APPLICATION OF LAPLACE TRANSFORM METHOD IN SOLVING SECOND ORDER PARTIAL DIFFERENTIAL EQUATION

Laplace Method:

$$\mathcal{L}[f(t)] = F(S) = \int_0^{-\infty} e^{-st} f(t) dt
\mathcal{L}[f^n(t)] = s^n y - s^{n-1} y(0) - s^{n-2} y'(0) \cdot \dots - s f^{n-2}(0) \cdot \dots - y^{n-1}(0)
\mathcal{L}[u_x(x,t)] = \int_0^{\infty} e^{-st} u(x,t) dt \equiv u(x,s)
\mathcal{L}[u_x(x,t)] = u_x(x,s)
\mathcal{L}[u_x(x,t)] = u_x(x,s)
\mathcal{L}[u_x(x,t)] = s u(x,s) - u(x,0)
\mathcal{L}[u_t(x,t)] = s^2 u(x,s) - s u(x,0) - u_t(x,0)
F(s) = \mathcal{L}[f(t)] \text{ then,}
\mathcal{L}[u(t-a) \cdot g(t-a)] = e^{-as} G(s)$$

P.D.E of Order 2

Examples:

$$(1) \frac{\partial^2 u}{\partial x^2}(x,t) = \frac{\partial u}{\partial x}(x,t), 0 < x < 2, t > 0 \quad u(0,t) = 0, u(2,t) = 0, u(x,0) = 3\sin(2\pi x)$$

Solution:

$$u_{xx}(x,t) = u_t(x,t)$$

taking the Laplace transform

$$\mathcal{L}\left[u_{xx}(x,t)\right] = \mathcal{L}\left[u_{t}(x,t)\right]$$

$$u_{xx}(x,s) = su(x,s) - u(x,0)$$

Using the condition, $u(x,0) = 3\sin(2\pi x)$

$$su(x,s) - 3\sin(2\pi x) = u_{xx}(x,s)$$

$$\implies u_{xx}(x,s) - su(x,s) = -3\sin(2\pi x)$$

$$\frac{d^2u}{dx^2} - su = -3\sin(2\pi x)$$

Solving the Homogenous Problem

$$\frac{d^2u}{dx^2} - su = 0$$

The characteristic equation is given by

$$m^2 - s = 0 \Rightarrow m = \pm \sqrt{s}$$

The homogenous solution is:

$$u_A(x,s) = A_1 e^{\sqrt{sx}} + A_2 e^{-\sqrt{sx}}$$

Solving the non-homogenous problem using the method of Undetermined Coefficient

i.e
$$\frac{d^2u}{dx^2} - su = -3\sin(2\pi x) - - - - - - - - - - (*)$$

$$U = \Delta_1 \sin(2\pi x) + \Delta_2 \cos(2\pi x) - - - - - - - - (a)$$

$$U' = 2\pi\Delta_1 \cos(2\pi x) - 2\pi\Delta_2 \sin(2\pi x) - - - - - - (b)$$

$$U'' = -4\pi^2 \Delta_1 \sin(2\pi x) - 4\pi^2 \Delta_2 \cos(2\pi x) - - - - - - (c)$$

Substituting (a) and (c) in equation (*)

$$-4\pi^{2}\Delta_{1}\sin(2\pi x) - 4\pi^{2}\Delta_{2}\cos(2\pi x) - s\Delta_{1}\sin(2\pi x) - S\Delta_{2}\cos(2\pi x) = -3\sin(2\pi x)$$

$$-4\pi^{2}\Delta_{1} - S\Delta_{1} = -3$$
 Also, $4\pi^{2}\Delta_{2} - S\Delta_{2} = 0$
 $-\Delta_{1} [4\pi^{2} + s] = -3$ $\Delta_{2} [s + 4\pi^{2}] = 0$

$$-\Delta_1 \left[4\pi^2 + s \right] = -3 \qquad \qquad \Delta_2 \left[s + 4\pi^2 \right] = 0$$

$$\Delta_1 = \frac{3}{s + 4\pi^2} \qquad \qquad \Delta_2 = 0$$

The particular solution is:

$$u_p(x,s) = \frac{3}{s+4\pi^2}\sin(2\pi x)$$

The general solution is given by:

$$u(x,s) = A_1 e^{\sqrt{sx}} + A_2 e^{-\sqrt{sx}} + \frac{3\sin(2\pi x)}{s + 4\pi^2}$$

Applying the boundary conditions u(0,t) = 0, u(2,t) = 0 $u(0,s) = A_1 + A_2 = 0 \Rightarrow A_1 = -A_2$

$$u(2,s) = A_1 e^{2\sqrt{s}} + A_2 e^{-2\sqrt{s}} = 0 \quad [\text{But } A_1 = -A_2]$$
$$-A_2 e^{2\sqrt{s}} + A_2 e^{-2\sqrt{s}} = 0$$
$$A_2 \left[e^{-2\sqrt{s}} - e^{2\sqrt{s}} \right] = 0 \quad \Rightarrow A_2 = 0, A_1 = 0$$
$$u(x,s) = \frac{3\sin(2\pi x)}{s + 4\pi^2}$$

Subtituing (a) and (c) in equation (*)
$$-c^{2}\pi^{2}n_{1}\sin(\pi x) - c^{2}\pi^{2}n_{2}\cos(\pi x) - s^{2}n_{1}\sin(\pi x) - s^{2}n_{2}\cos(\pi x) = \frac{-\sin(\pi x)}{s}$$

$$\implies -c^{2}\pi^{2}n_{1} - s_{2}n_{1} = \frac{-1}{s} \Rightarrow -n_{1}\left[s^{2} + c^{2}\pi^{2}\right] = \frac{-1}{s}$$

$$\implies n_{1} = \frac{1}{s\left[s^{2} + c^{2}\pi^{2}\right]}$$

Also,
$$-c^2\pi^2 n_2 \cos(\pi x) - s^2 n_2 \cos(\pi x) = 0$$

 $n_2 \left[s^2 + c^2\pi^2 \right] = 0$
 $\implies n_2 = 0$

Substituting n_1 and n_2 in (a)

$$u_p(x,s) = \frac{\sin(\pi x)}{s}$$

The general solution is given as:

Apply the boundary conditions; u(0,t) = 0 and u(1,t) = 0

$$u(0,s) = A_1 + A_2 = 0 \Longrightarrow A_1 = -A_2$$

 $u(1,s) = A_1 e^{\frac{s}{c}} + A_2 e^{-\frac{s}{c}} = 0 \Rightarrow A_2 = 0 \Rightarrow A_1 = 0$

Substituting ${}'A_1'$ and ${}'A_2'$ in eqution (**)

$$u(x,s) = \frac{\sin(\pi x)}{s\left[s^2 + c^2\pi^2\right]}$$

Applying Inverse Laplace Transform

$$\mathcal{L}^{-1}[u(x,s)] = \sin(\pi x) \mathcal{L}^{-1}\left[\frac{1}{s[s^2 + c^2\pi^2]}\right]$$

Resolving $\frac{1}{s\left[s^2+c^2\pi^2\right]}$ into partial fractions

$$\frac{1}{s\left[s^2 + c^2\pi^2\right]} = \frac{A}{s} + \frac{Bs + D}{s^2 + c^2\pi^2} = \frac{A\left[s^2 + c^2\pi^2\right] + \left[Bs + D\right]s}{s\left[s^2 + c^2\pi^2\right]}$$

$$1 = A\left[s^2 + c^2\pi^2\right] + Bs^2 + Ds$$

Taking the Inverse Laplace equation

$$\mathcal{L}^{-1}[u(x,s)] = \mathcal{L}^{-1}\left[\frac{3\sin(2\pi x)}{s + 4\pi^2}\right]$$

$$\mathbf{u}(\mathbf{x}, \mathbf{t}) = 3\mathbf{e}^{-4\pi^2 \mathbf{t}} \sin(2\pi \mathbf{x})$$

(2)
$$\frac{\partial^2 u}{\partial t^2}(x,t) = c^2 \frac{\partial^2 u}{\partial x^2}(x,t); 0 < x < 1, t > 0,$$
$$u(x,0) = 0, u_t(x,0) = 0, u(0,t) = 0, u(1,t) = 0$$

Solution:

$$u_{tt}(x,t) = c^2 u_{xx}(x,t) + \sin(\pi x)$$

Taking the Laplace transform

$$\mathcal{L}\left[u_{tt}(x,t)\right] = c^2 \mathcal{L}\left[u_{xx}(x,t)\right] + \mathcal{L}\left[\sin(\pi x)\right]$$
$$s^2 u(x,s) - su(x,0) - u_t(x,0) = c^2 u_{xx}(x,s) + \frac{\sin(\pi x)}{s}$$

Applying the initial conditions; u(x,0) = 0 and $u_t(x,0) = 0$

$$s^{2}u(x,s) - c^{2}u_{xx}(x,s) = \frac{\sin(\pi x)}{s}$$

Re-arranging

$$c^{2}u_{xx}(x,s) - s^{2}u(x,s) = -\frac{\sin(\pi x)}{s}$$

Solving the Homogenous problem

$$c^{2}\frac{d^{2}u}{dx^{2}}(x,s) - s^{2}u(x,s) = 0$$

The Auxillary equation is given by:

$$c^2m^2 - s^2 = 0 \Longrightarrow m^2 - \left(\frac{s}{c}\right)^2 = 0 \Longrightarrow m = \pm \frac{s}{c}$$

The homogenous solution is: $u(x,s) = A_1 e^{\frac{sx}{c}} + A_2 e^{-\frac{sx}{c}}$

Solving the non-homogenous problem by method of Undetermined Coefficient:

i.e
$$c^2 \frac{d^2 u}{dx^2}(x,s) - s^2 u(x,s) = -\frac{\sin(\pi x)}{s} - - - - - - - - - (*)$$

Let:

Comparing or Equating the Coefficients of boths sides:

$$s: D = 0$$

$$s^{2}: A + B = 0 \Longrightarrow A = -B$$

$$\operatorname{constant}: 1 = Ac^{2}\pi^{2} \Longrightarrow A = \frac{1}{c^{2}\pi^{2}} \Longrightarrow B = \frac{-1}{c^{2}\pi^{2}}$$

$$\therefore \frac{1}{s\left[s^{2} + c^{2}\pi^{2}\right]} = \frac{1}{sc^{2}\pi^{2}} - \frac{s}{(c^{2}\pi^{2})(s^{2} + c^{2}\pi^{2})} = \frac{1}{c^{2}\pi^{2}} \left[\frac{1}{s} - \frac{s}{s^{2} + c^{2}\pi^{2}}\right]$$

$$u(x,t) = \frac{\sin(\pi x)}{c^{2}\pi^{2}} \mathcal{L}^{-1} \left[\frac{1}{s} - \frac{s}{s^{2} + (c\pi)^{2}}\right]$$

$$\mathbf{u}(\mathbf{x},t) = \frac{\sin(\pi x)}{c^{2}\pi^{2}} \left[1 - \cos(\mathbf{c}\pi t)\right]$$

NEXT:

Solution of non-linear PDE, by the combined Laplace transform and the new Modified Variational Iteration Method.

SOLUTION OF NON-LINEAR PARTIAL DIFFERENTIAL EQUATION BY THE COMBINED LAPLACE TRANSFORM METHOD AND THE NEW MODIFIED VARIATIONAL ITERATION METHOD

Presenting a reliable combined Laplace transform and the new modified varitional Iteration method to solve some non-linear Partial Differential Equations. This method is more efficient and easy to handle non-linear PDEs.

Recall,

$$\mathcal{L}\left(\frac{\partial f(x,t)}{\partial t}\right) = sF(x,s) - f(x,0)$$

$$\mathcal{L}\left(\frac{\partial^2 f(x,t)}{\partial t^2}\right) = s^2 F(x,s) - sf(x,0) - \frac{\partial f(x,0)}{\partial t}$$

Where F(x, s) is the Laplace transform of (x, t) [x is considered as a dummy variable and t, a parameter].

Illustrating the basic concept of <u>He's Variational Iteration Method</u>, we consider the following general differential equations:

$$Lu(x,t) + Nu(x,t) = g(x,t) - - - - - - (i)$$
 with the initial condition, $u(x,0) = G(x) - - - (ii)$

Where L is a linear operator of the first Order, N is a non-linear operator and g(x,t) is non-homogenous term. According to Variational Iteration Method, we can construct a correction functional as follows:

$$u_{n+1} = u_n + \int_0^t \lambda \left[LU(x,s) + N(x,s) - g(x,s) \right] ds - - - - (iii)$$

where λ is a Lagrange Multiplier ($\lambda = -1$), the subscripts 'n' denotes the nth approximation, \bar{U}_n is considered as a restricted variation, i.e $\partial \bar{U}_n = 0$.

Equation (iii) is called a Correction Functional

Obtaining the Lagrange Multiplier ' λ ' by using Integration by Part of Equation (i), but the Lagrange Multiplier is of the form $\lambda = \lambda(x, t)$.

Then, Laplace transform of equation (iii), then the correction functional will be in the form:

$$\mathcal{L}\left[u_{n+1}(x,t)\right] = \mathcal{L}\left[u_n(x,t)\right] + \mathcal{L}\left[\int_0^t \lambda(x,t) \left(Lu_n(x,s) + Nu_n(x,s) - g(x,s)\right) ds\right], \ n \geq 0 - - - - - (iv)$$

Therefore,

$$\mathcal{L}[u_{n+1}(x,t)] = \mathcal{L}[u_n(x,t)] + \lambda [Lu_n(x,t) + Nu_n(x,t) - g(x,t)] - - - - - (v)$$

To find the optimal value of $\lambda(x,t)$, we first take the Variation with respect to $u_n(x,t)$ and in such a case, the integration is basically the single convolution to t, and hence, Laplace transform is appropriate to use.

thus:

$$\frac{\partial}{\partial u_n} \mathcal{L}\left[u_n(x,t)\right] + \mathcal{L}\left[\lambda(x,t)\right] \frac{\partial}{\partial u_n} \mathcal{L}\left[Lu_n(x,t) + Nu_n(x,t) - g(x,t)\right] - - - (vi)$$

Equation (vi) becomes,

$$\mathcal{L}\left[\partial u_{n+1}(x,t)\right] = \mathcal{L}\left[\partial u_n(x,t)\right] + \mathcal{L}\left[\lambda(x,t)\right] \partial \mathcal{L}\left[Lu_n(x,t)\right] - - - - - - (vii)$$
{i.e $\partial N\bar{u}_n(x,t) = 0$ and $\partial g(x,t) = 0$ }

We assume that L is a linear first-order Partial Differential Operator in this chapter given by $\frac{\partial}{\partial t}$ then, equation (vii) can be written in the form

$$\mathcal{L}\left[\partial u_{n+1}(x,t)\right] = \mathcal{L}\left[\partial u_{n}(x,t)\right] + \mathcal{L}\left[\lambda(x,t)\right]\left[s\mathcal{L}\partial u_{n}(x,t)\right]$$

the extreme condition of $u_{n+1}(x,t)$ requires that $\partial u_{n+1}(x,t) = 0$

$$\implies 0 = \mathcal{L} \left[\partial u_n(x,t) \right] \left[1 + s \mathcal{L} \left[\lambda(x,t) \right] \right]$$

$$\implies 1 + s\mathcal{L}\left[\lambda(x,t)\right] = 0$$

$$\Longrightarrow s\mathcal{L}\left[\lambda(x,t)\right] = -1$$

$$\Longrightarrow \mathcal{L}\left[\lambda(x,t)\right] = \frac{-1}{s}$$

Taking the Laplace Inverse of both sides

$$\lambda(x,t) = \mathcal{L}^{-1} \left[\frac{-1}{s} \right]$$

$$\lambda(x,t) = -1$$

This implies $\lambda = -1$

Substituting $(\lambda = -1)$ in equation (iii)

$$u_{n+1} = u_n - \int_0^t \left[Lu_n(x,s) + N\bar{u}_n(x,s) - g(x,s) \right] ds - - - - - - - - (viii)$$

The successive approximation ' u_{n+1} ' of the solution 'u' will be readily obtained by using the determined Lagrange Multiplier and any selective function u_n consequently, the solution is given by:

$$u(x,t) = \lim_{x \to \infty} u_n(x,t)$$

Also, from equation (i)

i.e
$$LU(x,t) + Nu(x,t) = g(x,t) - - - - - - (*)$$

taking the Laplace transform of both sides, we have

$$\mathcal{L}\left[LU(x,t)\right] + \mathcal{L}\left[Nu(x,t)\right] = \mathcal{L}\left[g(x,t)\right]$$

Using the differential property of Laplace transform and initial condition (ii), we have:

$$s\mathcal{L}\left[u_{x,t}\right] - h(x) = \mathcal{L}\left[g(x,t)\right] - \mathcal{L}\left[Nu(x,t)\right] - - - - - - - - (**)$$

Applying the inverse Laplace transform on both side of the equation (**), we find:

$$u(x,t) = G(x,t) - \mathcal{L}^{-1} \left[\frac{1}{s} \mathcal{L} \left[(Nu(x,t)) \right] \right] - - - - - (***)$$

Where G(x,t) represents the terms arising from the source term and the prescribed initial condition $\left[i.e\ G(x,t) = \mathcal{L}^{-1}\left\{\frac{1}{s}\left[\mathcal{L}\left[g(xt,)\right] + h(x)\right]\right\}\right]$

Taking the first Parital derivates with respect to 't' of equation (***) to obtain:

$$\frac{\partial}{\partial t}u(x,t) = \frac{\partial}{\partial t}G(x,t) - \frac{\partial}{\partial t}\mathcal{L}^{-1}\left\{\frac{1}{s}\mathcal{L}\left[Nu(xt,t)\right]\right\} - - - - - (****)$$

By the correction functional of the Variation iteration method:

$$u_{n+1}(x,t) = u_n - \int_0^t \left\{ (u_n)_1(x,s) - \frac{\partial}{\partial s} G(x,s) + \frac{\partial}{\partial s} \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[Nu(x,s) \right] \right\} \right\} ds$$

or

$$u_{n+1}(x,t) = G(x,t) - \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[N u_n(x,t) \right] \right\} - - - - - - - (* * **)$$

Equation (****) is the new modified correction functional of Laplace transform and the Variational Iteration Method, and the solution is given by:

$$u(x,t) = \lim_{u \to \infty} u_n(x,t)$$

<u>Next:</u> Solving some non-linear PDE, by using the new modified variational iteration Laplace transformation method:

Examples:

(1)
$$\frac{\partial u}{\partial t} = \left(\frac{\partial u}{\partial x}\right)^2 + u\frac{\partial^2 u}{\partial x^2}$$
; $u(x,0) = x^2$

Solution:

Given
$$u_t = u_x^2 + u u_{xx}$$
; $u(x,0) = x^2$

Taking Laplace transform, subject to the initial condition, we have:

$$\mathcal{L}\left[u_{t}\right] = \mathcal{L}\left[u_{x}^{2}\right] + \mathcal{L}\left[uu_{xx}\right]$$

$$s\mathcal{L}\left[u(x,t)\right] - u(x,0) = \mathcal{L}\left[u_x^2 + uu_{xx}\right]$$

$$s\mathcal{L}\left[u(x,t)\right] - x^2 = \mathcal{L}\left[u_x^2 + uu_{xx}\right]$$

$$\mathcal{L}\left[u(x,t)\right] = \frac{x^2}{s} + \frac{1}{s}\mathcal{L}\left[u_x^2 + uu_{xx}\right]$$

Taking the Inverse Laplace transform to obtain:

$$u(x,t) = \mathcal{L}^{-1} \left[\frac{x^2}{s} \right] + \mathcal{L}^{-1} \left[\frac{1}{s} \mathcal{L} \left[u_x^2 + u u_{xx} \right] \right]$$

$$u(x,t) = x^2 + \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[u_n^2 + u u_{xx} \right] \right\}$$
 The new correction functional is given as:

$$u_{n+1}(x,t) = x^2 + \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[(u_n)_x + u_n(u_n)_{xx} \right] \right\} \quad n \ge 0$$

The solution in series form is given by:

 $u_1(x,t) = x^2 + 6x^2t$

$$u_0(x,t) = x^2$$
 [or $u_0(x,t) = u(x,0)$]

$$u_{1}(x,t) = x^{2} + \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[(u_{0})_{x}^{2} + (u_{0}) (u_{0})_{xx} \right] \right\}$$

$$u_{1}(x,t) = x^{2} + \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[4x^{2} + 2x^{2} \right] \right\}$$

$$= x^{2} + \mathcal{L}^{-1} \left\{ \frac{1}{s} \left[\frac{4x^{2}}{s} + \frac{2x^{2}}{s} \right] \right\}$$

$$= x^{2} + \mathcal{L}^{-1} \left\{ \frac{6x^{2}}{s^{2}} \right\}$$

$$u_{2}(x,t) = x^{2} + \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[(u_{1})_{x}^{2} + (u_{1}) (u_{1})_{xx} \right] \right\}$$

$$u_{2}(x,t) = x^{2} + \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[(2x + 12xt)^{2} + (x^{2} + 6x^{2}t)(2 + 12t) \right] \right\}$$

$$= x^{2} + \mathcal{L}^{-1} \left\{ \frac{1}{s} \mathcal{L} \left[6x^{2} + 72x^{2}t + 216x^{2}t^{2} \right] \right\}$$

$$= x^{2} + \mathcal{L}^{-1} \left\{ \frac{1}{s} \left[\frac{6x^{2}}{s} + \frac{72x^{2}}{s^{2}} + \frac{216x^{2} \cdot 2}{s^{3}} \right] \right\}$$

$$= x^{2} + \mathcal{L}^{-1} \left[\frac{6x^{2}}{s^{2}} + \frac{72x^{2}}{s^{3}} + \frac{432x^{2}}{s^{4}} \right]$$

$$u_1(x,t) = x^2 + 6x^2t + 36x^2t^2 + 72x^2t^3$$

The series solution is given by:

(2)
$$u_{tt}(x,t) - u_{xx}(x,t) + u^{2}(x,t) = x^{2}t^{2}$$
, $u(x,0) = 0$, $\frac{\partial u(x,0)}{\partial u} = x$
 $\mathcal{L}[u_{tt}] = \mathcal{L}[x^{2}t^{2}] + \mathcal{L}[u_{xx} - u^{2}]$
 $s^{2}\mathcal{L}[u(x,t)] - su(x,0) - \frac{\partial u(x,0)}{\partial t} = \frac{2x^{2}}{s^{3}} + \mathcal{L}[u_{xx} - u^{2}]$

$$s^{2}\mathcal{L}\left[u(x,t)\right] = \frac{2x^{2}}{s^{3}} + x + \mathcal{L}\left[u_{xx} - u^{2}\right]$$

$$\mathcal{L}\left[u(x,t)\right] = \frac{2x^{2}}{s^{5}} + \frac{x}{s^{2}} + \frac{1}{s^{2}}\mathcal{L}\left[u_{xx} - u^{2}\right]$$

$$u(x,t) = \frac{x^{2}t^{4}}{12} + xt + \mathcal{L}^{-1}\left\{\frac{1}{s^{2}}\mathcal{L}\left[u_{xx} - u^{2}\right]\right\}$$

$$u_{n+1}(x,t) = xt + \frac{x^{2}t^{4}}{12} + \mathcal{L}^{-1}\left\{\frac{1}{s^{2}}\mathcal{L}\left[(u_{n})_{xx} - (u_{n})^{2}\right]\right\}$$

$$u_{1}(x,t) = xt + \frac{x^{2}t^{4}}{12} + \mathcal{L}^{-1}\left\{\frac{1}{s^{2}}\mathcal{L}\left[-x^{2}t^{2}\right]\right\}$$

$$u_{1}(x,t) = xt + \frac{x^{2}t^{4}}{12} - \frac{x^{2}t^{4}}{12} = xt$$

$$= xt$$

$$u(x,t) = xt$$