Model Checking of Fault-tolerant Systems

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Model Checking Modulo Theories

Model Checking

- a state type is a list of variables: x
- a state is a valuation for these variables
- a transition is a formula over the current state variables and the next state variables (usually represented as a guard $H(\mathbf{x})$ and a (partial) assignment $V(\mathbf{x}')$)
- $(H_1(\mathbf{x}) \wedge V_1(\mathbf{x}')) \vee \ldots \vee (H_n(\mathbf{x}) \wedge V_n(\mathbf{x}'))$

Modulo Theories

- the formulae can be in any theory
- example:
 - if the state type is a variable x of type int
 - transition: $x < 0 \land x' = x \lor x \ge 0 \land x' = x + 1$
 - describes a system which has a variable x which keeps increasing unless it is lower than 0.

Model Checking of a Fault-tolerant System

The Byzantine General Problem

- One general wants to give an order to n-1 lieutenants.
- Some of them may be faulty (including the general).
- In the end, they have to decide on the same order (at least for all the non faulty lieutenants/general)

Pseudo-Code

```
% message[i][j] is the message sent by lieutenant j to i
message: array of (lieutenants * lieutenants) to message
source: the general id
% value[i] is the order that lieutenant i will follow
value: array of lieutenants to message
% good[i] is true if lieutenant i is non faulty
good: array of lieutenants to boolean
```

Pseudo-Code

```
propagate():
  forall i, j do
    if good[i]
      message[j][i] <- message[i][source]</pre>
agree():
  forall i do
    if good[i]
      value[i] <- majority(message[i])</pre>
propagate();
propagate();
agree();
```

The Byzantine General Problem

- $\exists v \ \forall i \ good[i] \Rightarrow value[i] = v$
- How many lieutenants can be faulty? Does that work for a third of the lieutenants?
- $\#\{i \mid good[i]\} > 2N/3$

Sally

A model checker for infinite-state systems

- sri-csl.github.io/sally
- a symbolic model checker
- several engines: bmc, kind, ic3
- works with various smt solvers: mathsat, yices2, z3

Input language

- lisp-like language
- low level
- easy to parse and work with

state type

```
(define-state-type my_state_type
  ((x Real) (y Real))
)
```

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```

state formula

```
(define-states x_is_zero my_state_type
  (= x 0)
)
```

 transition: a first order formula over state variables and next state variables

```
(define-transition my_transition my_state_type
  (or
    (= next.x (+ state.x 1))
    next.x_is_zero
  )
)
```

queries: check that a property always holds

```
(query my_system
  (>= x 0)
)
```

A new old input language: Sal

Sal

- an older model checker, developed at SRI
- developed actively until 2006, minor versions until 2013
- finite state systems

Input language

- already used
- supports modules, composition

```
my_module: MODULE
BEGIN
  OUTPUT
    x: REAL,
    y: REAL
  INITIALIZATION
    x = 0;
  TRANSITION
    ...
END;
```

```
TRANSITION
  [x >= 0 -->
     x' = x + 1;
     y' IN { i: REAL | TRUE }
  []
  TRUE -->
     x' = 0;
     y' IN { i: REAL | TRUE }
]
```

- a lemma is translated to a Sally query
- multiple lemma
- syntax for temporal logic (not available in Sally)

```
my_context: CONTEXT =
BEGIN
  my_module: MODULE
    ...

always_positive: LEMMA
  my_module |- G(x >= 0);

wrong_lemma: LEMMA
  my_module |- G(x > 0 -> x = 1)
```

END

Parametrization

Arrays

Quantifiers

- for most examples, they can be avoided in transitions
- works only with z3
- example:

```
(forall (i Int) (select a i))
```

Counting in SMT

- $\phi(y) \wedge y = \# \{x | \psi(x)\}$
- $\psi(.)$: first order formula of Presburger arithmetic, then with arrays too
- how is it solved?

State of the art

- Bradley, Manna, and Sipma (2006): a decision procedure for a fragment of arrays, with distinct theories for elements and indexes
- Alberti, Ghilardi, and Pagani (2016): a decision procedure for counting on arithmetic and arrays, via various rewriting and quantifier eliminations, mix index and elements theories, but quantify only over one element at a time
- Bjørner, Gleissenthall, and Rybalchenko (n.d.): a model checking oriented way to deal with arrays (one update at a time for every arrays)

Counting over Presburger arithmetic

- given a model, one can compute the value of $\#\{x|\psi(x)\}$
- given an ordering on the integer variables, one can compute the symbolic value of $\#\{x|\psi(x)\}$
- ⇒ symbolic computation of cardinalities, for the ordering of a given model

- the ordering is called an oracle: when asked wether a > b, it looks in the model the value of a and b and answers accordingly.
- when the cardinality is computed symbolically, it is equal to a formula which holds under some assumptions, and the oracle can say what they are

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- when the cardinality is computed symbolically, it is equal to a formula which holds under some assumptions, and the oracle can say what they are
- example: $y = \#\{x | 0 \le x < z \land 0 \le x < u\}$
- if the oracle says z > u, then y can be computed and y = z.
- under the assumption z > u, y = z

- compute a symbolic interval list in which the formula is satisfiable i.e. $\exists I \in V_x(\psi) \ x \in I \Leftrightarrow \psi(x)$
- if members of $V_x(\psi)$ are disjoint $card(V_x(\psi)) = \sum_{[v,v'] \in \#_x(\psi))} (v v') = \#\{x | \psi(x)\}$

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- $V_x(y < x) = \{[y, +\infty)\}$

• $V_x(\psi \land \phi) = V_x(\psi) \sqcap V_x(\phi)$ where $A \sqcap B$ is the set of every intersection of an interval of A with an interval of B (of course some are empty and must be deleted)

- $V_x(\psi \land \phi) = V_x(\psi) \sqcap V_x(\phi)$ where $A \sqcap B$ is the set of every intersection of an interval of A with an interval of B (of course some are empty and must be deleted)
- Intersection between two intervals: [a,b) and [c,d) can be computed: there is an oracle giving the ordering on the variables, so max(a,c) and min(b,d) are computable given the assumptions that the oracle makes.

Then the intersection is [max(a, c), min(b, d)) if $max(a, c) \le min(b, d)$

- if $V_x(\psi) = \{[a_1, b_1), \dots [a_n, b_n)\}$ (with $a_1 \leq b_1 \leq \dots \leq b_n$, $a_1 \neq -\infty$ and $b_n = +\infty$)
- $V_{\mathsf{x}}(\neg \psi) = \{(-\infty, a_1), [b_1, a_2), \dots, [b_n, +\infty)\}$
- ullet other cases are easy too, disjunction on $a_1=-\infty$ and $b_n=+\infty$

Counting with multiplication

- to deal with constant multiplications, a modulo information can be added to every intervals (such as ([5,10),=1[3]) are the integers x between 5 and 10 and such that 3|x-1)
- intersection, negation of these intervals can be done in an analog way

Future Work

- Counting over arrays
- IC3 with arrays and counting quantifiers

References

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