

UNIVERSITY OF TECHNOLOGY SYDNEY
SCHOOL OF MATHEMATICAL AND PHYSICAL SCIENCES
37233 LINEAR ALGEBRA

Tutorial 6

Question 1.

Illustrate the effect of a linear transformation \mathcal{T} with the standard matrix $\mathbf{T} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ by mapping its action on a triangle with vertices $(0, 0)$, $(1, 0)$ and $(1, 1)$.

Question 2.

Let $\mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $\mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$, $\mathbf{y}_1 = \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix}$, $\mathbf{y}_2 = \begin{bmatrix} -5 \\ 0 \\ 3 \end{bmatrix}$, $\mathbf{y}_3 = \begin{bmatrix} -6 \\ 3 \\ 5 \end{bmatrix}$.

Let $\mathcal{T} : \mathbb{R}^3 \mapsto \mathbb{R}^3$ be a linear transformation that maps \mathbf{e}_i to \mathbf{y}_i .

(a) Write the standard matrix representation of \mathcal{T} .

(b) Find the image of $\mathbf{v} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$.

(c) Find the standard matrix of the reverse transformation from \mathbf{y}_i to \mathbf{e}_i .

(d) Using the reverse transformation, obtain the image of $[\mathbf{u}]_{\mathcal{Y}} = \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}$.

Question 3.

Let $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}$ be a basis for a vector space V . Explain why the \mathcal{B} -coordinates of vectors $\mathbf{b}_1, \dots, \mathbf{b}_n$ are the columns $\mathbf{e}_1, \dots, \mathbf{e}_n$ of the $n \times n$ identity matrix.

Question 4.

Let $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$ and $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \mathbf{c}_3\}$ be bases for a vector space V , and suppose $\mathbf{b}_1 = 2\mathbf{c}_1 - \mathbf{c}_2$, $\mathbf{b}_2 = 2\mathbf{c}_2 + 7\mathbf{c}_3$, and $\mathbf{b}_3 = \mathbf{c}_1 + 2\mathbf{c}_3$.

(a) Find the change-of-coordinate matrices from \mathcal{B} to \mathcal{C} , and from \mathcal{C} to \mathcal{B} .

(b) Find $[\mathbf{x}]_{\mathcal{C}}$ for $[\mathbf{x}]_{\mathcal{B}} = \begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix}$, and find $[\mathbf{x}]_{\mathcal{B}}$ for $[\mathbf{x}]_{\mathcal{C}} = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$.

Question 5.

Let

$$\mathbf{B} = \begin{bmatrix} 6 & 0 & 0 & 4 \\ 4 & 2 & 0 & 0 \\ 0 & -8 & 4 & 0 \\ 0 & 0 & 2 & -6 \end{bmatrix} \quad \text{and} \quad \mathbf{C} = \begin{bmatrix} 1 & 5 & -5 & 5 \\ 1 & 3 & -1 & 1 \\ 6 & -6 & -2 & 6 \\ 4 & -4 & 4 & -2 \end{bmatrix}$$

- (a) Check if the columns of \mathbf{B} form a basis \mathcal{B} for \mathbb{R}^4 , and if the columns of \mathbf{C} form another basis \mathcal{C} for \mathbb{R}^4 .

- (b) Find \mathcal{B} -coordinates of $\mathbf{x} = \begin{bmatrix} 4 \\ 4 \\ 4 \\ 4 \end{bmatrix}$.

- (c) Find the change-of-coordinate matrix from \mathcal{B} to \mathcal{C} .

- (d) Using the above matrix, find $[\mathbf{x}]_{\mathcal{C}}$.

It would be helpful to use **Mathematica** to facilitate the required calculations.

Question 6.

The Chebyshev polynomials are widely used in calculus and mathematical methods. The first five Chebyshev polynomials (of the first kind) are given by

$$\begin{aligned} T_0(x) &= 1 \\ T_1(x) &= x \\ T_2(x) &= 2x^2 - 1 \\ T_3(x) &= 4x^3 - 3x \\ T_4(x) &= 8x^4 - 8x^2 + 1 \end{aligned}$$

- (a) Confirm that the set of the above Chebyshev polynomials is a basis Θ for \mathbb{P}^4 .
- (b) Find the change of coordinates matrix from the standard basis \mathcal{P} in \mathbb{P}^4 , $\{x^0, x^1, x^2, x^3, x^4\}$, to the Chebyshev basis.
- (c) Define f as a polynomial of Maclaurin series for $\cos(4x)$, keeping the terms up to the fourth power in x , and write $[f]_{\mathcal{P}}$.
- (d) Using the change of coordinate matrix found in (b), find $[f]_{\Theta}$.

It may be helpful to use **Mathematica** to facilitate the required calculations.