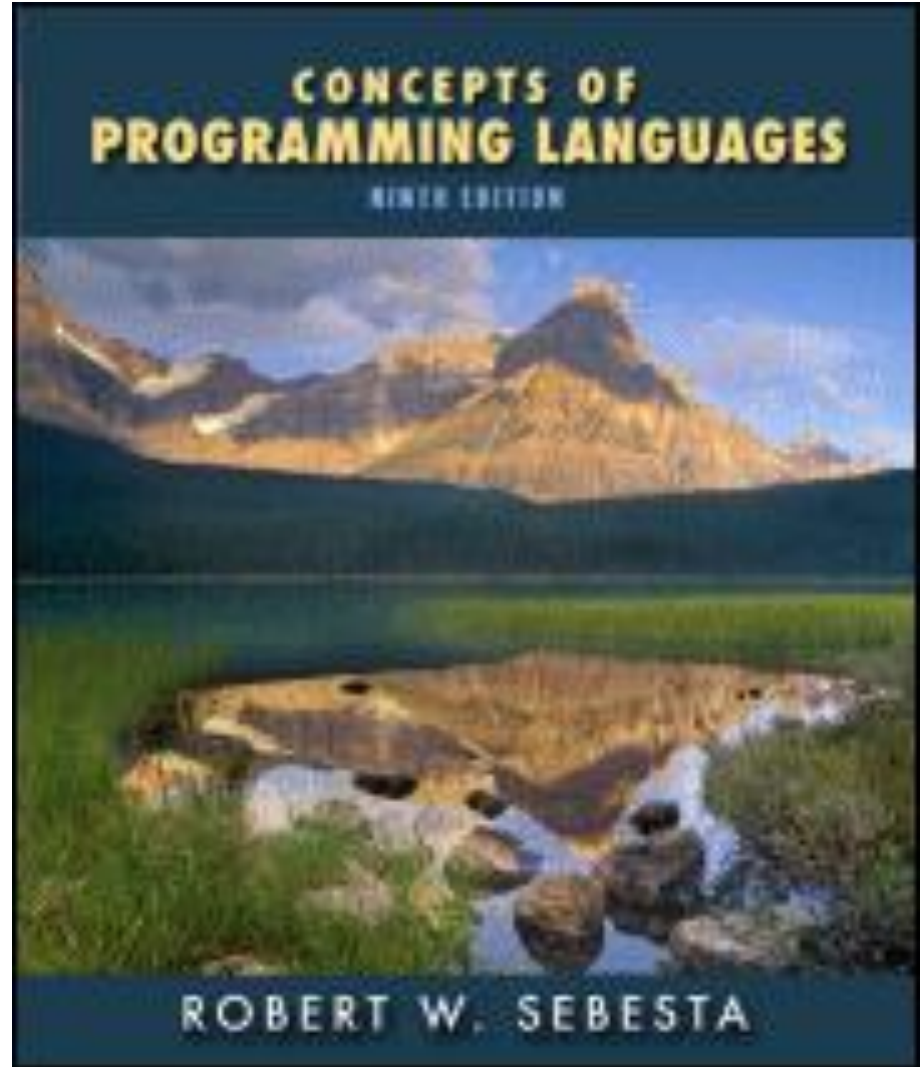


# Chapter 12

Support for  
Object-oriented  
Programming



# Ch12 – Support for Object-oriented Programming

12.1~12.9 Skipped

12.10 Implementation of Object-Oriented Constructs

# Implicit object parameter

- Implicit object parameter

- class A {

- public:

- compiled to

- A() : x(0) {}

- ⇒ A(A\* this) : this->x(0) {}

- void f() { x++; }

- ⇒ void f(A\* this) { this->x++; }

- private:

- int x;

- };

- A a;

- ⇒ A(&a);

- a.f();

- ⇒ f(&a);

this



a

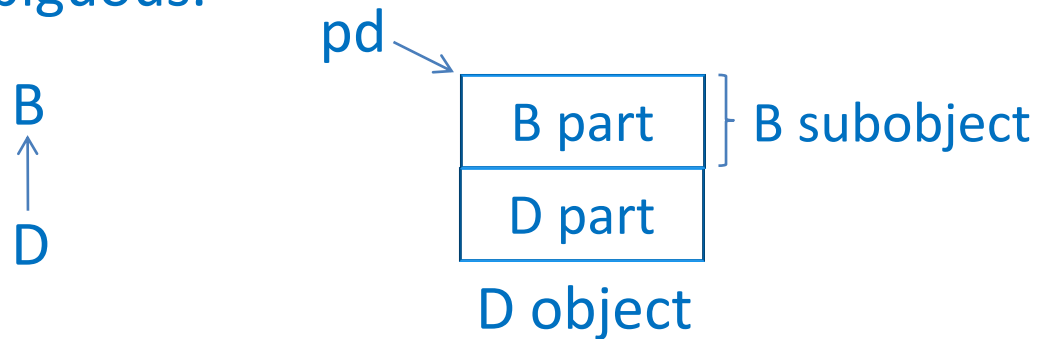


A object

# Standard pointer conversion

- Standard pointer conversion

- $D^*$  can be (implicitly) upcast to  $B^*$  or  
D can be (implicitly) upcast to  $B\&$ ,  
if B is accessible (i.e. a public member of B is accessible)  
and unambiguous.



- Upcast with single inheritance

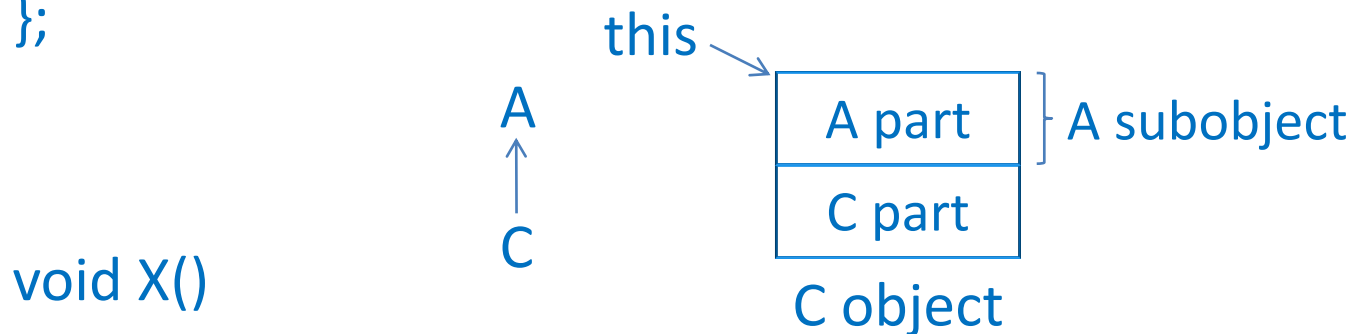
- Easy, the pointer remains the same, only its type changes.
- No ambiguity

# Single inheritance

- Upcast with single inheritance

- `class A { public: void f() {} }`  $\Rightarrow$  `void f(A* this) {}`
  - `class C : private A {`  $\Rightarrow$  `void g(C* this) { f(this); }`
  - `public: void g() { this->f(); }`
  - `};`

**upcast  $C^* \rightarrow A^*$**



```
void X()
{
```

```
    A& ra = *new C;
```

```
    ra.f();
```

```
}
```

// no, A is inaccessible

// otherwise, one can access C's

// private member f() through ra

# Multiple inheritance

- Upcast with multiple inheritance

- May need to adjust the pointer with some offset
- May be ambiguous

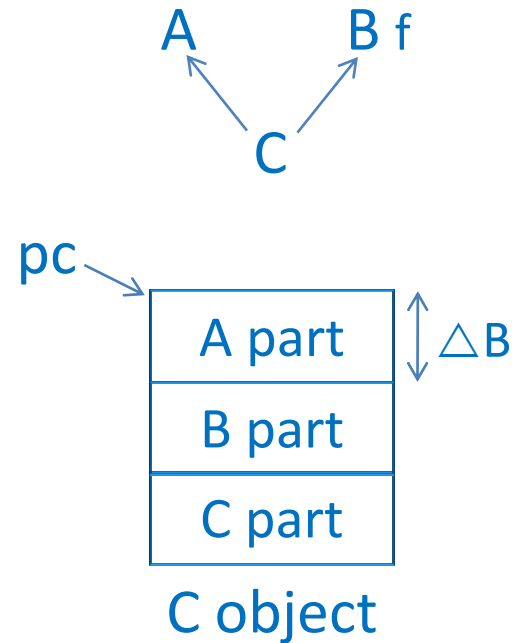
- ```
class A {};  
class B { public: void f(); };  
class C: public A, public B {};
```

`C* pc = new C;`

`pc->f();`

$\Rightarrow ((B^*) pc) \rightarrow f()$

$\Rightarrow ((B^*) ((char^*) pc + \Delta B)) \rightarrow f()$



# Multiple inheritance

- Upcast with multiple inheritance

- `class Z { public: void f(); };`  
`class A: public Z {};`  
`class B: public Z {};`  
`class C: public A, public B {};`

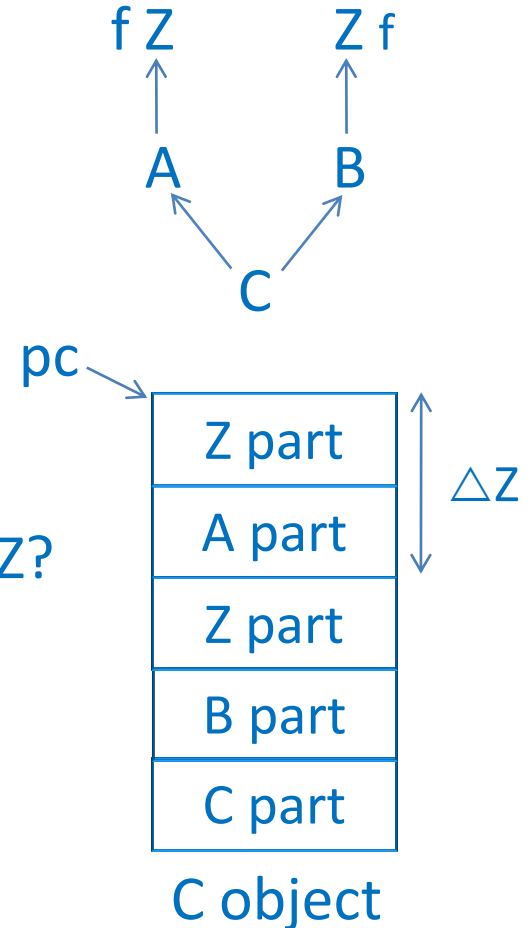
`C* pc = new C;`

`pc->f()` // ambiguous, which Z?

`pc->B::f()` // ok, `C::B::Z`

`((B*)pc) ->f()` // the same

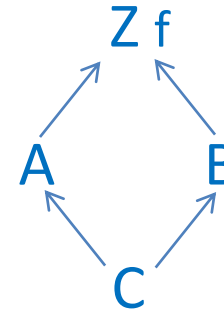
`((Z*)(B*)pc) ->f()` // the same



# Virtual base

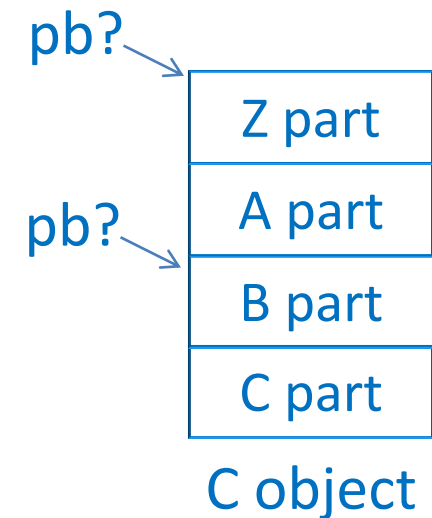
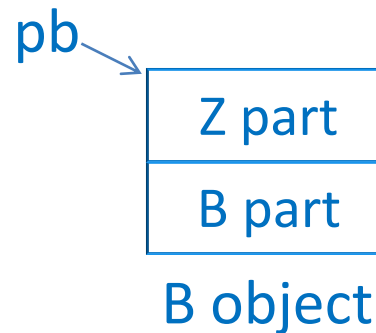
- Virtual base

- `class Z { public: void f(); };`  
`class A: public virtual Z {};`  
`class B: public virtual Z {};`  
`class C: public A, public B {};`



`B* pb = new B;`

`B* pb = new C;`



Bad layout, the Z subobject isn't in the same position relative to B part.

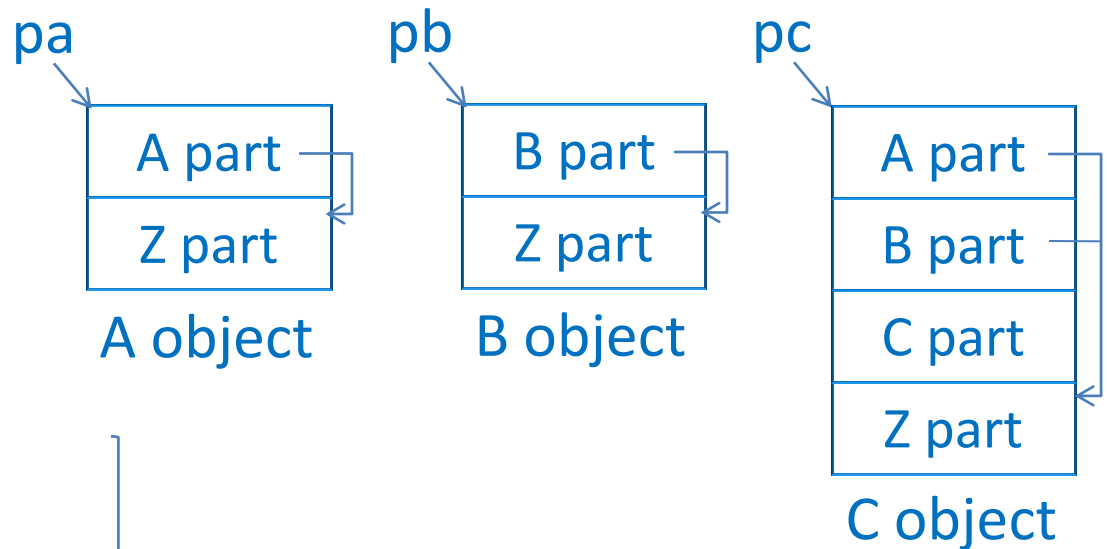


# Virtual base

- Virtual base

- The solution is to store a pointer to the Z subobject in all objects of classes that have Z as a virtual base.

- A\* pa = new A;  
B\* pb = new B;  
C\* pc = new C;



pa->f()

pb->f()

pc->f(), ((A\*)pc)->f()

((B\*)pc)->f()

} Use the stored pointer to upcast

# Member name lookup

- Member name lookup

- Class hierarchy considered as block structure



- In

exp.f                    // f is looked up in the static type of exp

exp.A::f                // f is looked up in the qualified type A

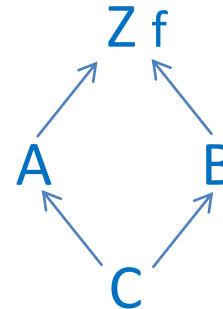
where A must be a base type of the static type of exp.

e.g. C\* pc = new C

pc->f(), i.e. (\*pc).f()

pc->A::f()

((A\*)pc)->f()



# Member name lookup

- Member name lookup

- It is ambiguous, if the resulting set of declarations are not all from subobjects of the same type.

e.g. C\* pc = new C;

pc->f() // ambiguous

pc->A::f() // A::f

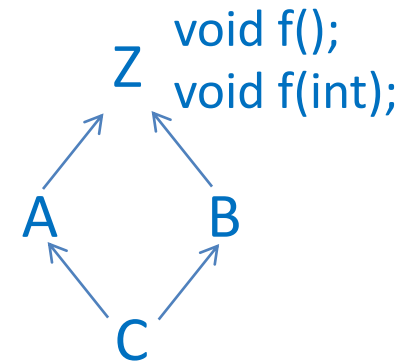
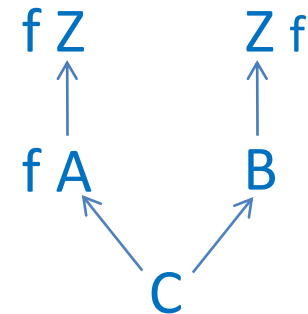
pc->B::f() // B::Z::f

pc->A::Z::f() // A::Z::f

- Otherwise, apply overloading resolution to the resulting set of declarations

e.g. C\* pc = new C;

pc->f()



# Member name lookup

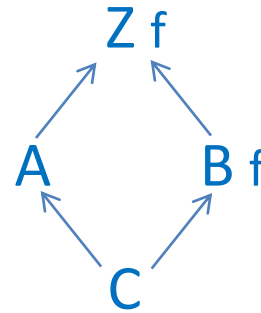
- Member name lookup

- Any hidden declaration of `f` is eliminated from consideration

e.g. `C* pc = new C;`

`pc->f()`      `// B::f`

`pc->A::f()`   `// Z::f`

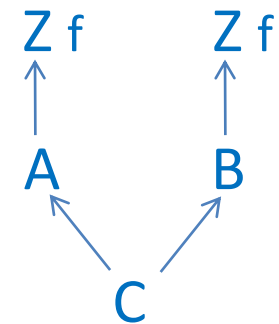


- It is ambiguous, if the resulting set of declarations has a nonstatic member and includes members from distinct subobjects of the same type.

e.g. `C* pc = new C;`

`pc->f()`      `// ambiguous, unless f is static`

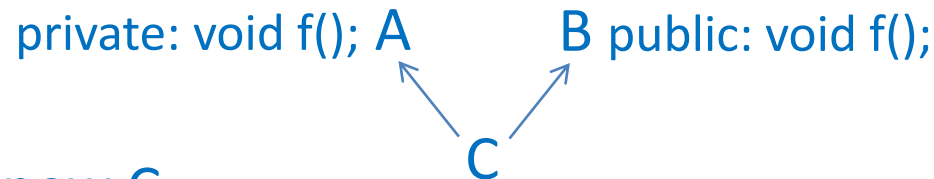
`pc->A::f()`   `// A::Z::f`



# Member name lookup

- Member name lookup

- Name lookup → overload resolution → access control
- Name lookup → access control



C\* pc=new C;

pc->f() // ambiguous, even if A::f is private

Why?

Access control is related to data encapsulation, and has nothing to do with the meaning of a program.

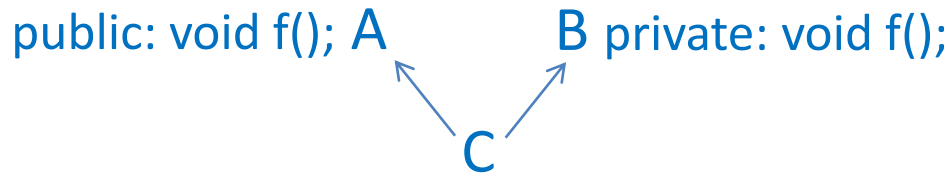
Thus, changing the accessibility of a class member should not change the meaning of a program.

# Member name lookup

- Member name lookup

- (Cont'd)

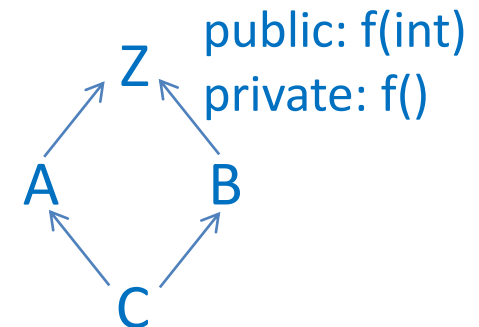
Were access control taken place before name lookup, B::f would be selected above, but A::f would be selected below



- Overload resolution → access control

`C* pc=new C;`

`pc->f()` // error, call private Z::f()



Were access control taken place before overloading resolution, the error would be "no viable function".

# Virtual function

- Virtual function

- A virtual function call depends on the object's dynamic type

- class A {

```
public: virtual void f();  
};
```

```
class C: public A {
```

```
public: virtual void f(); // overwrite A::f  
};
```

```
A* pa=new A;           // dynamic type A; static type A
```

```
pa->f();                // call A::f
```

```
A* pa=new C;           // dynamic type C; static type A
```

```
pa->f();                // call C::f
```

OOP = Virtual function  
+ Inheritance

# Virtual function lookup

- Virtual function lookup

- Step 1

Use member name lookup to resolve the function as usual.  
(The virtual specifier is ignored in this step.)  
(It is erroneous, if ambiguity arises.)

- Step 2

Find the *unique* final overrider of the virtual function along the path(s) from the object's dynamic type to the class containing the resolved function.  
(The class hierarchy is ill-formed, if there is no unique final overrider.)



# Virtual function lookup

- Virtual function lookup

- Example

|                                                         |              |              |             |
|---------------------------------------------------------|--------------|--------------|-------------|
| $\begin{array}{c} A\ f \\ \uparrow \\ C\ f \end{array}$ | A* pa=new C; |              |             |
|                                                         | pa->f()      | step 1: A::f | step 2: C:f |
|                                                         | C* pc=new C; |              |             |
|                                                         | pc->f()      | step 1: C::f | step 2: C:f |
|                                                         | A* pa=new A; |              |             |
|                                                         | pa->f()      | step 1: A::f | step 2: A:f |

Convention: A virtual function overrides itself.

# Virtual function lookup

- Virtual function lookup

- Difference between step 1 and step 2

## Step 1

Where to start     the static or qualified type

Where to search   all base types of the static or qualified type

Condition         hiding (parameters aren't considered)

## Step 2

Where to start     the dynamic type

Where to search   only the path(s) from the dynamic type to  
the class containing the resolved function

Condition         overriding (parameters are considered)

# Virtual function lookup

- Virtual function lookup

- C\* pc=new C;

pc->f()

step 1 C::f(int) not viable

A\* pa=new C;

pa->f()

step 1 A::f()

step 2 A::f()

- Z\* pz=new C;

pz->f()

step 1 Z::f

step 2 error

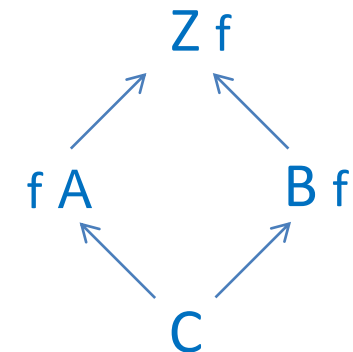
This class hierarchy is illegal, since

Z::f has two final overriders:

A::f along the path Z-A-C , and B::f along Z-B-C

A f()  
↑  
C f(int)

It doesn't matter if  
C::f is virtual or not



# Virtual function lookup

- Virtual function lookup

- Z\* pz=new C;

pz->f()

step 1 Z::f

step 2 A::f (downcast)

B\* pb=new C;

pb->f()

step 1 Z::f

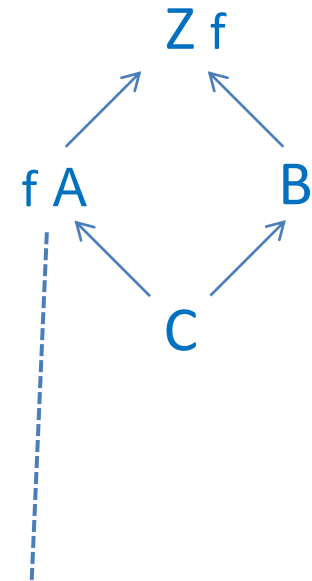
step 2 A::f (crosscast)

C\* pc=new C;

pc->f()

step 1 A::f

step 2 A::f (upcast)

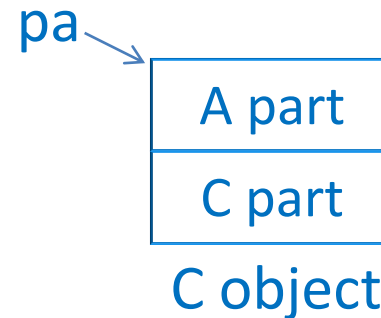
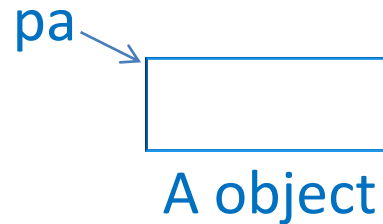


Inheritance via dominance  
since A::f dominates.

# Implementation of virtual functions

- How to tell the dynamic type?

- 



A\* pa=new A;

A\* pa=new C;

As such, there is no way to tell the dynamic type of \*pa.  
i.e. if pa points to a stand-alone or an embedded A object?

# Implementation of virtual functions

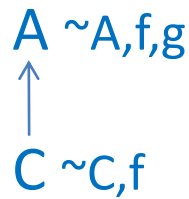
- Virtual table (vtble)
  - There is one vtble per polymorphic class (i.e. class that declares or inherits virtual functions) .
  - The vtble contains information about virtual functions; nonvirtual functions are not in the vtble.
- Virtual pointer (vptr)
  - Each object contains a vptr pointing to the vtble of its class.
- Single inheritance
  - $A \sim A, f, g$   
 $\uparrow$   
 $C \sim C, f$

Assume that all members are public virtual and all inheritances are public.  
Virtual dtors guarantee correct deletion, e.g.  
`A* pa=new C; delete pa;`

# Implementation of virtual functions

- Single inheritance

- Virtual table



By analyzing this inheritance lattice, the compiler constructs a virtual table for each class.

|        |   |
|--------|---|
| A::~~A | 0 |
| A::f   | 0 |
| A::g   | 0 |

A's vtbl

Dynamic type A

stand-alone A objects

|        |   |
|--------|---|
| C::~~C | 0 |
| C::f   | 0 |
| A::g   | 0 |

C/A's vtbl

Dynamic type C

C objects or embedded A objects

code pointer

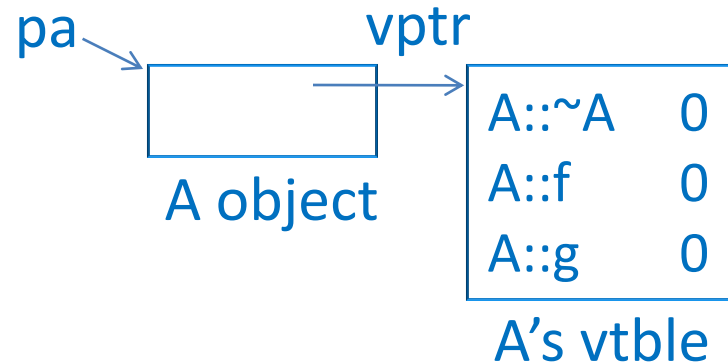
offset

# Implementation of virtual functions

- Single inheritance

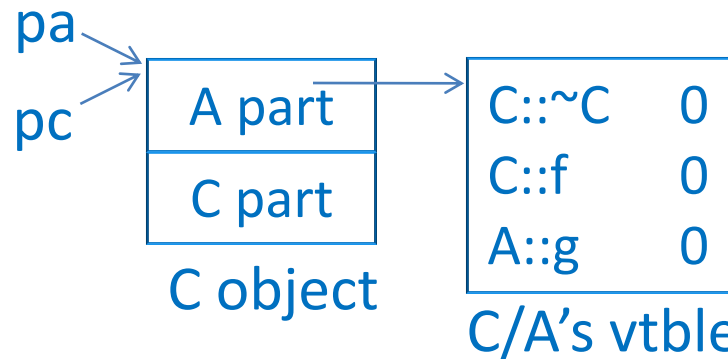
- Virtual pointers

A\* pa=new A;



A\* pa=new C;

C\* pc=new C;



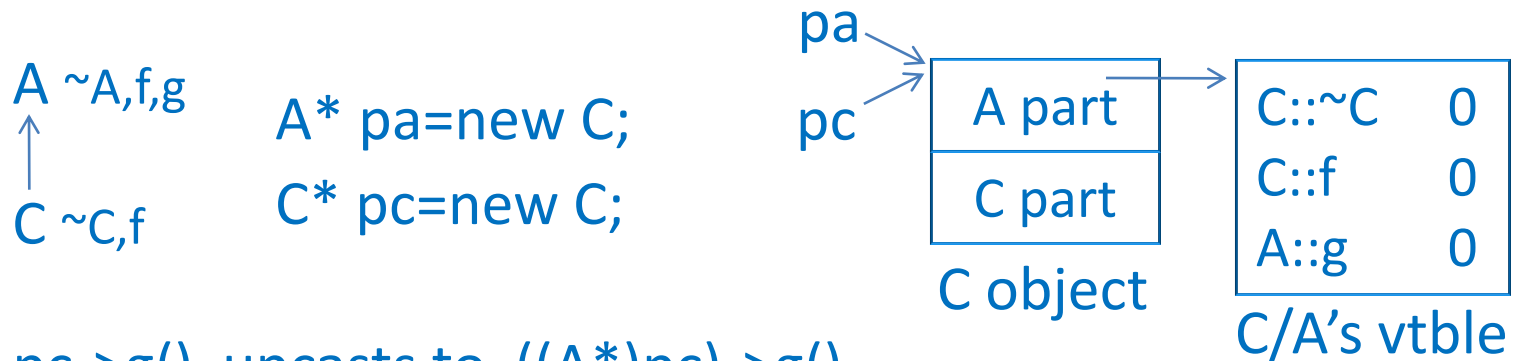
The call `pa->f()` can tell the dynamic type of `*pa`, but the call `pa->g()` can't. The point is: It doesn't matter.



# Implementation of virtual functions

- Single inheritance

- Observation 1 – Offsets help upcast, downcast, and crosscast



$\text{pc} \rightarrow g()$  upcasts to  $((A^*)\text{pc}) \rightarrow g()$

$\text{pa} \rightarrow f()$  downcasts to  $((C^*)\text{pa}) \rightarrow f()$

Due to single inheritance, the pointers remain the same in both cases. Thus, the offsets are all 0's.

N.B. If a language allows only single inheritance, the offsets needn't be stored in virtual tables.

# Implementation of virtual functions

- Single inheritance

- Observation 2

The set of virtual functions of a class is fixed. So, there is no need of searching the vtbl – the compiler knows where each function is.

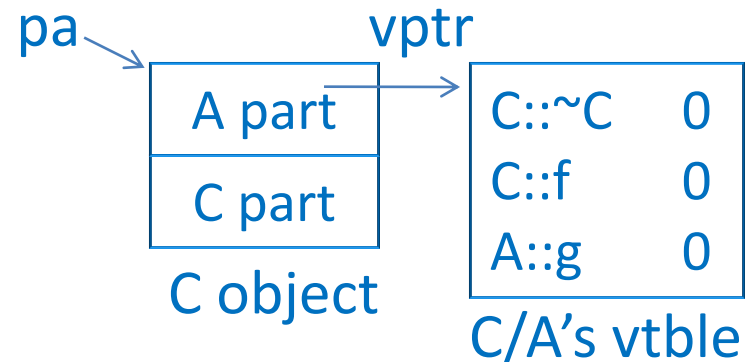
For example,

`pa->f()`

is compiled to

`pa->vp[1][0]((C*)((char*)pa+pa->vp[1][1]))`

N.B. The small piece of code used to implement virtual function call is called a *thunk*. (The vtbl contains code pointers + offsets – similar to closures.)



# Implementation of virtual functions

- Single inheritance

- Observation 3

Wherever it appears, the vtable of a class must have the same layout.

For example, stand-alone A's vtable and embedded A's vtable must have the same layout so that

`pa->f()`

can always be compiled to

`pa->vptr[1][0](((C*)((char*)pa+pa->vptr[1][1]))`

|        |   |
|--------|---|
| A::~~A | 0 |
| A::f   | 0 |
| A::g   | 0 |

A's vtable

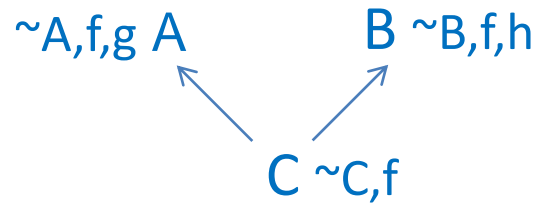
|        |   |
|--------|---|
| C::~~C | 0 |
| C::f   | 0 |
| A::g   | 0 |

C/A's vtable

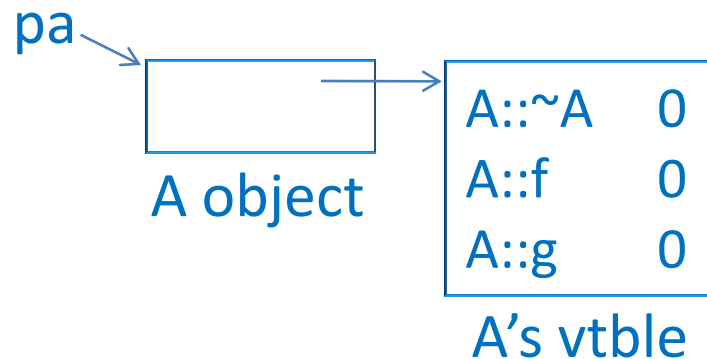
# Implementation of virtual functions

- Multiple inheritance

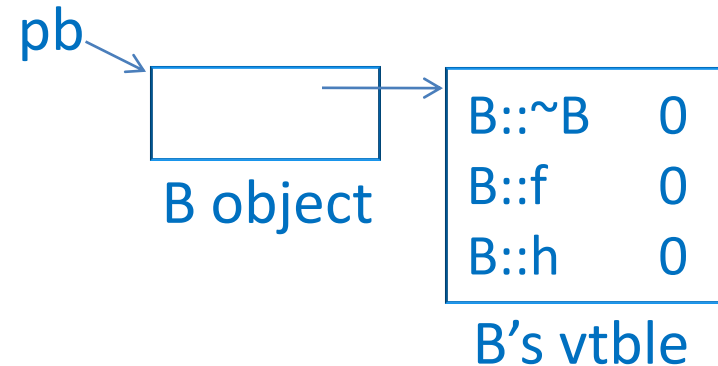
- 



- A\* pa=new A;



- B\* pb=new B;



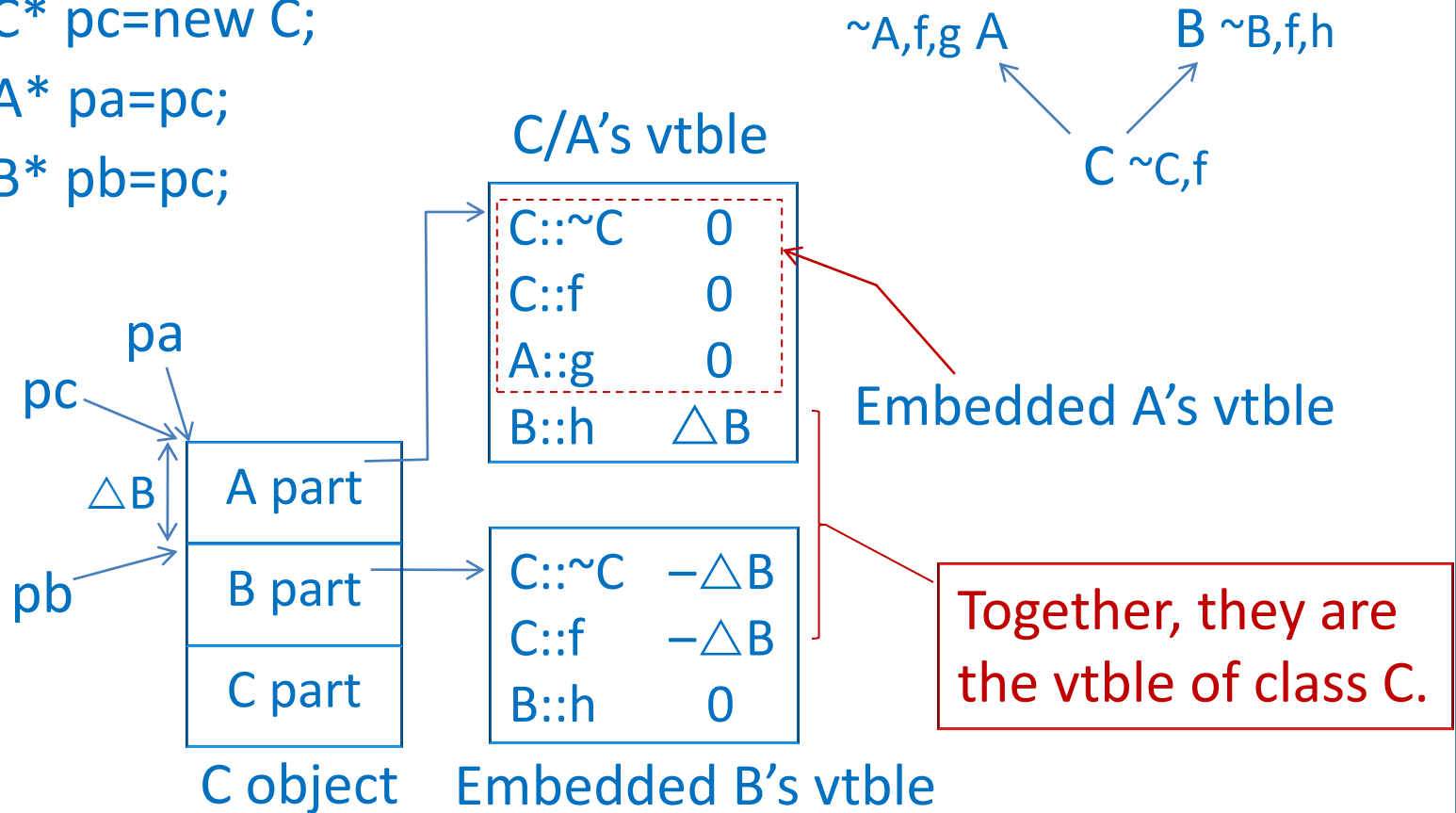
# Implementation of virtual functions

- Multiple inheritance

- $C^* \text{ pc} = \text{new } C;$

- $A^* \text{ pa} = \text{pc};$

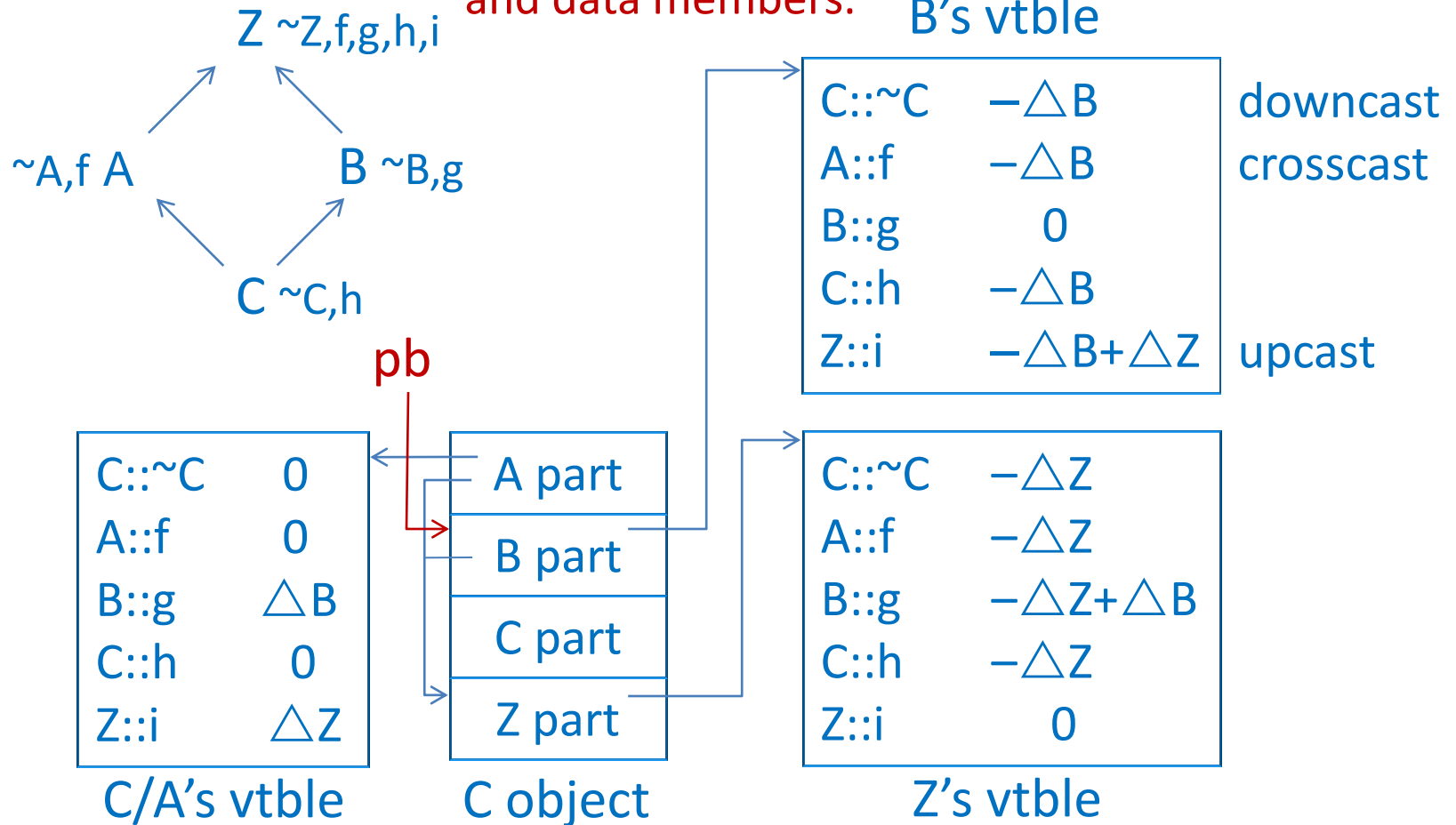
- $B^* \text{ pb} = \text{pc};$



# Implementation of virtual functions

- Virtual base

Virtual base pointers are for nonvirtual functions and data members.



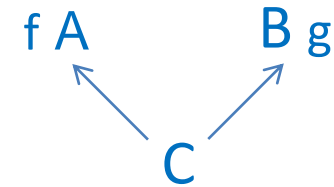
# Run-time type information (RTTI)

- RTTI has 3 components
  - `type_info` class  
record type information of a class
  - `typeid` operator  
obtain a `type_info` object
  - `dynamic_cast` operator  
browse the class hierarchy (upcast, downcast, crosscast)

# Run-time type information (RTTI)

- RTTI

- `class A { public: virtual void f() {} };`  
`class B { public: virtual void g() {} };`  
`class C: public A, public B {};`



- Upcast

```
C* pc=new C;
```

```
cout << typeid(*pc).name(); // class C (up to compiler)
```

```
typeid(*pc)==typeid(C) // true
```

```
dynamic_cast<B*>(pc)->g(); // upcast, compile-time check
```

```
static_cast<B*>(pc)->g(); // upcast, compile-time check
```

```
pc->g(); // upcast, compile-time check
```



# Run-time type information (RTTI)

- RTTI

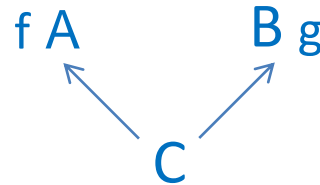
- Downcast

```
A* pa=new C;
```

```
cout << typeid(*pa).name();    // class C
dynamic_cast<C*>(pa)->g();      // runtime check, ok
static_cast<C*>(pa)->g();       // unchecked, but ok
```

```
A* pa=new A;
```

```
cout << typeid(*pa).name();    // class A
dynamic_cast<C*>(pa)            // fail; yield a null pointer
static_cast<C*>(pa)             // undefined
```



# Run-time type information (RTTI)

- RTTI

- Crosscast

```
A* pa=new C;
```

```
dynamic_cast<B*>(pa)->g();    // runtime check, ok
```

```
static_cast<B*>(pa)->g();    // unchecked, but ok
```

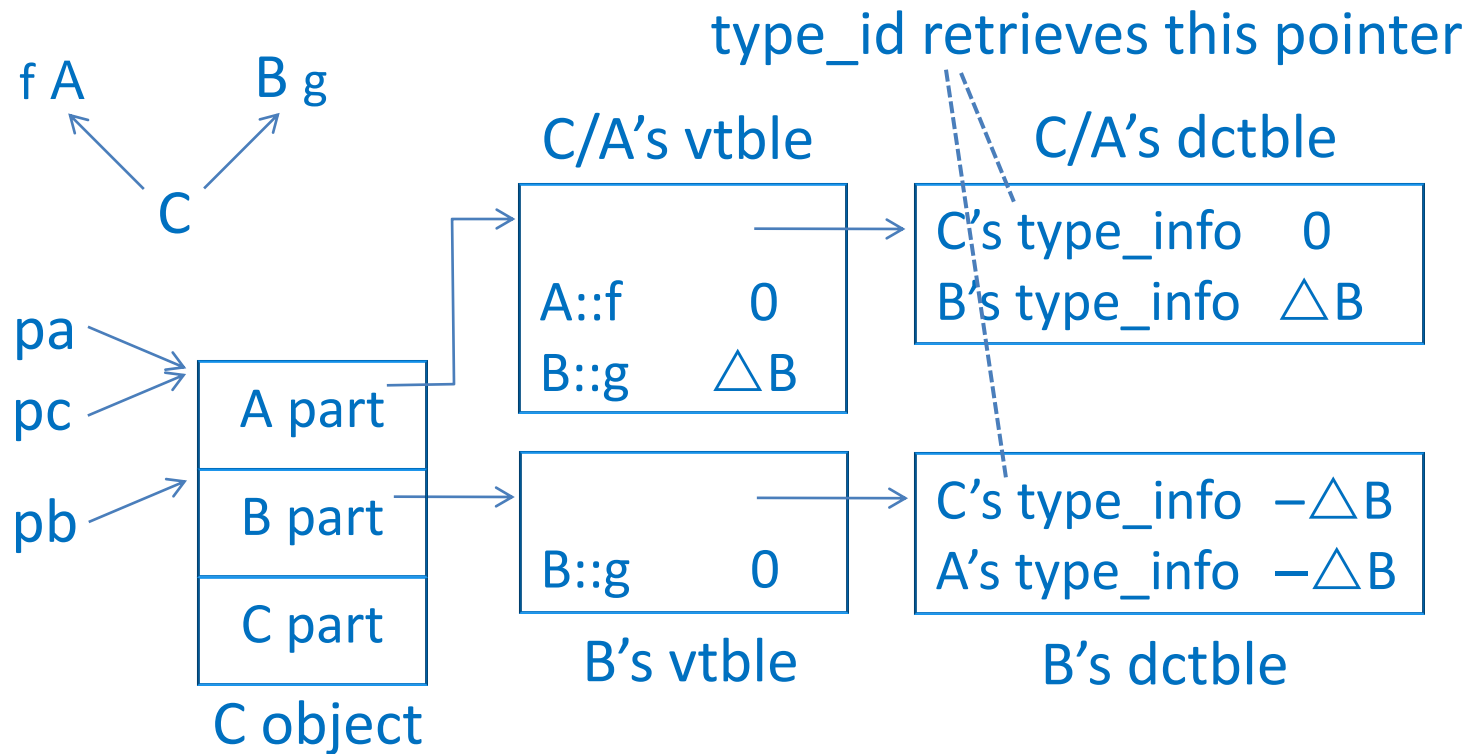
```
A* pa=new A;
```

```
dynamic_cast<B*>(pa)           // fail; yield a null pointer
```

```
static_cast<B*>(pa)           // undefined
```

# Run-time type information (RTTI)

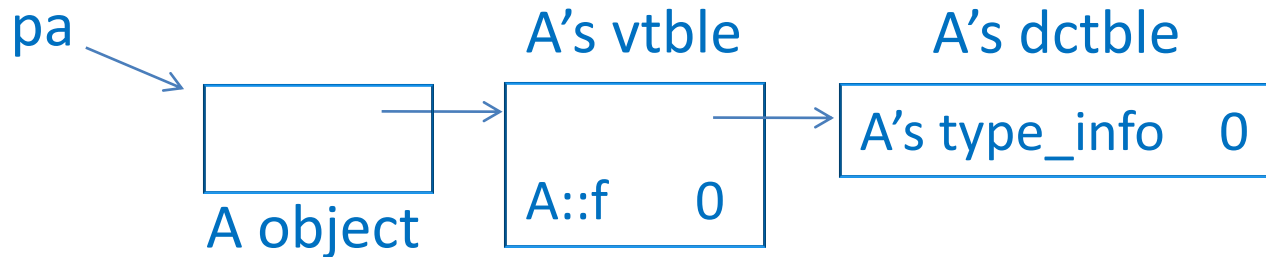
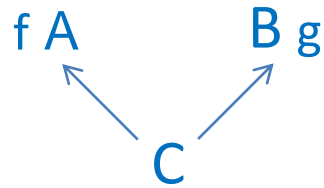
- Dynamic\_cast table (dctble)
  - Dctbles contain information necessary for type\_id and dynamic\_cast. (No information for upcast is stored.)



# Run-time type information (RTTI)

- `Dynamic_cast` table (dctble)

○

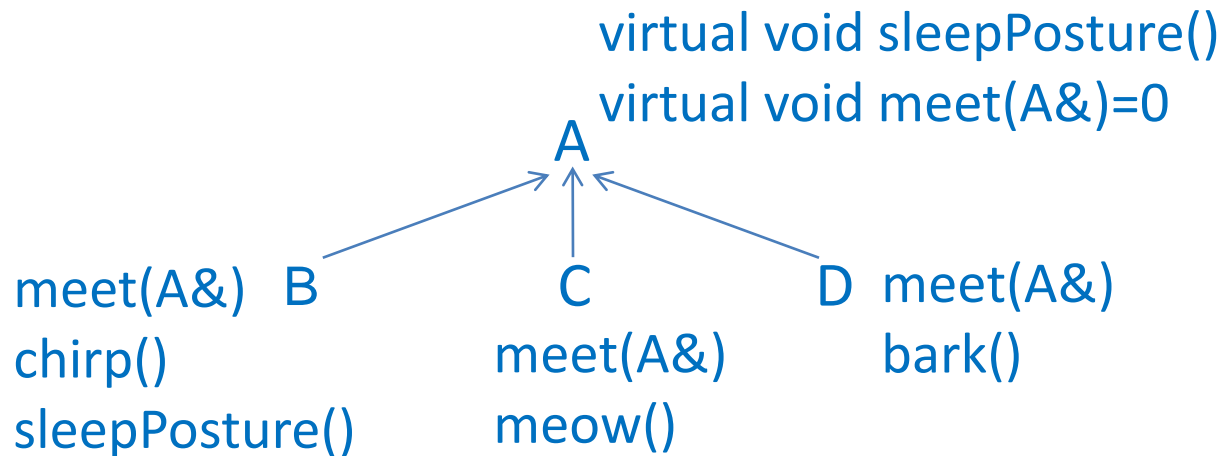


e.g.

`dynamic_cast<C*>(pa)` and `dynamic_cast<B*>(pa)` fail.

# Double dispatching

- Abstract and concrete class



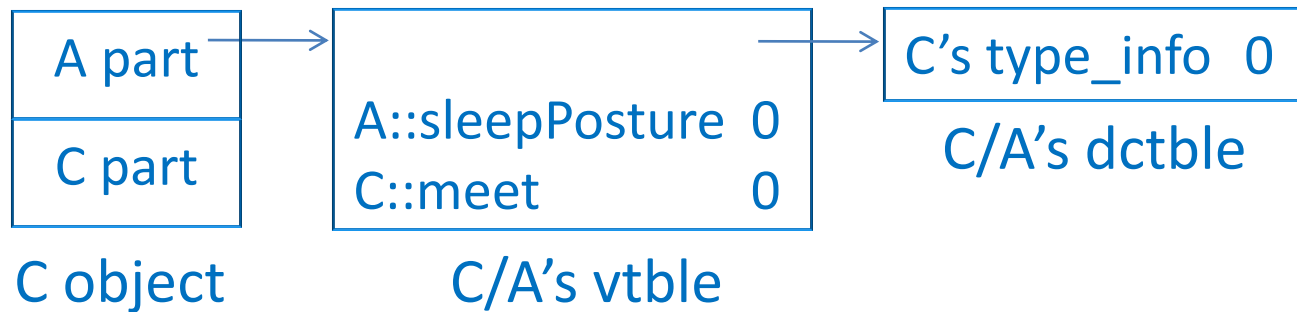
- A virtual function, e.g. `A::sleepPosture()` , provides an interface as well as a *default* implementation that may be overwritten.
- A pure virtual function, e.g. `A::meet(A&)` provides only an interface.

# Double dispatching

- Abstract and concrete class

- A is an abstract class; B, C, and D are concrete classes.
- A concrete class provides its own implementation of inherited pure virtual functions.
- No objects of an abstract class can be created except as subobjects of a class derived from it.

Thus, an abstract class doesn't have a stand-alone vtable, but has an embedded vtable as a subobject.



# Double dispatching

- Single dispatching

- A virtual function call that depends on the dynamic type of one object is called single dispatching, e.g.

A\* pa=new B;

pa->sleepPosture()      // B::sleepPosture()

- Virtual function mechanism directly supports single dispatching.

- Double dispatching

- A virtual function call that depends on the dynamic types of two objects is called double dispatching, e.g.

A &a1=\*new D, &a2=\*new C;

a1.meet(a2);                      // D::meet(A&) , where A is C

# Double dispatching

- Double dispatching

- Method 1 – Use typeid

```
void D::meet(A& a)
{
    bark();
    if (typeid(a)==typeid(B))
        static_cast<B&>(a).chirp();
    else if (typeid(a)==typeid(C))
        static_cast<C&>(a).meow();
    else if (typeid(a)==typeid(D))
        static_cast<D&>(a).bark();
}
```

static\_cast is better than dynamic\_cast, as it is efficient and guaranteed safe here



# Double dispatching

- Double dispatching

- Method 2 – Use `dynamic_cast`, pointer version

```
void D::meet(A& a)
{
    bark();
    if (B* pb=dynamic_cast<B*>(&a)) pb->chirp();
    else if (C* pc=dynamic_cast<C*>(&a)) pc->meow();
    else if (D* pd=dynamic_cast<D*>(&a)) pd->bark();
}
```

A failed `dynamic_cast` to a pointer type yields a null pointer

A failed `dynamic_cast` to a reference type throws a `bad_cast` object.

# Double dispatching

- Double dispatching

- Method 2 – Use `dynamic_cast`, reference version

```
void D::meet(A& a)
{
    bark();
    try { dynamic_cast<B&>(a).chirp(); }
    catch (bad_cast&) {
        try { dynamic_cast<C&>(a).meow(); }
        catch (bad_cast&) {
            dynamic_cast<D&>(a).bark();
        }
    }
}
```

# Double dispatching

- Double dispatching

- Method 3 – Use two single dispatchings

```
class B; class C; class D;
```

```
class A {
```

```
public:
```

```
    virtual void sleepPosture() { cout << "lying prone\n"; }
```

```
    virtual void meet(A&)=0;
```

```
    virtual void meet(B&)=0;
```

```
    virtual void meet(C&)=0;
```

```
    virtual void meet(D&)=0;
```

```
};
```

```
A& a1=*new D;  
A& a2=*new C;  
a1.meet(a2);
```

resolved to A::meet(A&)  
dispatch D::meet(A&)

# Double dispatching

- Double dispatching

- class B: public A {

- public:

- void chirp() { cout << "chirp\n"; }

- virtual void sleepPosture() { cout << "standing\n"; }

- virtual void meet(A& a) { a.meet(\*this); }

- virtual void meet(B& b) { chirp(); b.chirp(); }

- virtual void meet(C& c); // { chirp(); c.meow(); }

- virtual void meet(D& d); // { chirp(); d.bark(); }

- };

# Double dispatching

- Double dispatching

```
class C: public A {
```

```
public:
```

```
    void meow() { cout << "C::meow\n"; }
```

```
    virtual void meet(A& a) { a.meet(*this); }
```

```
    virtual void meet(B& b) { meow(); b.chirp(); }
```

```
    virtual void meet(C& c) { meow(); c.meow(); }
```

```
    virtual void meet(D& d); // { meow(); d.bark(); }
```

```
};
```

```
A& a1=*new C;
```

```
B& a2=*new B;
```

```
a1.meet(a2);
```

resolved to A::meet(B&)  
dispatch C::meet(B&)

# Double dispatching

- Double dispatching

```
class D: public A {  
public:
```

```
    void bark() { cout << "D::bark\n"; }  
    virtual void meet(A& a) { a.meet(*this); }  
    virtual void meet(B& b) { bark(); b.chirp(); }  
    virtual void meet(C& c) { bark(); c.meow(); }  
    virtual void meet(D& d) { bark(); d.bark(); }
```

```
};
```

```
void B::meet(C& c) { chirp(); c.meow(); }
```

```
void B::meet(D& d) { chirp(); d.bark(); }
```

```
void C::meet(D& d) { meow(); d.bark(); }
```

resolved to A::meet(D&)  
dispatch C::meet(D&)

