1} \sin \omega_0}{1 - 2 \alpha z^{-1} \cos \omega_0 + \alpha z^2}$$

Application of Z-Transform to LTI systems

Properties of LTI systems

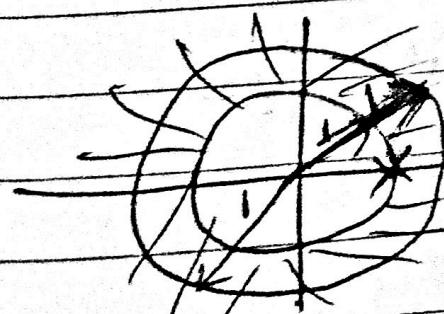
① Causality:

A system is said to be causal if its impulse response is zero for $n < 0$. Therefore impulse response of the system is right handed for the system to be causal. Then poles of transfer function in Z-domain lie ~~not~~ with in outermost pole & ROC lies outside the outermost pole of the transfer function.

② Stability:

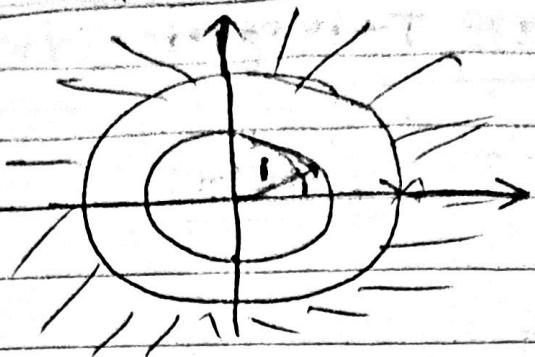
A system is said to be stable if its impulse response is absolutely summable & ROC of transfer function include unit circle.

Causal & stable system is

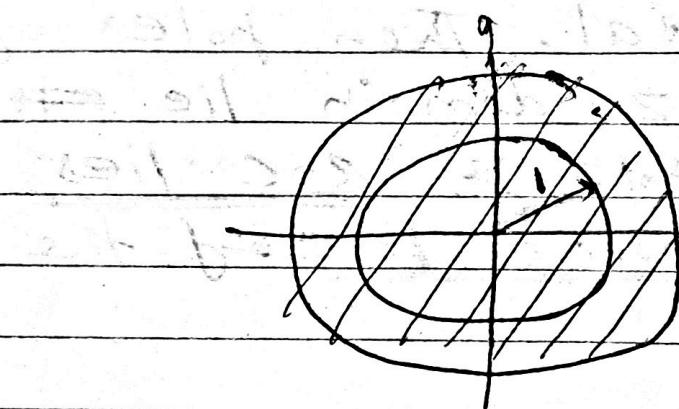


Poles are within the unit circle

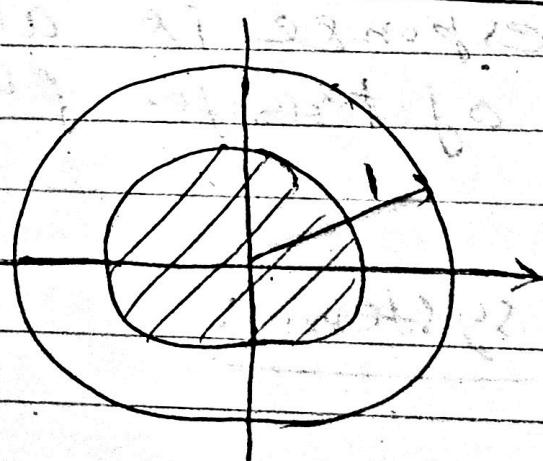
Causal & unstable



Non causal & stable



Non causal & unstable



* Causal \rightarrow ROC outside unit circle
 stable \rightarrow include unit circle

non causal \rightarrow lie outside unit circle

Causal \rightarrow lie inside unit circle

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A Causal LTI system is described by the difference equation

$$y[n] = ay[n-2] - 2x[n] + bx[n-1]$$

Find the condition for stability of system.

$$z \Rightarrow T_{Kaiy} z^{-t}$$

$$y[z] = a[\bar{z}^2 y[z]] - 2x[z] + b\bar{z} x[z]$$

$$y[z] [2 - a\bar{z}^2] = [b\bar{z} - 2] x[z]$$

$$\frac{y(z)}{x(z)} = \frac{b\bar{z} - 2}{2 - a\bar{z}^2}$$

$$H(z) = \frac{b - z^2 (b\bar{z} - 2)}{2 [z^2 - \frac{a}{2}]}$$

Charac. Eqⁿ

$$z^2 - \frac{a}{2} = 0$$

$$z = \pm \sqrt{\frac{a}{2}}$$

$$|z| = \sqrt{\frac{a}{2}}$$

Causal

For system to be stable, pole must lie within the unit circle.

$$\sqrt{\frac{a}{2}} < 1$$

$$a < 2$$