

**5.3** For  $T$  – Flip-Flop,

$$Q(t+1) = TQ' + T'Q = T \oplus Q$$

$$Q'(t+1) = [T \oplus Q]'$$

$$= T'Q' + TQ$$

**5.5** State table is also called as transition table.

The truth table describes a combinational circuit.

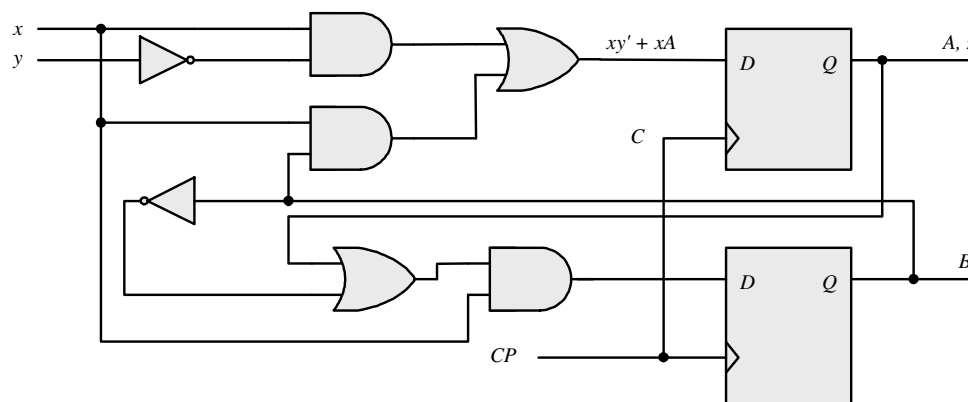
The state table describes a sequential circuit.

The characteristic table describes the operation of a flip-flop.

The excitation table gives the values of flip-flop inputs for a given state transition.

The four equations correspond to the algebraic expression of the four tables.

**5.6 (a)**



**(b)**

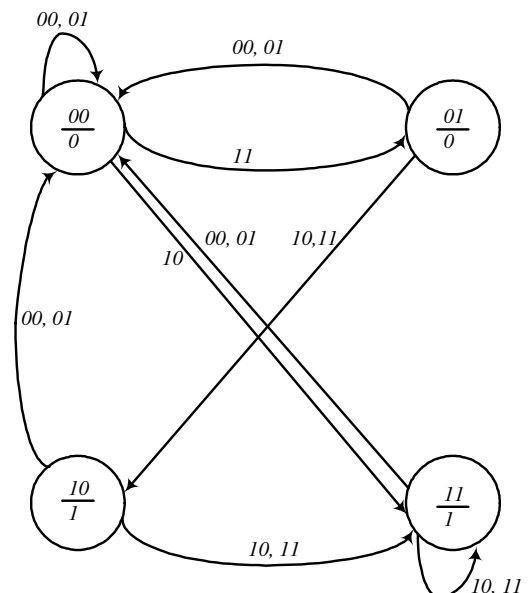
$$A(t+1) = xy' + xB$$

$$B(t+1) = xA + xB'$$

$$z = A$$

Present state		Inputs		Next state		Output
A	B	x	y	A	B	z
0	0	0	0	0	0	0
0	0	0	1	0	0	0
0	0	1	0	1	1	0
0	0	1	1	0	1	0
0	1	0	0	0	0	0
0	1	0	1	0	0	0
0	1	1	0	1	0	0
0	1	1	1	1	0	0
1	0	0	0	0	0	1
1	0	0	1	0	0	1
1	0	1	0	1	1	1
1	0	1	1	1	1	1
1	1	0	0	0	0	1
1	1	0	1	0	0	1
1	1	1	0	1	1	1
1	1	1	1	1	1	1

**(c)**



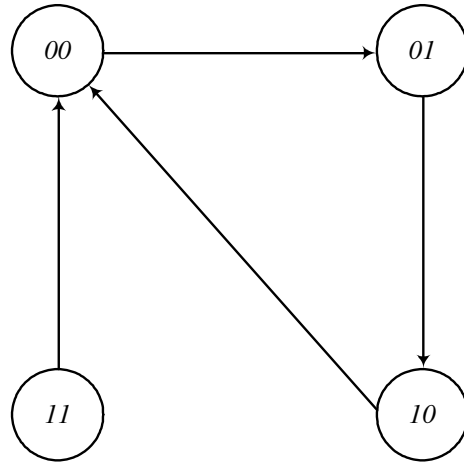
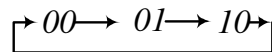
**5.8** A counter with a repeated sequence of 00, 01, 10.

Present state		Next state		FF Inputs	
A	B	A	B	$T_A$	$T_B$
0	0	0	0	0	1
0	1	1	0	1	1
1	0	0	0	1	0
1	1	0	0	1	1

$$T_A = A + B$$

$$T_B = A' + B$$

Repeated sequence:



**5.9 (a)**

$A(t)$	$B(t)$	$x$	$A(t+1)$	$B(t+1)$	$A(t+1):$
0	0	0	0	0	1
0	0	1	1	1	0
0	1	0	0	0	0
0	1	1	1	1	0
1	0	0	0	1	1
1	0	1	1	1	0
1	1	0	0	0	1
1	1	1	1	0	1

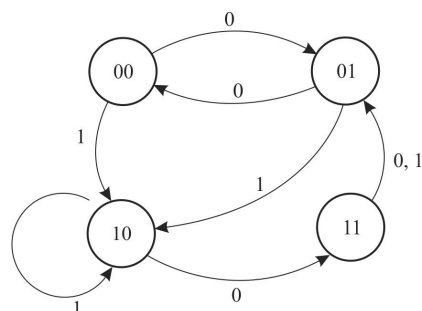
$A \backslash Bx$				
	00	01	11	10
0	0	1	1	0
1	1	1	0	0

$$A(t+1) = A'x + AB'$$

$A \backslash Bx$				
	00	01	11	10
0	1	0	0	0
1	1	0	1	1

$$B(t+1) = B'x' + AB$$

**(b)**



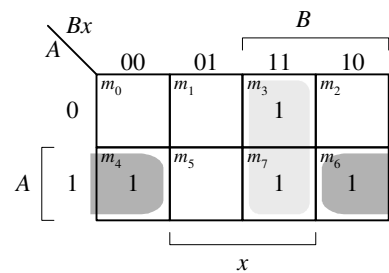
5.14

State	Assignment3
<i>a</i>	00001
<i>b</i>	00010
<i>c</i>	00100
<i>d</i>	01000
<i>e</i>	10000

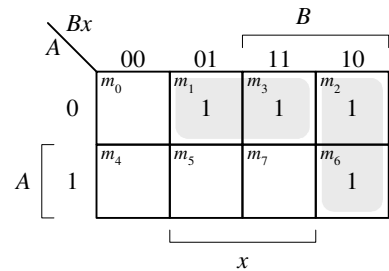
Present State	Next State					Output			
	A	B	C	D	E	$x = 0$	$x = 1$	$x = 0$	$x = 1$
a	0	0	0	0	1	00001	00010	0	0
b	0	0	0	1	0	00100	01000	0	0
c	0	0	1	0	0	00001	01000	0	0
d	0	1	0	0	0	10000	01000	0	1
e	1	0	0	0	0	00001	01000	0	1

5.16 (a)

Present state		Input <i>x</i>	Next state	
<i>A</i>	<i>B</i>		<i>A</i>	<i>B</i>
0	0	0	0	0
0	0	1	0	1
0	1	0	0	1
0	1	1	1	1
1	0	0	1	0
1	0	1	0	0
1	1	0	1	1
1	1	1	1	0



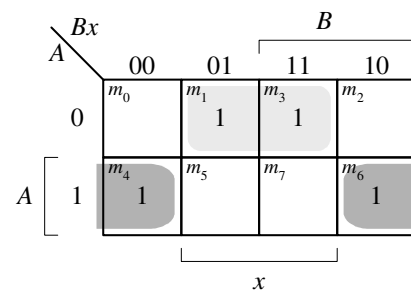
$$D_A = Ax' + Bx$$



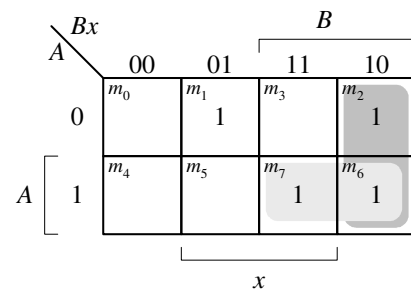
$$D_B = A'x + Bx'$$

(b)

Present state		Input <i>x</i>	Next state	
<i>A</i>	<i>B</i>		<i>A</i>	<i>B</i>
0	0	0	0	0
0	0	1	1	1
0	1	0	0	1
0	1	1	1	0
1	0	0	1	0
1	0	1	0	0
1	1	0	1	1
1	1	1	0	1

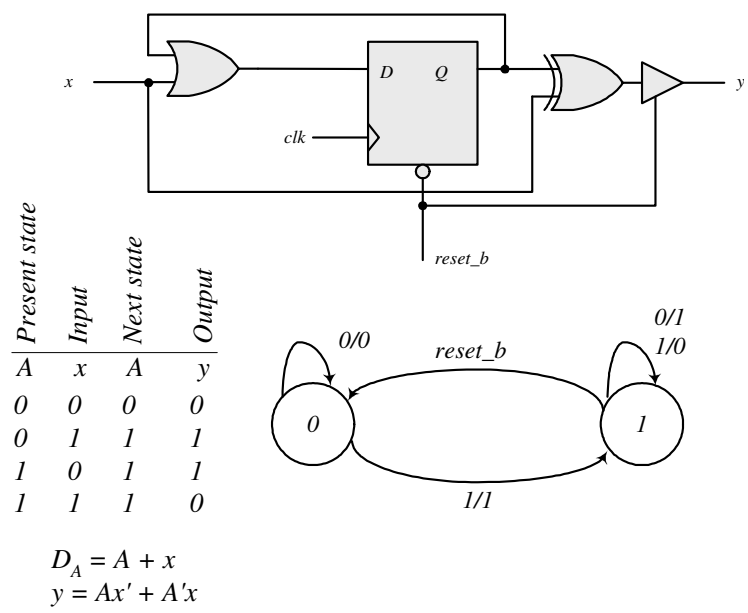


$$D_A = A'x + Ax'$$



$$D_B = AB + Bx'$$

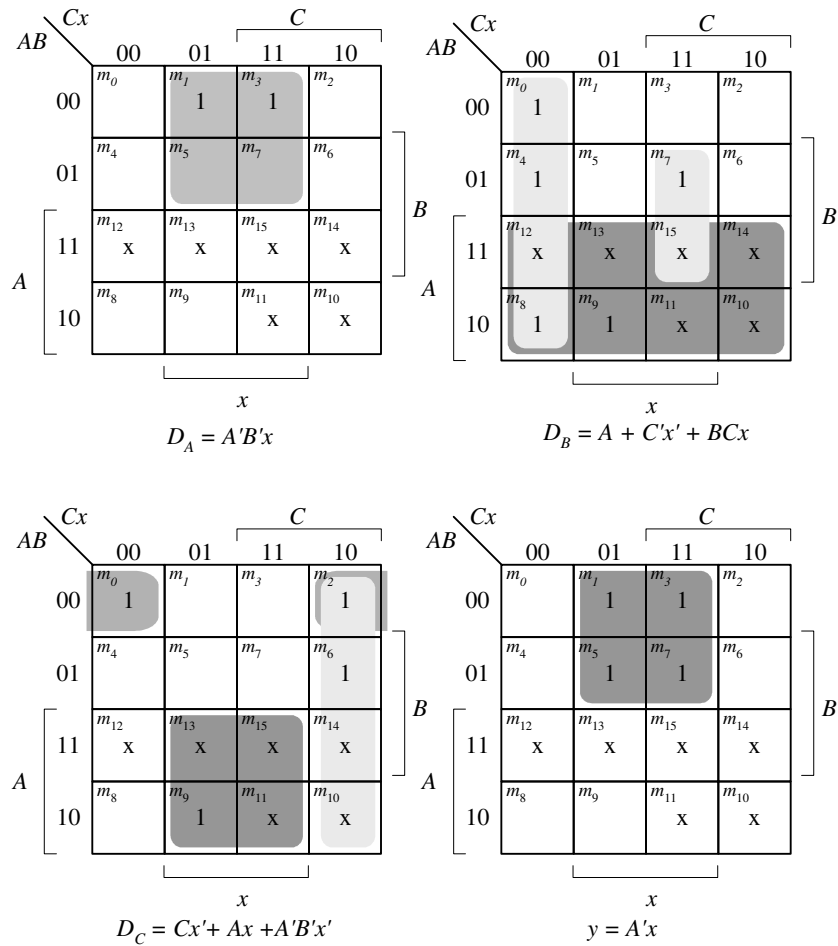
**5.17** The output is 0 for all 0 inputs until the first 1 occurs, at which time the output is 1. Thereafter, the output is the complement of the input. The state diagram has two states. In state 0: output = input; in state 1: output = input'.



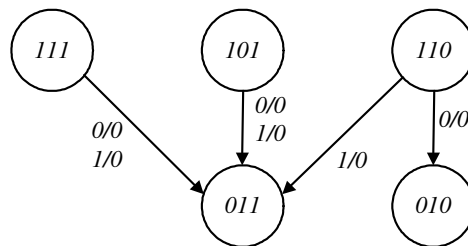
**5.19 (a)** Unused states (see Fig. P5.19): 101, 110, 111.

Present state	Input	Next state	Output
ABC	x	ABC	y
000	0	011	0
000	1	100	1
001	0	001	0
001	1	100	1
010	0	010	0
010	1	000	1
011	0	001	0
011	1	010	1
100	0	010	0
100	1	011	1

$d(A, B, C, x) = \Sigma (10, 11, 12, 13, 14, 15)$



The machine is self-correcting, i.e., the unused states transition to known states.



(b) With JK flip=flops, the state table is the same as in (a).

Flip-flop inputs					
$J_A$	$K_A$	$J_B$	$K_B$	$J_C$	$K_C$
0	x	1	x	1	x
1	x	0	x	0	x
0	x	0	x	x	0
1	x	0	x	x	1
0	x	x	0	0	x
0	x	x	1	0	x
0	x	x	1	x	0
0	x	x	0	x	1
x	1	1	x	0	x
x	1	1	x	1	x

$J_A = B'x$        $K_A = 1$   
 $J_B = A + C'x'$        $K_B = C'x + Cx'$   
 $J_C = Ax + A'B'x'$        $K_C = x$   
 $y = A'x$   
 The machine is self-correcting  
 because  $K_A = 1$ .