Array

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Array in C++

- A set of consecutive memory storing identical data type object,
- int A[100]; float B[30]; Object C[200];
- Direct access, given index i, A[i] gives the i+1st integer stored in array A.
- A, the address where array A begin, an int is 4 bytes, we find A[i] at address A + i, the value is *(A + i).
- It takes constant time to compute the address, then direct access the memory location.
- We are talking about detail implementation, not the abstract data type.

Array, ADT

- A set of pairs < index, value >, a correspondence or a mapping
- The operations
 - Retrieve the value for a given index,
 - store a value to the array at a given index.

- Array can be used to implement other data types,
- Ordered or linear list (store those objects that you can define "linear order"). Ordering is an important information for efficient computation.
- examples are
 - Days of the week, (Sunday, Monday, Tuesday, Wednesday, Thursday, Friday, Saturday).
 - Value of card deck (Ace, 2, 3, 4, 5, 6, 7, 8, 9, 10, Jack, Queen, King).
 - Floor of a building (Basement, Lobby, mezzanine, first, second).
 - Or an empty list ().

Ordered List

- Can be written in the form $(a_0, a_1, \ldots, a_{n-1})$
- operations performed on list (ADT definitions needs data objects and operations (methods))
 - Find the length n of the list.
 - Read list from left to right (or from right to left).
 - Retrieve the *i*th element, $0 \le i < n$.
 - Insert a new element at the position $i, 0 \le i < n$, causing elements numbered i, i + 1, ..., n 1 to become numbered i + 1, i + 2, ..., n.
 - Delete the element at position i, $0 \le i < n$, causing elements numbered i + 1, ..., n 1 to become numbered i, i + 1, ..., n 2.

Ordered List-Implementation Consideration

- Use an array (C++ array).
 - Find the length, $\Theta(1)$.
 - read the list, $\Theta(n)$.
 - Retrieve the *i*th element, $\Theta(1)$.
 - Insert a new element, suppose we know where to insert, first move data around then insert.
 - Delete an element, suppose we know what to delete, delete it and move data around.

Polynominal

- A problem requires ordered list.
- Building ADT for the representation and manipulation of polynominals in a single variable.
- Two such polynominals are $a(x) = 3x^2 + 2x 4$ and $b(x) = x^8 10x^5 3x^3 + 1$
- There are 3 terms in a(x), $3x^2$, 2x, and -4.
- Coefficients of the 3 terms are 3, 2, and -4; the exponents are 2, 1, 0.
- The degree is the largest exponent among the nonzero terms.
- A term can be representated as a pair (coeficient, exponent), such as (3,2), a method that we have chance only display the nonzero terms.

Polynominal

- Operations applied to two polynominals.
- Sum of two polynominals, product of two polynominals
- $a(x) = \sum a_i x^i$ and $b(x) = \sum b_i x^i$; then
- $a(x) + b(x) = \sum (a_i + b_i)x^i$,
- $a(x)b(x) = \sum (a_i x^i \cdot \sum (b_j x^j))$
- also substraction and division

In C++ class class Polynominal { public: Polynominal(); Polynominal Add(Polynominal poly); Polynominal Mult(Polynominal poly); float Eval(float f);What should the private data look like? (detail implementation!)

Polynominal Represnetation

First approach

```
private:

int Degree;

float coef[MaxDegree + 1];
```

- MaxDegree represents the largest-degree polynominal, $n \leq MaxDegree$.
- coef[i] stores a_{n-i} .
- A polynominal a, a.degree = n, $a.coef[i] = a_{n-i}$, $0 \le i \le n$.
- Space MaxDegree is allocated, regarless the number of terms (not a function of input size).

Polynominal Representation
 Second Approach, space needed depend on the degree.

```
private:
    int degree;
    float *coef;
```

and we need the constructor

```
Polynominal :: Polynominal (int d) \\ \{ \\ degree = d; \\ coef = new float [degree + 1]; \\ \}
```

Polynomial Representation

- A problem with the second approach
- Zero terms also take space,
- $a(n) = n^{1000} + 1;$
- It take 1001 memory spaces but there are just only two nonzero terms.

Polynominal Representation, The Third Approach

class Polynominal; // forward declaration

```
class Term {
friend Polynominal;
private:
    float coef;
    int exp;
};
```

The private data members of Polynominal are private:

```
Term *termArray;
int capacity;
int terms;
```

- Third approach fixes the problem with the first and the second approaches.
- Memory required depends on the problem size (number of nonzero terms).
- Addition, $Polynominal\ a$, b, c; c = a + b;
- if (a.termArray[i].exp == b.termArray[j].exp)
- c.termArray[k].exp = (a.termArray[i].exp + b.termArray[j].exp);
- Another example is shown in Figure 2.1. An old implementation using an array.

- Using two arrays, float * coef and int * exp.
- A polynomial a, a.start and a.finish point to start and finish locations where a stored in arrays.
- Figure 2.1.
- A garbage collection problem.
 - compare new and delete operations for different approaches (C++ and the old array approaches)

Sparse Matrices

Matrix

- mathematical object arises in many physical problems.
- Study the way to represent matrices so that the operations to be performed on them can be carried out efficiently.
- A matrix: m rows and n columns, an $m \times n$ matrix, there are mn elements,
- ullet m=n, square matrix.

$$\begin{bmatrix} -27 & 3 & 4 \\ 6 & 82 & -2 \\ 109 & -64 & 11 \\ 12 & 8 & 9 \\ 48 & 27 & 47 \end{bmatrix}$$

 $\begin{bmatrix} 15 & 0 & 0 & 22 & 0 & -15 \\ 0 & 11 & 3 & 0 & 0 & 0 \\ 0 & 0 & 0 & -6 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 91 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 28 & 0 & 0 & 0 \end{bmatrix}$

(1)

(2)

- A matrix can be stored in a C++ 2D array, a[m][n], element a[i][j] can be efficiently access.
- The second matrix contains many zeros, a sparse matrix.
- In practice, many matrices are large but sparse, develope a sparse matrix ADT.

```
class SparseMatrix
{
  public:
     SparseMatrix (int r, int c, int t);
     SparseMatrix Transpose();
     SparseMatrix Add(SparseMatrix b);
     SparseMatrix Multiply(SparseMatrix b);
};
```

Sparse Matrix Representation

- Try not to store zero terms.
- A nonzero term can be represented by a triple < row, col, value >.
- use an array of triples to store the non-zero terms.
- To make operations easier, the non-zero terms are stored according
 - sorted according to row index,
 - sorted according to column index in the same row.

```
class SparseMatrix;
class MatrixTerm {
friend class SparseMatrix;
private:
    int row, col, value;
and in class SparseMatrix;
private:
    int rows, cols, terms, capacity;
    MatrixTerm *smArray;
```

Left, Sparse Matrix of (b), Right, its transpose

	row	col	value		row	col	value
smArray[0]	0	0	15	smArray[0]	0	0	15
smArray[1]	0	3	22	smArray[1]	0	4	91
smArray[2]	0	5	-15	smArray[2]	1	1	11
smArray[3]	1	1	11	smArray[3]	2	1	3
smArray[4]	1	2	3	smArray[4]	2	5	28
smArray[5]	2	3	-6	<i>smArray</i> [5]	3	0	22
smArray[6]	4	0	91	<i>smArray</i> [6]	3	2	-6
smArray[7]	5	2	28	smArray[7]	5	0	-15

Transposing a Matrix

Change row and column, $A = B^T$, A[i][j] = B[j][i]; Direct change row and column in sparse matrix representation, row index is not sorted.

	row	col	value		row	col	\overline{value}
smArray[0]	0	0	15	smArray[0]	0	0	15
smArray [1]	0	3	22	smArray[1]	3	0	22
smArray[2]	0	5	-15	smArray[2]	5	0	-15
smArray[3]	1	1	11	smArray[3]	1	1	11
smArray[4]	1	2	3	smArray[4]	2	1	3
smArray[5]	2	3	-6	smArray[5]	3	2	-6
smArray[6]	4	0	91	smArray[6]	0	4	91
$_smArray$ [7]	5	2	28	smArray[7]	2	5	28

- Try to fix the unsorted problem.
 - observation: row are originally ordered,
 - find all elements in column 0 and store them in row 0, find all elements in column 1, ...
 - to process column i, scan the whole list once,
 - cols, rows, and terms denote number of columns, number of rows, and number of terms.
 - total time required is $O(terms \cdot cols)$.
 - in the worst case, $terms = cols \cdot rows$, i.e., we have $O(rows \cdot cols^2)$, worse than a straightforward implementation that takes $\Theta(rows \cdot cols)$ time.

FastTranspose

- First determine the number of elements in each column.
- We can then calculate the starting position for each row in the transposed matrix.

[0] [1] [2] [3] [4] [5]
$$rowSize$$
 3 2 1 0 1 1 $rowStart$ 0 3 5 6 6 7

• Total time O(cols + terms).

Representation of Arrays

- Multidimensional arrays are stored in a 1-D array. (Actually, any data type objects are stored in a 1-D array, i.e., memory.) And recall that we need random access.
- An array declared as $a[u_1][u_2], \dots, [u_n]$, the number of elements $\prod_{i=1}^n u_i$.
- Two way to store array a[m][n], row major and column major. Row major, store array row by row, Column major, column by column.

- 1-D array a[m], a the starting address of array a (address of a[0]), denoted α , a[i] stored at $\alpha + i$.
- **2-D** array a[m][n], a address of a[0][0], a[i][j] is stored at $\alpha + i \cdot n + j$.
- What if a sparse matrix
 - upper triangle
 - band
- Given a sparse matrix A[i][j], we store only the nonzero terms in a 1D array B, s.t. for a given (i, j) we return A[i][j] by calculating the address we store A[i][j] in B and retrieve it in B.

String Abstract Data Type

- C-string using array, C provides functions to precess string of char.
- A string ADT

```
class String
{
public:
   String (char *init, int m);
   int length();
   String Concat (String t);
   String Substr(int, i, int j);
   int Find(String pat);
}
```

String Matching

- Given two strings, s and pat, we usually say that s is the text and pat is the pattern.
- Determine whether pat in s by using the function Find, Find returns -1 if pat is not in s or returns the position in s where pat starts.
- Naive appraoch, compareing pat with string starting s[i] for every $0 \le i \le |s| |pat|$.
- if matched, return i, otherwise, move to i + 1.
- Worst case will be $|s| \cdot |pat|$.
- Can we do better?

Knuth-Morris-Pratt Algorithm

- An O(|pat| + |s|) time algorithm, and it is "optimal".
- Basic idea, a mismatch also tells us something.
- Calculate information from the pattern, pat, so that when a mismatch occurs, we don't have to start at the next position in s.

- The pattern pat = abcabcacab
- The string $s = s_0 s_1 \dots s_{m-1}$.
- Suppose that we are determining whether or not there is a match beginning s_i .
- If $s_i \neq a$ then we proceed by comparing s_{i+1} and a.

$$s = -a$$
???.. $pat = abcabcabcabcab$

- If $s_i = a$, we compare b against s_{i+1}
- if $b \neq s_{i+1}$, since that first question mark can be anything but not b,
- we proceed by comparing a and s_{i+1} .

$$s = - a b ? ? .$$
 $pat = a b c a b c a c a b$

- Suppose that we have $s_i s_{i+1} = ab$, but $c \neq s_{i+2}$,
- ullet We proceed by comparing a and s_{i+2}
- because we know that s_{i+1} is b, it cannot be a, so we don't have to compare a and s_{i+1} . And s_{i+2} is not c but can be any other, so we compare a and s_{i+2} .

$$s = -$$
 a b c a ? ? $pat =$ a b c a b c a c a b

- Suppose that we match abca and $s_i s_{i+1} s_{i+2} s_{i+3}$ but b does not match s_{i+4} ,
- Since we know s_{i+3} is a, we can proceed by comparing s_{i+4} and b, the 2nd character in pat.

Failure Function

If $p = p_0 p_1 \dots p_{n-1}$ is a pattern, then the failure function, f, is defined as

$$f(j) = \begin{cases} \text{largest } k < j \text{ s.t. } p_0 \dots p_k = p_{j-k} \dots p_j & \text{if such a } k \ge 0 \text{ exist} \\ -1 & \text{otherwise.} \end{cases}$$

pat = abcabcacab

Matching Algorithm

If a partial match is found s.t. $s_{i-j} cdots s_{i-1} = p_0 cdots p_{j-1}$ and $s_i \neq p_j$ then matching may be resumed by comparing s_i and $p_{f(j-1)+1}$ if $j \neq 0$. If j = 0, then we may continue by comparing s_{i+1} and p_0 .

1 2 3 4 5 6 pat a b c a b c a b f -1 -1 -1 0 1 2 3 -1 0 1 $a \ b \ c \ a \ b \ c \ a \ b \ c \ a \ b \ c \ a \ b \ c \ a \ b \ c \ c$ a b c a b c a ca b c a b c a ca b c a b c a ca b c a b c aa b c a

a

Matching Algorithm

• Time complexity O(length(S)).

- the correctness of the algorithm depends on the failure function can be computed in O(length(P)).
- restate the failure function

$$f(j) = \begin{cases} -1 & \text{if } j = 0\\ f^m(j-1) + 1 & \text{where } m \text{ is the least integer}\\ k \text{ for which } p_{f^k(j-1)+1} = p_j\\ -1 & \text{if there is no } k \text{ satisfying the above} \end{cases}$$

- $f^1(j) = f(j)$ and $f^m(j) = f(f^{m-1}(j))$
- Program 2.17 (next page), time complexity O(length(P))

- If j = 6, $p_j = a$,
- m = 1, f(5) + 1 = 3, $p_3 = a = p_j$, then f(6) = 3

• If j = 5, $p_5 = c$,

• If j = 9, $p_9 = b$,

• If j = 7, $p_7 = c$,

$$= 1, f(6) + 1 = 4, p_4 = b \neq p_7,$$

$$= 2, f(3) + 1 = 1, p_1 = b \neq p_7,$$

$$= 3, f(0) + 1 = 0, p_0 = a \neq p_7,$$

• thus f(7) = -1.

```
void String::FailureFunction()
  int lengthP=Length();
  f[0] = -1;
  for (int j=1; j<legnthP; j++)</pre>
         int i=f[j-1];
         while ((*(str+j)!=*(str+i+1)) \&\& (i>=0))
           i=f[i];
         if (*(str+j) == *(str+i+1))
           f[j]=i+1;
         else f[j] = -1;
```