

Linear Algebra, Assignment 8

Alex Hiller (11850637)

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Question 1

Part (a)

$$\mathbf{y} = \begin{bmatrix} 7 \\ 1 \end{bmatrix} \quad \mathbf{u} = \begin{bmatrix} 8 \\ -6 \end{bmatrix}$$

Finding $\mathbf{y} = \hat{\mathbf{y}} + \mathbf{z}$

$$\hat{\mathbf{y}} = \text{proj}_{\mathbf{u}}(\mathbf{y}) = \sum_{i=1}^p \frac{\mathbf{y} \cdot \mathbf{u}_i}{\mathbf{u}_i \cdot \mathbf{u}_i} \cdot \mathbf{u}_i \Rightarrow p = 1 \Rightarrow \hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \cdot \mathbf{u}_1$$

$$\mathbf{y} \cdot \mathbf{u}_1 = (7)(8) + (1)(-6) = 56 - 6 = 50$$

$$\mathbf{u}_1 \cdot \mathbf{u}_1 = (8)(8) + (-6)(-6) = 64 + 36 = 100$$

$$\hat{\mathbf{y}} = \frac{50}{100} \begin{bmatrix} 8 \\ -6 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 8 \\ -6 \end{bmatrix}$$

$$\therefore \hat{\mathbf{y}} = \begin{bmatrix} 4 \\ -3 \end{bmatrix}$$

$$\mathbf{z} = \mathbf{y} - \hat{\mathbf{y}}$$

$$\therefore \mathbf{z} = \begin{bmatrix} 7 \\ 1 \end{bmatrix} - \begin{bmatrix} 4 \\ -3 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

Hence the orthogonal decomposition is:

$$\mathbf{y} = \begin{bmatrix} 4 \\ -3 \end{bmatrix} + \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

Part (b)

This would just be the modulus of \mathbf{z} .

$$\|\mathbf{z}\| = \sqrt{3^2 + 4^2} = \sqrt{9 + 16} = 5$$

Question 2

$$\mathcal{W} = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$$

$$\mathbf{y}_1 = \begin{bmatrix} 5 \\ 3 \\ 5 \end{bmatrix} \quad \mathbf{y}_2 = \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix} \quad \mathbf{u}_1 = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix} \quad \mathbf{u}_2 = \begin{bmatrix} -15 \\ 2 \\ 4 \end{bmatrix}$$

Part (a)

First vector:

$$\mathbf{y}_1 = \hat{\mathbf{y}}_1 + \mathbf{z}_1$$

$$\hat{\mathbf{y}}_1 = \text{proj}_{\mathcal{W}}(\mathbf{y}_1) = \sum_{i=1}^{p=2} \frac{\mathbf{y}_1 \cdot \mathbf{u}_i}{\mathbf{u}_i \cdot \mathbf{u}_i} \cdot \mathbf{u}_i$$

$$\hat{\mathbf{y}}_1 = \frac{\mathbf{y}_1 \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \cdot \mathbf{u}_1 + \frac{\mathbf{y}_1 \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \cdot \mathbf{u}_2 = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}$$

$$\mathbf{z}_1 = \mathbf{y}_1 - \hat{\mathbf{y}}_1 = \begin{bmatrix} 5 \\ 3 \\ 5 \end{bmatrix} - \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 6 \end{bmatrix}$$

$$\therefore \mathbf{y}_1 = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 2 \\ 3 \\ 6 \end{bmatrix}$$

Second vector:

$$\mathbf{y}_2 = \hat{\mathbf{y}}_2 + \mathbf{z}_2$$

$$\hat{\mathbf{y}}_2 = \frac{\mathbf{y}_2 \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \cdot \mathbf{u}_1 + \frac{\mathbf{y}_2 \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \cdot \mathbf{u}_2 = \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix}$$

$$\mathbf{z}_2 = \mathbf{y}_2 - \hat{\mathbf{y}}_2 = \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix} - \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix} = \mathbf{0}$$

$$\therefore \mathbf{y}_2 = \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Part (b)

Distance from \mathbf{y}_1 to \mathcal{W} is equal to the modulus of the \mathbf{z} component of the orthogonal decomposition.

$$\|\mathbf{z}_1\| = \sqrt{2^2 + 3^2 + 6^2} = 7$$

$$\|\mathbf{z}_2\| = 0$$

Therefore, \mathbf{y}_1 is 7 units from \mathcal{W} and \mathbf{y}_2 is 0 units from \mathcal{W} .

$$\therefore \mathbf{y}_2 \in \mathcal{W}$$

Question 3

Part (a)

The Gram-Schmidt (a method used to convert a basis to an orthogonal basis) can concisely be written as:

$$\mathbf{v}_k = \mathbf{x}_k - \sum_{j=1}^{k-1} \text{proj}_{\mathbf{v}_j}(\mathbf{x}_k)$$

Our vectors are:

$$\mathbf{a}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} \quad \mathbf{a}_2 = \begin{bmatrix} 4 \\ 2 \\ 2 \\ 0 \end{bmatrix} \quad \mathbf{a}_3 = \begin{bmatrix} 4 \\ 3 \\ 2 \\ 1 \end{bmatrix}$$

Finding our orthogonal set ...

$$\mathbf{v}_1 = \mathbf{x}_1$$

$$\mathbf{v}_2 = \mathbf{x}_2 - \text{proj}_{\mathbf{v}_1}(\mathbf{x}_2) = \mathbf{v}_1 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1$$

$$\mathbf{v}_3 = \mathbf{x}_3 - \text{proj}_{\mathbf{v}_1}(\mathbf{x}_3) - \text{proj}_{\mathbf{v}_2}(\mathbf{x}_3) = \mathbf{v}_1 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2$$

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} \quad \mathbf{v}_2 = \begin{bmatrix} 3 \\ 3 \\ 1 \\ 1 \end{bmatrix} \quad \mathbf{v}_3 = \begin{bmatrix} -1/10 \\ -1/10 \\ 3/10 \\ 3/10 \end{bmatrix}$$

Part (b)

Finding our orthonormal set:

$$\mathbf{u}_1 = \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|} \quad \mathbf{u}_2 = \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|} \quad \mathbf{u}_3 = \frac{\mathbf{v}_3}{\|\mathbf{v}_3\|}$$

$$\mathbf{u}_1 = \begin{bmatrix} 1/2 \\ -1/2 \\ 1/2 \\ -1/2 \end{bmatrix} \quad \mathbf{u}_2 = \begin{bmatrix} 3\sqrt{5}/10 \\ 3\sqrt{5}/10 \\ \sqrt{5}/10 \\ \sqrt{5}/10 \end{bmatrix} \quad \mathbf{u}_3 = \begin{bmatrix} -\sqrt{5}/10 \\ -\sqrt{5}/10 \\ 3\sqrt{5}/10 \\ 3\sqrt{5}/10 \end{bmatrix}$$

Question 4

Ways to check whether a vector belongs to certain spaces:

$$\mathbf{v} \in \text{Col}(\mathbf{A}) \text{ if } \exists \mathbf{A}, \mathbf{x} \text{ s.t. } \mathbf{Ax} = \mathbf{v}$$

$$\mathbf{v} \in \text{Row}(\mathbf{A}) \text{ if } \exists \mathbf{A}, \mathbf{x} \text{ s.t. } \mathbf{A}^T \mathbf{x} = \mathbf{v}$$

$$\mathbf{v} \in \text{Nul}(\mathbf{A}) \text{ if } \exists \mathbf{A} \text{ s.t. } \mathbf{Av} = \mathbf{0}$$

Part (a)

Can a vector \mathbf{v} exist s.t. $\mathbf{v} \in \text{Col}(\mathbf{A})$ and $\mathbf{v} \in \text{Row}(\mathbf{A})$?

If $\mathbf{v} \in \text{Col}(\mathbf{A})$, then:

$$\mathbf{Ax} = \mathbf{v}$$

But if $\mathbf{v} \in \text{Row}(\mathbf{A})$, then:

$$\mathbf{A}^T \mathbf{x} = \mathbf{v}$$

Then:

$$\mathbf{A}^{-1} \mathbf{A}^T \mathbf{x} = \mathbf{x}$$

Meaning the following must hold for \mathbf{v} to be contained in both vector spaces.

$$\mathbf{A}^{-1} \mathbf{A}^T = \mathbf{I}$$

Corollary:

This must also mean that \mathbf{A} is a square, non-singular matrix.

Note: This might mean (I'm not sure) that \mathbf{A} has to be the identity?

Part (b)

Can a vector \mathbf{v} exist s.t. $\mathbf{v} \in \text{Row}(\mathbf{A})$ and $\mathbf{v} \in \text{Nul}(\mathbf{A})$?

The matrix \mathbf{A} is a linear map s.t. for an $m \times n$ matrix:

$$\mathbf{A} : \mathbb{R}^n \mapsto \mathbb{R}^m$$

It should also be noted that:

$$\text{Row}(\mathbf{A}) \subset \mathbb{R}^m$$

$$\text{Nul}(\mathbf{A}) \subset \mathbb{R}^m$$

Then if \mathbf{A} is a square, non-singular matrix, then:

$$\mathbf{A}^T \mathbf{x} = \mathbf{v} \quad \mathbf{A} \mathbf{v} = \mathbf{0}$$

$$\mathbf{v} = \mathbf{A}^{-1} \mathbf{0} = \mathbf{0}$$

$$\therefore \mathbf{A}^T \mathbf{x} = \mathbf{0}$$

By invertible-matrix-theorem:

$$(\mathbf{A}^{-1})^T = (\mathbf{A}^T)^{-1} \Rightarrow \exists (\mathbf{A}^T)^{-1} \forall \mathbf{A}^{-1}$$

Meaning that $\mathbf{x} = \mathbf{0}$ and $\mathbf{v} = \mathbf{0}$ for \mathbf{v} to lie in both $\text{Row}(\mathbf{A})$ and $\text{Nul}(\mathbf{A})$.

Part (c)

Can a vector \mathbf{v} exist s.t. $\mathbf{v} \in \text{Col}(\mathbf{A})$ and $\mathbf{v} \in \text{Nul}(\mathbf{A})$?

The matrix \mathbf{A} is a linear map s.t. for an $m \times n$ matrix:

$$\mathbf{A} : \mathbb{R}^n \mapsto \mathbb{R}^m$$

It should also be noted that:

$$\text{Col}(\mathbf{A}) \subset \mathbb{R}^m$$

$$\text{Nul}(\mathbf{A}) \subset \mathbb{R}^n$$

Meaning that $m = n$ for there to be a vector, \mathbf{v} , that lies in both spaces.

What we are now really asking is that:

$$\exists \mathbf{v} \mid \mathbf{v} \in (\text{Col}(\mathbf{A}) \cap \text{Nul}(\mathbf{A}))$$

A solution is the trivial solution, $\mathbf{v} = \mathbf{0}$.

Constraint from the column space:

$$\mathbf{A} \mathbf{x} = \mathbf{v} = \mathbf{0}$$

Constraint from the null space:

$$\mathbf{A} \mathbf{v} = \mathbf{0}$$

And again, if \mathbf{A} is a square, invertible matrix, then:

$$\mathbf{v} = \mathbf{0}$$

Meaning:

$$\mathbf{A} \mathbf{x} = \mathbf{0}$$

And hence:

$$\mathbf{x} = \mathbf{0}$$