

## 1. General description

The HEF4017B is a 5-stage Johnson decade counter with ten spike-free decoded active HIGH outputs (Q0 to Q9), an active LOW carry output from the most significant flip-flop ( $\bar{Q}_5\text{-}9$ ), active HIGH and active LOW clock inputs ( $CP_0$ ,  $\bar{CP}_1$ ) and an overriding asynchronous master reset input (MR).

The counter is advanced by either a LOW-to-HIGH transition at  $CP_0$  while  $\bar{CP}_1$  is LOW or a HIGH-to-LOW transition at  $\bar{CP}_1$  while  $CP_0$  is HIGH (see Table 3).

When cascading counters, the  $\bar{Q}_5\text{-}9$  output, which is LOW while the counter is in states 5, 6, 7, 8, and 9, can be used to drive the  $CP_0$  input of the next counter. A HIGH on MR resets the counter to zero ( $Q_0 = \bar{Q}_5\text{-}9 = \text{HIGH}$ ;  $Q_1$  to  $Q_9 = \text{LOW}$ ) independent of the clock inputs ( $CP_0$ ,  $\bar{CP}_1$ ).

Automatic counter code correction is provided by an internal circuit: following any illegal code the counter returns to a proper counting mode within 11 clock pulses.

Schmitt trigger action makes the clock inputs highly tolerant of slower rise and fall times.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

## 2. Features and benefits

- Automatic counter correction
- Tolerant of slow clock rise and fall times
- Fully static operation
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
  - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2000 V
  - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1000 V
- Specified from -40 °C to +125 °C

## 3. Ordering information

Table 1. Ordering information

Type number	Package				Version
	Temperature range	Name	Description		
HEF4017BT	-40 °C to +125 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm		<a href="#">SOT109-1</a>

## 4. Functional diagram

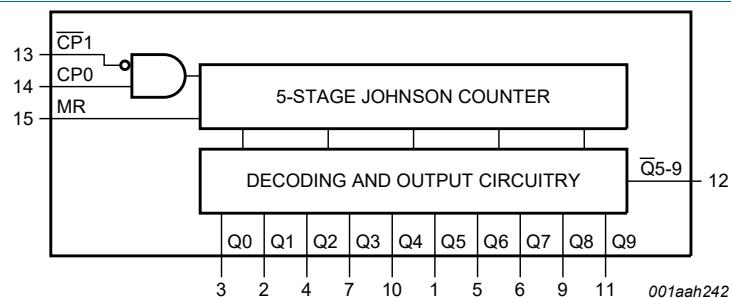


Fig. 1. Functional diagram

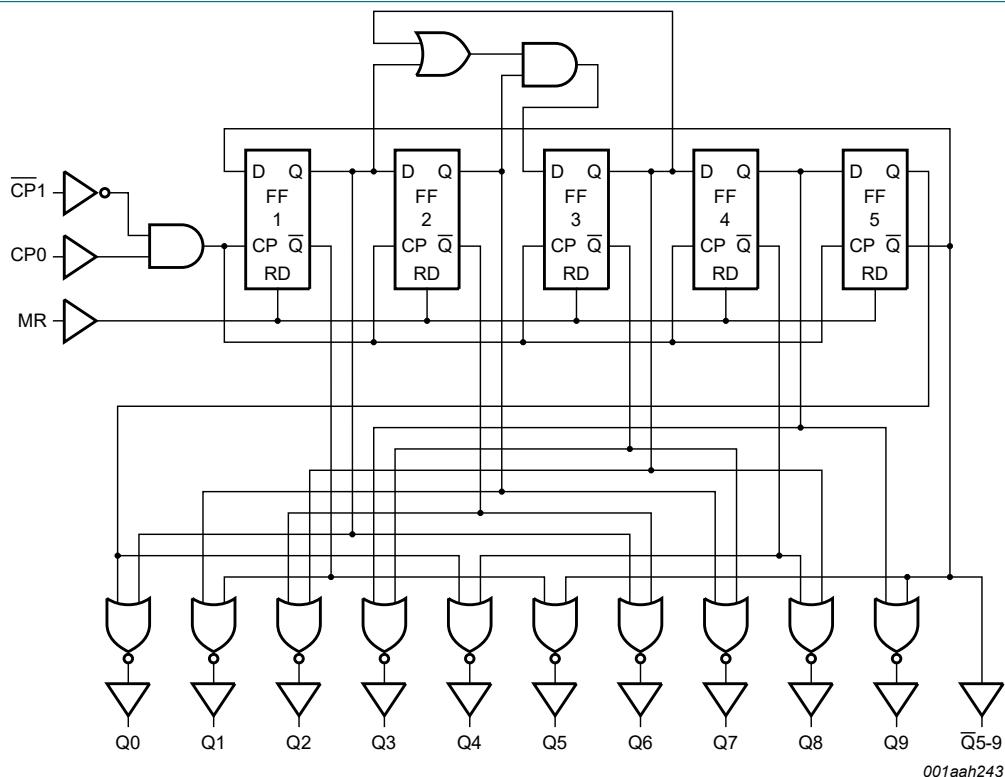


Fig. 2. Logic diagram

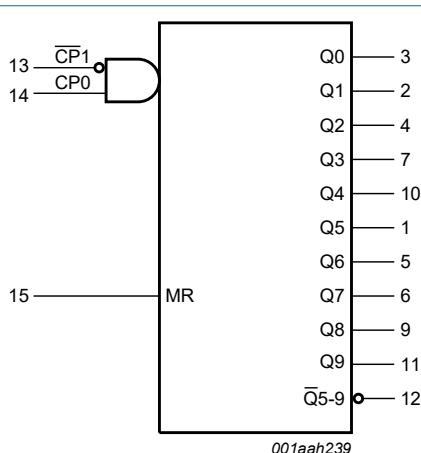


Fig. 3. Logic symbol

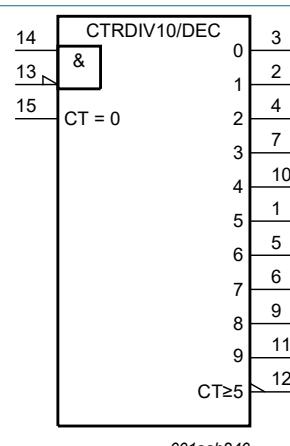


Fig. 4. IEE logic symbol

## 5. Pinning information

### 5.1. Pinning

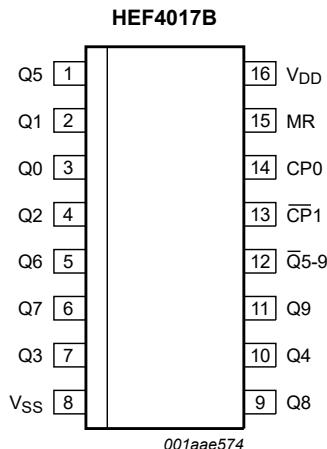


Fig. 5. Pin configuration

### 5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
Q0, Q1, Q2, Q3, Q4, Q5, Q6, Q7, Q8, Q9	3, 2, 4, 7, 10, 1, 5, 6, 9, 11	decoded output
V <sub>SS</sub>	8	ground supply voltage
Q̄5-9	12	carry output (active LOW)
CP1	13	clock input (HIGH-to-LOW edge-triggered)
CP0	14	clock input (LOW-to-HIGH edge-triggered)
MR	15	master reset input
V <sub>DD</sub>	16	supply voltage

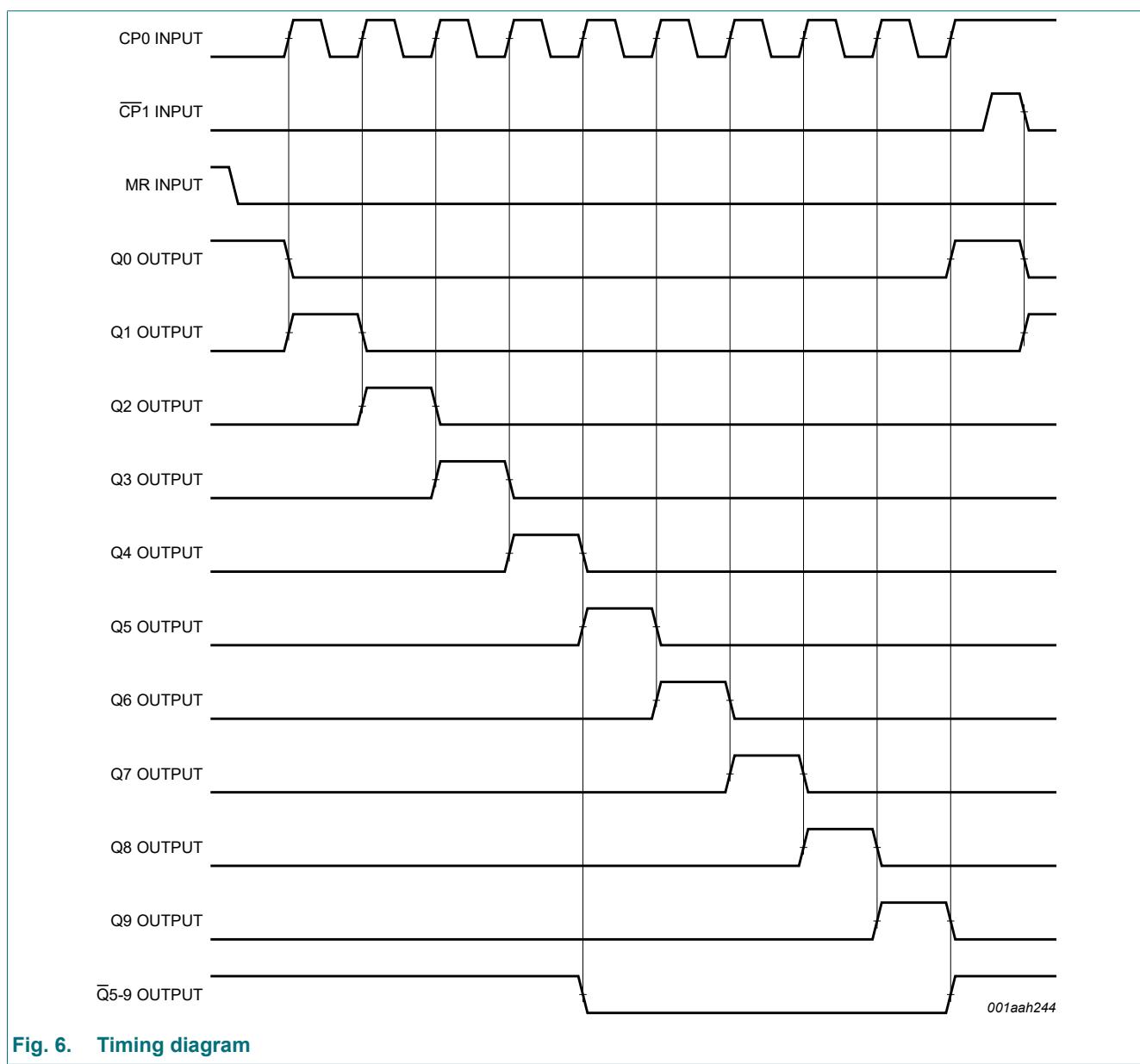
## 6. Functional description

**Table 3. Function table**

H = HIGH voltage level; L = LOW voltage level; X = don't care;

↑ = positive-going transition; ↓ = negative-going transition.

MR	CP0	CP1	Operation
H	X	X	$Q_0 = \bar{Q}_{5-9} = H$ ; $Q_1$ to $Q_9 = L$
L	H	↓	counter advances
L	↑	L	counter advances
L	L	X	no change
L	X	H	no change
L	H	↑	no change
L	↓	L	no change



**Fig. 6. Timing diagram**

## 7. Limiting values

**Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < -0.5 V or V <sub>I</sub> > V <sub>DD</sub> + 0.5 V	-	±10	mA
V <sub>I</sub>	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < -0.5 V or V <sub>O</sub> > V <sub>DD</sub> + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+125	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = -40 °C to +125 °C [1]	-	500	mW
P	power dissipation	per output	-	100	mW

[1] For SOT109-1 (SO16) package: P<sub>tot</sub> derates linearly with 12.4 mW/K above 110 °C.

## 8. Recommended operating conditions

**Table 5. Recommended operating conditions**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V <sub>DD</sub>	supply voltage		3	-	15	V
V <sub>I</sub>	input voltage		0	-	V <sub>DD</sub>	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	-	3.75	μs/V
		V <sub>DD</sub> = 10 V	-	-	0.5	μs/V
		V <sub>DD</sub> = 15 V	-	-	0.08	μs/V

## 9. Static characteristics

**Table 6. Static characteristics**

V<sub>SS</sub> = 0 V; V<sub>I</sub> = V<sub>SS</sub> or V<sub>DD</sub> unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> = -40 °C		T <sub>amb</sub> = 25 °C		T <sub>amb</sub> = 85 °C		T <sub>amb</sub> = 125 °C		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level input voltage	I <sub>O</sub>   < 1 μA	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level input voltage	I <sub>O</sub>   < 1 μA	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub>   < 1 μA; V <sub>I</sub> = V <sub>SS</sub> or V <sub>DD</sub>	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> = -40 °C		T <sub>amb</sub> = 25 °C		T <sub>amb</sub> = 85 °C		T <sub>amb</sub> = 125 °C		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>OL</sub>	LOW-level output voltage	I <sub>O</sub>   < 1 μA; V <sub>I</sub> = V <sub>SS</sub> or V <sub>DD</sub>	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
		V <sub>O</sub> = 4.6 V	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		V <sub>O</sub> = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
I <sub>OL</sub>	LOW-level output current	V <sub>O</sub> = 0.4 V	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
		V <sub>O</sub> = 0.5 V	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
I <sub>I</sub>	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μA
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A; V <sub>I</sub> = V <sub>SS</sub> or V <sub>DD</sub>	5 V	-	5	-	5	-	150	-	150	μA
			10 V	-	10	-	10	-	300	-	300	μA
			15 V	-	20	-	20	-	600	-	600	μA
C <sub>I</sub>	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

## 10. Dynamic characteristics

Table 7. Dynamic characteristics

T<sub>amb</sub> = 25 °C; V<sub>SS</sub> = 0 V; for test circuit see Fig. 10

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula [1]	Min	Typ	Max	Unit
t <sub>PHL</sub>	HIGH to LOW propagation delay	CP0, CP1 → Q0 to Q9; see Fig. 7	5 V	113 ns + (0.55 ns/pF)C <sub>L</sub>	-	140	280	ns
			10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		CP0, CP1 → Q5-9; see Fig. 7	5 V	118 ns + (0.55 ns/pF)C <sub>L</sub>	-	145	290	ns
			10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		MR → Q1 to Q9; see Fig. 8	5 V	88 ns + (0.55 ns/pF)C <sub>L</sub>	-	115	230	ns
			10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula [1]	Min	Typ	Max	Unit
t <sub>PLH</sub>	LOW to HIGH propagation delay	CP0, CP1 → Q0 to Q9; see <a href="#">Fig. 7</a>	5 V	98 ns + (0.55 ns/pF)C <sub>L</sub>	-	125	250	ns
			10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		CP0, CP1 → Q5-9; see <a href="#">Fig. 7</a>	5 V	98 ns + (0.55 ns/pF)C <sub>L</sub>	-	125	250	ns
			10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		MR → Q5-9; see <a href="#">Fig. 8</a>	5 V	83 ns + (0.55 ns/pF)C <sub>L</sub>	-	110	220	ns
			10 V	34 ns + (0.23 ns/pF)C <sub>L</sub>	-	45	90	ns
			15 V	27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns
		MR → Q0; see <a href="#">Fig. 8</a>	5 V	103 ns + (0.55 ns/pF)C <sub>L</sub>	-	130	260	ns
			10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	105	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	75	ns
t <sub>t</sub>	transition time	see <a href="#">Fig. 7</a>	5 V	[2] 10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>h</sub>	hold time	CP0 → CP1; see <a href="#">Fig. 9</a>	5 V		90	45	-	ns
			10 V		40	20	-	ns
			15 V		20	10	-	ns
		CP1 → CP0; see <a href="#">Fig. 9</a>	5 V		80	40	-	ns
			10 V		40	20	-	ns
			15 V		30	10	-	ns
t <sub>w</sub>	pulse width	CP0 input LOW; minimum width; see <a href="#">Fig. 8</a>	5 V		80	40	-	ns
			10 V		40	20	-	ns
			15 V		30	15	-	ns
		CP1 input HIGH; minimum width; see <a href="#">Fig. 8</a>	5 V		80	40	-	ns
			10 V		40	20	-	ns
			15 V		30	15	-	ns
		MR input HIGH; minimum width; see <a href="#">Fig. 8</a>	5 V		50	25	-	ns
			10 V		30	15	-	ns
			15 V		20	10	-	ns
t <sub>rec</sub>	recovery time	MR input; see <a href="#">Fig. 8</a>	5 V		60	30	-	ns
			10 V		30	15	-	ns
			15 V		20	10	-	ns
f <sub>max</sub>	maximum frequency	see <a href="#">Fig. 8</a>	5 V		6	12	-	MHz
			10 V		12	30	-	MHz
			15 V		15	30	-	MHz

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

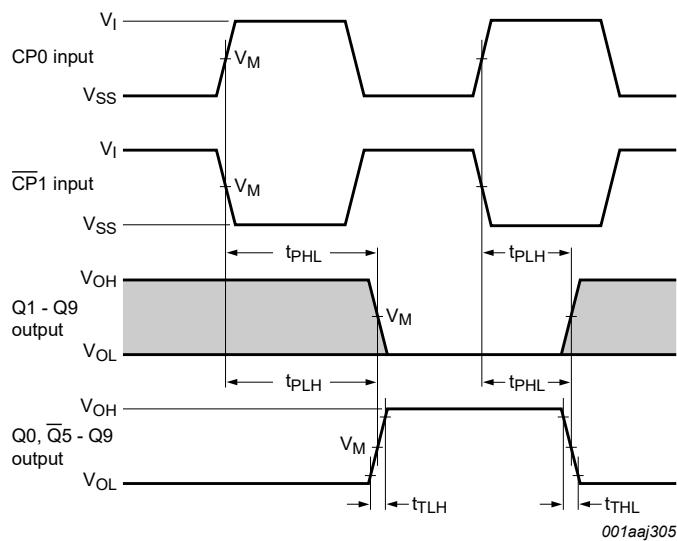
[2] t<sub>t</sub> is the same as t<sub>THL</sub> and t<sub>T LH</sub>.

**Table 8. Dynamic power dissipation  $P_D$** 

$P_D$  can be calculated from the formulas shown.  $V_{SS} = 0 \text{ V}$ ;  $t_r = t_f \leq 20 \text{ ns}$ ;  $T_{amb} = 25^\circ\text{C}$ .

Symbol	Parameter	V <sub>DD</sub>	Typical formula for P <sub>D</sub> (μW)	where:
P <sub>D</sub>	dynamic power dissipation	5 V	$P_D = 500 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$	$f_i$ = input frequency in MHz; $f_o$ = output frequency in MHz; $C_L$ = output load capacitance in pF; $V_{DD}$ = supply voltage in V; $\sum(C_L \times f_o)$ = sum of the outputs.
		10 V	$P_D = 2200 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$	
		15 V	$P_D = 6000 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$	

### 10.1. Waveforms and test circuit

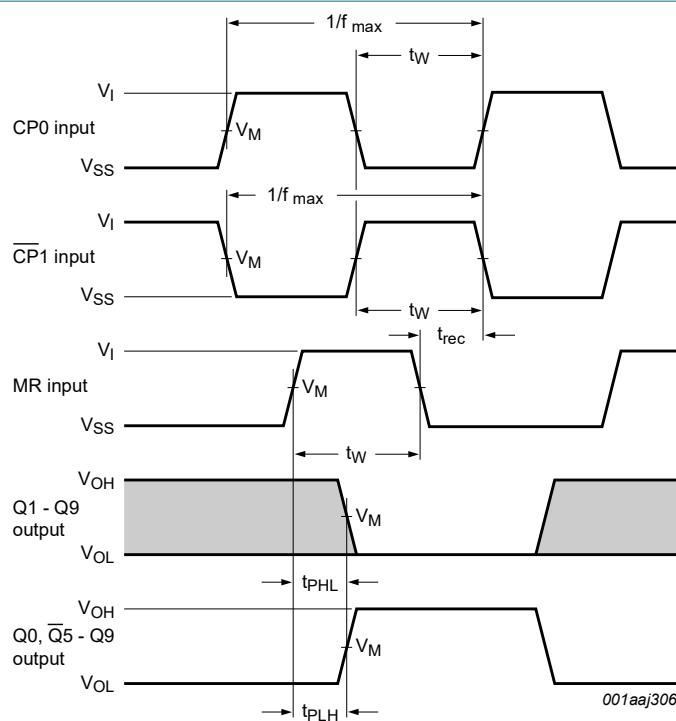


Conditions:  $\overline{CP1} = \text{LOW}$ , while CP0 triggers on a LOW-to-HIGH transition.  $\overline{CP1}$  triggers on a HIGH-to-LOW transition.

The shaded areas indicate where the output state is set by the input count.

Measurement points given in [Table 9](#).

**Fig. 7. Propagation delays for CP0,  $\overline{CP1}$  to Qn,  $\overline{Q5-9}$  outputs and the output transition times**

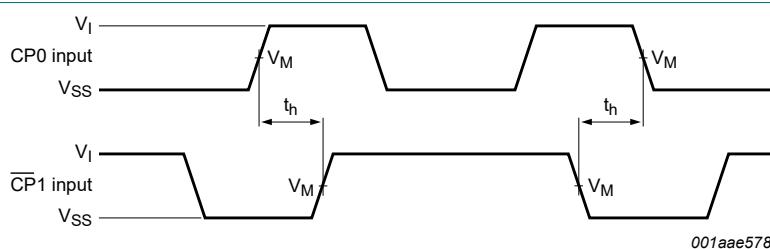


Conditions:  $\bar{CP}1$  = LOW, while CP0 triggers on a LOW-to-HIGH transition;  $t_W$  and  $t_{rec}$  are measured when CP0 = HIGH;  $\bar{CP}1$  triggers on a HIGH-to-LOW transition.

The shaded areas indicate where the output state is set by the input count.

Measurement points given in [Table 9](#).

**Fig. 8. Minimum pulse width for CP0,  $\bar{CP}1$  and MR input; maximum frequency for CP0 and  $\bar{CP}1$  input; recovery time for MR and the MR input to  $Q_n$  and  $Q_5$ -9 output propagation delays**



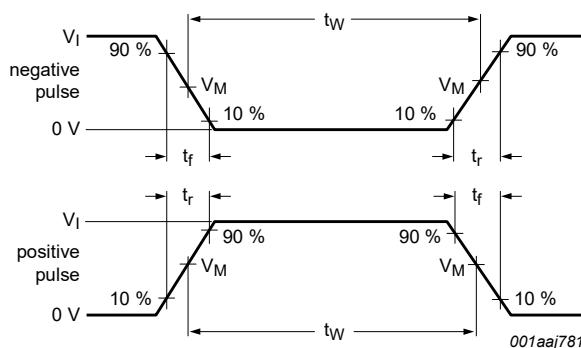
Hold times are shown as positive values, but may be specified as negative values.

Measurement points given in [Table 9](#).

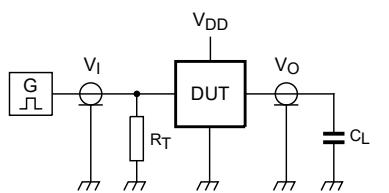
**Fig. 9. Hold times for CP0 to  $\bar{CP}1$  and  $\bar{CP}1$  to CP0**

**Table 9. Measurement points**

Supply voltage	Input	Output
$V_{DD}$	$V_M$	$V_M$
5 V to 15 V	$0.5 \times V_{DD}$	$0.5 \times V_{DD}$



a. Input waveforms



b. Test circuit

Test data is given in [Table 10](#).

Definitions test circuit:

$C_L$  = load capacitance including jig and probe capacitance;

$R_T$  = termination resistance should be equal to the output impedance  $Z_0$  of the pulse generator.

Fig. 10. Test circuit for measuring switching times

Table 10. Test data

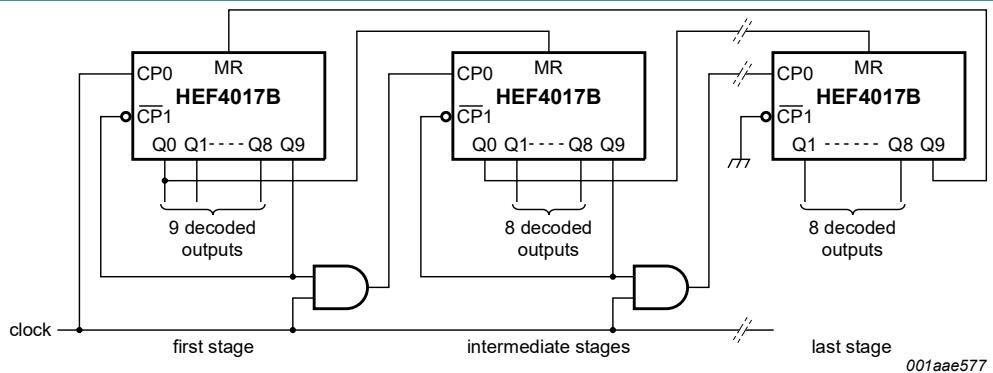
Supply voltage	Input	Load
$V_{DD}$	$V_I$	$t_r, t_f$
5 V to 15 V	$V_{SS}$ or $V_{DD}$	$\leq 20 \text{ ns}$
		50 pF

## 11. Application information

Some examples of applications for the HEF4017B are:

- Decade counter with decimal decoding
- 1 out of n decoding counter (when cascaded)
- Sequential controller
- Timer

[Fig. 11](#) shows a technique for extending the number of decoded output states for the HEF4017B. Decoded outputs are sequential within each stage and from stage to stage, with no dead time (except propagation delay).



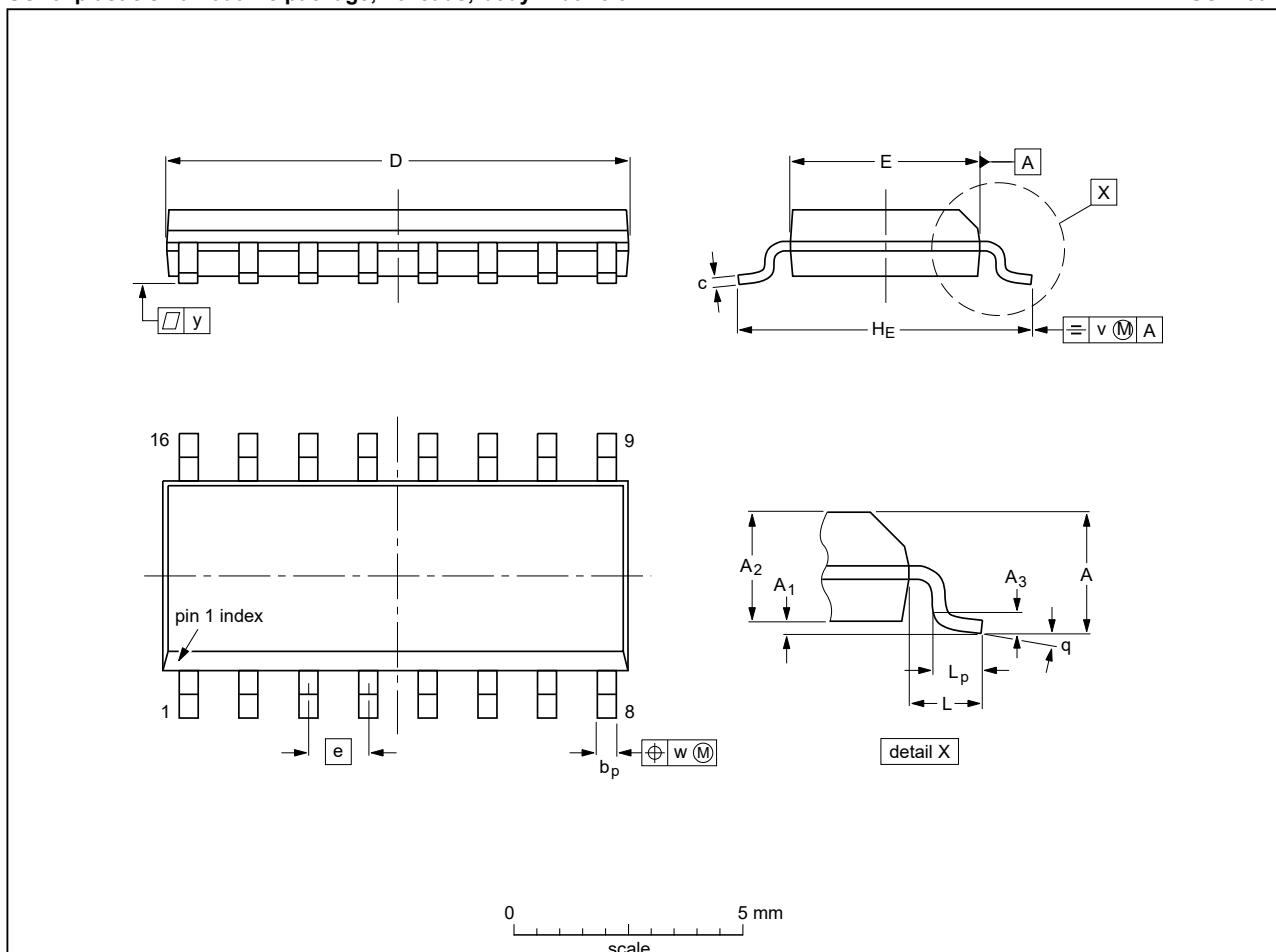
Enabling the counter on  $\overline{CP1}$  when CP0 is HIGH, or on CP0 when  $\overline{CP1}$  is LOW, causes an extra count.

**Fig. 11. Counter expansion**

## 12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



Dimensions (inch dimensions are derived from the original mm dimensions)

Unit	A	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	v	w	y	θ	
mm	max 1.75	0.25			0.51	0.25	10.0	4.0		6.2		1.27	0.2	0.25	0.1	8°	
mm	nom			0.25					1.27		1.05					0°	
mm	min 0.10	1.25		0.31	0.10	9.8	3.8		5.8		0.4					0°	
inches	max 0.069	0.010			0.020	0.010	0.394	0.16		0.244		0.05		0.008	0.01	0.004	8°
inches	nom			0.01					0.05		0.041						0°
inches	min 0.004	0.049		0.012	0.004	0.386	0.15		0.228		0.016						0°

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

sot109-1\_po

Outline version	References				European projection	Issue date
	IEC	JEDEC	JEITA			
SOT109-1		MS-012				03-02-19 23-10-27

Fig. 12. Package outline SOT109-1 (SO16)

## 13. Abbreviations

**Table 11. Abbreviations**

Acronym	Description
ANSI	American National Standards Institute
CDM	Charged Device Model
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
ESDA	ElectroStatic Discharge Association
HBM	Human Body Model
JEDEC	Joint Electron Device Engineering Council

## 14. Revision history

**Table 12. Revision history**

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4017B v.10	20240808	Product data sheet	-	HEF4017B v.9
Modifications:			<ul style="list-style-type: none"> <li>• <a href="#">Section 2</a>: ESD specification updated according to the latest JEDEC standard.</li> <li>• <a href="#">Fig. 12</a>: Aligned SO package outline drawing to JEDEC MS-012</li> <li>• <a href="#">Table 4</a>: Derating values for <math>P_{tot}</math> total power dissipation updated.</li> <li>• The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>• Legal texts have been adapted to the new company name where appropriate.</li> </ul>	
HEF4017B v.9	20160408	Product data sheet	-	HEF4017B v.8
Modifications:			<ul style="list-style-type: none"> <li>• Type number HEF4017BP (SOT38-4) removed.</li> </ul>	
HEF4017B v.8	20111118	Product data sheet	-	HEF4017B v.7
HEF4017B v.7	20110914	Product data sheet	-	HEF4017B v.6
HEF4017B v.6	20091105	Product data sheet	-	HEF4017B v.5
HEF4017B v.5	20090709	Product data sheet	-	HEF4017B v.4
HEF4017B v.4	20081209	Product data sheet	-	HEF4017B_CNV v.3
HEF4017B_CNV v.3	19950101	Product specification	-	HEF4017B_CNV v.2
HEF4017B_CNV v.2	19950101	Product specification	-	-

## 15. Legal information

### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
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