### Model Checking of Fault-tolerant Systems

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### Model Checking Modulo Theories

### Model Checking

- a state type is a list of variables: x
- a state is a valuation for these variables
- a transition is a formula over the current state variables and the next state variables (usually represented as a guard  $H(\mathbf{x})$  and a (partial) assignment  $V(\mathbf{x}')$ )
- $(H_1(\mathbf{x}) \wedge V_1(\mathbf{x}')) \vee \ldots \vee (H_n(\mathbf{x}) \wedge V_n(\mathbf{x}'))$

#### Modulo Theories

- the formulae can be in any theory
- example:
  - if the state type is a variable x of type int
  - transition:  $x < 0 \land x' = x \lor x \ge 0 \land x' = x + 1$
  - describes a system which has a variable x which keeps increasing unless is is lower than 0.

## Model Checking of a Fault-tolerant System

### The Byzantine General Problem

#### Pseudo-Code

# Sally

### A model checker for infinite-state systems

- sri-csl.github.io/sally
- a symbolic model checker
- several engines: bmc, kind, ic3
- works with various smt solvers: mathsat, yices2, z3

# Input language

- lisp-like language
- low level
- easy to parse and work with

state type

```
(define-state-type my_state_type
  ((x Real) (y Real))
)
```

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)
```

state formula

```
(define-states x_is_zero my_state_type
  (= x 0)
)
```

 transition: a first order formula over state variables and next state variables

```
(define-transition my_transition my_state_type
  (or
(= next.x (+ state.x 1))
next.x_is_zero
  )
)
```

### Input language

queries

# A new old input language: Sal

### Sal

- an older model checker, developed at SRI
- developed actively until 2006, minor versions until 2013
- finite state systems

## Input language

- already used
- supports modules, composition

```
my_module: MODULE
BEGIN
  OUTPUT
    x: REAL,
    y: REAL
  INITIALIZATION
    x = 0;
  TRANSITION
    ...
END;
```

```
TRANSITION
  [x >= 0 -->
     x' = x + 1;
     y' IN { i: REAL | TRUE }
  []
  TRUE -->
     x' = 0;
     y' IN { i: REAL | TRUE }
]
```

- a lemma is translated to a Sally query
- multiple lemma
- syntax for temporal logic (not available in Sally)

```
my_context: CONTEXT =
BEGIN
  my_module: MODULE
    ...

always_positive: LEMMA
  my_module |- G(x >= 0);

wrong_lemma: LEMMA
  my_module |- G(x > 0 -> x = 1)
```

**END** 

### Parametrization

### Arrays

### Quantifiers

- for most examples, they can be avoided in transitions
- works only with z3
- example:

```
(forall (i Int) (select a i))
```

# Counting in SMT

- $\phi(y) \wedge y = \# \{x | \psi(x)\}$
- $\psi(.)$ : first order formula of Presburger arithmetic, then with arrays too
- how is it solved?

#### State of the art

- Bradley, Manna, and Sipma (2006): a decision procedure for a fragment of arrays, with distinct theories for elements and indexes
- Alberti, Ghilardi, and Pagani (2016): a decision procedure for counting on arithmetic and arrays, via various rewriting and quantifier eliminations, mix index and elements theories, but quantify only over one element at a time
- Bjørner, Gleissenthall, and Rybalchenko (n.d.): a model checking oriented way to deal with arrays (one update at a time for every arrays)

# Counting over Presburger arithmetic

- given a model, one can compute the value of  $\#\{x|\psi(x)\}$
- given an ordering on the integer variables, one can compute the symbolic value of  $\#\{x|\psi(x)\}$
- ⇒ symbolic computation of cardinalities, for the ordering of a given model

- the ordering is called an oracle: when asked wether a > b, it looks in the model the value of a and b and answers accordingly.
- when the cardinality is computed symbolically, it is equal to a formula which holds under some assumptions, and the oracle can say what they are

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- example:  $y = \#\{x | 0 \le x < z \land 0 \le x < u\}$
- if the oracle says z > u, then y can be computed and y = z.
- under the assumption z > u, y = z

- compute a symbolic interval list in which the formula is satisfiable i.e.  $\exists I \in V_x(\psi) \ x \in I \Leftrightarrow \psi(x)$
- if members of  $V_x(\psi)$  are disjoint  $card(V_x(\psi)) = \sum_{[v,v'] \in \#_x(\psi))} (v v') = \#\{x | \psi(x)\}$

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- $V_x(y < x) = \{[y, +\infty)\}$

•  $V_x(\psi \land \phi) = V_x(\psi) \sqcap V_x(\phi)$ where  $A \sqcap B$  is the set of every intersection of an interval of A with an interval of B (of course some are empty and must be deleted)

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- Intersection between two intervals: [a,b) and [c,d) can be computed: there is an oracle giving the ordering on the variables, so max(a,c) and min(b,d) are computable given the assumptions that the oracle makes.

Then the intersection is [max(a, c), min(b, d)) if  $max(a, c) \le min(b, d)$ 

- if  $V_x(\psi) = \{[a_1, b_1), \dots [a_n, b_n)\}$  (with  $a_1 \leq b_1 \leq \dots \leq b_n$ ,  $a_1 \neq -\infty$  and  $b_n = +\infty$ )
- $V_{\mathsf{x}}(\neg \psi) = \{(-\infty, a_1), [b_1, a_2), \dots, [b_n, +\infty)\}$
- ullet other cases are easy too, disjunction on  $a_1=-\infty$  and  $b_n=+\infty$

### Counting with multiplication

- to deal with constant multiplications, a modulo information can be added to every intervals (such as ([5,10),=1[3]) are the integers x between 5 and 10 and such that 3|x-1)
- intersection, negation of these intervals can be done in an analog way

#### **Future Work**

- Counting over arrays
- IC3 with arrays and counting quantifiers

#### References

Alberti, Francesco, Silvio Ghilardi, and Elena Pagani. 2016. "Counting Constraints in Flat Array Fragments." *CoRR* abs/1602.00458. http://arxiv.org/abs/1602.00458.
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